

1.) Description

Included is a driver program called `p3_driver` that takes as an argument the path to a file containing all the configuration information necessary to create and test an ID3 decision tree. The tree is constructed by helper function in the driver program with the help of data structures in `DTreeNode.h` and `patterns.h/cc`. It is programmed in `c` and `c++`. The program prints tree construction related information to `stdout` and prints the actual output vectors and error values to the file specified in the config file passed from the commandline.

2.) Trace - I'm not sure if you want to include the output in here, since I don't actually print the output to `stdout` I'm going to first paste what the program prints to `stdout` then paste the stuff it prints to the file. Also I output my tree differently from the example because the example was hard for me to read. And the decision values print before the tree are 0 based, in actuality they are zero based in memory at all times but I added 1 when I printed it to make it match the log file.

```
jlusby@Manon:~/code/machine-learning/p3/code$ ./p3_driver ../test/lenses-dtl.cfg
```

```
decision:6
```

```
0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
```

```
1
```

```
decision:0
```

```
0 2 4 5 7 10 11 14
```

```
0
```

```
decision:5
```

```
0 2 4 5 7
```

```
decision:3
```

```
2 4 7
```

```
0
```

```
1
```

```
0
```

```
7 false then
```

```
1 false then
```

```
6 false then
```

```
FALSE
```

```
6 true then
```

```
4 false then
```

```
TRUE
```

```
4 true then
```

```
FALSE
```

```
1 true then
```

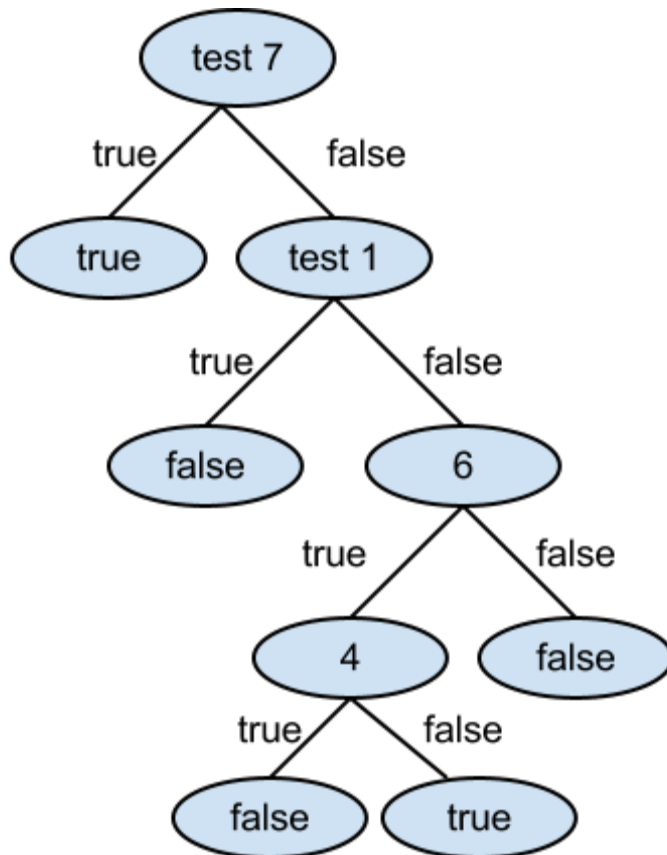
```
FALSE
```

```
7 true then
```

```
TRUE
```

0011000011
0011001110
0011011110
0100111110
0101000000
0101010000
1000101110
1001000000
0.125

3.) graphical representation of the tree (from trace)



7 false then
1 false then
6 false then
FALSE
6 true then
4 false then
TRUE
4 true then
FALSE
1 true then

FALSE
7 true then
TRUE

4.) Analysis of the likely true error of the learned decision tree based on performance on testing set

5.) brief summary of what was learned

Learned about decision learning trees, which was cool. This project is probably my favorite so far. I got to play around with autoconf and automake some more which was fun. I kinda skimmed through it though because I was a little afraid I would be strapped for time on this project. As always got lots of good practice with vim and git.

6.) Citations

David Noelle - for source code for pattern set. also used some lines from his compilation files to get mine set up quicker.

The textbook - for an in depth explanation of the ID3 decision learning algorithm

Machine Learning class - general knowledge

Stefan Achleitner - Compared output with his once we had both finished our code to ensure we were both getting the same tree for testing set.