Ex. No. : 5 Date:

Register No.: 231701055 Name: Suga V

Write a program that allows the user to perform 3D transformations on basic 3D objects (cube, pyramid) and view the results.

AIM:

• To write a program that allows the user to perform **3D transformations** (translation, rotation, scaling) on basic 3D objects (cube and pyramid) and visualize the results using computer graphics.

Procedure:

- 1. Define the 3D object (cube or pyramid) using vertices and edges/faces.
- 2. Apply transformation matrices for:
 - a. Translation (shifting along x, y, z).
 - b. Scaling (enlarging or shrinking).
 - c. Rotation (around x, y, z axes).
- 3. Multiply the original vertices by the chosen transformation matrix.
- 4. Use **perspective or orthographic projection** to convert 3D coordinates into 2D screen coordinates.
- 5. Draw the transformed object on the screen.
- 6. Allow the user to select object type (cube/pyramid) and the transformation to apply.

Program:

import numpy as np import matplotlib.pyplot as plt from mpl_toolkits.mplot3d.art3d import Poly3DCollection def create cube():

```
return np.array([
     [0, 0, 0],
     [1, 0, 0],
     [1, 1, 0],
     [0, 1, 0],
     [0, 0, 1],
     [1, 0, 1],
     [1, 1, 1],
     [0, 1, 1]
  ])
def create_pyramid():
  return np.array([
     [0, 0, 0],
     [1, 0, 0],
     [1, 1, 0],
     [0, 1, 0],
     [0.5, 0.5, 1]
  ])
# ----- Transformations -----
def translate(vertices, tx, ty, tz):
  T = np.array([tx, ty, tz])
  return vertices + T
def scale(vertices, sx, sy, sz):
  S = np.diag([sx, sy, sz])
  return np.dot(vertices, S)
def rotate_x(vertices, angle):
  rad = np.radians(angle)
  R = np.array([
     [1, 0, 0],
     [0, np.cos(rad), -np.sin(rad)],
```

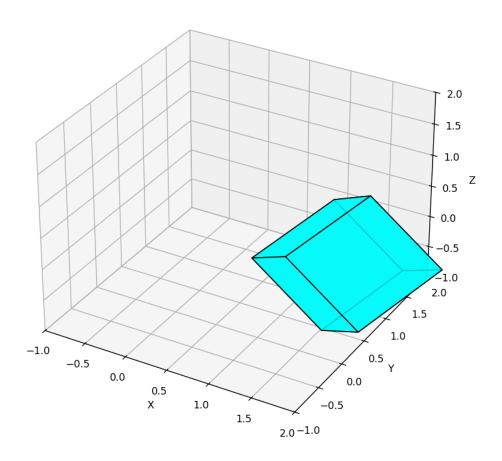
```
[0, np.sin(rad), np.cos(rad)]
  ])
  return np.dot(vertices, R)
def rotate y(vertices, angle):
  rad = np.radians(angle)
  R = np.array([
     [np.cos(rad), 0, np.sin(rad)],
     [0, 1, 0],
     [-np.sin(rad), 0, np.cos(rad)]
  ])
  return np.dot(vertices, R)
def rotate z(vertices, angle):
  rad = np.radians(angle)
  R = np.array([
     [np.cos(rad), -np.sin(rad), 0],
     [np.sin(rad), np.cos(rad), 0],
     [0, 0, 1]
  ])
  return np.dot(vertices, R)
# ----- Draw -----
def draw object(vertices, faces,
title):
  fig = plt.figure()
  ax = fig.add subplot(111,
projection='3d')
  poly3d = [[vertices[vert] for vert
in face] for face in faces]
```

```
ax.add collection3d(Poly3DCollecti
on(poly3d, facecolors='cyan',
linewidths=1, edgecolors='black',
alpha=0.8))
  ax.set_title(title)
  ax.set xlabel('X')
  ax.set ylabel('Y')
  ax.set_zlabel('Z')
  ax.auto_scale_xyz([0, 2], [0, 2],
[0, 2]
  plt.show()
# ----- Main -----
choice = input("Choose object
(cube/pyramid): ").lower()
if choice == "cube":
  vertices = create_cube()
  faces = [[0,1,2,3], [4,5,6,7],
[0,1,5,4], [2,3,7,6], [1,2,6,5],
[0,3,7,4]
elif choice == "pyramid":
  vertices = create pyramid()
  faces = [[0,1,2,3], [0,1,4], [1,2,4],
[2,3,4], [3,0,4]]
else:
  print("Invalid choice.")
  exit()
# Apply transformations
vertices = translate(vertices, 0.5, 0.5,
0)
vertices = scale(vertices, 1.2, 1.2,
1.2)
```

vertices = rotate_x(vertices, 30)
vertices = rotate_y(vertices, 45)

Draw
draw_object(vertices, faces,
f"Transformed
{choice.capitalize()}")

Transformed Cube



Final vertices for cube:

Result:

The program successfully creates **3D objects** (cube/pyramid).