关于试验细节的一些说明

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- 可以先看"实验的结果"部分,不需要了解详细过程也可以看到验证的结果。

实验流程的说明

首先,实验项目在https://github.com/SugarSBN/QCNN-robustness-verifier,全部使用C++,不依赖任何第三方库,可直接编译执行。

大体流程是,有一个类Polygon,该类有一个重要的成员变量:vector < PureState > points,它里面是四个PureState,构成了一个四边形。 Polygon里还有一个成员变量:center :: PureState,表示我们需要验证的量子态。

然后我们对这个Polygon验证,这部分在"域的验证"这一部分说明。

一旦Polygon得到验证,那么就可以通过数值计算得到一个鲁棒域。这一部分在"鲁棒界的确定说明"。

然后是"实验的结果"。

最后讨论了 "Polygon" 的选择。

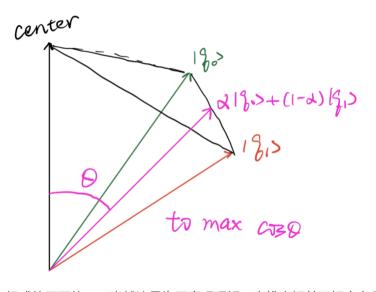
域的验证

```
vector<bool> Polygon :: verify(int ans){
   PureState tmp;
   vector<bool> res;
   for (int i = 0;i < points.size();i++){
       tmp = points[i];
       tmp.apply_circuit(c);
       res.push_back(tmp.predict() == ans);
   }
   return res;
}</pre>
```

verify函数非常简单,就是给出一个类ans,然后对polygon的四个顶点分类,返回这四个顶点是否都被分到了ans类里。

鲁棒界的确定

一旦四个顶点都被verify了,就可以开始计算鲁棒域。



我们可以先考虑下对于四边形的一条边 q_0q_1 ,和center组成的四面体。(当然这是为了直观理解,高维空间并不好定义几何体)可以确定的是,我们需要做的事情,就是寻找:

$$max_{lpha \in [0,1]} rac{center \cdot (lpha | q_0
angle + (1-lpha) | q_1
angle)}{||lpha | q_0
angle + (1-lpha) | q_1
angle||} = cos heta$$

因为我们需要寻找最小的 θ 。如果对于这条边,找到了最小的 θ ,再对剩下三条边都找一下,然后取最小值,就可以通过之前的理论推导得到一个 ε 。

其实归一化后的基是 $\sqrt{2^n-1}(\{X,Y,Z,I\}^{\otimes n}-I^{\otimes n})$ 。前面系数是怎么得来的?可以看一下简单推导:

原始情况下:
$$\rho = \frac{1}{2^n}(I + \overrightarrow{v} \cdot \overrightarrow{\sigma})$$

$$Tr(\sigma_i \sigma_j) = 2^n \delta_{ij}$$
然后就有:
$$Tr(\rho^2) = \frac{1}{4^n}(2^n + |\overrightarrow{v}|^2 2^n)$$
其中 $|\overrightarrow{v}|^2$ 乘的 2^n 就是 $Tr(\sigma_i \sigma_j) = 2^n \delta_{ij}$ 前的那个 2^n .
因为我们想要 $Tr(\rho^2) = 1 \Leftrightarrow |\overrightarrow{v}|^2 = 1$
所以就要使得 $Tr(\sigma_i \sigma_j) = (4^n - 2^n)\delta_{ij}$
所以基前面需要乘一个系数 $\sqrt{2^n - 1}$

然后此时有:

$$egin{aligned} Fidelity(\psi_1,\psi_2) &= \left| \left< \psi_1 | \psi_2 | \right>
ight|^2 \ &= rac{1 + (2^n - 1) \overrightarrow{v_1} \cdot \overrightarrow{v_2}}{2^n} \end{aligned}$$

回到之前需要最大化的值:

$$max_{lpha \in [0,1]} rac{center \cdot \left(lpha | q_0
angle + (1-lpha) | q_1
angle
ight)}{||lpha | q_0
angle + (1-lpha) | q_1
angle ||} = cos heta$$

由于我懒得求导,会发现分母 $||\alpha|q_0\rangle+(1-\alpha)|q_1\rangle||\geq \frac{1}{\sqrt{2}}$ 的(因为转的比较小, $|q_0\rangle$ 和 $|q_1\rangle$ 成锐角),所以我直接把上面的结果算作:

$$\sqrt{2}*max(cos(center,|q_0\rangle),cos(center,|q_1\rangle))$$

也就有了cal()函数。

然后 $robust_bound$ 函数就是对每条边都cal了一下,最后取个最大的 $cos\theta$,最后计算出bound:

$$arepsilon = 1 - maxFidelity = 1 - maxrac{1 + (2^n - 1)cos heta}{2^n}$$

实验的结果

前面都是原理性说明,我不是很有信心表达清楚。但是我们可以看一下结果。

```
bool Verifier :: random_sampling_check(int samples) const{
    srand((int) time (NULL));
    PureState nq = q;
    printf("Robust bound: %.41f\n", robust_bound);
    for (int t = 0;t < samples;t++){</pre>
        double phi = (double)rand() / (double)RAND_MAX * 7;
        int tg = rand() % nqubits;
        int gate = rand() % 3;
        double distance;
        Gate g = gate == 0 ? RX : (gate == 1 ? RY : RZ);
        nq.apply_operator(Operator(g, tg, vector<int>{}, phi));
        distance = 1 - q.fidelity(nq);
        while(1 - q.fidelity(nq) > robust_bound || distance < (robust_bound - 0.01)){</pre>
            phi = (double)rand() / (double)RAND_MAX * 7;
            tg = rand() % nqubits;
            gate = rand() % 3;
            g = gate == 0 ? RX : (gate == 1 ? RY : RZ);
            nq = PureState(q);
            nq.apply_operator(Operator(g, tg, vector<int>{}, phi));
            distance = 1 - q.fidelity(nq);
        nq.apply_circuit(c);
           printf("sample %d: Distance = %.4lf CENTER = %d\n SAMPLE = %d\n", t, distance, predict, nq.predict());
        else printf("sample %d: Distance = %.41f CENTER = SAMPLE = %d\n", t, distance, predict);
```

可以看一下我取点的随机策略,我随机生成了一个角度phi,一个target qubit,一个gate(RX, RY, RZ)。然后将gate作用在target qubit上转phi角度。

为了增加数据的强度,如果产生的状态和center态的distance离得太远(差0.01以上),则我会重新生成。也就是说,sample的点一定会特别靠近验证出来的robust 边界。

```
Guan's robust bound: 0.016063
Robust bound: 0.1397
sample 0: Distance = 0.1307 CENTER = SAMPLE = 0
sample 1: Distance = 0.1380 CENTER = SAMPLE = 0
sample 2: Distance = 0.1304 CENTER = SAMPLE = 0
sample 3: Distance = 0.1386 CENTER = SAMPLE
sample 5: Distance = 0.1307 CENTER = SAMPLE = 0
sample 6: Distance = 0.1371 CENTER = SAMPLE = 0
sample 7: Distance = 0.1341 CENTER = SAMPLE = 0
sample 8: Distance = 0.1329 CENTER = SAMPLE = 0
 amnle 11 · Distance = 0 1331 CENTER = SAMPLE =
sample 12: Distance = 0.1390 CENTER = SAMPLE = 0
sample 13: Distance = 0.1335 CENTER = SAMPLE = 0
sample 14: Distance = 0.1299 CENTER = SAMPLE = 0
sample 16: Distance = 0.1359 CENTER = SAMPLE = 0
sample 20: Distance = 0.1381 CENTER = SAMPLE = 0
sample 21: Distance = 0.1367 CENTER = SAMPLE = 0
sample 22: Distance = 0.1303 CENTER = SAMPLE = 0
sample 24: Distance = 0.1309 CENTER = SAMPLE = 0
 sample 74: Distance = 0.1389 CENTER = SAMPLE = 0
 sample 75: Distance = 0.1370 CENTER = SAMPLE = 0
 sample 76: Distance = 0.1387 CENTER = SAMPLE
 sample 78: Distance = 0.1389 CENTER = SAMPLE = 0
 sample 79: Distance = 0.1344 CENTER = SAMPLE = 0
 sample 80: Distance = 0.1389 CENTER = SAMPLE = 0
  sample 82: Distance = 0.1320 CENTER = SAMPLE
 sample 83: Distance = 0.1375 CENTER = SAMPLE = 0
 sample 84: Distance = 0.1334 CENTER = SAMPLE = 0
 sample 85: Distance = 0.1353 CENTER = SAMPLE = 0
 sample 86: Distance = 0.1307 CENTER = SAMPLE = 0
 sample 87: Distance = 0.1359 CENTER = SAMPLE
 sample 88: Distance = 0.1315 CENTER = SAMPLE = 0
 sample 89: Distance = 0.1376 CENTER = SAMPLE = 0
 sample 90: Distance = 0.1345 CENTER = SAMPLE = 0
 sample 91: Distance = 0.1372 CENTER = SAMPLE = 0
  sample 93: Distance = 0.1363 CENTER = SAMPLE
 sample 95: Distance = 0.1321 CENTER = SAMPLE = 0
 sample 96: Distance = 0.1347 CENTER = SAMPLE = 0
 sample 97: Distance = 0.1299 CENTER = SAMPLE = 0
 sample 98: Distance = 0.1380 CENTER = SAMPLE
```

可以看到,对第一个center态,我随即抽取了100个sample,都得到了验证。而且数据中不乏离robust bound特别近的点(distance = 0.1394等)而我也输出了官老师lemma1的robust bound,对于第一个样本点guan老师的robust bound只给了0.016。

如果不输出详细的sample过程,我们可以对不同的center态进行random sampling check。我选择了MNIST数据集前一百个测试点,每个测试点random sample 一百次。共耗时将近1小时,结果如下:

```
| Fig. | Post | Special Special | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,000 | #4,00
```

我觉得结果出人意料得不错,很多时候比官老师的lemma1给出的quick check效果要好很多,而且理论速度更快。

这里可能有疑问,为什么有时候验证出来robust bound是负数?这其实很显然,因为之前求 $\max cos heta$ 时,我直接放缩到 $\sqrt{2}$,可能会过大了。

其次

如果对于一个eps,我们的polygon四个顶点并没有被完全分入同一个类怎么办?为了节省时间,我使用了最简单朴素的方法。 即我把初始eps设成1.6,然后如果没被验证,就把eps - 0.05,缩小四边形直到能验证了为止。因此会发现验证出来的robust bound都是一些离散的值。

Polygon的选择

```
Polygon :: Polygon(PureState center, int nnqubits, Circuit nc, double eps){
    points.clear();
    nqubits = nnqubits;
    c = nc;

    center_state = center;
    center.apply_operator(Operator(RY, 0, vector<int>{}, eps));
    points.push_back(center);

    center = center_state;
    center.apply_operator(Operator(RY, 1, vector<int>{}, eps));
    points.push_back(center);

    center = center_state;
    center.apply_operator(Operator(RY, 0, vector<int>{}, -eps));
    points.push_back(center);

    center = center_state;
    center.apply_operator(Operator(RY, 1, vector<int>{}, -eps));
    points.push_back(center);
}
```

这部分, center是一个PureState, 然后我选取了一个四边形。即四个量子态:

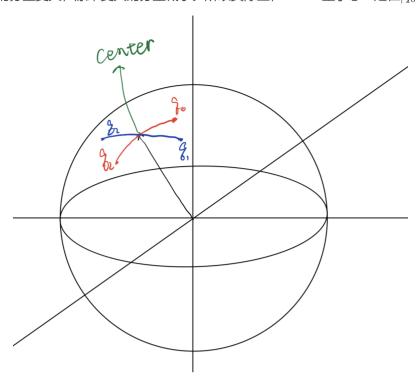
当然这是为了节省时间,也可以缩短步长或者做更精细的启发式验证。

- 将center的第0个qubit作用门RY(eps)得到的量子态 $|q_0\rangle$
- 将center的第1个qubit作用门RY(eps)得到的量子态 $|q_1
 angle$
- 将center的第0个qubit作用门RY(-eps)得到的量子态 $|q_2\rangle$
- 将center的第1个qubit作用门RY(-eps)得到的量子态 $|q_3\rangle$

为什么这么取呢?实际上,将量子态作用门 $I\otimes I\otimes\ldots\otimes I\otimes RY$ 并不对应着绕着轴 $I\otimes I\otimes\ldots\otimes I\otimes RY$ 进行旋转?(这里我不清楚,我就认为他不对)

但是可以换一种理解方式,因为作用门后量子态还是纯态,所以一定是绕着某个轴旋转的。(考虑之前推导的 $|\psi
angle$ 对应的向量 \overrightarrow{v})

因为高维空间的旋转并不是很好理解,可以再换一种想法。把量子态既然看作向量了,由于我们取的是旋转一个负角度,作用门的本质是向量中一些分量变大,一些分量减小;而作用负数RY正好可以使得原来减小的分量变大,原来变大的分量减小。所以实际上,center量子态一定在 $|q_0\rangle$ 和 $|q_2\rangle$ 的连线上。



想法就是虽然我不知道是绕着哪个轴旋转的,但它一定是个旋转。数字上,就是将向量一些分量变大一些分量减小。由于对称性,center态一定是被 $|q_0
angle,\dots|q_3
angle$ 包围的,这就足够了。