



**NITTE**  
EDUCATION TRUST

**N.M.A.M. INSTITUTE OF TECHNOLOGY**  
(An Autonomous Institution affiliated to Visvesvaraya Technological University, Belagavi)  
Nitte – 574 110, Karnataka, India

## **Department of Electronics and Communication Engineering**

**Microprocessor and Microcontroller Application Lab. (19EC507)**

### **Ultrasonic Rangefinder using 8051 Microcontroller**

**By**

Suhas – Reg. No: 4NM19EC180

Suman Kumar – Reg. No: 4NM19EC181

Sumith S Kumar – Reg. No: 4NM19EC182

Suraksha S Bolar – Reg. No: 4NM19EC183

Section: D

#### **Abstract:**

In this project, we have built an Ultrasonic Rangefinder using 8051 Microcontroller and Ultrasonic Sensor. We have different ways to measure the distance. One way is to use Ultrasonic Sensor for distance measurement. This ultrasonic rangefinder can measure distances up to 4 meters at an accuracy of 3mm. AT89s51 microcontroller, ultrasonic transducer module HC-SR04 and 3 common anode 7 segment display forms the basis of this circuit. The ultrasonic module sends a signal to the object, then picks up its echo and outputs a waveform whose time period is proportional to the distance. The microcontroller accepts this signal, performs necessary processing and displays the corresponding distance on the 3 digit seven segment display. This circuit finds a lot of application in automotive parking sensors, obstacle warning systems, terrain monitoring robots, industrial distance measurements etc. In distance measurement-Ultrasonic sensors use high-frequency sound waves that are above the upper limit of human hearing and can transverse through different mediums (which affect the speed of sound) to determine where an object is relative to the point of the transducer. The time it takes for the emitted sound wave to reflect back to the transducer is multiplied by the speed of sound and divided by two for an accurate distance measurement.

### **Objective of the Ultrasonic Rangefinder using 8051 Microcontroller :**

- 1.**The ultrasonic module HC-SR04 is interfaced to the AT89C51 (8051 microcontroller) through the ports and also used for transmitting the 8 bit display data to the 3 common anode 7 segment display.
- 2.** To develop algorithm to calculate time delay between transmitting Ultrasonic waves and picking up its echoes
- 3.** To detect the presence and give the position of the object
- 4.** To develop algorithm to interface Three common anode 7 segment displays with AT89C51 to display the corresponding distance measured.

Title and objectives are approved by

(Signature)

Name :

Designation :

**Remarks if any by External Examiners during SEE**

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| Examiner 1 |      |           |
| Examiner 2 |      |           |