Capstone Project

January 1, 2022

1 Capstone Project

1.1 Image classifier for the SVHN dataset

1.1.1 Instructions

In this notebook, you will create a neural network that classifies real-world images digits. You will use concepts from throughout this course in building, training, testing, validating and saving your Tensorflow classifier model.

This project is peer-assessed. Within this notebook you will find instructions in each section for how to complete the project. Pay close attention to the instructions as the peer review will be carried out according to a grading rubric that checks key parts of the project instructions. Feel free to add extra cells into the notebook as required.

1.1.2 How to submit

When you have completed the Capstone project notebook, you will submit a pdf of the notebook for peer review. First ensure that the notebook has been fully executed from beginning to end, and all of the cell outputs are visible. This is important, as the grading rubric depends on the reviewer being able to view the outputs of your notebook. Save the notebook as a pdf (File -> Download as -> PDF via LaTeX). You should then submit this pdf for review.

1.1.3 Let's get started!

We'll start by running some imports, and loading the dataset. For this project you are free to make further imports throughout the notebook as you wish.

```
In [1]: import tensorflow as tf
    import pandas as pd
    import numpy as np
    import matplotlib.pyplot as plt
    import random
    from scipy.io import loadmat

from tensorflow.keras.models import Sequential
    from tensorflow.keras.layers import Dense, Flatten, Dropout, Conv2D, MaxPooling2D, Batfrom tensorflow.keras.callbacks import ModelCheckpoint, EarlyStopping
    from tensorflow.keras.optimizers import Adam
```



For the cap-

stone project, you will use the SVHN dataset. This is an image dataset of over 600,000 digit images in all, and is a harder dataset than MNIST as the numbers appear in the context of natural scene images. SVHN is obtained from house numbers in Google Street View images.

• Y. Netzer, T. Wang, A. Coates, A. Bissacco, B. Wu and A. Y. Ng. "Reading Digits in Natural Images with Unsupervised Feature Learning". NIPS Workshop on Deep Learning and Unsupervised Feature Learning, 2011.

Your goal is to develop an end-to-end workflow for building, training, validating, evaluating and saving a neural network that classifies a real-world image into one of ten classes.

Both train and test are dictionaries with keys X and y for the input images and labels respectively.

1.2 1. Inspect and preprocess the dataset

- Extract the training and testing images and labels separately from the train and test dictionaries loaded for you.
- Select a random sample of images and corresponding labels from the dataset (at least 10), and display them in a figure.
- Convert the training and test images to grayscale by taking the average across all colour channels for each pixel. *Hint: retain the channel dimension, which will now have size* 1.
- Select a random sample of the grayscale images and corresponding labels from the dataset (at least 10), and display them in a figure.

```
# # plt.imshow(train_images)
        # print(train)
        print(train_images.shape)
        print(test_images.ndim)
(32, 32, 3, 73257)
In [4]: train_images = np.moveaxis(train_images, -1, 0)
        test_images = np.moveaxis(test_images, -1, 0)
In [5]: print(train_images.shape)
(73257, 32, 32, 3)
In [6]: train_labels = np.where(train_labels==10, 0, train_labels)
        test_labels = np.where(test_labels==10, 0, test_labels)
In [7]: random_indices = random.sample(range(0,train_images.shape[0]), 10)
        fig, ax = plt.subplots(1,10, figsize = (10,10))
        for i in range(10):
            ax[i].set_axis_off()
            ax[i].imshow(train_images[random_indices[i]])
            ax[i].set_title(train_labels[random_indices[i]])
                                                                  [0]
In [8]: def convert2gray(train_data, test_data):
            train_data = np.mean(train_data, axis = -1, keepdims = True)
            test_data = np.mean(test_data, axis = -1, keepdims = True)
            return (train_data, test_data)
In [9]: gray_train_img, gray_test_img = convert2gray(train_images, test_images)
In [10]: random_indices = random.sample(range(0,gray_train_img.shape[0]), 10)
         fig, ax = plt.subplots(1,10, figsize = (10,10))
         for i in range(10):
             ax[i].set_axis_off()
             ax[i].imshow(gray_train_img[random_indices[i], :, :, 0], cmap='gray')
             ax[i].set_title(train_labels[random_indices[i]])
```



1.3 2. MLP neural network classifier

- Build an MLP classifier model using the Sequential API. Your model should use only Flatten and Dense layers, with the final layer having a 10-way softmax output.
- You should design and build the model yourself. Feel free to experiment with different MLP architectures. *Hint: to achieve a reasonable accuracy you won't need to use more than 4 or 5 layers.*
- Print out the model summary (using the summary() method)
- Compile and train the model (we recommend a maximum of 30 epochs), making use of both training and validation sets during the training run.
- Your model should track at least one appropriate metric, and use at least two callbacks during training, one of which should be a ModelCheckpoint callback.
- As a guide, you should aim to achieve a final categorical cross entropy training loss of less than 1.0 (the validation loss might be higher).
- Plot the learning curves for loss vs epoch and accuracy vs epoch for both training and validation sets.
- Compute and display the loss and accuracy of the trained model on the test set.

```
In [11]: def get_new_MLP_model():
           model = Sequential([
               Flatten(input_shape= train_images[0].shape),
               Dense(512, activation='relu'),
               Dense(512, activation='relu'),
               Dense(256, activation='relu'),
               Dense(128, activation='relu'),
               Dense(10, activation='softmax')
           ])
           return model
       model = get_new_MLP_model()
       model.summary()
Model: "sequential"
Layer (type)
                        Output Shape
______
flatten (Flatten)
                         (None, 3072)
```

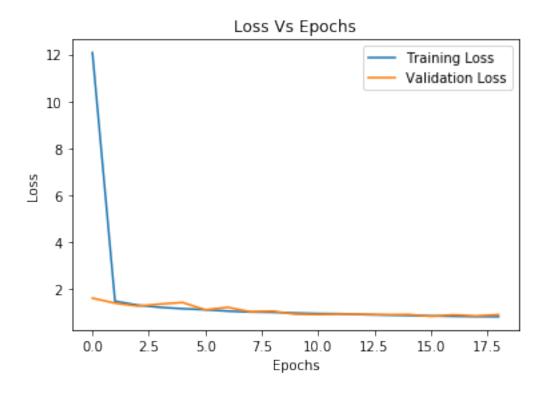
```
dense (Dense)
             (None, 512)
                         1573376
-----
             (None, 512)
dense_1 (Dense)
                         262656
dense 2 (Dense)
             (None, 256)
                         131328
-----
dense 3 (Dense)
             (None, 128)
                         32896
._____
dense 4 (Dense)
            (None, 10)
                         1290
Total params: 2,001,546
Trainable params: 2,001,546
Non-trainable params: 0
 ______
In [12]: cp_path = 'Checkpoint/best_model'
    cp = ModelCheckpoint(cp_path,
             save_best_only=True,
             save_weights_only=True,
             verbose= False,
             save_freq='epoch',
             monitor='val_loss',
             mode='min')
In [13]: early_stop = EarlyStopping(monitor='val_loss', mode='min', patience=3)
In [14]: model.compile(optimizer='adam', loss='sparse_categorical_crossentropy', metrics=['acc
In [15]: history = model.fit(train_images, train_labels, epochs = 30, batch_size=64, verbose=1
Train on 65931 samples, validate on 7326 samples
Epoch 1/30
Epoch 2/30
Epoch 3/30
Epoch 4/30
Epoch 5/30
Epoch 6/30
Epoch 7/30
Epoch 8/30
Epoch 9/30
```

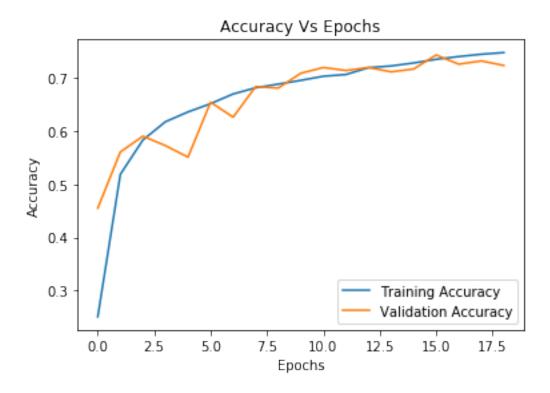
```
Epoch 10/30
Epoch 11/30
Epoch 12/30
Epoch 13/30
Epoch 14/30
Epoch 15/30
Epoch 16/30
Epoch 17/30
Epoch 18/30
Epoch 19/30
In [16]: plt.plot(history.history['loss'])
 plt.plot(history.history['val_loss'])
 plt.title("Loss Vs Epochs")
 plt.ylabel('Loss')
```

plt.legend(['Training Loss', 'Validation Loss'], loc='upper right')

plt.xlabel('Epochs')

plt.show()





Test Loss is 1.065633964450651 Test Accuracy is 0.6899201273918152

1.4 3. CNN neural network classifier

- Build a CNN classifier model using the Sequential API. Your model should use the Conv2D, MaxPool2D, BatchNormalization, Flatten, Dense and Dropout layers. The final layer should again have a 10-way softmax output.
- You should design and build the model yourself. Feel free to experiment with different CNN architectures. *Hint: to achieve a reasonable accuracy you won't need to use more than 2 or 3 convolutional layers and 2 fully connected layers.*)
- The CNN model should use fewer trainable parameters than your MLP model.
- Compile and train the model (we recommend a maximum of 30 epochs), making use of both training and validation sets during the training run.
- Your model should track at least one appropriate metric, and use at least two callbacks during training, one of which should be a ModelCheckpoint callback.
- You should aim to beat the MLP model performance with fewer parameters!
- Plot the learning curves for loss vs epoch and accuracy vs epoch for both training and validation sets.

• Compute and display the loss and accuracy of the trained model on the test set.

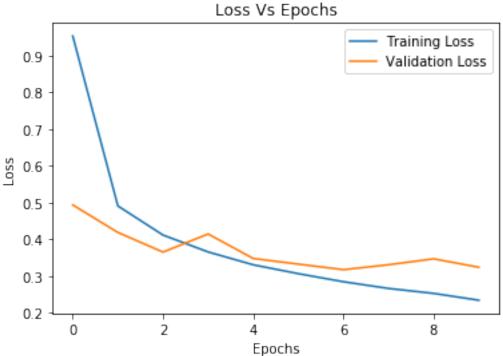
```
In [19]: def get_new_CNN_model():
          model = Sequential([
              Conv2D(16, (3,3), padding='same', activation='relu', input_shape= train_image
              BatchNormalization(),
              MaxPooling2D((2,2)),
              Conv2D(16, (3,3), padding='same', activation='relu'),
              BatchNormalization(),
              MaxPooling2D((2,2)),
              Conv2D(16, (3,3), padding='same', activation='relu'),
              BatchNormalization(),
              MaxPooling2D((2,2)),
              Flatten(),
              Dense(256, activation='relu'),
              Dropout(0.2),
              Dense(128, activation='relu'),
              Dropout(0.2),
              Dense(10, activation='softmax')
          1)
          return model
       cnn_model = get_new_CNN_model()
       cnn_model.summary()
Model: "sequential_1"
            Output Shape Param #
Laver (type)
______
conv2d (Conv2D)
                      (None, 32, 32, 16)
                                            448
-----
batch_normalization (BatchNo (None, 32, 32, 16)
max_pooling2d (MaxPooling2D) (None, 16, 16, 16) 0
conv2d_1 (Conv2D) (None, 16, 16, 16) 2320
batch_normalization_1 (Batch (None, 16, 16, 16) 64
max_pooling2d_1 (MaxPooling2 (None, 8, 8, 16) 0
conv2d_2 (Conv2D) (None, 8, 8, 16) 2320
batch_normalization_2 (Batch (None, 8, 8, 16) 64
max_pooling2d_2 (MaxPooling2 (None, 4, 4, 16)
```

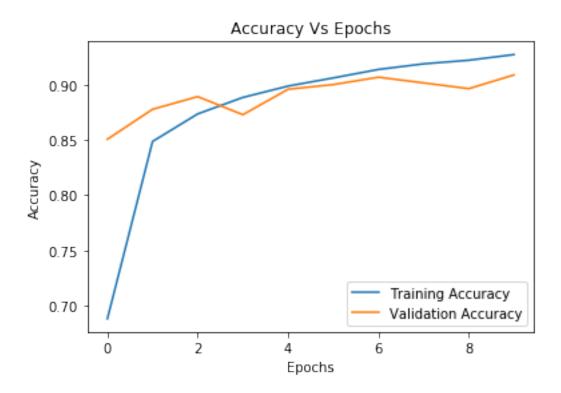
```
dense_5 (Dense)
                (None, 256)
                               65792
                (None, 256)
dropout (Dropout)
dense_6 (Dense)
                (None, 128)
                               32896
dropout_1 (Dropout)
               (None, 128)
dense_7 (Dense)
          (None, 10)
                               1290
_____
Total params: 105,258
Trainable params: 105,162
Non-trainable params: 96
In [20]: checkpoint_path = 'CNN_Checkpoint/best_model'
     cp = ModelCheckpoint(checkpoint_path,
                 save_best_only=True,
                 save_weights_only=True,
                 verbose=False,
                 save_freq='epoch',
                 monitor='val_loss',
                 mode='min')
In [21]: early_stop = EarlyStopping(monitor='val_loss', mode='min', patience=3)
In [22]: cnn_model.compile(optimizer='adam', loss='sparse_categorical_crossentropy', metrics=[
In [23]: history = cnn_model.fit(train_images, train_labels, epochs=30, batch_size=64,
                   verbose=1, validation_split=0.1, callbacks=[cp, early_stop])
Train on 65931 samples, validate on 7326 samples
Epoch 1/30
Epoch 2/30
Epoch 3/30
Epoch 4/30
Epoch 5/30
Epoch 6/30
Epoch 7/30
```

(None, 256)

flatten_1 (Flatten)

```
Epoch 8/30
Epoch 9/30
65931/65931 [===
                        ======] - 361s 5ms/sample - loss: 0.2532 - accuracy: 0.92
Epoch 10/30
65931/65931 [====
                           ====] - 360s 5ms/sample - loss: 0.2346 - accuracy: 0.92
In [24]: plt.plot(history.history['loss'])
      plt.plot(history.history['val_loss'])
      plt.title("Loss Vs Epochs")
      plt.ylabel('Loss')
      plt.xlabel('Epochs')
      plt.legend(['Training Loss', 'Validation Loss'], loc='upper right')
      plt.show()
                         Loss Vs Epochs
                                         Training Loss
```





1.5 4. Get model predictions

- Load the best weights for the MLP and CNN models that you saved during the training run.
- Randomly select 5 images and corresponding labels from the test set and display the images with their labels.
- Alongside the image and label, show each model's predictive distribution as a bar chart, and the final model prediction given by the label with maximum probability.

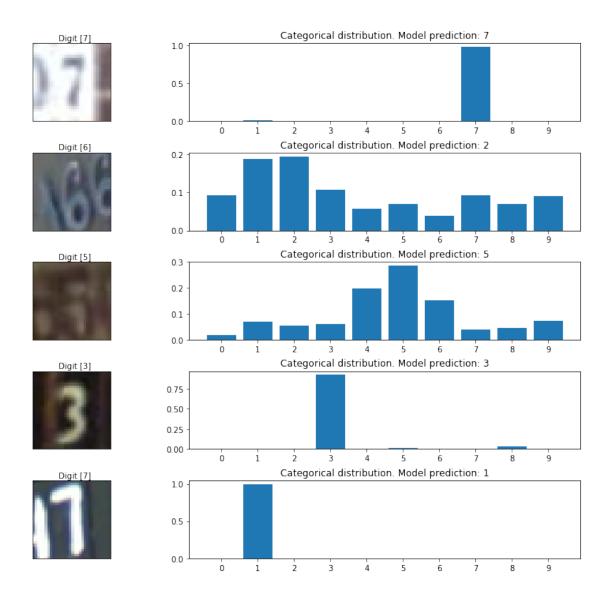
```
random_test_labels = test_labels[random_inx, ...]

predictions = model.predict(random_test_images)

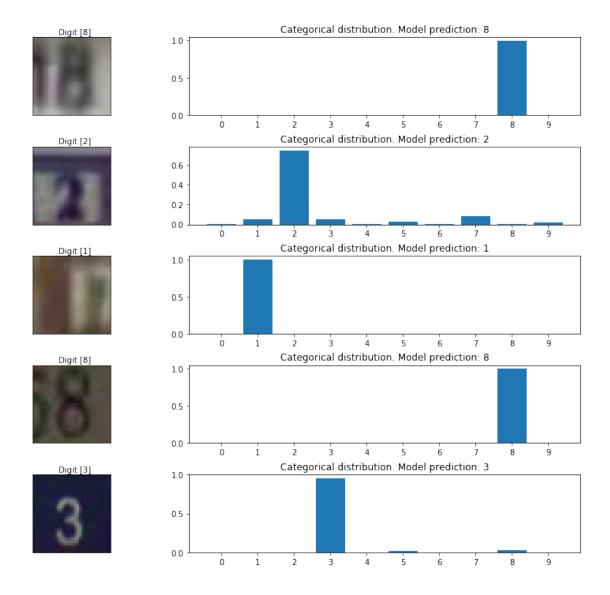
fig, axes = plt.subplots(5, 2, figsize=(16, 12))
fig.subplots_adjust(hspace=0.4, wspace=-0.2)

for i, (prediction, image, label) in enumerate(zip(predictions, random_test_image(axes[i, 0].imshow(np.squeeze(image)))
    axes[i, 0].get_xaxis().set_visible(False)
    axes[i, 0].get_yaxis().set_visible(False)
    axes[i, 0].text(10., -1.5, f'Digit {label}')
    axes[i, 1].bar(np.arange(len(prediction)), prediction)
    axes[i, 1].set_xticks(np.arange(len(prediction)))
    axes[i, 1].set_title(f"Categorical distribution. Model prediction: {np.argmax}

plt.show()
```



In [31]: show_predictive_distribution(Best_CNN)



In []: