

# ENDSEM 2022: ANTENA CURRENT IN HALF WAVE DIPOLE ANTENA

SUHAS C - EE20B132

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## 1 Aim :

- Obtaining the current using known values like boundary conditions.
- Finding  $J$  (M-Q)\* $J=Im$ \*QB equation

## 2 Pseudo-code

- First run the program and call current function.
- Allocate some variable to the given values and find  $R_z, R_u, P, P_B, Q, Q_B$   $J$  and current using (M-Q)\* $J=Im$ \*QB equation and by initial conditions respectively
- Plot currents and compare them.

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```
from pylab import *
import system-function as name
Note: lstsq is found as scipy.linalg.lstsq
ones(List)
zeros(List)
range(N0,N1,Nstep)
arange(N0,N1,Nstep)
linspace(a,b,N)
logspace(log10(a),log10(b),N)
X,Y=meshgrid(x,y)
where(condition)
where(condition & condition)
where(condition | condition)
a=b.copy()
lstsq(A,b) to fit  $A*x=b$ 
A.max() to find max value of numpy array (similalry min)
A.astype(type) to convert a numpy array to another type (eg int)
def func(args):
...
return List
```

```

matrix=c_[vector,vector,...] to create a matrix from vectors
figure(n) to switch to, or start a new figure labelled n
plot(x,y,style,...,lw=...)
semilogx(x,y,style,...,lw=...)
semilogy(x,y,style,...,lw=...)
loglog(x,y,style,...,lw=...)

```

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### 3 Code

#### 3.1 Question 1

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```

""" Question 1 """
#Calculating Vector Z
z = np.linspace(-1,1,2*N+1)

#Calculating u vector
u = np.arange(1, 2*N)
#Removing the middlemost element
u = np.delete(u, N-1, axis=0)

#Calculating the I vector(standard expression) - the actual I
Current_Vector = np.zeros(2*N+1)
Current_Vector[0:N] = Maximum_Current*sin(k*(1+z[0:N])) # for -l < z < 0
Current_Vector[N:2*N+1] = Maximum_Current*sin(k*(1-z[N:2*N+1])) # for 0 < z < l
I = Current_Vector

#Applying the given Boundary Condition

Unknown_Current=I[u]

```

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#### 3.2 Question 2

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```

""" QUESTION - 2 """
# Function to compute and return matrix M, H_phi
def H_p(J,n=N,r=a):
    Matrix = (1/(2*pi*r))*(identity(2*N-2))
    V = np.dot(Matrix,J)
    return Matrix,V

Matrix,H_phi = H_p(Unknown_Current,N,a) # Getting the matrix M

```

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#### 3.3 Question 3

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```

""" QUESTION - 3 """
# Computing vectors Rz, Ru and matrices PB, P
r = a
def Rij(z,r=a):

```

```

        ziz , zjz = np.meshgrid(z , z) #Return coordinate Matrices from coordinate vectors
        Radius = sqrt (( ziz-zjz )**2 + r**2*np.ones ((2*N+1,2*N+1)))
        return Radius

Rz = Rij (z , a)

def Rij (z , u , r=a):
    ziu , zju = np.meshgrid(z [u] , z [u]) #Return coordinate Matrices from coordinate v
    R = sqrt (( ziu-zju )**2 + r**2*np.ones ((2*N-2,2*N-2)))
    return R

Ru = Rij (z , u , a)

def pij (r , k=k , z=dz):
    P = ((mu0/(4*pi)))*(exp(-1j*k*r))*z/r
    return P

P_ij = pij (Ru , k , dz)

RiN = Rz [N]
RiN = np.delete (RiN , [0 , N , 2*N] , 0)

Eq_0 = (exp(-1j*k*RiN))

P_B = ((mu0/(4*pi)))*(Eq_0)*dz/RiN

Eq_1 = (-1j*k/Ru)-(1/Ru**2)
Eq_2 = (-1j*k/RiN)-(1/RiN**2)

```

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### 3.4 Question 4

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```

""" QUESTION - 4 """
# Computing the matrices Qij and QB

Q_ij = -P_ij*(r/mu0)*(Eq_1)
Q_B = -P_B*(r/mu0)*(Eq_2)

```

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### 3.5 Question 5

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```

""" QUESTION - 5 """
# Solving for the current vector , I and comparing with the actual expression
#M1 = identity (2*N-2)/(2*pi*a)

Matrix_1 = np.identity (2*N-2)/(2*pi*r)
Unknown_Current_1 = dot (linalg.inv (Matrix_1-Q_ij) , Q_B)

#Printing all the Matrices
print ((Rz).round(2))
print ((Ru).round(2))
print ((P_ij).round(2))

```

```

print((P-B).round(2))
print((Q-ij).round(2))
print((Q-B).round(2))

# Finding I(expected value of current)
# Adding the three values given in question

Current_1 = np.insert(Unknown_Current_1,0,0)
Current_1 = np.insert(Current_1,N,Maximum_Current)
Current_1 = np.insert(Current_1,2*N,0)

plt.figure(1)
plt.plot(z,Current_1)
plt.plot(z,I)
plt.grid(True)
plt.savefig("/figure1.png")
plt.show()

print((I).round(2))
print((Current_1).round(2))

```

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## 4 Printing the matrices

At  $N = 4$

### 4.1

Matrix  $R_z$ :

```

[[0.01 0.13 0.25 0.38 0.5  0.63 0.75 0.88 1.  ]
 [0.13 0.01 0.13 0.25 0.38 0.5  0.63 0.75 0.88]
 [0.25 0.13 0.01 0.13 0.25 0.38 0.5  0.63 0.75]
 [0.38 0.25 0.13 0.01 0.13 0.25 0.38 0.5  0.63]
 [0.5  0.38 0.25 0.13 0.01 0.13 0.25 0.38 0.5  ]
 [0.63 0.5  0.38 0.25 0.13 0.01 0.13 0.25 0.38]
 [0.75 0.63 0.5  0.38 0.25 0.13 0.01 0.13 0.25]
 [0.88 0.75 0.63 0.5  0.38 0.25 0.13 0.01 0.13]
 [1.   0.88 0.75 0.63 0.5  0.38 0.25 0.13 0.01]]

```

### 4.2

Matrix Ru:

$$\begin{bmatrix} 0.01 & 0.13 & 0.25 & 0.5 & 0.63 & 0.75 \\ 0.13 & 0.01 & 0.13 & 0.38 & 0.5 & 0.63 \\ 0.25 & 0.13 & 0.01 & 0.25 & 0.38 & 0.5 \\ 0.5 & 0.38 & 0.25 & 0.01 & 0.13 & 0.25 \\ 0.63 & 0.5 & 0.38 & 0.13 & 0.01 & 0.13 \\ 0.75 & 0.63 & 0.5 & 0.25 & 0.13 & 0.01 \end{bmatrix}$$

4.3

Matrix P:

$$\begin{bmatrix} 0. & -0.j & 0. & -0.j & 0. & -0.j & 0. & -0.j & 0. & -0.j & 0. & -0.j \end{bmatrix}$$

4.4

Matrix PB:

$$\begin{bmatrix} 0. & -0.j & 0. & -0.j & 0. & -0.j & 0. & -0.j & 0. & -0.j & 0. & -0.j \end{bmatrix}$$

4.5

Matrix Q:

$$\begin{bmatrix} 7.96170e+02-1.000e-02j & 1.02400e+01+3.670e+00j & 3.91000e+00+2.880e+00j \\ 1.67000e+00+2.450e+00j & 1.30000e+00+2.360e+00j & 1.06000e+00+2.300e+00j \\ 5.12000e+00+1.830e+00j & 1.59233e+03-2.000e-02j & 1.53600e+01+5.500e+00j \\ 2.93000e+00+3.240e+00j & 2.00000e+00+2.940e+00j & 1.51000e+00+2.750e+00j \\ 1.30000e+00+9.600e-01j & 1.02400e+01+3.670e+00j & 2.38850e+03-2.000e-02j \\ 6.51000e+00+4.790e+00j & 3.52000e+00+3.890e+00j & 2.34000e+00+3.430e+00j \\ 3.30000e-01+4.900e-01j & 1.17000e+00+1.300e+00j & 3.91000e+00+2.880e+00j \\ 3.98084e+03-4.000e-02j & 3.07200e+01+1.100e+01j & 9.11000e+00+6.710e+00j \\ 2.20000e-01+3.900e-01j & 6.70000e-01+9.800e-01j & 1.76000e+00+1.950e+00j \\ 2.56000e+01+9.170e+00j & 4.77700e+03-5.000e-02j & 3.58400e+01+1.284e+01j \\ 1.50000e-01+3.300e-01j & 4.30000e-01+7.900e-01j & 1.00000e+00+1.470e+00j \\ 6.51000e+00+4.790e+00j & 3.07200e+01+1.100e+01j & 5.57317e+03-6.000e-02j \end{bmatrix}$$

4.6

Matrix QB:

$$\begin{bmatrix} 0. & -0.j & 0.01-0.j & 0.05-0.j & 0.05-0.j & 0.01-0.j & 0. & -0.j \end{bmatrix}$$

4.7

I assumed:

```
[0.    0.38 0.71 0.92 1.    0.92 0.71 0.38 0. ]
```

4.8

I derived:

```
[ 0.+0.j -0.+0.j -0.+0.j -0.+0.j  1.+0.j -0.+0.j -0.+0.j -0.+0.j  0.+0.j]
```

```
[0.-0.j 0.-0.j 0.-0.j 0.-0.j 0.-0.j 0.-0.j]
```

## 5 plot

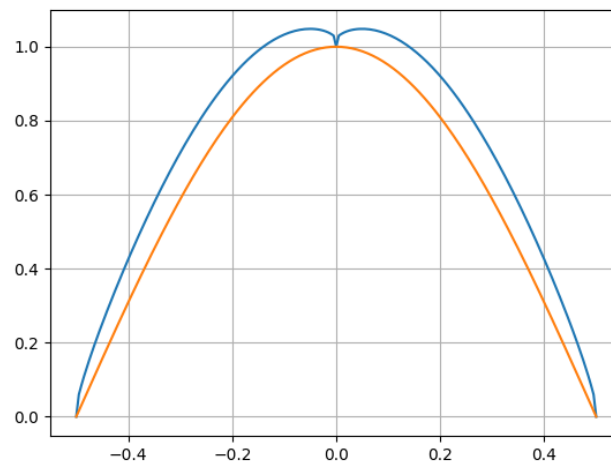
Our final equation is

$$MJ = QJ + QB$$

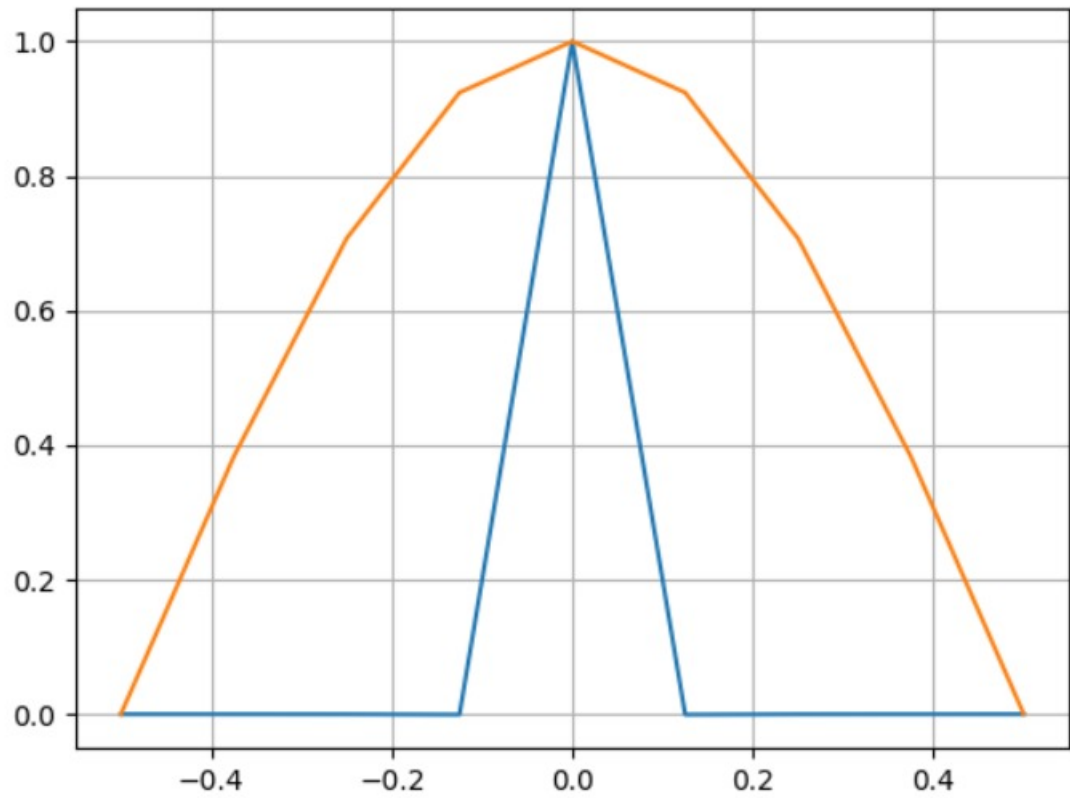
Invert (M-Q) and obtain J. Use inv(M-Q) in python. Add the Boundary currents (zero at  $i=0$ ,  $i=2N$ , and  $I_m$  at  $i=N$ ). Then plot this current vs.  $z$  and also plot the equation assumed for current at the top of this question paper. The python code used is as follows

```
J = matmul(inv(Matrix(N, a) - Q) , Q_B) * Im
```

### 5.1 For $N = 100$



## 5.2 For $N = 4$



## 6 Conclusion :

- On increasing the value of  $N$ , the both graphs will merge each other.
- On increasing  $N$ , the magnitude of points which are away from the centre are increasing.