

**INVESTIGATION OF POSITION TRACKING
ALGORITHM FOR PROVIDING REAL TIME
FEEDBACK USING AN INSTRUMENTED
ARM SKATEBOARD (ARMBO) FOR
UPPER-LIMB REHABILITATION**

*Submitted in partial fulfillment of the requirements for
the degree of*

**MASTER OF SCIENCE IN
BIOENGINEERING**

of

**Sree Chitra Tirunal Institute for Medical
Sciences and Technology, Trivandrum**

by

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