

# UNIT 2: Search Algorithms

Random search, Search with closed and open list, Depth first and Breadth first search, Heuristic search, best first search, A\* algorithm, Game Search.

## Random Search ¶

**What it is:** A method where you **try options at random** to see if they solve the problem.

**How it works:**

1. **Pick a random choice** from all possible moves or solutions.
2. **Check** if it reaches the goal.
3. If **not**, pick another **random choice** and try again.

**Pros:** Simple to implement.

**Cons:** Can take a **long time** if the solution is hard to find.

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## Open and Closed Lists in Search

- **Open List (To-Do List):**  
These are the **nodes** or **states** your algorithm still needs to explore. Think of it like a “**to-do**” list in search.
  - **Closed List (Done List):**  
These are the **nodes** or **states** your algorithm has **already checked**. Think of it like a “**done**” list in search.
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## Depth-First Search (DFS)

- **Process:** Go **deep** into one branch of the graph or tree before exploring other branches.
- **Analogy:** Imagine **tunneling** straight down in a cave until you can't go further, then coming back up to start digging another tunnel.

**Depth-First Search (DFS) Uses**

1. **Maze or Puzzle Solving** → DFS dives into one path fully; if it's a dead end, it backtracks.
  2. **Detecting Cycles** → DFS helps find loops in networks, like checking for circular dependencies.
  3. **Tree-Based Problems** → Many algorithms (e.g., checking each branch of a family tree) use DFS to explore everything in one direction before moving on.
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## Breadth-First Search (BFS)

- **Process:** Explore all nodes **level by level**, starting from the root, then moving to its neighbors, and so on.
- **Analogy:** Imagine **spreading out** like a wave, visiting everything close first, then moving to the next layer.

**Breadth-First Search (BFS) Uses**

1. **Social Networks** → Finding the shortest connection between two people (e.g., "friend-of-a-friend").
  2. **Route Finding** → In simple maps or grids, BFS quickly finds the shortest path.
  3. **Web Crawlers** → BFS visits pages level by level, discovering links in a structured way.
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**Note:** Practice 1-2 problem questions on both Search, we have also covered this in our respective AI classes

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# Heuristics in AI

In Artificial Intelligence, **heuristics** are **rules of thumb** or **educated guesses** used to **guide a search** or **decision-making** process. Instead of checking **every possible path** (which can be huge), a heuristic helps the AI **focus** on **promising** options first.

Heuristics (Very Simple Explanation): A heuristic is like a useful shortcut that helps quickly guess or estimate a good solution instead of looking at every single possibility. It doesn't always give the perfect answer, but it's usually fast and good enough for most purposes.

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## Why Do We Use Heuristics?

1. **Speed:** They help the AI find **good solutions quickly** rather than getting stuck exploring all possibilities.
  2. **Practical:** Many AI problems (like puzzles or route-finding) would take too long to solve with **brute force** methods.
  3. **Easy to Apply:** They can be made from **domain knowledge** (e.g., how far we are from a goal, or how many steps remain).
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## Uses of Heuristics in Various Sectors

### 1. Healthcare

- **Diagnosis:** Doctors and AI systems use heuristics to quickly narrow down possible diseases.
- **Scheduling:** Hospitals use simple rules to assign staff and arrange appointments efficiently.

### 2. Banking

- **Fraud Detection:** Heuristic rules spot unusual spending patterns, helping banks catch fraud faster.
- **Loan Approvals:** Banks use quick checks (e.g., credit score thresholds) to decide on lending.

### 3. E-Commerce

- **Recommendation Systems:** Heuristics pick products likely to interest the customer, based on browsing history.
- **Inventory Management:** Simple guidelines help decide when to reorder stock to avoid shortages.

### 4. Transportation

- **Route Planning:** Apps use heuristics (like shortest distance) to suggest fast travel routes.
- **Traffic Management:** Cities apply rules to adjust traffic lights or reroute vehicles.

### 5. Marketing

- **Customer Segmentation:** Heuristics group people by behavior or location for targeted campaigns.
- **Ad Placement:** Quick rules decide which ads to show, based on user interests or keywords.

### 6. Gaming

- **Computer Players:** Games like chess or tic-tac-toe use heuristics to focus on promising moves first.
  - **Difficulty Levels:** Heuristic adjustments make the computer opponent easier or harder.
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## Example in Search Algorithms

- **A\*** algorithm uses a **heuristic function** ( $h(n)$ ) to guess how close you are to the goal.
  - This helps **prioritize** exploring states that look more promising, **speeding up** the search.
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## Limitations

- **Not Always Perfect:** Heuristics can **overestimate or underestimate**, leading to suboptimal paths.
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## Conclusion

Heuristics in AI are **simple guidelines** that make problem-solving **faster and more efficient**. They're **key** in **search algorithms**, **game-playing** agents, and **many other AI applications** where exploring all paths is impossible.

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# A\* Algorithm (A Star Algorithm)

The A\* algorithm is a popular search and pathfinding algorithm used in many fields, including robotics and game development, due to its performance and accuracy. **It finds the shortest path from a start node to a target node while trying to minimize the total cost (distance, time, etc.).**

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## 1. Key Components

- **$g(n)$** : Actual cost from the start node to node  **$n$** .
  - **$h(n)$** : Heuristic estimate from node  **$n$**  to the goal. Must be **admissible** (never overestimates).
  - **$f(n) = g(n) + h(n)$** : Total estimated cost of the path through  **$n$** .
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## 2. Basic Steps

1. **Initialization**: Put the **start node** into an **open list** of nodes to explore.
  2. **Select Node**: Pick the node in the open list with the **lowest  $f(n)$** .
  3. **Goal Check**: If this node **is the goal**, we are done.
  4. **Neighbors**: For each neighbor of the chosen node:
    - Calculate its  **$f(n)$** .
    - If this neighbor is **not** in the open list, add it.
    - If it **is** in the open list but now has a **lower  $f(n)$** , **update** it.
  5. **Move On**: Move the chosen node to a **closed list** so it's not revisited.
  6. **Repeat** until the goal is found or the open list is **empty** (no solution).
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## 3. Choosing the Heuristic

- A **good heuristic** makes A\* faster by guiding the search in a **promising direction**.
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## Conclusion

A\* finds **shortest paths** efficiently if  **$h(n)$**  does **not** overestimate. It's widely used in **games, navigation apps, and robot path planning**.

Follow this link to practice A\* problem: <https://www.101computing.net/a-star-search-algorithm/>  
(<https://www.101computing.net/a-star-search-algorithm/>).

## SMA (Simplified Memory-Bounded A)

What is it?

- SMA\* is a **pathfinding** method like A\*, but it uses **limited memory**.
  - It helps in **large problems** where normal A\* might **run out of memory**.
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How Does It Work?

1. **Store Only Best Paths**: SMA\* keeps the **most promising nodes** in memory.
  2. **Memory Full?**: If memory is getting full, SMA\* **removes** less promising nodes.
  3. **Re-Expand**: If it needs a removed node again, it **re-calculates** it.
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Why Use SMA\*?

- It **prevents memory overload**, which can happen in big searches.
  - It **still** finds a **good path**, but it **may take longer** because it sometimes re-does work.
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