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1934 2932 Shu Zhon
            Let B denotes the angle that aline with fixed point of rotation makes with
                 Then tan\theta = \lambda \Rightarrow \theta = \arctan \lambda
                     d\theta = \frac{1}{1+\lambda^2}d\lambda
                  So the dietribution of the angle & is given by
                      do = 1 1 - d.
                    Hence, pidef of This given by fright = 1 1+42 ye R.
2. P(W=1)>0 for all 1>1
     P(W>i+j/W>i) = P(W>j)
      P(w>i+j|w>i) = \frac{P(w>i+j)}{P(w>i)} = P(w>j) \Rightarrow P(w>i+j) = P(w>j)
\frac{\infty}{P(w>i)} P(w>i) = P(w>j) \Rightarrow P(w>i+j) = P(w>i) P(w>j)
    Also = P(w>i+j)= = P(w>i) P(w>j) @
    We let j=k in 0 and i=k in 0. hence we have
          ZP(W>i)P(w>k)=ZP(w>k)P(W>j); Hence consequently
      \Rightarrow P(W>k)\sum_{i=2}^{\infty}P(W>j)=P(W>k+1)\sum_{j=1}^{\infty}P(W>j)
          Let a denotes ZP(W>j); Also we evaluate k=1; Assume P(X=1)=P
       Hence Q = \frac{1-p}{p}
Therefore (1-p) p(x > k) = p(x > k+1); Since p(x \ge 1) = 1
         Hene P(A>K)= (1-p) }-1
        Hence P(x=k) = (1-p)k-1_(1-p) = p(1-p)k-1 = pqk-1, Thus Wis Geometrically distributed
3 x follows the exponential distribution
      -f(\alpha) = \lambda_{\epsilon} - \lambda_{\alpha}
      Since [7] can only take integer values,
        P[x] = m, x - [x] \leq t) = \int_{m}^{m+t} \lambda e^{-\lambda x} dx = e^{-\lambda m} \left( -e^{-\lambda (m-t)} = e^{-\lambda m} (1 - e^{-\lambda t}) \right)
      Henre, Q. E.D.
4. PIX307=1.
  o Fia)= joo P(a>t) de
                                                                  E(x') = \int_0^\infty rx'^{-1} \overline{f}_{x(x)} dx
      Flat = Joand Flat = - Joand Fala)
                                                                         = 10 rxr-1 (1- Fx1y) dy.
      Integration by parts gives that
            E(xr) = - xr Fx(1) | 00 + | 00 rxr-1 Fx(1) dx
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Since Ender Tima Da ar Fala = 0

Stats 510 Assignment 2.

Hence E(x) = sup & Tp(q) >0 Since We can simply take T= /m >0.

b) Given that MI = OXZ, since both MINZ is simple in I(n2) = Sup E(x1) > E(x1); Hence I(n) > E(x1); O.ED.

6.
$$P(X > x + y | X > x) = P(X > y)$$

Hence $\int_{y}^{+\infty} f(x) dx = \frac{\int_{x + y}^{\infty} f(x) dx}{\int_{x}^{\infty} f(x) dx}$ we assume $y = dx$, hence $\int_{dx}^{+\infty} f(x) dx = \frac{\int_{x + k \cdot y}^{\infty} f(x) dx}{\int_{x}^{\infty} f(x) dx}$

We assume $y = dx$, hence $\int_{dx}^{+\infty} f(x) dx = \frac{\int_{x + k \cdot y}^{\infty} f(x) dx}{\int_{x}^{\infty} f(x) dx}$

We assume $y = dx$, hence $\int_{dx}^{+\infty} f(x) dx = \frac{\int_{x + k \cdot y}^{+\infty} f(x) dx}{\int_{x}^{+\infty} f(x) dx}$

Hence $\Rightarrow \int_{0}^{dx} f(x) dx = \int_{0}^{+\infty} f(x) dx = \frac{\int_{x + k \cdot y}^{+\infty} f(x) dx}{\int_{0}^{+\infty} f(x) dx}$
 $\Rightarrow -\int_{0}^{+\infty} f(x) dx = \int_{0}^{+\infty} f(x) dx$

No. hence $Q = \int_{0}^{+\infty} f(x) dx$
 $\Rightarrow -\int_{0}^{+\infty} f(x) dx = \int_{0}^{+\infty} f(x) dx$
 $\Rightarrow -\int_{0}^{+\infty} f(x) dx = \int_{0}^{+\infty} f(x) dx$