BPR: Bayesian Personalized Ranking from Implicit Feedback

by

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presented by Sukwon Yun

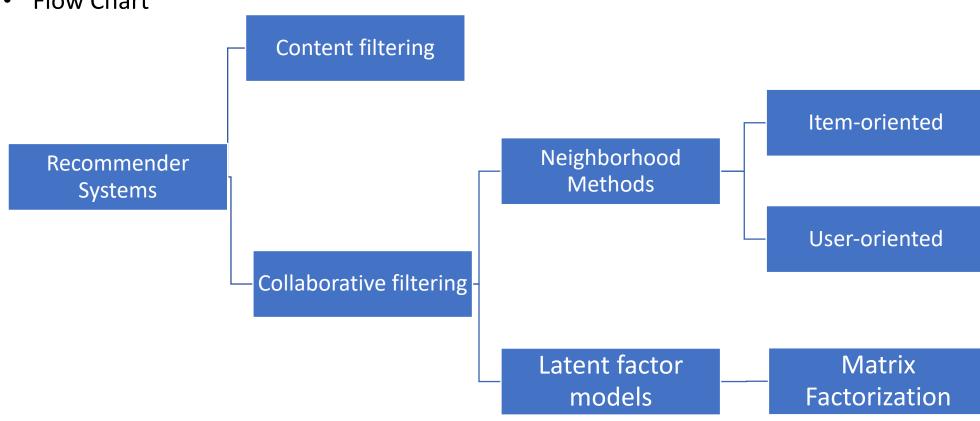


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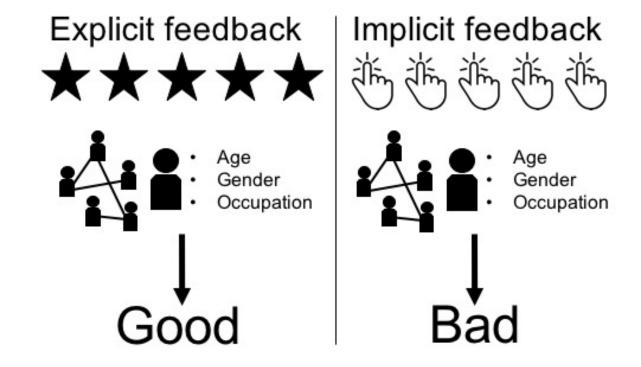


Flow Chart





Implicit feedback





Optimization Method

Minimize sum-of-squared-errors

$$\min_{q^*,p^*} \sum_{(u,i)\in\kappa} (r_{ui} - q_i^T p_u)^2 + \lambda(||q_i||^2 + ||p_u||^2)$$

$$\min_{p^*,q^*,b^*} \sum_{(u,i) \in K} c_{ui} (r_{ui} - \mu - b_u - b_i - p_u^T q_i)^2 + \lambda (||p_u||^2 + ||q_i||^2 + b_u^2 + b_i^2)$$

Maximize log-posterior probability

$$\ln p(U, V|R, \sigma^2, \sigma_V^2, \sigma_U^2) = -\frac{1}{2\sigma^2} \sum_{i=1}^N \sum_{j=1}^M I_{ij} (R_{ij} - U_i^T V_j)^2 - \frac{1}{2\sigma_U^2} \sum_{i=1}^N U_i^T U_i - \frac{1}{2\sigma_V^2} \sum_{j=1}^M V_j^T V_j$$
$$-\frac{1}{2} \left(\left(\sum_{i=1}^N \sum_{j=1}^M I_{ij} \right) \ln \sigma^2 + ND \ln \sigma_U^2 + MD \ln \sigma_V^2 \right) + C$$

BPR-OPT :=
$$\ln p(\Theta|>_u)$$

= $\ln p(>_u|\Theta) p(\Theta)$
= $\ln \prod_{(u,i,j)\in D_S} \sigma(\hat{x}_{uij}) p(\Theta)$
= $\sum_{(u,i,j)\in D_S} \ln \sigma(\hat{x}_{uij}) + \ln p(\Theta)$
= $\sum_{(u,i,j)\in D_S} \ln \sigma(\hat{x}_{uij}) - \lambda_{\Theta} ||\Theta||^2$



• Bayesian Probability

"From experienced past, For the interested future"

$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$
 Posterior



Personalized Ranking

$$S \subseteq U \times I$$

$$>_u \subset I^2$$

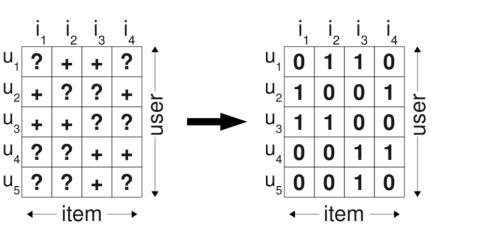
$$\forall i, j \in I : i \neq j \Rightarrow i >_{u} j \lor j >_{u} i \qquad (totality)$$

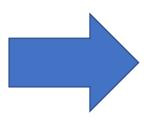
$$\forall i, j \in I : i >_{u} j \land j >_{u} i \Rightarrow i = j \qquad (antisymmetry)$$

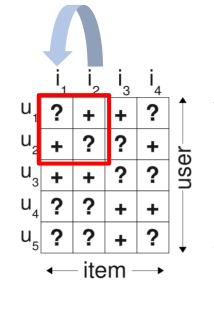
$$\forall i, j, k \in I : i >_{u} j \land j >_{u} k \Rightarrow i >_{u} k \qquad (transitivity)$$

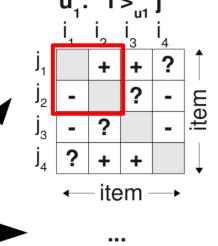


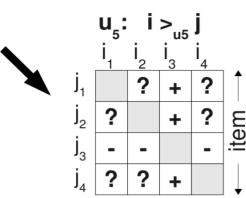
Personalized Ranking











← item →

$$D_S := \{(u, i, j) | i \in I_u^+ \land j \in I \setminus I_u^+ \}$$

BPR-OPT

$$\prod_{u \in U} p(>_u |\Theta) = \prod_{(u,i,j) \in U \times I \times I} p(i>_u j|\Theta)^{\delta((u,i,j) \in D_S)} \cdot (1 - p(i>_u j|\Theta))^{\delta((u,j,i) \notin D_S)}$$

$$\delta(b) := \begin{cases} 1 & \text{if } b \text{ is true,} \\ 0 & \text{else} \end{cases}$$

$$p(\Theta|>_u) \propto p(>_u|\Theta) p(\Theta)$$

$$\prod_{u \in U} p(>_{u} |\Theta) = \prod_{(u,i,j) \in D_{S}} p(i>_{u} j|\Theta)$$

$$p(i>_{u} j|\Theta) := \sigma(\hat{x}_{uij}(\Theta))$$

BPR-OPT

$$\begin{split} p(\Theta) \sim N(\mathbf{0}, \ \lambda_{\Theta}I) \\ N(\Theta|\mu, \Sigma) &= \frac{1}{(2\pi)^{d/2}|\Sigma|^{1/2}} exp(-\frac{1}{2}(\Theta - \mu)^T \Sigma^{-1}(\Theta - \mu)) \\ &\propto exp(-\frac{1}{2}\Theta^T(\frac{1}{\lambda_{\Theta}}I)\Theta) \\ &= exp(-\frac{1}{2\lambda_{\Theta}}\Theta^T\Theta) \simeq exp(-\lambda_{\Theta}\|\Theta\|^2) \end{split}$$

$$p(\Theta) \simeq exp(-\lambda_{\Theta} \|\Theta\|^2)$$

$$p(i >_u j | \Theta) := \sigma(\hat{x}_{uij}(\Theta))$$

BPR-OPT :=
$$\ln p(\Theta|>_u)$$

= $\ln p(>_u|\Theta) p(\Theta)$
= $\ln \prod_{(u,i,j)\in D_S} \sigma(\hat{x}_{uij}) p(\Theta)$
= $\sum_{(u,i,j)\in D_S} \ln \sigma(\hat{x}_{uij}) + \ln p(\Theta)$
= $\sum_{(u,i,j)\in D_S} \ln \sigma(\hat{x}_{uij}) - \lambda_{\Theta}||\Theta||^2$

" Maximize Posterior Probability "



Analogies between AUC

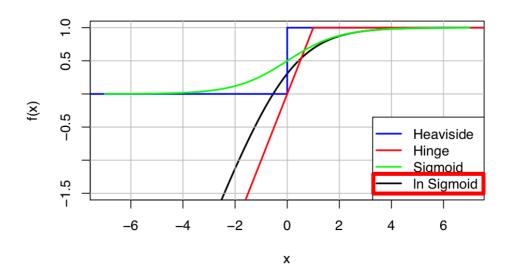
$$AUC(u) = \sum_{(u,i,j)\in D_S} z_u \,\delta(\hat{x}_{uij} > 0)$$

$$z_u = \frac{1}{|U|\,|I_u^+|\,|I\setminus I_u^+|}$$

$$\delta(x > 0) = H(x) := \begin{cases} 1, & x > 0 \\ 0, & \text{else} \end{cases}$$

BPR-OPT =
$$\sum_{(u,i,j)\in D_S} \ln \sigma(\hat{x}_{uij}) - \lambda_{\Theta} ||\Theta||^2$$

Loss functions



LEARNBPR

$$\frac{\partial \text{BPR-OPT}}{\partial \Theta} = \sum_{(u,i,j) \in D_S} \frac{\partial}{\partial \Theta} \ln \sigma(\hat{x}_{uij}) - \lambda_{\Theta} \frac{\partial}{\partial \Theta} ||\Theta||^2$$

$$\propto \sum_{(u,i,j) \in D_S} \frac{-e^{-\hat{x}_{uij}}}{1 + e^{-\hat{x}_{uij}}} \cdot \frac{\partial}{\partial \Theta} \hat{x}_{uij} - \lambda_{\Theta} \Theta$$

(1) Full gradient descent

$$\Theta \leftarrow \Theta - \alpha \frac{\partial BPR\text{-}OPT}{\partial \Theta}$$

- (-) slow convergence
- (-) skewness
- (-) possibility of i's domination

(2) Stochastic gradient descent with bootstrap

$$\Theta \leftarrow \Theta + \alpha \left(\frac{e^{-\hat{x}_{uij}}}{1 + e^{-\hat{x}_{uij}}} \cdot \frac{\partial}{\partial \Theta} \hat{x}_{uij} + \lambda_{\Theta} \Theta \right)$$

- (+) faster convergence
- (+) less probability in consecutive updating
- (+) abandon full cycle



- Application in Matrix Factorization

$$\hat{x}_{uij} := \hat{x}_{ui} - \hat{x}_{uj}$$

$$\hat{x}_{ui} = \langle w_u, h_i \rangle = \sum_{f=1}^k w_{uf} \cdot h_{if}$$

$$\frac{\partial}{\partial \theta} \hat{x}_{uij} = \begin{cases} (h_{if} - h_{jf}) & \text{if } \theta = w_{uf}, \\ w_{uf} & \text{if } \theta = h_{if}, \\ -w_{uf} & \text{if } \theta = h_{jf}, \\ 0 & \text{else} \end{cases}$$

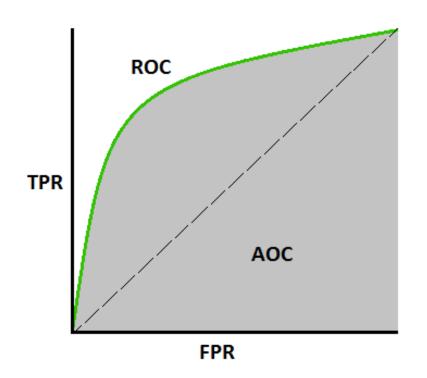
- Application in Adaptive K-Nearest-Neighbor

$$\hat{x}_{ui} = \sum_{l \in I_u^+ \land l \neq i} c_{il}$$

$$c_{i,j}^{\text{cosine}} := \frac{|U_i^+ \cap U_j^+|}{\sqrt{|U_i^+| \cdot |U_j^+|}}$$

$$\frac{\partial}{\partial \theta} \hat{x}_{uij} = \begin{cases} +1 & \text{if } \theta \in \{c_{il}, c_{li}\} \land l \in I_u^+ \land l \neq i, \\ -1 & \text{if } \theta \in \{c_{jl}, c_{lj}\} \land l \in I_u^+ \land l \neq j, \\ 0 & \text{else} \end{cases}$$

- Computing AUC

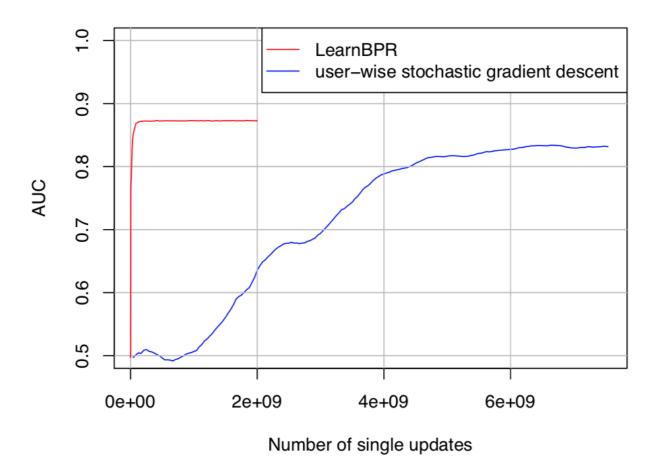


AUC =
$$\frac{1}{|U|} \sum_{u} \frac{1}{|E(u)|} \sum_{(i,j) \in E(u)} \delta(\hat{x}_{ui} > \hat{x}_{uj})$$

$$E(u) := \{(i,j)|(u,i) \in S_{\text{test}} \land (u,j) \not\in (S_{\text{test}} \cup S_{\text{train}})\}$$

3. Results

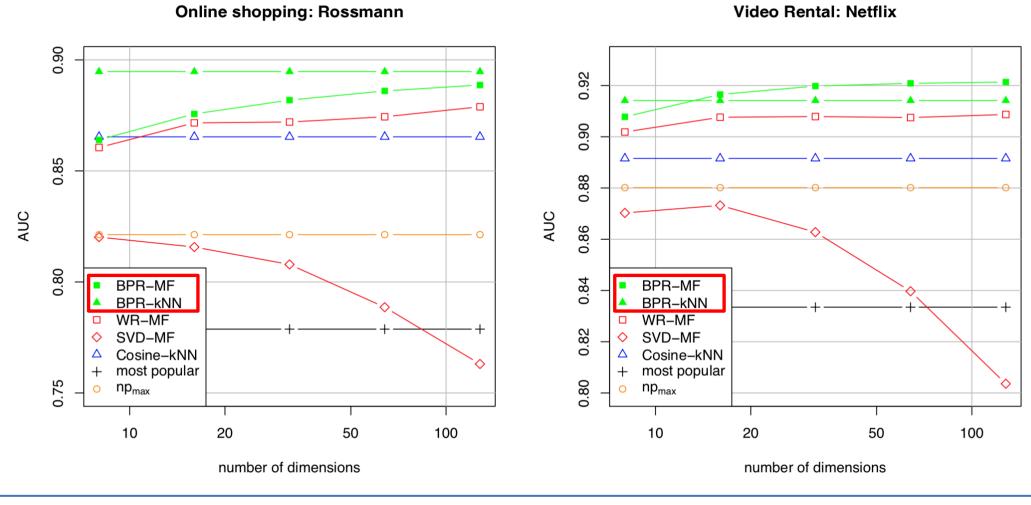
Convergence on Rossmann dataset





3. Results







4. Implementation

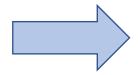


4. Implementation



5. Key takeaways

- (1) BPR for personalized ranking
- (2) BPR-OPT by Maximizing posterior estimator
- (3) LEARN BPR by SGD + bootstrap sampling
- (4) Application in MF, kNN



"Importance of optimizing models for the right Criterion"



5. Discussions

- (-) Based on Offline learning (Unable to handle real-time feedback)
- (-) Assumed Independency for user's act
- (-) Loss of information due to focusing on binary cases -> Kim, D., & Lee, E. R. (2017). Modified Bayesian personalized ranking for non-binary implicit feedback
- (-) Uniformly selected triples (u, i, j)
 -> Gantner, Z., Drumond, L. (2012, June). Personalized ranking for non-uniformly sampled items.
- (-) AUC isn't the optimal metric



References

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