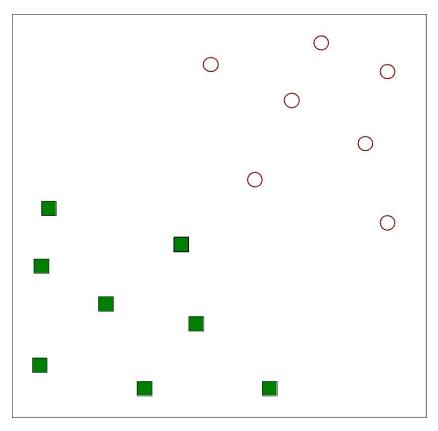
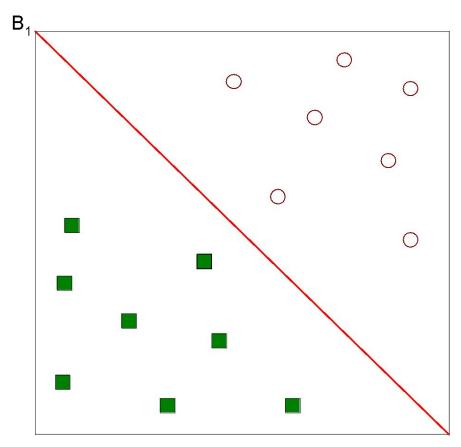
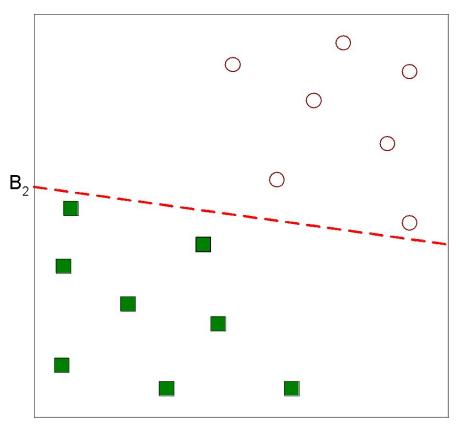
CS4104 Applied Machine Learning
Support Vector Machines
(SVM)



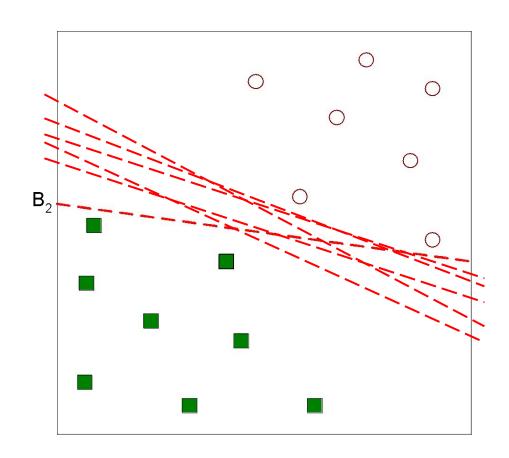
• Find a linear hyperplane (decision boundary) that will separate the data



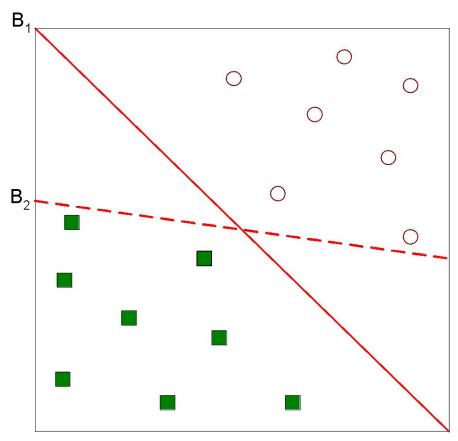
• One Possible Solution



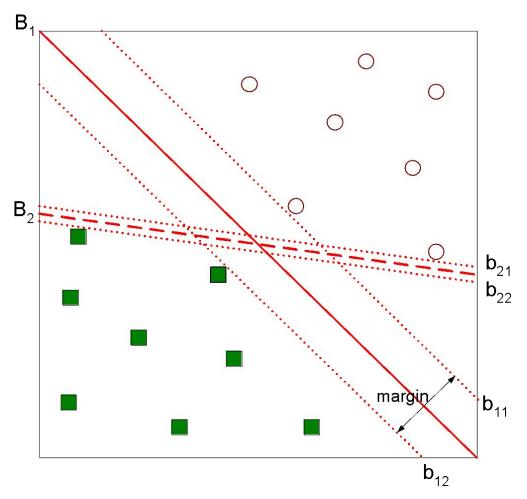
Another possible solution



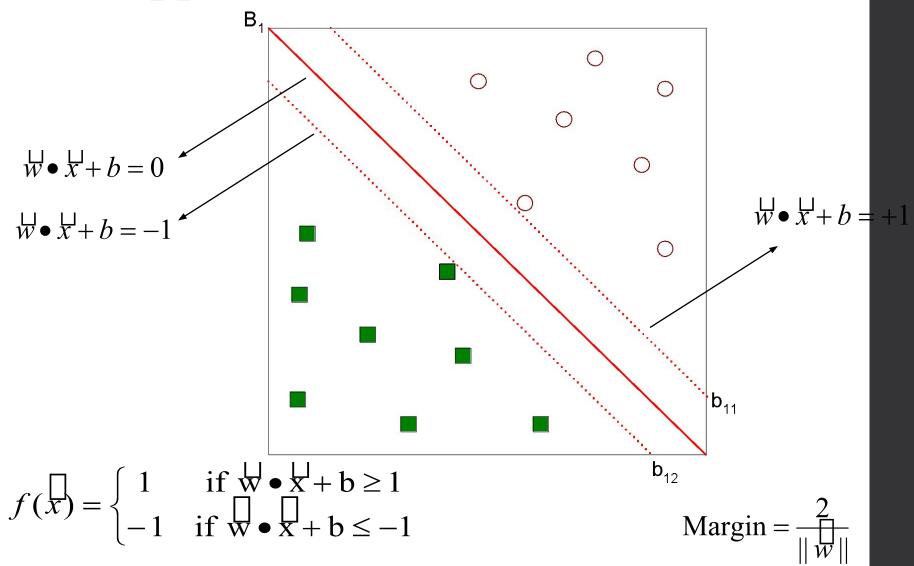
Other possible solutions



- Which one is better? B1 or B2?
- How do you define better?



• Find hyperplane maximizes the margin => B1 is better than B2



#### Linear SVM

Linear model:

$$f(x) = \begin{cases} 1 & if \quad w. \, x + b \ge 1 \\ -1 & if \quad w. \, x + b \le -1 \end{cases}$$

- Learning the model is equivalent to determining the values of *W* and *b*.
  - How to find *W* and *b* from training data?

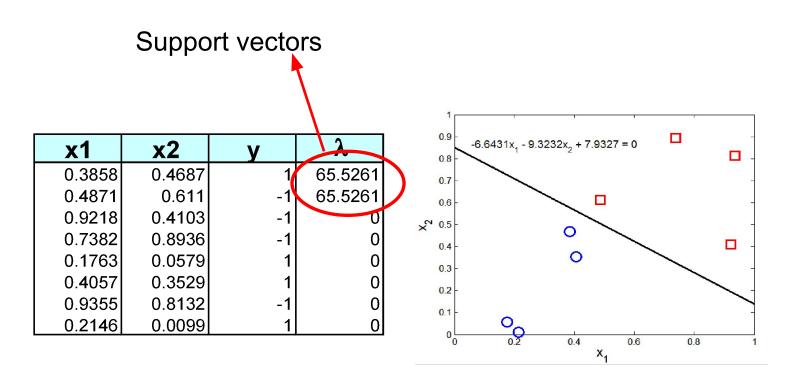
#### Learning Linear SVM

- Objective is to maximize:
  - $Margin = \frac{2}{|W|}$
- Which is equivalent to minimizing:
  - $L(W) = \frac{|W|^2}{2}$
- Subject to the following constraints:

$$\cdot \ y_i = \begin{cases} 1 & if \quad w. \, x_i + b \ge 1 \\ -1 & if \quad w. \, x_i + b \le -1 \end{cases}$$

- OR
  - $y_i(w.x_i + b) \ge 1 : i = 1,2,3,...,N$
- This is a constrained optimization problem
- Solve it using Lagrange multiplier method

### Example of Linear SVM

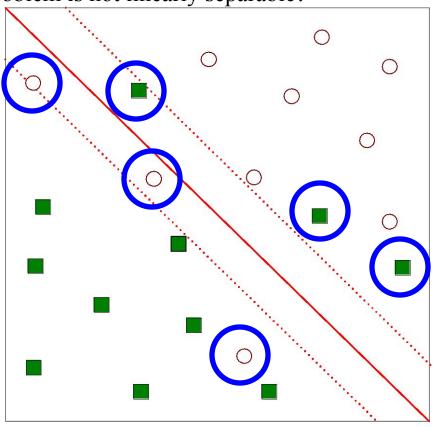


#### Learning Linear SVM

- Decision boundary depends only on support vectors
  - If you have data set with same support vectors, decision boundary will not change
  - How to classify using SVM once  ${\bf w}$  and b are found? Given a test record,  ${\bf x_i}$

$$f(x) = \begin{cases} 1 & if \quad w. \, x + b \ge 1 \\ -1 & if \quad w. \, x + b \le -1 \end{cases}$$

• What if the problem is not linearly separable?



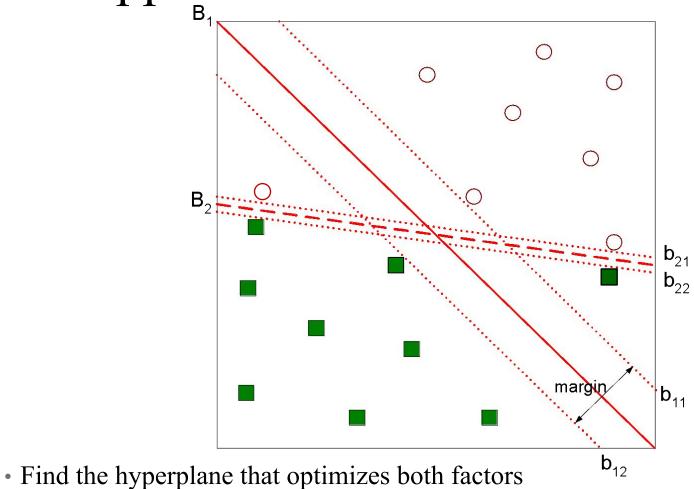
- What if the problem is not linearly separable?
  - Introduce slack variables
    - Need to minimize:

$$L(w) = \frac{\|\vec{w}\|^2}{2} + C\left(\sum_{i=1}^{N} \xi_i^k\right)$$

• Subject to:

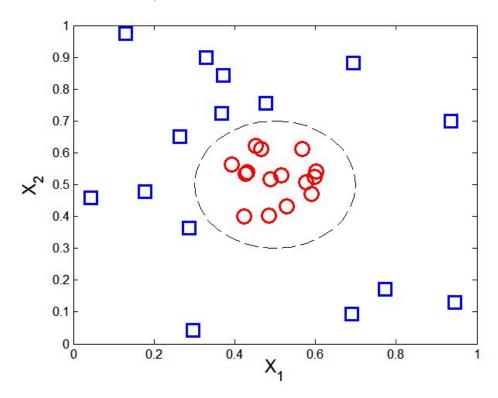
$$y_{i} = \begin{cases} 1 & \text{if } \mathbf{w} \bullet \mathbf{x}_{i} + \mathbf{b} \ge 1 - \xi_{i} \\ -1 & \text{if } \mathbf{w} \bullet \mathbf{x}_{i} + \mathbf{b} \le -1 + \xi_{i} \end{cases}$$

• If k is 1 or 2, this leads to similar objective function as linear SVM but with different constraints (see textbook)



# Nonlinear Support Vector Machines

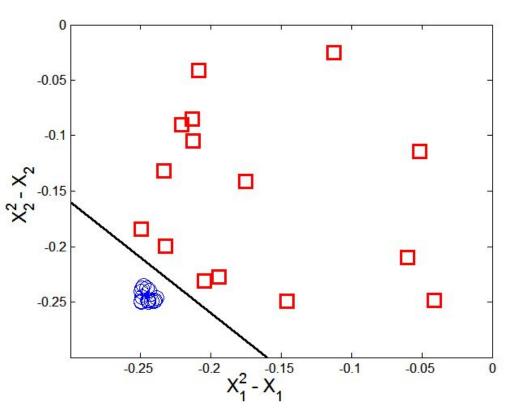
What if decision boundary is not linear?



$$y(x_1, x_2) = \begin{cases} 1 & \text{if } \sqrt{(x_1 - 0.5)^2 + (x_2 - 0.5)^2} > 0.2\\ -1 & \text{otherwise} \end{cases}$$

# Nonlinear Support Vector Machines

• Transform data into higher dimensional space



$$x_1^2 - x_1 + x_2^2 - x_2 = -0.46.$$

$$\Phi:(x_1,x_2)\longrightarrow (x_1^2,x_2^2,\sqrt{2}x_1,\sqrt{2}x_2,1).$$

$$w_4x_1^2 + w_3x_2^2 + w_2\sqrt{2}x_1 + w_1\sqrt{2}x_2 + w_0 = 0.$$

Decision boundary:

$$\stackrel{\square}{w} \bullet \Phi(\stackrel{\square}{x}) + b = 0$$

#### Learning Nonlinear SVM

Optimiz 
$$\min_{\boldsymbol{w}} \frac{\|\mathbf{w}\|^2}{2}$$
 subject to 
$$y_i(\boldsymbol{w} \cdot \Phi(\boldsymbol{x}_i) + b) \geq 1, \ \forall \{(\boldsymbol{x}_i, y_i)\}$$

• Which leads to the same set of equations (but involve  $\Phi(x)$  instead of x)

$$\begin{split} L_D &= \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i,j} \lambda_i \lambda_j y_i y_j \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_j) \qquad \mathbf{w} = \sum_i \lambda_i y_i \Phi(\mathbf{x}_i) \\ & \lambda_i \{ y_i (\sum_j \lambda_j y_j \Phi(\mathbf{x}_j) \cdot \Phi(\mathbf{x}_i) + b) - 1 \} = 0, \end{split}$$

$$f(\mathbf{z}) = sign(\mathbf{w} \cdot \Phi(\mathbf{z}) + b) = sign(\sum_{i=1}^{n} \lambda_i y_i \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{z}) + b).$$

#### Learning NonLinear SVM

- Issues:
  - What type of mapping function  $\Phi$  should be used?
  - How to do the computation in high dimensional space?
    - Most computations involve dot product  $\Phi(x_i)$   $\Phi(x_i)$
    - Curse of dimensionality?

#### Learning Nonlinear SVM

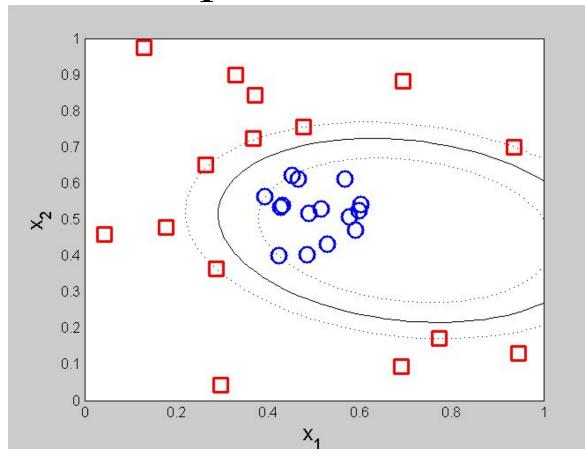
- Kernel Trick:
  - $\Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_j) = K(\mathbf{x}_i, \mathbf{x}_j)$
  - K(x<sub>i</sub>, x<sub>j</sub>) is a kernel function (expressed in terms of the coordinates in the original space)
    - Examples:

$$K(\mathbf{x}, \mathbf{y}) = (\mathbf{x} \cdot \mathbf{y} + 1)^{p}$$

$$K(\mathbf{x}, \mathbf{y}) = e^{-\|\mathbf{x} - \mathbf{y}\|^{2}/(2\sigma^{2})}$$

$$K(\mathbf{x}, \mathbf{y}) = \tanh(k\mathbf{x} \cdot \mathbf{y} - \delta)$$

#### Example of Nonlinear SVM



SVM with polynomia degree 2 kernel

#### Learning Nonlinear SVM

- Advantages of using kernel:
  - Don't have to know the mapping function  $\Phi$
  - Computing dot product  $\Phi(x_i)$  ·  $\Phi(x_j)$  in the original space avoids curse of dimensionality
- Not all functions can be kernels
  - Must make sure there is a corresponding  $\Phi$  in some high-dimensional space
  - Mercer's theorem (see textbook)

- The learning problem is formulated as a convex of ting attour problem
  - Efficient algorithms are available to find the global minima
  - Many of the other methods use greedy approaches and find locally optimal solutions
  - High computational complexity for building the model
- Robust to noise
- Overfitting is handled by maximizing the margin of the decision boundary,
- SVM can handle irrelevant and redundant better than many other techniques
- The user needs to provide the type of kernel function and cost function
- Difficult to handle missing values

What about categorical variables?