

**Jahangirnagar University**  
**Department of Computer Science and Engineering**

LAB REPORT  
ON  
CSE-206 (NUMERICAL METHODS LAB)

EXPERIMENT No.: 04

EXPERIMENT NAME: Determining The Root of a Non-Linear Equation Using Secant Method.



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### Experiment No: 04

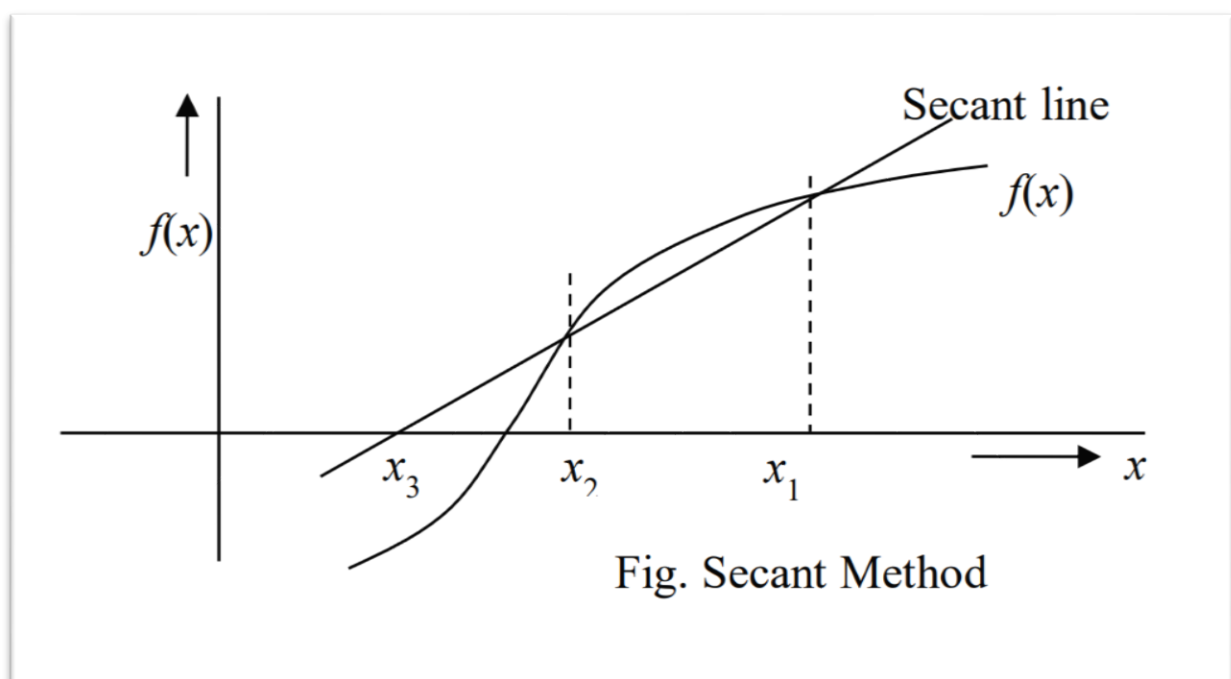
Name of the Experiment: Determining the root of a non-linear equation using secant method.

### Objectives:

- ✚ Understanding the process of finding the root of non-linear equation using Scant Method.
- ✚ Executing the implementation of the algorithm of Scant Method.
- ✚ To achieve the accurate root and expected output of a given nonlinear function.
- ✚ To be able to interpret the advantages and disadvantages of Scant Method.

### Theory:

Secant method uses two initial estimates but does not require that they must bracket the root. The basic concept is illustrated in the following figure:



**Fig 01:** Graphical Depiction of Secant Method.

Consider the points  $x_1$  and  $x_2$  as starting values. They don't bracket the root. Slope of the secant line passing through  $x_1$  and  $x_2$  is given by

$$\frac{f(x_1)}{x_1 - x_3} = \frac{f(x_2)}{x_2 - x_3}$$

or,

$$f(x_1)(x_2 - x_3) = f(x_2)(x_1 - x_3)$$

or,

$$x_3[f(x_2) - f(x_1)] = f(x_2)x_1 - f(x_1)x_2$$

Therefore,

$$x_3 = x_2 - \frac{f(x_2)(x_2 - x_1)}{f(x_2) - f(x_1)}$$

In general form,

$$x_{i+1} = x_i - \frac{f(x_i)(x_i - x_{i-1})}{f(x_i) - f(x_{i-1})}$$

### Algorithm:

#### ***Secant Method:***

1. Choose two initial points  $x_1$  and  $x_2$ , accuracy level required, E.
2. Compute  $f_1=f(x_1)$  and  $f_2=f(x_2)$ .
3. Compute

$$x_3 = x_2 - \frac{f_2 x_1 - f_1 x_2}{f_2 - f_1}$$

4. Test for accuracy of  $x_3$ .

If  $|\frac{x_3 - x_2}{x_3}| > E$ , then Set  $x_1=x_2$  and  $f_1=f_2$  Set  $x_2=x_3$  and  $f_2=f_3$  Go to step 3

Otherwise, Set root =  $x_3$  Print results.

5. Stop.

### Coding in C:

```
#include<stdio.h>
#include<math.h>
#define EPS 0.000001
#define MAXIT 50
#define F(x) (x)*(x) - 4 * (x) - 10
int cnt;
float root, x1, x2;
int sec(float a, float b)
{
    float x3, f1, f2, err;
    x1 = a;
    x2 = b;
    cnt = 1;


    int c;
    do
    {
        f1 = F(x1);
        f2 = F(x2);
        if(fabs(f1 - f2) <=EPS) return 1;
        x3 = x2 - (f2 * (x2 - x1) / (f2 - f1));
        x1 = x2;
        f1 = f2;
        x2 = x3;
    }
```

```

        f2 = F(x3);
        cnt++;
        if(cnt > MAXIT)
        {
            return 2;
        }
    }
    while(fabs(f1 - f2) >= EPS);
    root = x3;
    return 3;
}
int main()
{
    int s = 0;
    float a, b, x1, x2;
    printf("\n");
    printf("F(x) = (x)*(x) - 4 * (x) - 10\n\n");
    printf("SOLUTION BY SECANT METHOD\n\n");
    printf("Input starting with values : ");
    scanf("%f%f",&a,&b);
    printf("\n");
    s = sec(a, b);
    if(s == 1)
    {
        printf("\nDIVISION BY ZERO\n");
        printf("Last x1 = %.6f\n",x1);
        printf("Last x2 = %.6f\n",x2);
        printf("NO. OF ITERATIONS = %d\n\n",cnt - 1);
    }
    else if(s == 2)
    {
        printf("\nNO COVERGENCE IN %d ITERATIONS\n\n",MAXIT);
    }
    else
    {
        printf("\nRoot = %.6f\n",root);
        printf("F(root) = %.6f\n",F(root));
        printf("NO. OF ITERATIONS = %d\n\n",cnt - 1);
    }
    return 0;
}

```

### Output:

 C:\Users\ASUS\Desktop\Sec.exe

```
F(x) = (x)*(x) - 4 * (x) - 10  
  
SOLUTION BY SECANT METHOD  
  
Input starting with values : 1 6  
  
Root = 5.741657  
F(root) = -0.000001  
NO. OF ITERATIONS = 6  
  
Process returned 0 (0x0)   execution time : 4.139 s  
Press any key to continue.
```

**Fig 02:** Output Obtained.

### Discussion:

From the above experiment, we can observe that, Secant method doesn't need to bracket the root. Its convergence is slower than Newton-Raphson method. It doesn't need derivative to find the root of a nonlinear equation which makes it more convenient than Newton-Raphson method.

As the initial guesses don't bracket the root, it is uncertain whether the method will converge or not.

This method is easier to implement. If time is not the issue, then we can use this method to easily determine a root of a non-linear equation.

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