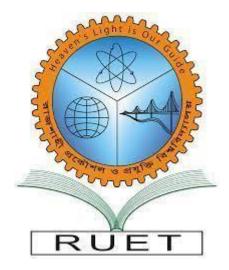
### Rajshahi University of Engineering & Technology



## **Department: Electrical & Computer Engineering**

Course No: ECE 4124

**Course Name: Digital Signal Processing Sessional** 

### **Submitted By:**

Sumaiya Tabassum Roll: 1810023

#### **Submitted To:**

Hafsa Binte Kibria Lecturer, Dept of ECE **Experiment No: 5** 

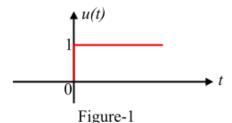
**Experiment Date: 22.5.23** 

**Experiment Name: Study about causal, anti causal & non causal signal.** 

#### **Theory:**

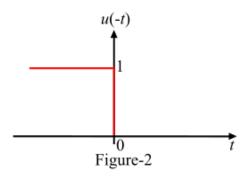
#### **Causal Signal:**

A continuous time signal x(t) is called causal signal if the signal x(t) = 0 for t < 0. Therefore, a causal signal does not exist for negative time. The unit step signal u(t) is an example of causal signal .Similarly, a discrete time sequence x(n) is called the causal sequence if the sequence x(n) = 0 for n < 0.



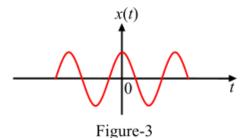
#### **Anti-Causal Signal:**

A continuous-time signal x(t) is called the anti-causal signal if x(t) = 0 for t > 0. Hence, an anti-causal signal does not exist for positive time. The time reversed unit step signal u(-t) is an example of anti-causal signal .Similarly, a discrete time sequence x(n) is said to be anti-causal sequence if the sequence x(n) = 0 for t > 0.



#### **Non-Causal Signal:**

A signal which is not causal is called the non-causal signal. Hence, by the definition, a signal that exists for positive as well as negative time is neither causal nor anti-causal, it is non-causal signal. The sine and cosine signals are examples of non-causal signal (see Figure-3).



#### **Zeroes & Poles:**

The values of z for which H(z) = 0 are called the zeros of H(z), and the values of z for which H(z) is infinite are referred to as the poles of H(z).

#### **Code & Output:**

#### **Causal Signal:**

Code:

```
clc;
clear all;
close all;
x=[3 1 4 2 5];
l=length(x);
A=0;
z=sym('z');
for i=0:1-1
        A=A+x(i+1).*z^(-i);
end
disp('Causal Output:');
disp(A);
```

#### **Output:**

```
Causal Output: 1/z + 4/z^2 + 2/z^3 + 5/z^4 + 3
```

#### **Anti Causal Signal:**

Code:

```
clc;
clear all;
close all;
y=[3 1 4 2 5];
x=fliplr(y);
l=length(x);
A=0;
z=sym('z');
for i=0:l-1
        A=A+x(i+1).*z^(i);
end
disp('AntiCausal Output:');
disp(A);
```

#### **Output:**

```
AntiCausal Output: 3*z^4 + z^3 + 4*z^2 + 2*z + 5
```

# Non Causal Signal: Code:

```
clc;
clear all;
close all;
x = [3 1 4 2 5];
n=length(x);
k=input('Enter zero index:');
p=[];
for i=0:k-1
    p(i+1) = x(i+1);
end
h=fliplr(p);
a=length(h);
A=0;
z=sym('z');
for i=0:a-1
    A=A+h(i+1).*z^{(i)};
end
q=[];
for i=1:(n-k)
    q(i) = x(i+k);
end
b=length(q);
for i=0:b-1
    A=A+q(i+1).*z^{(-(i+1))};
end
disp(A);
```

#### **Output:**

```
Enter zero index:3 z + 2/z + 5/z^2 + 3*z^2 + 4
```

# Inverse Z transform & plotting zeroes and poles of the discrete signal $x=[3\ 1\ 4\ 2\ 5]$ : Code:

```
clc;
clear all;
close all;
x=[3 1 4 2 5];
l=length(x);
A=0;
z=sym('z');
for i=0:1-1
    A=A+x(i+1).*z^{(-i)};
end
disp('Causal Output:');
disp(A);
f=iztrans(A);
disp(f);
z=[];
p=[0];
zplane(z,p);
grid;
```

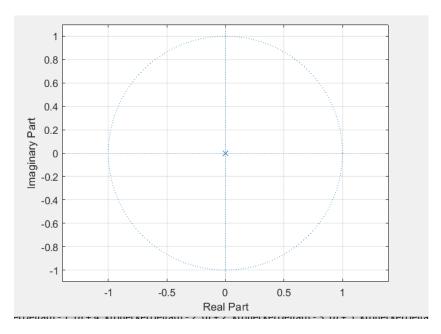
#### **Output:**

**Causal Output:** 

```
1/z + 4/z^2 + 2/z^3 + 5/z^4 + 3
```

kroneckerDelta(n - 1, 0) + 4\*kroneckerDelta(n - 2, 0) + 2\*kroneckerDelta(n - 3, 0) + 5\*kroneckerDelta(n - 4, 0) + 3\*kroneckerDelta(n, 0)

#### **Plotting Zeroes and Poles:**



#### **Conclusion:**

Here the same discrete signal has been used for getting causal ,anti causal and non causal signal. The output signal gained for causal one was x(t)=0 for t<0 & x(t)=0 for t>0. Then the inverse transform and the plotting of poles and zeroes were also gained successfully.