D. Given, S is a linearly independent subset of a vector space V.

Also, B is a vector in V such that B ≠ span(s)

Adjoining B to S:
new set, Snew = S U { B }

Let S = { u, uz, ---, un }

Case-I:- Co-efficient of B is ZERO:
Given S is linearly independent.

i.  $\alpha_i u_i + \alpha_i u_{i+1} - - + \alpha_i u_i = 0$  if and only if  $\alpha_i = \alpha_i = - - = \alpha_i = 0$   $\{\alpha_i = \}$  scalary.

Now calculating for Snew, when  $i \le i \le n$  when  $i \le i \le n$  and  $\alpha_i u_i + \alpha_i u_i + - + \alpha_i u_i + \alpha_{i+1} B = 0$  family when  $\alpha_i = \alpha_i = - - = \alpha_i = 0$ .

So, we can say that Snew is also linearly independent iff  $\{\alpha_{n+1} = 0\}$  (Trivial Case)

Case-II: Co-efficient of B is NOT zero:

We will prove thu by contradiction.

Given, B  $\neq$  spani(S)

Let Snew be linearly dependent to  $\alpha_{n+1} \neq 0$ .  $\alpha_{n+1} + \alpha_{n+1} + \cdots + \alpha_{n+1} + \alpha_{n+1} = 0$ or, B =  $\left(\frac{-\alpha_1}{\alpha_{n+1}}\right) u_1 + \left(\frac{-\alpha_2}{\alpha_{n+1}}\right) u_1 + \cdots + \left(\frac{-\alpha_n}{\alpha_{n+1}}\right) u_n$ 

So, & can be written as a linear combination of vectors present in S.

: Thus is a contradiction to the fact that B & span(S).

So, by contradiction we can say & now say that Snew is actually Linearly Independent.

Hence, by case-I and case-II, we have proved that:

Snew is also Linearly Independent.

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2 Given: S is a subspace of a Vector Space V.  To prove: span(S) = S
To prove: - span(s) - s
Proof.  Span(s) is the set of all finite linear combinations of vectors present in S.  So, for any vector $v \in S$ , it will ast also satisfy $v \in Span(S)$ .
:. S = Span (S) [U]
Now, let vector u e span(s).
So, .
$u = \alpha_1 s_1 + \alpha_2 s_2 + \dots + \alpha_m s_m$ where, scalar $\alpha_i \in F$ , $s_i \in S$ ,
since S is a subspace, so it satisfies
and scalar multiplication.
So, $u \in S$ . : We can say that, $Span(s) \subseteq S \widehat{W}$
From (i) and (ii),
Span(S) = S

Let 
$$A = \begin{bmatrix} 12 & 4 & 4 \\ 5 & 4 & 5 \\ 2 & 3 & 4 \end{bmatrix}$$
 and  $X = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix}$ 

: Null space i.e. N(A) = X such that AX = 0Now, reducing the matrix  $A_{*}$  (echelon form):- $\begin{bmatrix} 12 & 4 & 4 \\ 5 & 4 & 5 \\ 2 & 3 & 4 \end{bmatrix} \xrightarrow{R_{2}=R_{2}-(\frac{5}{12})R_{1}} \begin{bmatrix} 12 & 4 & 4 \\ 0 & \frac{7}{3} & \frac{10}{3} \\ 2 & 3 & 4 \end{bmatrix}$ 

Now, 
$$AX = 0$$
  
i.e.  $\begin{bmatrix} 12 & 4 & 4 \\ 0 & \frac{1}{3} & \frac{10}{3} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$ 

So, 
$$12x_1 + 4x_2 + 4x_3 = 0$$
  
 $6x_1, 3x_1 + x_2 + x_3 = 0$  --- (i)  
 $\frac{7}{3}x_1 + \frac{10}{3}x_3 = 0$   
 $6x_1, 4x_2 + \frac{10}{3}x_3 = 0$  --- (ii)

Let 
$$x_3 = \alpha$$
. --- (ii)

: From (ii) 1 (iii),

 $x_2 = -\frac{10}{7} \alpha$  --- (iv)

From 
$$(\underline{i})$$
,  $(\underline{i}\underline{n})$  &  $(\underline{i}\underline{v})$ ,
$$x_1 = -\frac{x_2}{3} - \frac{x_3}{3}$$

$$= \frac{10}{21} \cdot \frac{1}{3} - \frac{x_3}{3}$$

$$= \frac{x_3}{7} - \frac{x_3}{3}$$

:. Nullspace of A i.e. 
$$N(A)$$
:
$$X = \begin{bmatrix} \frac{\alpha}{4} \\ -10\alpha/4 \\ \alpha \end{bmatrix}$$
(where  $\alpha = x_3$ )

(b) 
$$\begin{bmatrix} 1 & 2 & 3 \\ 6 & 5 & 4 \\ 3 & 4 & 4 \end{bmatrix}$$
  
Let  $A = \begin{bmatrix} 1 & 2 & 3 \\ 6 & 5 & 4 \\ 3 & 4 & 4 \end{bmatrix}$  and  $X = \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix}$ 

.. 
$$N(A) = X$$
 such that  $AX = 0$   
Now reducing the matrix  $A$  (echelon form):-
$$\begin{bmatrix} 1 & 2 & 3 \\ 6 & 5 & 4 \\ 3 & 4 & 4 \end{bmatrix} \xrightarrow{R_1 = R_2 - 6R_1} \begin{bmatrix} 1 & 2 & 3 \\ 0 & -7 & -14 \\ 3 & 4 & 4 \end{bmatrix}$$

(P.T.O.)

Now 
$$AX = 0$$
  
i.e.  $\begin{bmatrix} 1 & 2 & 3 \\ 0 & -7 & -14 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$   

$$x_1 + 2x_1 + 3x_3 = 0 --- (i)$$

$$-7x_2 - 14x_3 = 0$$
or,  $x_1 + 2x_3 = 0 --- (ii)$ 

$$-x_3 = 0$$
or,  $x_3 = 0 --- (ii)$ 

$$x_1 = x_2 = x_3 = 0$$

$$\therefore \text{ Nullspace of } A \text{ i.e. } N(A) :--$$

$$X = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$X = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

(c) 
$$\begin{bmatrix} 12 & 3 & 9 \\ 20 & 5 & 15 \\ 16 & 4 & 12 \end{bmatrix}$$

Let  $A = \begin{bmatrix} 12 & 3 & 9 \\ 20 & 5 & 15 \\ 16 & 4 & 12 \end{bmatrix}$  and  $X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ 

$$\therefore N(A) = X \text{ such that } AX = 0$$

Now reducing the matrix  $A \text{ (echelon form)}$ :
$$\begin{bmatrix} 12 & 3 & 9 \\ 20 & 5 & 15 \\ 16 & 4 & 12 \end{bmatrix} \xrightarrow{R_2 = R_2 - \left(\frac{5}{3}\right)R_1} \begin{bmatrix} 12 & 3 & 9 \\ 0 & 0 & 0 \\ 16 & 4 & 12 \end{bmatrix}$$

$$R_{3}=R_{3} + \frac{4}{3}R_{1} = \begin{bmatrix} 12 & 3 & 9 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_{1}=\{\frac{1}{3}\}R_{1}} \begin{bmatrix} 4 & 1 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\therefore 4x_{1} + x_{2} + 3x_{3} = 0 \qquad ---- (i)$$
Let  $x_{1} = x$  and  $x_{3} = x_{3} = 0$ 

$$So, x_{1} = -x_{4} + 3x_{3} = 0$$

$$\therefore \text{Nullspace of } A = \begin{bmatrix} -1 \\ 4 \\ 4 \end{bmatrix}$$

$$\therefore \text{Nullspace of } A = \begin{bmatrix} -1 \\ 4 \\ 4 \end{bmatrix} = \begin{bmatrix} -1 \\ 4 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 4 \\ 1 \\$$

Given, W is a subspace of V with a bosis tdi: i e [m] j i.e. :- $B_{\omega} = \{\alpha_1, \alpha_2, ---, \alpha_m\}$ and dim (W) = m Since Bo is a linearly Independent set (by definition of Basis), so:  $a_1 x_1 + a_2 x_2 + - - + a_{3n} x_m = 0$  iff  $a_1 = a_2 = - - = a_m = 0$ where scalars  $a_i \in F$ , and  $1 \le i \le m$ Now, given & ∈ V\W. Let S = { d; + B : i ∈ [m]} = { a, + B, d, + B, ---, dm + By : We have to prove that: a) Span(S) is a subspace of V. b) dim (Span(8)) = m Proof :a) Since any (xi+B) E V as it is closed under vector addition, therefore, S is a subset of V ie. SCV So, by definition, we know that: Spari(S) will form a subspace of V:- W b) Checking for Linear Independence of S: a, (\alpha, + &) + ar(\alpha, + &) + -- + am (\alpha m + &) = (a1x1 + a2x2+ -- + amxm) + (a1+a2+-+ am) & = 0 iff (a=a====am=0) { from eq. (1) }

So, Span (S) is a subspace for which S is the basis, i.e. Span (S) is the set of all finite linear combination of elements in S.

Now, S has 'm' no. of elements, and S is atterbases of Span (S).

i. dim (Span (S)) = m - (iii)

Hence, we have proved that (from (ii) k(iii):

The span of set { di + B: i \in [m] j ie. Span (S) is a m-dimensional subspace of V.

a) The no. of linear transformations T: V > V: Given, F is a finite field with prelements where p is a prime. V is a k-dimensional vector space over F. Let {b, , b2, -- , bx } ke a bosis of V. :. We can define at T: V > V as:- ; T(bi) = dibi + dibi+ - - + aik bk  $T(b_2) = \alpha_{21}b_1 + \alpha_{22}b_2 + \cdots + \alpha_{2K}b_K$ The man of the said of the many of T(bx)= dk1 b1 + dk2 b2 + - - + dxx bx So, the no of linear transformations is the no. of different combinations of dis where 1 1 1, i sk.

the have pr choices for each dij and we have total kxk ro of dij's.

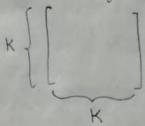
:. Total no. of linear transformations:- $\Rightarrow (pn)^{(k\times k)}$ 

= (b)nk2 | pm

b) The no. of invertible linear transformations T:V->V: Given F is a finite field with p<sup>n</sup> elements where p is a prime.

V is a k-dimensional vector space over F.

We can represent the no. of invertible linear transformations in the form of kxk invectible matrices (where each of its elements EF).



1st row - It can be anything excluding the 0- Vector

.. No of possibilities = (pn)x-1 {1 for overtox}

2nd sow: It can be anything excluding the multiples of 1st sous.

.. No of possibilities = (pn)k - pn = pnk - pn

3rd row: It can be anything excluding the multiples of 1st and 2nd round. No of possibilities = (pn)k-(pnxpn) = pnk-p2n

Kth row: It can be anything excluding the multiples of the first (k-1) rows.

: No. of possibilities = pnk - p(k-1)n

: Total no. of linear transformations: => (pnk-1) (pnk-pn) (pnk-pn) -- (pnk-p(k-nn) =  $(p^{nK}-1) \times \prod (p^{nK}-p^{in})$