# SUMANT BAGRI

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### **OBJECTIVE**

- Highly motivated and a persistent learner aspiring to become an artificial intelligence engineer
- Passionate about developing Smart Robotics supporting healthcare professionals/patients & commercialized applications
- Acquired a strong background in the operations of global financial markets relevant to ETPs, FX and Digital Assets and therefore open to exciting opportunities in the field of financial technology

### **EDUCATION**

September 2022 – December 2023 (expected)

**MSc in Applied Computing** University of Toronto, Department of Computer Science

Courses (ongoing): Introduction to Machine Learning, Introduction to Mobile Robotics, Computational Imaging

## **Bachelor and Master of Technology**

August 2015 - August 2020

Indian Institute of Technology Bombay, Mechanical Engineering Minor in Electrical Engineering

### **EXPERIENCE**

### Flow Traders Asia Pte. Ltd

October 2020 – April 2022

**Trading Operations Engineer** 

- Manage, maintain and optimize all internal, software and hardware stacks largely integrated with the Linux kernel
- Provide first-contact incident resolution to trading desks ensuring that their performance requirements are met
- Work with development to build and test exchange APIs for different APAC markets
- Implement automated ops-engines and relevant monitoring tools improving control and enabling streamlined deliveries

# Research/Academic Projects

### **IIT Bombay**

Capturing cutting tool failure in micro-milling

September 2019 – August 2020

- Developed a novel protocol and designed an experimental setup for micro-milling of non-linear slots
- Implemented an image processing pipeline to extract tool-wear data from captured tool images
- Modelled and tuned ANN and DBN to classify and predict tool-wear and end-of-tool-life based on force and vibration data

### **University of Toronto**

October 2018 - December 2018

Autonomous Navigation and Obstacle Avoidance Robot

- Developed a pattern matching based depth first search (DFS) algorithm for self-localization of robot
- Enabled autonomous navigation through a pre-defined maze using OOP in C++ implemented on an Arduino Mega
- Optimized control parameters for PID control on a self-designed robot with custom assembly to enable obstacle avoidance

### **TECHNICAL SKILLS**

**Programming Languages:** C/C++, Python, Bash

**Distributed Computing:** Hadoop, Disco, CUDA, OpenMP

Data Streaming: Elasticsearch, Kafka, Logstash, Filebeat Databases: BigQuery, PostgreSQL, MariaDB

Microservices and Cloud computing: Kubernetes, Docker

TensorFlow. Keras Machine learning:

#### **PUBLICATIONS**

Bagri, S., Manwar, A., Varghese, A., Mujumdar, S., & Joshi, S. S., "Tool wear and remaining useful life prediction in micro-milling along complex tool paths using neural networks", Journal of Manufacturing Processes, 71, 2021, 679-698