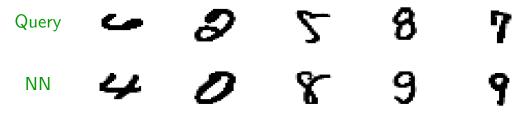
Improving the performance of nearest neighbor

Recall: nearest neighbor on MNIST

- Images of handwritten digits, represented as vectors in \mathbb{R}^{784} .
- Labels 0 − 9
- Training set: 60,000 points; test set: 10,000 points

Test error of nearest neighbor using Euclidean distance: 3.09%

Examples of errors:



Ideas for improvement: (1) k-NN (2) better distance function.

K-nearest neighbor classification

To classify a new point:

- Find the k nearest neighbors in the training set.
- Return the most common label amongst them.

In real life, there's no test set. How to decide which *k* is best?

Cross-validation

How to estimate the error of k-NN for a particular k?

10-fold cross-validation

- Divide the training set into 10 equal pieces. Training set (call it S): 60,000 points Call the pieces S_1, S_2, \ldots, S_{10} : 6,000 points each.
- For each piece S_i :
 - Classify each point in S_i using k-NN with training set $S S_i$
 - Let ϵ_i = fraction of S_i that is incorrectly classified
- Take the average of these 10 numbers:

estimated error with
$$k$$
-NN $= \frac{\epsilon_1 + \cdots + \epsilon_{10}}{10}$

Another improvement: better distance functions

The Euclidean (ℓ_2) distance between these two images is very high!



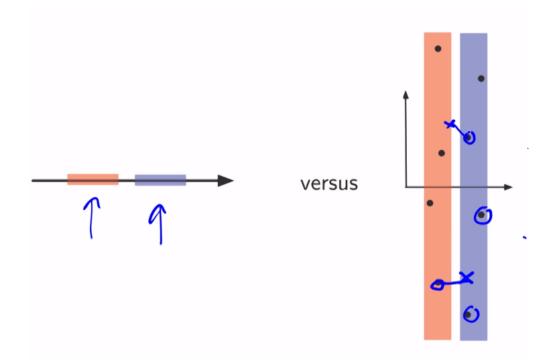
Much better idea: distance measures that are invariant under:

- Small translations and rotations. e.g. tangent distance.
- A broader family of natural deformations. e.g. shape context.

Test error rates: $\frac{\ell_2}{3.09}$ tangent distance shape context 0.63

Related problem: feature selection

Feature selection/reweighting is part of picking a distance function. And, one noisy feature can wreak havoc with nearest neighbor!



Algorithmic issue: speeding up NN search

Naive search takes time O(n) for training set of size n: slow!

Luckily there are data structures for speeding up nearest neighbor search, like:

- 1 Locality sensitive hashing
- 2 Ball trees
- **3** *K*-d trees

These are part of standard Python libraries for NN, and help a lot.