5CS037 Concepts and Technologies of Al Workshop -1 Numpy For Matrix Manipulation.

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1. Numpy: Introduction.

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- ► The NumPy(Numeric Python) package provides basic routines for manipulating large arrays and matrices of numeric data.
- ► The SciPy(Scientific python) package extends the functionality of NumPy with a substantial collection of useful algorithms.

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Numpy Arrays: Introduction

- ➤ The Central feature of Numpy is the array object class. Arrays are similar to lists in Python, except that every element of an array must be of the same dtype.
- Arrays make operations with large amounts of numeric data very fast and are generally more efficient than lists.
- Example (Importing Numpy and Creating Arrays of Zeros):

```
import numpy as np
# initialize an all zero array with size 2 X 3:
zeros_arr = np.zeros((2,3))
print(" A zeros array is \n", zeros_arr, "with dimensions", zeros_arr.shape, "\n")
```

Task Set -I: Creating an Array.

- Based on above example. Complete the following tasks:
 - 1. Initialize an empty array with size 2X2.
 - 2. Initialize an all one array with size 4X2.
 - Return a new array of given shape and type, filled with fill_value.{Hint: np.full}
 - 4. Return a new array of zeros with same shape and type as a given array. {Hint: np.zeros_like}
 - Return a new array of ones with same shape and type as a given array. {Hint: np.ones_like}
 - 6. For an existing list new_list = [1,2,3,4] convert to an numpy array.{Hint: np.array()}

Array Manipulation: Numerical Ranges

Observe the output of following code:

```
import numpy as np
     range_arr = np.arange(10)
     print("An array given range is \n", range_arr,
      "with dimensions", range_arr.shape, "\n")
4 # return evenly spaced values within a given
     interval.
     linspace_arr = np.linspace(2.0, 3.0, num = 5,
5
     endpoint=false)
    print("An evenly spaced array given range is \
     n", linspace_arr, "with dimensions", linspace_arr
     . shape, "\n")
7 # return evenly spaced numbers over a specified
     interval.
```

Task Set-II: Array Manipulation

- ► Numerical Ranges and Array Indexing:
 - 1. Create an array with values ranging from 10 to 49. {Hint:np.arrange()}.
 - Create a 3X3 matrix with values ranging from 0 to 8.
 {Hint:look for np.reshape()}
 - 3. Create a 3X3 identity matrix.{Hint:np.eye()}
 - 4. Create a random array of size 30 and find the mean of the array.

```
{Hint:check for np.random.random() and array.mean() function}
```

- Create a 10X10 array with random values and find the minimum and maximum values.
- 6. Create a zero array of size 10 and replace 5^{th} element with 1.
- 7. Reverse an array arr = [1,2,0,0,4,0].
- 8. Create a 2d array with 1 on border and 0 inside.
- 9. Create a 8X8 matrix and fill it with a checkerboard pattern.

Task Set-III: Array Arithmetic

► For the following arrays:

```
x = np.array([[1,2],[3,5]]) and
y = np.array([[5,6],[7,8]]);
v = np.array([9,10]) and w = np.array([11,12]);
Perform following with numpy:
```

- 1. Add the two array.
- 2. Subtract the two array.
- 3. Multiply the array with any integers of your choice.
- 4. Find the square of each element of the array.
- 5. Find the dot product between: v(and)w; x(and)v; x(and)y.
- Concatenate x(and)y along row and Concatenate v(and)w along column.
 - {Hint:try np.concatenate() or np.vstack() functions.
- 7. Concatenate x(and)v; if you get an error, observe and explain why did you get the error?

Task Set-IV: Vector Arithmetic

Euclidean Norm of a Vector u is given by:

$$\|\mathbf{u}\| = \sqrt{u_1^2 + u_2^2 + \ldots + u_n^2}$$

Angle Between Two Vectors u and v is given by:

$$cos\theta = \frac{u.v}{\|\mathbf{u}\|.\|\mathbf{v}\|}$$
$$\theta = arccos(\frac{u.v}{\|\mathbf{u}\|\|\mathbf{v}\|})$$

Based on the above equation complete the code blocks in next slide:

Complete the codes

```
def euclidean_norm(vector):
1
      "Arguments:
2
      A function which calculates norm of any given
3
      vector.
      inputs: vector: an 1D array
4
      output: norm of a vector(a scalar)
5
6
          import math
7
8
          norm_vector = # write your code here
9
          return norm vector
10
      import numpy as np
      arr = [0.5, -1.2, 3.3, 4.5]
11
      norm_arr = euclidean_norm(arr)
12
      print("The norm of an arr \n", norm_arr "\n")
13
```

Complete the codes

```
def anglebetweenvectors(vector1, vector2):
1
           "Arguments:
2
           This function calculates the angle between two
3
       vector.
           inputs:
4
           vector1: an 1D ndarray (numpy array).
5
          vector2: an 1D ndarray (numpy array).
6
          outputs:
7
           angle: angle between two vectors (a scalar)
9
           angle = # your code here.
10
           return angle
11
      import numpy as np
12
      arr1 = [0,1]
13
      arr2 = [1,0]
14
      angle = anglebetweenvectors(arr1, arr2)
15
      print("The angle is\n", angle "\n")
16
```

2. Matrix Arithmetic with Numpy

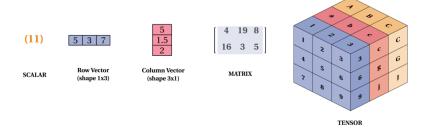


Figure: Matrix Form Representations

Matrix Additions and Multiplications

Recreate the operations shown in the image.

$$X = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad Y = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$
$$X + Y = \begin{bmatrix} \frac{1+2}{0+1} & \frac{0+1}{1+2} \end{bmatrix} = \begin{bmatrix} \frac{3}{1} & 1 \\ 1 & 3 \end{bmatrix}$$

Figure: Matrix Addition

$$X = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad Y = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$
$$X \circ Y = \begin{bmatrix} \frac{(1)2}{(0)1} & \frac{(0)1}{(1)2} \end{bmatrix} = \begin{bmatrix} \frac{2}{0} & 0 \\ 0 & 2 \end{bmatrix}$$

Figure: Matrix Multiplication (Perform both Hadamard and Regular Multiplication)

Task Set-V: Matrix Operations

For the following arrays:

```
A = np.array([[3,4],[7,8]]) and
```

B = np.array([[5,3],[2,1]]);

Prove following with Numpy:

- 1. Prove $A.A^{-1} = I$.
- 2. Prove $AB \neq BA$.
- 3. Prove $(AB)^T = B^T A^T$.

Task Set-VI: Solve System of Linear Equations

Solve the following system of Linear equation using Inverse Methods.

$$2x - 3y + z = -1$$
$$x - y + 2z = -3$$
$$3x + y - z = 9$$

{Hint: First use Numpy array to represent the equation in Matrix form. Then Solve for: AX = B}

► Now: solve the above equation using np.linalg.inv function.{Explore more about "linalg" function of Numpy}