

Artificial Intelligence Lab Report



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Program 1 - Tic Tac toe

Algorithm

* Implement TIC TAC TOE Game

→ Pseudocode

function minimax (Node, depth, isMaximizingPlayer)
 if node is a terminal state
 return evaluate (node)

if isMaximizingPlayer :

 bestvalue = -infinity

 for each child in node :

 value = minimax (child, depth+1, false)

 bestvalue = max (bestvalue, value)

 return bestvalue

else :

 bestvalue = +infinity

 for each child in node :

 value = minimax (child, depth+1, true)

 bestvalue = min (bestvalue, value)

 return bestvalue

10/4/24

Code

```

import random
class TicTacToe:
    def __init__(self):
        self.board = []
        def create_board(self):
            for i in range(3):
                row = []
                for j in range(3):
                    row.append('-')
                self.board.append(row)
        def get_random_first_player(self):
            return random.randint(0, 1)
        def fix_spot(self, row, col, player):
            self.board[row][col] = player
        def is_player_win(self, player):
            win = None
            n = len(self.board)
            for i in range(n):
                win = True
                for j in range(n):
                    if self.board[i][j] != player:
                        win = False
                        break
            if win:
                return win
            for i in range(n):
                win = True
                for j in range(n):
                    if self.board[j][i] != player:
                        win = False
                        break
            if win:
                return win
            win = True
            for i in range(n):
                if self.board[i][i] != player:
                    win = False
                    break
            if win:
                return win

```

```

        return win
    win = True
    for i in
range(n):
        if self.board[i][n - 1 - i] != player:
            win = False
            break
    if win:
        return win
    return False
    for row in self.board:
        for item in row:
            if item == '-':
                return False
    return True
def is_board_filled(self):
    for row in self.board:
        for item in row:
            if item == '-':
                return False
    return True
def swap_player_turn(self, player):
    return 'X' if player == 'O' else 'O'
def show_board(self):
    for row in self.board:

        for item in row:
            print(item, end=" ")
        print()
def start(self):
    self.create_board()
    player = 'X' if self.get_random_first_player() == 1 else 'O'
    while True:
        print(f'Player {player} turn')
        self.show_board()
        row, col = list(
            map(int, input("Enter row and column numbers to fix spot: ").split()))
        print()
        self.fix_spot(row - 1, col - 1, player)
        if self.is_player_win(player):
            print(f'Player {player} wins the game!')
            break

```

```

        if self.is_board_filled():
            print("Match Draw!")
            break
        player = self.swap_player_turn(player)
    print()
    self.show_board()
tic_tac_toe = TicTacToe()
tic_tac_toe.start()

```

Output Snapshot

```

Player 0 turn
- - -
- - -
- - -
Enter row and column numbers to fix spot: 0 3
Player X turn
- - -
- - -
- - 0
Enter row and column numbers to fix spot: 1 2
Player 0 turn
- X - - -
- - 0
Enter row and column numbers to fix spot: 3 0
Player X turn
- X -
- - -
- - 0
Enter row and column numbers to fix spot: 3 2
Player 0 turn
- X -
- - -
- X 0
Enter row and column numbers to fix spot: 2 1
Player X turn
- X -
0 - -
- X 0
Enter row and column numbers to fix spot: 2 2
Player X wins the game!

```

Program 2 - 8 Puzzle

Algorithm

* Solution to 8-Puzzle Problem.

→ BFS:-

Algorithm

Let fringe be a list containing the initial state

Loop

if fringe is empty return failure

Node ← remove-first (fringe)

if Node is a goal

then return the path from initial state to node, and add

generated nodes to the fringe

End Loop.

→ DFS :

Algorithm

Let fringe be a list containing the initial state

Loop

if fringe is empty return failure

node ← remove-first (fringe)

if Node is a goal

then return the path from

initial state to Node

else generate all successors.

State space tree ?

Code

```

import sys
import numpy as np
class Node:
    def __init__(self, state, parent, action):
        self.state = state
        self.parent = parent
        self.action = action

class StackFrontier:
    def __init__(self):
        self.frontier = []
    def add(self, node):
        self.frontier.append(node)
    def contains_state(self, state):
        return any((node.state[0] == state[0]).all() for node in self.frontier)
    def empty(self):
        return len(self.frontier) == 0
    def remove(self):
        if self.empty():
            raise Exception("Empty Frontier")
        else:
            node = self.frontier[-1]
            self.frontier = self.frontier[:-1]
            return node

class QueueFrontier(StackFrontier):
    def remove(self):
        if self.empty():
            raise Exception("Empty Frontier")
        else:
            node = self.frontier[0]
            self.frontier = self.frontier[1:]
            return node

class Puzzle:
    def __init__(self, start, startIndex, goal, goalIndex):
        self.start = [start, startIndex]
        self.goal = [goal, goalIndex]
        self.solution = None

    def neighbors(self, state):
        mat, (row, col) = state

```



```

results = []
if row > 0:
    mat1 = np.copy(mat)
    mat1[row][col] = mat1[row - 1][col]
    mat1[row - 1][col] = 0
    results.append(('up', [mat1, (row - 1, col)]))
if col > 0:
    mat1 = np.copy(mat)
    mat1[row][col] = mat1[row][col - 1]
    mat1[row][col - 1] = 0
    results.append(('left', [mat1, (row, col - 1)]))
if row < 2:
    mat1 = np.copy(mat)
    mat1[row][col] = mat1[row + 1][col]
    mat1[row + 1][col] = 0
    results.append(('down', [mat1, (row + 1, col)]))
if col < 2:
    mat1 = np.copy(mat)
    mat1[row][col] = mat1[row][col + 1]
    mat1[row][col + 1] = 0
    results.append(('right', [mat1, (row, col + 1)]))
return results

def print(self):
    solution = self.solution if self.solution is not None else None

    print("Start State:\n", self.start[0], "\n")
    print("Goal State:\n", self.goal[0], "\n")
    print("\nStates Explored: ", self.num_explored, "\n")
    print("Solution:\n ")
    for action, cell in zip(solution[0], solution[1]):
        print("action: ", action, "\n", cell[0], "\n")
    print("Goal Reached!!")

def does_not_contain_state(self, state):
    for st in self.explored:
        if (st[0] == state[0]).all():
            return False
    return True

def solve(self):
    self.num_explored = 0
    start = Node(state=self.start, parent=None, action=None)

```

```

frontier = QueueFrontier()
frontier.add(start)
self.explored = []
while True:
    if frontier.empty():
        raise Exception("No solution")
    node = frontier.remove()
    self.num_explored += 1
    if (node.state[0] == self.goal[0]).all():
        actions = []
        cells = []
        while node.parent is not None:
            actions.append(node.action)
            cells.append(node.state)
            node = node.parent
        actions.reverse()
        cells.reverse()
        self.solution = (actions, cells)
        return
    self.explored.append(node.state)
    for action, state in self.neighbors(node.state):
        if not frontier.contains_state(state) and self.does_not_contain_state(state): child =
            Node(state=state, parent=node, action=action)
            frontier.add(child)

start = np.array([[1, 2, 3], [8, 0, 4], [7, 6, 5]])

goal = np.array([[2, 8, 1], [0, 4, 3], [7, 6, 5]])
startIndex = (1, 1)
goalIndex = (1, 0)
p = Puzzle(start, startIndex, goal, goalIndex)
p.solve() p.print()

```


Program 03 - A* Algorithm

25/10

Lab-03

* A* Algorithm

function A* Search (problem) returns a solution
or failure

node \leftarrow a node n with n state:
problem.initial state.

frontier \leftarrow a priority queue ordered
by ascending g th & only elements

Loop do

if empty > (frontier) then return
failure.

$n \leftarrow \text{pop}(\text{frontier})$

if problem.goalTest (n .state) then
return solution

for each action a in problem
actions (n .state) do

$n' \leftarrow \text{childNode}(\text{problem}, n, a)$
insert (n' , $g(n') + h(n')$,
frontier)

Code

```

def print_b(src):
    state = src.copy()
    state[state.index(-1)] = ''
    print(
f"""
{state[0]} {state[1]} {state[2]}
{state[3]} {state[4]} {state[5]}
{state[6]} {state[7]} {state[8]}
"""
    )
def h(state, target):
    count = 0
    i = 0
    for j in state:
        if state[i] != target[i]:
            count = count+1
    return count
def astar(state, target):
    states = [src]
    g = 0
    visited_states = []
    while len(states):
        print(f"Level: {g}")
        moves = []
        for state in states:
            visited_states.append(state)
            print_b(state)
            if state == target:
                print("Success")
                return
            moves += [move for move in possible_moves(
                state, visited_states) if move not in moves]
            costs = [g + h(move, target) for move in moves]
            states = [moves[i]
                for i in range(len(moves)) if costs[i] == min(costs)]
            g += 1
        print("Fail")
def possible_moves(state, visited_state):

```

```

b = state.index(-1)
d = []
if b - 3 in range(9):
    d.append('u')
if b not in [0, 3, 6]:
    d.append('l')
if b not in [2, 5, 8]:
    d.append('r')
if b + 3 in range(9):
    d.append('d')
pos_moves = []
for m in d:
    pos_moves.append(gen(state, m, b))
return [move for move in pos_moves if move not in visited_state]
def gen(state, m, b):
    temp = state.copy()
    if m == 'u':
        temp[b - 3], temp[b] = temp[b], temp[b - 3]
    if m == 'l':
        temp[b - 1], temp[b] = temp[b], temp[b - 1]
    if m == 'r':
        temp[b + 1], temp[b] = temp[b], temp[b + 1]
    if m == 'd':
        temp[b + 3], temp[b] = temp[b], temp[b + 3]
    return temp
src = [1, 2, 3, -1, 4, 5, 6, 7, 8]
target = [1, 2, 3, 4, 5, 6, 7, 8, -1]
astar(src, target)

```

Output Snapshot

Enter the start state matrix

```

1 0 1 0
1 0 0 1
1 1 1 1

```

Enter the goal state matrix

```

1 1 0 1
1 0 0 1
1 1 1 0

```

```

|
|
\ '/'

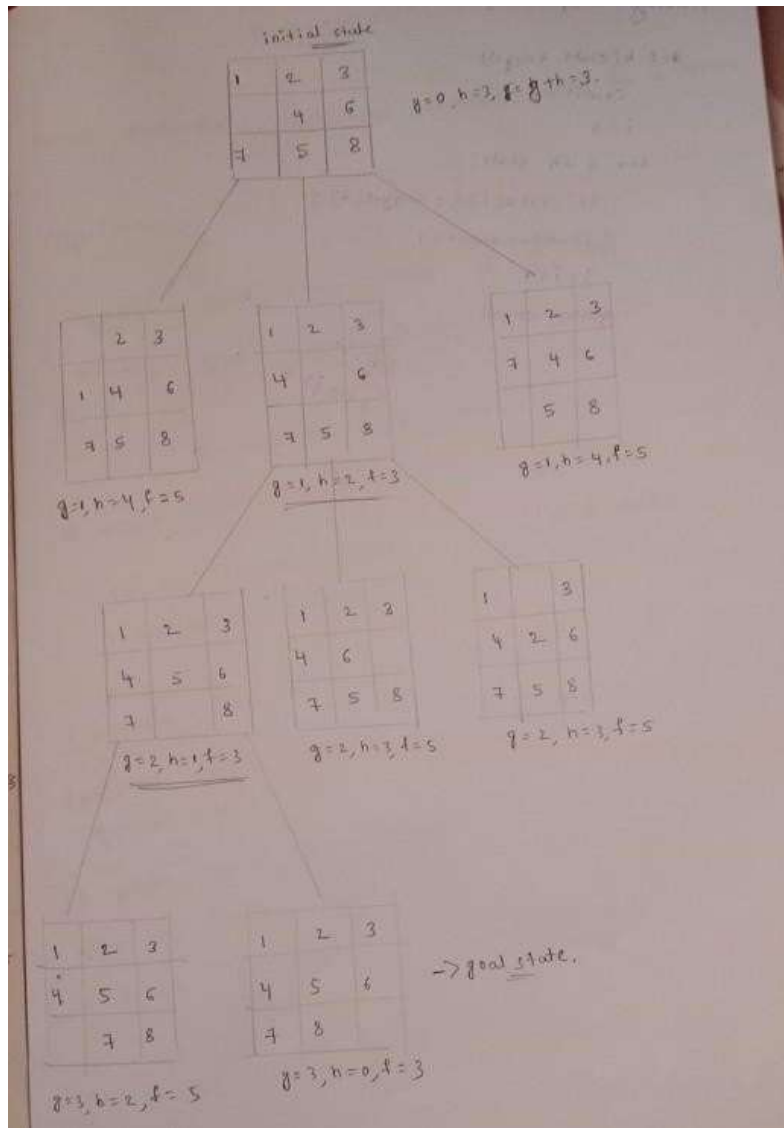
```

```

1 0 1 0
1 0 0 1
1 1 1 1

```

State Space Tree



Program 4 - Vacuum Cleaner

Algorithm

18/10

* Implementing Vacuum cleaner agent

Algorithm:

1. Initialize the agent's starting (A,B)
2. Loop untill all cells are clean:
 - a. Perceive the current cell
 - b. If the cell is dirty
 - i. clean the current cell
 - c. else:
 - i. check surrounding to check if they are dirty.
 - ii. move to the next dirty cell
 - iii. If no dirty cells are perceiving
3. End

Stop

18/10

Code

```

def vacuum_world():

    goal_state = {'A': '0', 'B': '0'}
    cost = 0

    location_input = input("Enter Location of Vacuum: ")
    status_input = input("Enter status of " + location_input + " : ")
    status_input_complement = input("Enter status of other room : ")
    print("Initial Location Condition {A : " + str(status_input_complement) + ", B : " +
    str(status_input) + " }" )

    if location_input == 'A':
        print("Vacuum is placed in Location A")
        if status_input == '1':
            print("Location A is Dirty.")
            goal_state['A'] = '0'

            cost += 1 #cost for suck
            print("Cost for CLEANING A " + str(cost))
            print("Location A has been Cleaned.")

            if status_input_complement == '1':
                print("Location B is Dirty.")
                print("Moving right to the Location B. ")
                cost += 1
                print("COST for moving RIGHT " + str(cost))
                goal_state['B'] = '0'
                cost += 1
                print("COST for SUCK " + str(cost))
                print("Location B has been Cleaned. ")
            else:
                print("No action" + str(cost))
                print("Location B is already clean.")

        if status_input == '0':
            print("Location A is already clean ")
            if status_input_complement == '1':
                print("Location B is Dirty.")
                print("Moving RIGHT to the Location B. ")
                cost += 1
                print("COST for moving RIGHT " + str(cost))

```

```

    goal_state['B'] = '0'
    cost += 1
    print("Cost for SUCK" + str(cost))
    print("Location B has been Cleaned. ")
else:
    print("No action " + str(cost))
    print(cost)
    print("Location B is already clean.")

else:
    print("Vacuum is placed in location B")
    if status_input == '1':
        print("Location B is Dirty.")
        goal_state['B'] = '0'
        cost += 1
        print("COST for CLEANING " + str(cost))

    print("Location B has been Cleaned.")

    if status_input_complement == '1':
        print("Location A is Dirty.")
        print("Moving LEFT to the Location A. ")
        cost += 1
        print("COST for moving LEFT " + str(cost))
        goal_state['A'] = '0'
        cost += 1
        print("COST for SUCK " + str(cost))
        print("Location A has been Cleaned.")

    else:
        print(cost)
        print("Location B is already clean.")

    if status_input_complement == '1':
        print("Location A is Dirty.")
        print("Moving LEFT to the Location A. ")
        cost += 1
        print("COST for moving LEFT " + str(cost))
        goal_state['A'] = '0'
        cost += 1
        print("Cost for SUCK " + str(cost))
        print("Location A has been Cleaned. ")

```

else:

print("No action " + str(cost))

print("Location A is already clean.")

print("GOAL STATE: ")

print(goal_state)

print("Performance Measurement: " + str(cost))

vacuum_world()

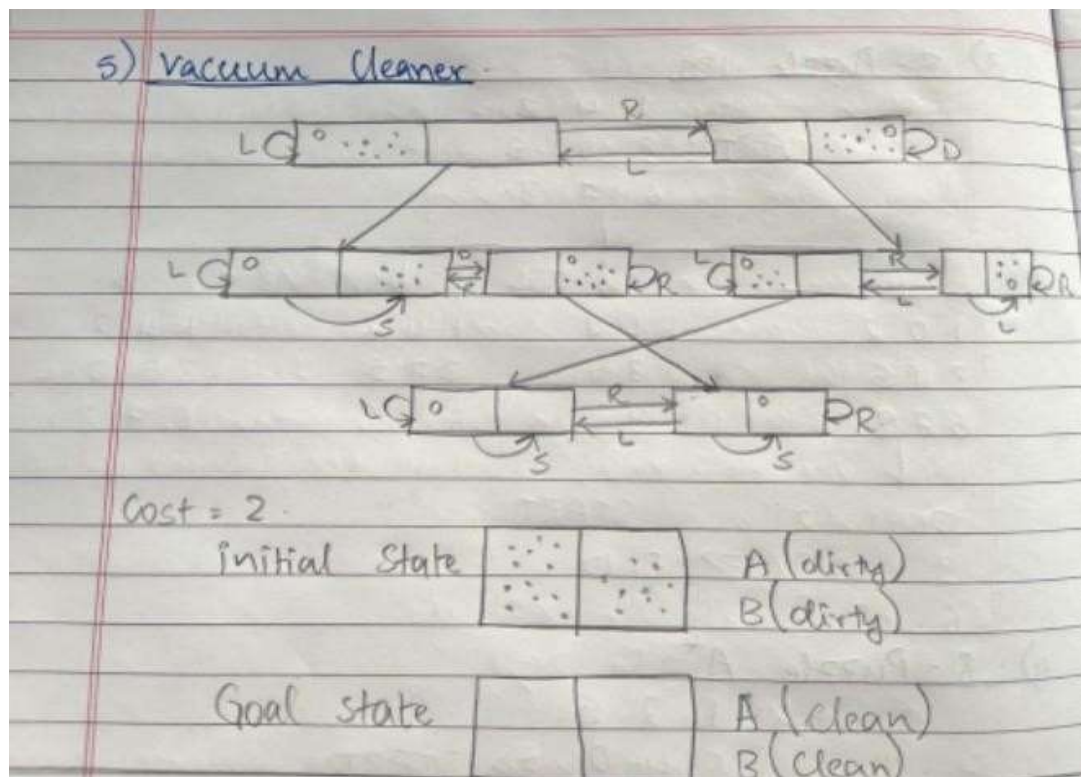
Output Snapshot

```

Enter Location of Vacuum: A
Enter status of A : 0
Enter status of other room : 1
Initial Location Condition {A : 1, B : 0 }
Vacuum is placed in Location A
Location A is already clean
Location B is Dirty.
Moving RIGHT to the Location B.
COST for moving RIGHT 1
Cost for SUCK2
Location B has been Cleaned.
GOAL STATE:
{'A': '0', 'B': '0'}
Performance Measurement: 2

```

State Space Tree



Program-05 Hill Climbing

Algorithm

8/11

Lab-4

Implement Hill climbing search algorithm to solve N-Queens problem.

function HILL-CLIMBING(problem) returns a state that is a local maximum.

current \leftarrow Make-Node(problem.INITIAL-STATE)

Loop do

neighbor \leftarrow a highest-valued successor of current

if neighbor.VALUE \leq current.VALUE then return current.STATE

Execute current \leftarrow neighbor.

Implement:

		9	
9			
			9
	9		

\leftarrow Goal.

state	score.
3120	2
1320	1
1230	1
1203	1

Code

```

import random

class NQueensHillClimbing:
    def __init__(self, N):
        self.N = N

    def calculate_heuristic(self, board):
        """Calculate the number of attacking pairs of queens."""
        attacks = 0
        for i in range(self.N):
            for j in range(i + 1, self.N):
                if board[i] == board[j] or abs(board[i] - board[j]) == abs(i - j):
                    attacks += 1
        return attacks

    def get_neighbors(self, board):
        """Generate all possible neighbors by moving each queen to a new row."""
        neighbors = []
        for col in range(self.N):
            for row in range(self.N):
                if board[col] != row:
                    new_board = board[:]
                    new_board[col] = row
                    neighbors.append(new_board)
        return neighbors

    def hill_climbing(self, initial_board):
        """Perform the hill climbing algorithm to solve the N-Queens problem."""
        current_board = initial_board
        current_heuristic = self.calculate_heuristic(current_board)

        while True:
            neighbors = self.get_neighbors(current_board)
            neighbors_heuristics = [self.calculate_heuristic(neighbor) for neighbor in neighbors]
            min_heuristic = min(neighbors_heuristics)

            # If the heuristic cannot be improved, stop
            if min_heuristic >= current_heuristic:
                break

```

```

    # Move to the neighbor with the best heuristic
    best_index = neighbors_heuristics.index(min_heuristic)
    current_board = neighbors[best_index]
    current_heuristic = min_heuristic

```

```

return current_board, current_heuristic

```

```

def solve(self, max_restarts=100):

```

```

    """Solve the N-Queens problem using Random Restart Hill Climbing."""

```

```

    for restart in range(max_restarts):

```

```

        # Start with a random initial state

```

```

        initial_board = [random.randint(0, self.N - 1) for _ in range(self.N)]

```

```

        solution, heuristic = self.hill_climbing(initial_board)

```

```

        if heuristic == 0:

```

```

            return solution # Found a solution

```

```

    return None # No solution found after max_restarts

```

```

# Example Usage

```

```

if __name__ == "__main__":

```

```

    N = 8 # Size of the chessboard

```

```

    n_queens = NQueensHillClimbing(N)

```

```

    solution = n_queens.solve(max_restarts=1000) # Try up to 1000 random restarts

```

```

    if solution:

```

```

        print("Solution found:")

```

```

        print(solution)

```

```

    # Display the board

```

```

    for row in range(N):

```

```

        line = ""

```

```

        for col in range(N):

```

```

            if solution[col] == row:

```

```

                line += "Q "

```

```

            else:

```

```

                line += ". "

```

```

        print(line)

```

```

    else:

```

```

        print("No solution found, even after random restarts.")

```

Output Snapshot

```
➤ Solution found:  
[7, 3, 0, 2, 5, 1, 6, 4]  
. . Q . . . . .  
. . . . . Q . .  
. . . Q . . . .  
. Q . . . . .  
. . . . . Q .  
. . . . Q . . .  
. . . . . Q .  
Q . . . . . .
```

Program 6: Simulated Annealing

Algorithm

LAB-5

Implement Stimulated Annealing algorithm for n-Queen problem

=>

current \leftarrow initial state

T \leftarrow a large positive value

While T > 0 do

 next \leftarrow a random neighbor of current

$\Delta E \leftarrow$ current.cost - next.cost

 if $\Delta E > 0$ then

 current \leftarrow next

 else

 current \leftarrow next with probability.

 end if

 decrease T

end while.

return current.

15/11/24

Output :-

Final Solution : [1, 3, 0, 2]

Number of conflicts : 0

Code

```

import random
import math

class NQueensSimulatedAnnealing:
    def __init__(self, N):
        self.N = N

    def calculate_heuristic(self, board):
        """Calculate the number of attacking pairs of queens."""
        attacks = 0
        for i in range(self.N):
            for j in range(i + 1, self.N):
                if board[i] == board[j] or abs(board[i] - board[j]) == abs(i - j):
                    attacks += 1
        return attacks

    def get_random_neighbor(self, board):
        """Generate a random neighbor by moving one queen to a different row."""
        neighbor = board[:]
        col = random.randint(0, self.N - 1) # Pick a random column
        row = random.randint(0, self.N - 1) # Pick a random row
        while neighbor[col] == row:
            row = random.randint(0, self.N - 1) # Ensure the new row is different
        neighbor[col] = row
        return neighbor

    def simulated_annealing(self, initial_board, max_steps=1000, initial_temp=100, cooling_rate=0.99):
        """Solve the N-Queens problem using Simulated Annealing."""
        current_board = initial_board
        current_heuristic = self.calculate_heuristic(current_board)
        temperature = initial_temp

        for step in range(max_steps):
            if current_heuristic == 0:
                return current_board # Solution found

            # Generate a random neighbor
            neighbor = self.get_random_neighbor(current_board)
            neighbor_heuristic = self.calculate_heuristic(neighbor)

            # Calculate the change in heuristic
            delta_heuristic = neighbor_heuristic - current_heuristic

            # Decide whether to accept the neighbor
            if delta_heuristic < 0 or random.uniform(0, 1) < math.exp(-delta_heuristic / temperature):
                current_board = neighbor
                current_heuristic = neighbor_heuristic

            # Cool down the temperature
            temperature *= cooling_rate

```

```
return None # No solution found within the maximum steps
```

```
def solve(self):
```

```
    """Solve the N-Queens problem using Simulated Annealing."""
```

```
    initial_board = [random.randint(0, self.N - 1) for _ in range(self.N)] # Random initial state
```

```
    return self.simulated_annealing(initial_board)
```

```
# Example Usage
```

```
if __name__ == "__main__":
```

```
    N = 8 # Size of the chessboard
```

```
    n_queens = NQueensSimulatedAnnealing(N)
```

```
    solution = n_queens.solve()
```

```
    if solution:
```

```
        print("Solution found:")
```

```
        print(solution)
```

```
    # Display the board
```

```
    for row in range(N):
```

```
        line = ""
```

```
        for col in range(N):
```

```
            if solution[col] == row:
```

```
                line += "Q "
```

```
            else:
```

```
                line += ". "
```

```
        print(line)
```

```
    else:
```

```
        print("No solution found.")
```

```
if ans:
```

```
    print("Knowledge Base entails query")
```

```
else:
```

```
    print("Knowledge Base does not entail query")
```

OUTPUT

```
Solution found:  
[2, 5, 1, 6, 0, 3, 7, 4]  
. . . . Q . . . .  
. . Q . . . . .  
Q . . . . . . .  
. . . . . Q . . .  
. . . . . . Q  
. Q . . . . . .  
. . . Q . . . . .  
. . . . . Q .
```

Program-07- Unification in FOL

Algorithm

22/11

UNIFICATION ALGORITHM

=> Step 1: If ψ_1 or ψ_2 is a variable or constant

a) If ψ_1 or ψ_2 are identical, return Nil

b) Else if ψ_2 is a variable,

a. then if ψ_2 occurs in ψ_1 , then
return failure

b. Else return $\{\psi_2/\psi_1\}$

c) Else if ψ_1 is a variable,

a) If ψ_1 occurs in ψ_2 then return
Failure.

b) Else return $\{\psi_1/\psi_2\}$

d) Else return Failure.

Step 2: If the initial Predicate symbol in
 ψ_1 & ψ_2 are not same, then return
failure.

Step 3: If ψ_1 & ψ_2 have a different
number of arguments,
return failure.

Step 4: Set Substitution set (SUBST) to Nil

Step 5: For $i = 1$ to the number of elements

a) Call Unify function with the i th
element of ψ_1 & i th element of ψ_2

b) If $S = \text{failure}$ then return failure.

c) If $S \neq \text{Nil}$ then do.

Code

```

def is_variable(term):
    """Check if a term is a variable."""
    return isinstance(term, str) and term.islower()

def is_constant(term):
    """Check if a term is a constant."""
    return isinstance(term, str) and term.isupper()

def unify(term1, term2, subst=None):
    """
    Unify two terms.
    Args:
        term1: The first term (variable, constant, or function).
        term2: The second term (variable, constant, or function).
        subst: Current set of substitutions (dictionary).
    Returns:
        A substitution dictionary if unification is successful, otherwise None.
    """
    if subst is None:
        subst = {}

    if term1 == term2: # If terms are identical
        return subst

    if is_variable(term1): # If term1 is a variable
        return unify_variable(term1, term2, subst)

    if is_variable(term2): # If term2 is a variable
        return unify_variable(term2, term1, subst)

    if isinstance(term1, tuple) and isinstance(term2, tuple):
        # If terms are functions, unify their name and arguments
        if term1[0] != term2[0] or len(term1[1]) != len(term2[1]):
            return None # Function names or argument lengths differ
        for arg1, arg2 in zip(term1[1], term2[1]):
            subst = unify(arg1, arg2, subst)
            if subst is None:
                return None
        return subst

    return None # Terms cannot be unified

def unify_variable(var, term, subst):
    """
    Unify a variable with a term.
    Args:

```

var: The variable (string).

term: The term to unify with (variable, constant, or function).

subst: Current set of substitutions (dictionary).

Returns:

Updated substitution dictionary or None.

"""

if var in subst: # Variable already substituted

return unify(subst[var], term, subst)

if occurs_check(var, term, subst): # Prevent infinite loops

return None

subst[var] = term

return subst

def occurs_check(var, term, subst):

"""

Check if a variable occurs in a term (to prevent infinite loops).

Args:

var: The variable (string).

term: The term to check against.

subst: Current set of substitutions (dictionary).

Returns:

True if var occurs in term, False otherwise.

"""

if var == term:

return True

if isinstance(term, tuple): # If term is a function, check its arguments

return any(occurs_check(var, arg, subst) for arg in term[1])

if var in subst and occurs_check(var, subst[var], subst):

return True

return False

def apply_substitution(term, subst):

"""

Apply a substitution to a term.

Args:

term: The term to substitute (variable, constant, or function).

subst: The substitution dictionary.

Returns:

The term after applying the substitution.

"""

if is_variable(term) and term in subst:

return apply_substitution(subst[term], subst)

if isinstance(term, tuple): # If the term is a function, apply substitution to its arguments

return (term[0], [apply_substitution(arg, subst) for arg in term[1]])

return term # Return the term as-is for constants or unbound variables

Example Usage

```

if __name__ == "__main__":
    # Example terms:
    term1 = ("f", ["x", "y"]) # f(x, y)
    term2 = ("f", ["a", "b"]) # f(a, b)

    # Perform unification
    result = unify(term1, term2)
    if result:
        print("Unification successful! Substitution:")
        print(result)

        # Apply substitution to the original terms
        term1_substituted = apply_substitution(term1, result)
        term2_substituted = apply_substitution(term2, result)

        print("\nTerms after substitution:")
        print(f"Term 1: {term1_substituted}")
        print(f"Term 2: {term2_substituted}")
    else:
        print("Unification failed.")
else:
    print("Knowledge Base doesn't entail the query, no empty set produced after resolution")
    clauses = input('Enter the clauses ').split()
    query = input('Enter the query: ')
    checkResolution(clauses, query)

```

Output Snapshot

```

Unification successful! Substitution:
{'x': 'a', 'y': 'b'}

Terms after substitution:
Term 1: ('f', ['a', 'b'])
Term 2: ('f', ['a', 'b'])

```

Program-08 Forward Reasoning

Algorithm

LAB-8

Forward Reasoning Algorithm

⇒

function FOL-FC-ASK (KB, α) returns false
 inputs: KB, the knowledge base, a set of fo
 α , the query, an atomic sentence
 local variable: new, the new sentences

repeat until new is empty

new $\leftarrow \{\}$

for each rule in KB do

for each θ such that SUBST

for some p_1, \dots, p_n in KB

$q' \leftarrow \text{SUBST}(\theta, q)$

if q' does not unify with some
 sentence already in KB

add q' to new

$\phi \leftarrow \text{UNIFY}(q', \alpha)$

if ϕ is not fail then return

add new to KB

return false.

Code

```

def is_variable(term):
    """Check if a term is a variable."""
    return isinstance(term, str) and term.islower()

def apply_substitution(term, subst):
    """Apply a substitution to a term."""
    if is_variable(term) and term in subst:
        return apply_substitution(subst[term], subst)
    if isinstance(term, tuple): # If term is a function, apply substitution to arguments
        return (term[0], [apply_substitution(arg, subst) for arg in term[1]])
    return term # Return the term as-is for constants or unbound variables

def unify(term1, term2, subst=None):
    """Unify two terms."""
    if subst is None:
        subst = {}
    if term1 == term2:
        return subst
    if is_variable(term1):
        return unify_variable(term1, term2, subst)
    if is_variable(term2):
        return unify_variable(term2, term1, subst)
    if isinstance(term1, tuple) and isinstance(term2, tuple):
        if term1[0] != term2[0] or len(term1[1]) != len(term2[1]):
            return None
        for arg1, arg2 in zip(term1[1], term2[1]):
            subst = unify(arg1, arg2, subst)
            if subst is None:
                return None
        return subst
    return None

def unify_variable(var, term, subst):
    """Unify a variable with a term."""
    if var in subst:

```

```

    return unify(subst[var], term, subst)
if occurs_check(var, term, subst):
    return None
subst[var] = term
return subst

def occurs_check(var, term, subst):
    """Check if a variable occurs in a term."""
    if var == term:
        return True
    if isinstance(term, tuple):
        return any(occurs_check(var, arg, subst) for arg in term[1])
    if var in subst and occurs_check(var, subst[var], subst):
        return True
    return False

def forward_reasoning(kb, query):
    """
    Perform forward reasoning on the knowledge base (KB) to prove the query.
    Args:
        kb: The knowledge base, a list of first-order logic rules or facts.
        query: The goal to prove.
    Returns:
        True if the query can be proved, otherwise False.
    """
    known_facts = set()
    new_facts = True

    while new_facts:
        new_facts = False

        for rule in kb:
            if isinstance(rule, tuple) and rule[0] == "implies": # Implication rule
                conditions, conclusion = rule[1], rule[2]

                substitutions = [{}]

```

```

for condition in conditions:
    next_substitutions = []
    for fact in known_facts:
        subst = unify(condition, fact)
        if subst is not None:
            next_substitutions.append(subst)
    substitutions = [
        {**s1, **s2} for s1 in substitutions for s2 in next_substitutions
    ]

    for subst in substitutions:
        derived_fact = apply_substitution(conclusion, subst)
        if derived_fact not in known_facts:
            known_facts.add(derived_fact)
            new_facts = True

    else: # It's a fact
        if rule not in known_facts:
            known_facts.add(rule)
            new_facts = True

# Check if the query is in the known facts
for fact in known_facts:
    if unify(fact, query) is not None:
        return True

return False

# Example Usage
if __name__ == "__main__":
    # Knowledge Base
    kb = [
        ("implies", [("human", ["x"]], ("mortal", ["x"])), # human(x) -> mortal(x)
        ("human", ["socrates"]), # human(socrates)
    ]

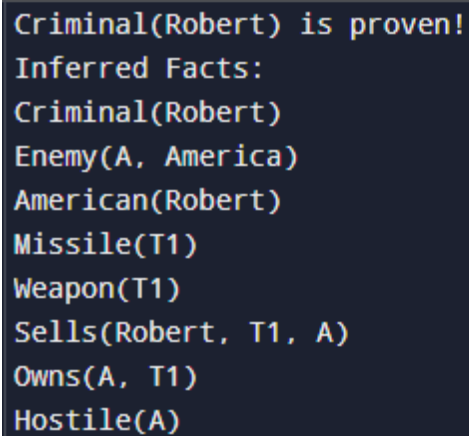
```

```
# Query
query = ("mortal", ["socrates"]) # Is Socrates mortal?

# Perform forward reasoning
result = forward_reasoning(kb, query)

if result:
    print(f"The query {query} is true based on the knowledge base.")
else:
    print(f"The query {query} cannot be proved from the knowledge base.")
```

Output Snapshot



```
Criminal(Robert) is proven!
Inferred Facts:
Criminal(Robert)
Enemy(A, America)
American(Robert)
Missile(T1)
Weapon(T1)
Sells(Robert, T1, A)
Owns(A, T1)
Hostile(A)
```

Program 09: Resolution

Algorithm

* query using resolution.

→ function: resolution (KB, query): return query
if true or false.

input: KB, the Knowledge base, set of
propositional

query: 0 to 1 to proven.

Classes = convert to CNF (KB

negated query = negate (query)

new-classes = set().

apply the resolution rules.

- Select the class containing complementary class.

- resolve the two to form
or new clause.

- add the new-classes is
empty().

contradiction is found.

if new = {} print "query if true"
else print 'false'

Output:

KB PRG

TOR

TPVS

RVTS

TS

Resolution.

TR

TOR

TO

PRG

TARS

P

S

A-9

Code:

```

from sympy.logic.boolalg import Or, And, Not, Implies
from sympy import symbols

def knowledge_base_resolution():
    """
    Demonstrate resolution-based proof in propositional logic.
    """
    # Step 1: Define symbols
    P, Q, R = symbols('P Q R')

    # Step 2: Define the Knowledge Base (KB)
    kb = And(
        Implies(P, Q), # If P, then Q
        Implies(Q, R), # If Q, then R
        P               # P is true
    )

    # Step 3: Define the query
    query = R

    # Step 4: Negate the query and add it to the KB
    kb_with_negated_query = And(kb, Not(query))

    # Step 5: Convert KB to Conjunctive Normal Form (CNF)
    from sympy.logic.boolalg import to_cnf
    kb_cnf = to_cnf(kb_with_negated_query, simplify=True)

    print("Knowledge Base in CNF:", kb_cnf)

    # Step 6: Apply Resolution
    # Note: Implementing resolution directly requires symbolic manipulation of CNF clauses.
    # For simplicity, we demonstrate by showing the result from the CNF.

    # Check satisfiability
    from sympy.logic.inference import satisfiable
    result = satisfiable(kb_cnf, all_models=False)

    if result:
        print("The query is NOT proved (no contradiction found).")
        print("Satisfying assignment:", result)
    else:
        print("The query is proved (contradiction found).")

# Example usage
if __name__ == "__main__":
    knowledge_base_resolution()

```

OUTPUT SNAPSHOT:

Knowledge Base in CNF: False
The query is proved (contradiction found).

Program 10: FOL to CNF

Algorithm:

* Convert a given FOL to CNF.

Function FOL to CNF.

Eliminate: implication and
biconditional.

$$A \rightarrow B : \neg A \vee B$$

$$A \leftrightarrow B : (\neg A \vee B) \wedge (A \vee \neg B)$$

- Move negation Inward (If any)
- Standardize variable with unique variable name.
- Eliminate existential & universal quantifiers.
- Distribute \vee over \wedge .
- Simplify the result.

Output

$$\forall x (\exists y (P(x, y) \rightarrow Q(y)) \wedge \neg R(x))$$

- Eliminate implication:

$$\forall x (\exists y (\neg P(x, y) \vee Q(y)) \wedge \neg R(x))$$

- Eliminate existential quantifier

$$\forall x ((\neg Q(f(x)) \vee Q(g(x))) \wedge \neg R(x))$$

Drop variable quantifiers: $g = f(x)$

$$\forall x ((\neg P(x, f(x)) \vee (f(x))) \wedge \neg R(x))$$

Code:

```

from sympy.logic.boolalg import Or, And, Not, Implies, Equivalent
from sympy import symbols

def convert_to_cnf(statement):
    """
    Convert a given first-order logic statement into Conjunctive Normal Form (CNF).
    """
    from sympy.logic.boolalg import to_cnf
    return to_cnf(statement, simplify=True)

def knowledge_base_resolution():
    """
    Demonstrate resolution-based proof in propositional logic.
    """
    # Step 1: Define symbols
    P, Q, R = symbols('P Q R')

    # Step 2: Define the Knowledge Base (KB)
    kb = And(
        Implies(P, Q), # If P, then Q
        Implies(Q, R), # If Q, then R
        P               # P is true
    )

    # Step 3: Define the query
    query = R

    # Step 4: Negate the query and add it to the KB
    kb_with_negated_query = And(kb, Not(query))

    # Step 5: Convert KB to Conjunctive Normal Form (CNF)
    from sympy.logic.boolalg import to_cnf
    kb_cnf = to_cnf(kb_with_negated_query, simplify=True)

    print("Knowledge Base in CNF:", kb_cnf)

    # Step 6: Apply Resolution
    # Note: Implementing resolution directly requires symbolic manipulation of CNF clauses.
    # For simplicity, we demonstrate by showing the result from the CNF.

    # Check satisfiability
    from sympy.logic.inference import satisfiable
    result = satisfiable(kb_cnf, all_models=False)

```



```

if result:
    print("The query is NOT proved (no contradiction found).")
    print("Satisfying assignment:", result)

```

```

else:
    print("The query is proved (contradiction found).")

```

```

# Example usage for converting FOL to CNF

```

```

if __name__ == "__main__":

```

```

    # Define symbols for FOL example

```

```

    A, B, C = symbols('A B C')

```

```

    # Example FOL statement: (A -> B) AND (B -> C)

```

```

    fol_statement = And(Implies(A, B), Implies(B, C))

```

```

    # Convert to CNF

```

```

    cnf_statement = convert_to_cnf(fol_statement)

```

```

    print("Original FOL Statement:", fol_statement)

```

```

    print("Converted CNF Statement:", cnf_statement)

```

```

    # Run resolution demonstration

```

```

    knowledge_base_resolution()

```

OUTPUT SNAPSHOT:

```

Original FOL Statement: (Implies(A, B)) & (Implies(B, C))
Converted CNF Statement: (B | ~A) & (C | ~B)
Knowledge Base in CNF: False
The query is proved (contradiction found).

```

Program 11: Alpha Beta Pruning

Algorithm:

* Implement alpha-Beta pruning.

Function minimax (node, depth, alpha, beta, maximizingPlayer) is

if depth == 0 or node is a terminal node.

then

return static evaluation of node.

if Maximize player then.

maxEva = -infinity.

for each child of node do

eva = minimax (child, depth-1, alpha, beta, false)

maxEva = max (maxEva, eva).

alpha = max (alpha, maxEva).

if beta <= alpha.

break.

return maxEva.

else.

minEva = +infinity.

for each child of node do.

eva = minimax (child, depth-1, alpha, beta, true)

minEva = min (minEva, eva)

beta = min (beta, eva)

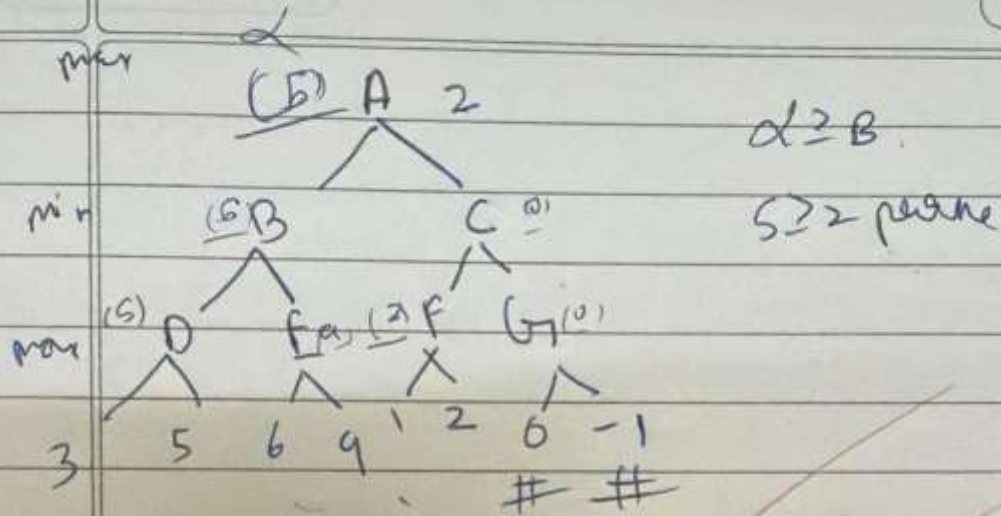
if beta <= alpha

break.

return minEva

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Code:

```
from sympy.logic.boolalg import Or, And, Not, Implies, Equivalent
from sympy import symbols
```

```
def convert_to_cnf(statement):
```

```
    """
```

```
    Convert a given first-order logic statement into Conjunctive Normal Form (CNF).
```

```
    """
```

```
    from sympy.logic.boolalg import to_cnf
```

```
    return to_cnf(statement, simplify=True)
```

```
def alpha_beta_pruning(depth, node_index, maximizing_player, values, alpha, beta):
```

```
    """
```

```
    Implement the Alpha-Beta Pruning algorithm.
```

```
    Parameters:
```

```
        depth (int): Current depth in the game tree.
```

```
        node_index (int): Index of the current node in the game tree.
```

```
        maximizing_player (bool): True if the current player is maximizing, False otherwise.
```

```
        values (list): Terminal node values (leaf nodes).
```

```
        alpha (float): Alpha value for pruning.
```

```
        beta (float): Beta value for pruning.
```

```
    Returns:
```

```
        int: The optimal value for the current player.
```

```
    """
```

```
    if depth == 0 or node_index >= len(values):
```

```
        return values[node_index]
```

```
    if maximizing_player:
```

```
        max_eval = float('-inf')
```

```
        for i in range(2): # Assume binary tree
```

```
            eval = alpha_beta_pruning(depth - 1, node_index * 2 + i, False, values, alpha, beta)
```

```
            max_eval = max(max_eval, eval)
```

```
            alpha = max(alpha, eval)
```

```
            if beta <= alpha:
```

```
                break # Beta cut-off
```

```
        return max_eval
```

```
    else:
```

```
        min_eval = float('inf')
```

```
        for i in range(2): # Assume binary tree
```

```
            eval = alpha_beta_pruning(depth - 1, node_index * 2 + i, True, values, alpha, beta)
```

```
            min_eval = min(min_eval, eval)
```

```
            beta = min(beta, eval)
```

```
            if beta <= alpha:
```

```
                break # Alpha cut-off
```

```
        return min_eval
```

```
def knowledge_base_resolution():
```

```
    """
```

```
    Demonstrate resolution-based proof in propositional logic.
```

```
"""
```

```
# Step 1: Define symbols
```

```
P, Q, R = symbols('P Q R')
```

```
# Step 2: Define the Knowledge Base (KB)
```

```
kb = And(
```

```
    Implies(P, Q), # If P, then Q
```

```
    Implies(Q, R), # If Q, then R
```

```
    P             # P is true
```

```
)
```

```
# Step 3: Define the query
```

```
query = R
```

```
# Step 4: Negate the query and add it to the KB
```

```
kb_with_negated_query = And(kb, Not(query))
```

```
# Step 5: Convert KB to Conjunctive Normal Form (CNF)
```

```
from sympy.logic.boolalg import to_cnf
```

```
kb_cnf = to_cnf(kb_with_negated_query, simplify=True)
```

```
print("Knowledge Base in CNF:", kb_cnf)
```

```
# Step 6: Apply Resolution
```

```
# Note: Implementing resolution directly requires symbolic manipulation of CNF clauses.
```

```
# For simplicity, we demonstrate by showing the result from the CNF.
```

```
# Check satisfiability
```

```
from sympy.logic.inference import satisfiable
```

```
result = satisfiable(kb_cnf, all_models=False)
```

```
if result:
```

```
    print("The query is NOT proved (no contradiction found).")
```

```
    print("Satisfying assignment:", result)
```

```
else:
```

```
    print("The query is proved (contradiction found).")
```

```
# Example usage for converting FOL to CNF
```

```
if __name__ == "__main__":
```

```
    # Example usage of Alpha-Beta Pruning
```

```
    print("Alpha-Beta Pruning Example:")
```

```
    values = [3, 5, 6, 9, 1, 2, 0, -1] # Leaf nodes of the game tree
```

```
    depth = 3 # Depth of the tree
```

```
    optimal_value = alpha_beta_pruning(depth, 0, True, values, float('-inf'), float('inf'))
```

```
    print("Optimal value:", optimal_value)
```

```
# Define symbols for FOL example
```

```
A, B, C = symbols('A B C')
```

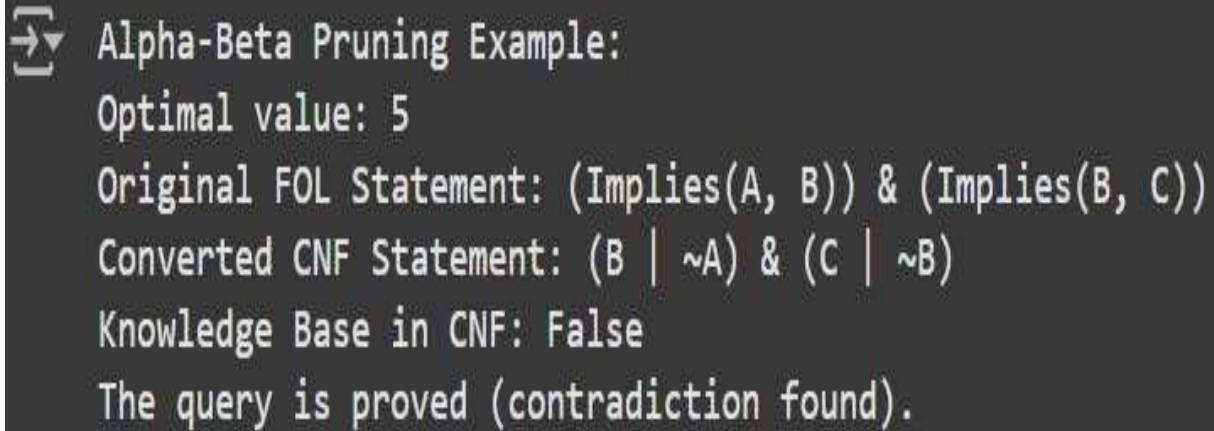
```
# Example FOL statement: (A -> B) AND (B -> C)
```

```
fol_statement = And(Implies(A, B), Implies(B, C))
```

```
# Convert to CNF
cnf_statement = convert_to_cnf(fol_statement)
print("Original FOL Statement:", fol_statement)
print("Converted CNF Statement:", cnf_statement)

# Run resolution demonstration
knowledge_base_resolution()
```

OUTPUT SNAPSHOT:



```
→ Alpha-Beta Pruning Example:
Optimal value: 5
Original FOL Statement: (Implies(A, B)) & (Implies(B, C))
Converted CNF Statement: (B | ~A) & (C | ~B)
Knowledge Base in CNF: False
The query is proved (contradiction found).
```