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## Problem 1

Suppose H is the median filter operator, f, g are two images. We want to show that for some (x, y) that  $H(f(x, y) + g(x, y)) \neq H(f(x, y)) + H(g(x, y))$ .

Suppose for some pixel (x,y) in f, we have surrounding pixels as the matrix, where the median is 4, so H(f(x,y)) = 4:

$$\begin{bmatrix} 0 & 0 & 0 \\ 2 & 4 & 5 \\ 6 & 7 & 8 \end{bmatrix}$$

Also, for the same pixel (x, y) in g, we have surrounding pixels as the matrix, where the median is 5, so H(g(x, y)) = 5, and H(f(x, y)) + H(g(x, y)) = 9

$$\begin{bmatrix} 4 & 4 & 4 \\ 5 & 4 & 7 \\ 6 & 7 & 8 \end{bmatrix}$$

By matrix addition, the corresponding pixels in matrix f + g should be the matrix below, where the median is 8, so H(f(x,y) + g(x,y)) = 8

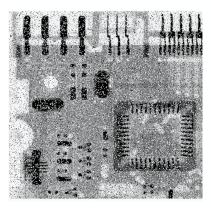
$$\begin{bmatrix} 4 & 4 & 4 \\ 7 & 8 & 12 \\ 12 & 14 & 16 \end{bmatrix}$$

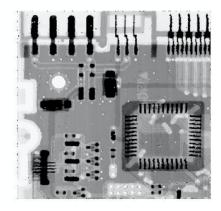
Since  $H(f(x,y)+g(x,y)) \neq H(f(x,y))+H(g(x,y))=9$ , we have proved that the median operator is not linear.

## Problem 2

- % the code for the median filter is shown below
- % the method is explained in detail in the code comment
- % the median filter creates a good-quality and clear denoising image
- % for this picture, the median filter does a better job than the average
- % filter, since the median filter has less blurring of the edges.

```
% read the original image
I=imread('Fig3.37(a).jpg');
% B is the output of the image
B=I:
% Since we want the boundary pixels to be unchanged, we adjust the size
% of our loop to be M/N-2 and start with (2,2)
for i = 1 : size(I,1) - 2
    for j=1: size(I,2)-2
        % create a mask for the median filter
        mask=zeros(9,1);
        % create an iterator for the mask
        inc=1;
        \% we are using a 3*3 mask here
        for x=1:3
             for y=1:3
                % assin values in the sequence by the original image
                 mask(inc) = I(i+x-1, j+y-1);
                 inc=inc+1;
            end
        end
        % sort the mask sequence
        % median is the fifth element is a sorted list
        median=sort (mask);
        B(i,j)=median(5);
    end
end
B=uint8(B);
subplot(1,2,1)
imshow(uint8(I))
subplot(1,2,2)
imshow(uint8(B))
```





## Problem 3

```
% the code for the composite Laplacian Mask is shown below
\% the composite Laplacian mask makes the image sharper and clearer
% read the original image
I=imread ('Fig3.40(a).jpg');
% mask for the composite Lapalacian mask
w = [0 -1 0; -1 5 -1; 0 -1 0];
\% if we use the builtin convolution function to create the output image
\% \text{ img} = \text{conv2}(\text{double}(I), w, 'same');
[x,y] = size(I);
g = z e ros(x+2,y+2);
%then, store f within g
for i=1:x
    for j=1:y
         g(i+1,j+1)=I(i,j);
    end
end
%traverse through the matrix, keep the boundaries unchanged
for i = 2 : size(I,1) - 2
    for j = 2: size (I, 2) - 2
         img(i,j)=g(i,j)*w(1,1)+g(i+1,j)*w(2,1)+g(i+2,j)*w(3,1)
        + g(i, j+1)*w(1,2)+g(i+1, j+1)*w(2,2)+g(i+2, j+1)*w(3,2)
         + g(i, j+2)*w(1,3)+g(i+1, j+2)*w(2,3)+g(i+2, j+2)*w(3,3);
    end
end
\operatorname{subplot}(1,2,1)
imshow(uint8(I))
subplot(1,2,2)
imshow(uint8(img))
```



