

Part A

1. Answer the following Questions (Any Five).

5 × 2 = 10

- What is the resolution of an image?
- If we use direct coding with 8 bits per primary color, how many possible colors do we have for each pixel?
- What do you require for 3D viewing an object? Mathematically how do you specify the view plane?
- Ideally view volume is infinite but in reality we prefer to use a finite volume, why?
- How do you specify the finite view volume?
- If  $d_i = -3$ ,  $x_i = 3$ ,  $y_i = 2$  what will be the  $x_{i+1}$  and  $y_{i+1}$  for Bresenham's line drawing algorithm?
- The direct coding method is flexible in that it allows the allocation of a different number of bits to each primary color. If we use 5 bits each for red and blue and 6 bits for green for a total of 16 bits per pixel, how many possible simultaneous colors do we have?

2. Answer the following Questions (Any Four).

4 × 5 = 20

- Under the standard perspective transformation  $P_{erk}$ , what is the projected image of a point in the plane  $z = -d$ ? What does this anomaly called?
- Given points  $P_1(1, 2, 0)$ ,  $P_2(3, 6, 20)$  and  $P_3(2, 4, 6)$  and a viewpoint  $C(0, 0, -10)$ , determine which points obscure the others when viewed from C.
- When eight-way symmetry is used to obtain a full circle from pixel coordinates generated for the first octant, certain pixels are set or plotted twice. This phenomenon is sometimes referred to as over-stroke. How to remove this over-stroke phenomenon?
- Compare between 'Bresenham's', and 'Direct' line drawing approach.
- What steps are required to plot a dashed circle? Modify Bresenham's circle drawing algorithm to achieve this.
- Apply Bresenham's line algorithm to draw a line from (2,3) to (8,12). Show the steps and the resulting pixel coordinates.

3. Answer the following Questions (Any TWO).

2 × 10 = 20

- Let R be a rectangular window whose lower left-hand corner is at L(-3,1) and upper right-hand corner is at R(2,6).
  - Find the region codes for the endpoints  $A(-2, 3) \rightarrow B(1, 2)$ ,  $C(-4, 7) \rightarrow D(-2, 10)$  and  $E(-4, 2) \rightarrow F(-1, 7)$ .
  - Find the clipping categories for the line segment in part-i.
  - Use the Cohen-Sutherland algorithm to clip the line segments in part-i.
- Triangle ABC where the vertices of  $\triangle ABC$  are A(-1,-3), B(-4,-1), and C(-6,-4) undergoes a composition of transformations described as: a translation 10 units to the right, then a reflection in the x-axis. After all the transformations are applied what will be the triangle coordinates?
- Reflect the diamond-shaped polygon whose vertices are A(-1, 0), B(0, -2), C(1, 0), and D(0, 2) about the horizontal line  $y = 3$ .

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## Part B

4. Answer the following Questions (Any Five).

5 × 2 = 10

- (a) What is "Histogram Equalization" in image processing?
- (b) What is region code? What does each bit represent?
- (c) What is "Analog Image"?
- ~~(d)~~ Find the transformation that scales (with respect to the origin) by 'a' units in the X direction for point P(x,y).
- ~~(e)~~ What are the conditions for the clipping candidate in the Cohen-Sutherland algorithm?
- (f) How do you model an object in computer graphics?
- (g) What are the geometric forms used for modeling of objects?

5. Answer the following Questions (Any Four).

5 × 4 = 20

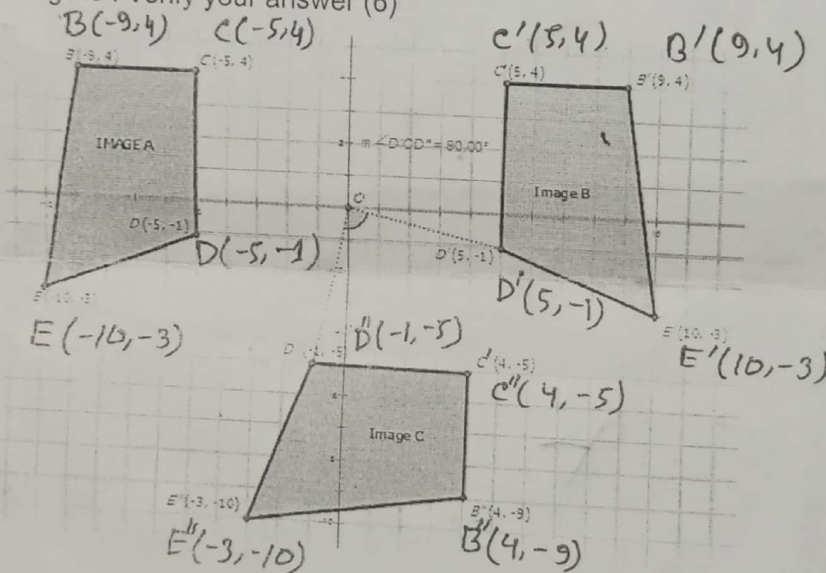
- (a) Find the normalization transformation that maps a window whose lower left corner is at (1,1) and upper right corner is at (3,5) onto a viewport that is the entire normalized device screen.
- ~~(b)~~ What are the types of Image Compression Techniques? Differentiate between them.
- ~~(c)~~ Apply Cohen-Sutherland line clipping to clip a line segment with endpoints (-5, 4) and (7, 10) against a window with corners (-3, 8) and (5, 6).
- ~~(d)~~ The matrix  $\begin{pmatrix} 1 & a \\ b & 1 \end{pmatrix}$  defines a transformation called a simultaneous shearing or shearing for short. The special case when  $b = 0$  is called shearing in the x direction. When  $a = 0$  we have shearing in the y direction. Illustrate the effect of these shearing transformations on the square A(0,0), B(1,0), C(1,1), and D(0,1) when  $a=2$  and  $b=3$ . Draw suitable diagrams.
- ~~(e)~~ Tilting is defined as a rotation about the x-axis followed by a rotation about the y-axis: (i) find the tilting matrix; (ii) does the order of performing rotation matter? Show mathematically.
- ~~(f)~~ Show that  $S_{a,b} \cdot S_{c,d} = S_{c,d} \cdot S_{a,b} = S_{ac} \cdot S_{bd}$ .

6. Answer the following Questions (Any Two).

2 × 10 = 20

- ~~(a)~~ Use the Cohen-Sutherland algorithm to clip two lines P1(35,10)- P2(65,40) and P3(65,20)-P4(95,10) against a window A(50,10), B(80,10), C(80,40) and D(50,40). Also, find the clipping position.
- ~~(b)~~ Find a transformation  $A_V$  which aligns a given vector  $V$  with the vector  $K$  along the positive z axis.
- ~~(c)~~ Under the standard perspective transformation  $P_{erk}$ , what is the projected image of the line segment joining  $P_1(-1, 1, -2d)$  to  $P_2(2, 2, 0)$ . Use suitable figures.

1. What is 8-way symmetry for a Circle? Explain. (2+2)
2. In Bransenham's Circle drawing algorithm, we defined the decision variable  $d_i = D(T) + D(S)$  where T is the top pixel and S is the lower. Is there any chance that  $d_i = 0$  but pixels S and T are not equally far from the true circle? Justify your answer. (5)
3. Modify the "Midpoint circle drawing" algorithm pseudocode to draw a dashed circle. A "dashed circle" generally refers to a circular shape or outline where the perimeter is represented by a dashed or dotted line rather than a solid line. (5)
4. Define the possible steps & find the composite matrix to transform 'Image A' to 'Image C'. Verify your answer (6)



$$C'' = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} m(x_k + 1) \\ n(y_k + 1) \end{pmatrix}$$

$$M_{12} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

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initial variable,  $x=0$ ,  $y=n$   
decision variable,  $(1-n)$

$$A \times B \times C$$

$$= A \times (B \times C)$$

$$= (A \times B) \times C$$

$$= A \times B \times C$$

$$A \times B \times C$$

$$= A \times (B \times C)$$

$$= (A \times B) \times C$$

$$= A \times B \times C$$



Shahjalal University of Science and Technology  
Software Engineering

Institute of Information and Communication Technology  
4<sup>th</sup> Year 2<sup>nd</sup> Semester Final Examination' (Session: 2016-17)

Course Code: SWE 423 Credits: 3 Course Title: Computer Graphics and Image Processing  
Time: 2 hrs Total Marks: 50

Group A

[Answer all the questions]

1. Answer any TWO

2x2.5=5

- a) Write the basic differences between Sutherland-Hodgeman and Weiler-Atherton Algorithm.
- b) Compute the size of a 640 X 480 image at 240 pixels per inch.
- c) Give real life examples of co-ordinate transformation.

2. Answer any TWO

2x10=20

- a)
  - I. Write the differences between DDA line drawing and Bresenham's Line Drawing algorithm.
  - II. What do you understand by composite transformation? Explain with example.
  - III. The endpoints of a given line are (0,0) and (6,18). Compute each value of y as x steps from 0 to 6 and plot the results.
- b)
  - I. Perform a 45° rotation of triangle A(0,0), B(1,1), C(5,2) about a point P(-1,-1)
  - II. Let  $S_x = \frac{vx_{max} - vx_{min}}{wx_{max} - wx_{min}}$  and  $S_y = \frac{vy_{max} - vy_{min}}{wy_{max} - wy_{min}}$ . Express window-to-viewport mapping in the form of a composite transformation matrix.
- c)
  - I. What do you understand by polygon and polylines? Explain their differences.
  - II. What are 4 connected and 8 connected pixels. Explain with possible diagrams and examples.
  - III. Clipping against rectangular windows whose sides are aligned with the x and y axes involves computing intersections with vertical and horizontal lines. Find the intersections of a line segment  $P_1P_2$  [joining  $P_1(x_1, y_1)$  to  $P_2(x_2, y_2)$ ] with
    - (a) the vertical line  $x = a$  and
    - (b) the horizontal line  $y = b$ .

2+3+5  
=10

5+5=10

2+3+5  
=10

**Group B**  
[Answer all the questions]

2x2.5=5

3. Answer any TWO

- Name two algorithms that can be used to find out the visible portion of given lines in a certain viewport.
- What is the resolution of an image?
- What do you understand by window to viewport mapping?

2x10=20

4. Answer any TWO

- Give two real life examples of scaling transformation.
  - What do you understand by Circle Symmetry property?
  - Find the normalization transformation that maps a window whose lower left corner is at (1,1) and upper right corner is at (3,5) onto -
    - a viewport that is the entire normalized device screen and
    - a viewport that has lower left corner at (0,0) and upper right corner at  $(\frac{1}{2}, \frac{1}{2})$ .

2+3+5  
=10

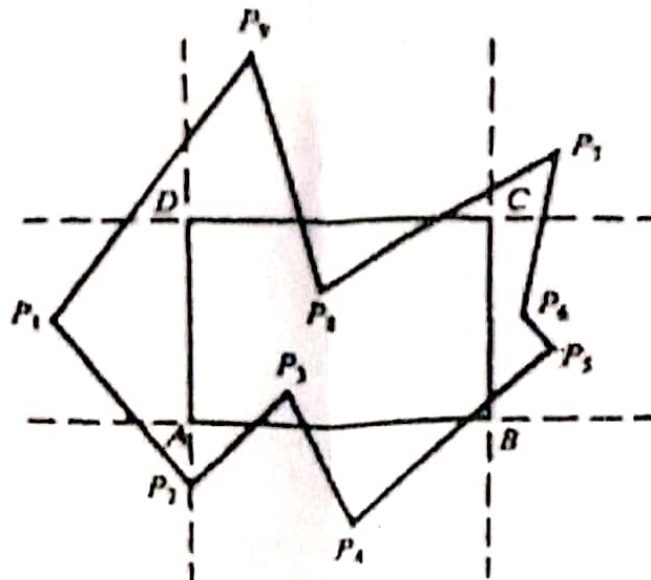
- Define translation.
  - How can we determine whether a point  $P(x,y)$  lies to the left or to the right of a line segment joining the points  $A(x_1, y_1)$  and  $B(x_2, y_2)$ . Explain with necessary diagrams.

2+3+5  
=10

- Magnify the triangle with vertices  $A(0,0)$ ,  $B(1,1)$ , and  $C(5,2)$  to twice its size while keeping  $C(5,2)$  fixed.

c)

5+5=10



- Clip the above polygon using Sutherland-Hodgeman algorithm. Show the figures at each step.
- Describe the transformation  $M_1$  which reflects an Object about a line L. Draw necessary diagrams.