Aufgabe 1 : Elektrodynamischer Wandler

Ein elektrodynamischer Wandler (z.B. das Antriebssystem eines Lautsprechers) hat die folgenden Kenngrößen:

- \bullet Flußdichte im Luftspalt: $B = 1.2 \text{ Vs/m}^2$
 - $\bullet \;$ Schwingspulendurchmesser: $d=2\;\mathrm{cm},\,N=100\;\mathrm{Windungen}$
 - bewegte Masse m=8 g

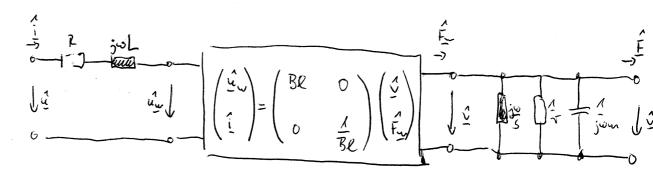
Q=4

• mechanische Resonanzfrequenz $f_0=50$ Hz, Güte (beides für elektrischen Leerlauf)

1700 Hz

• im mechanisch festgebremsten Zustand ist der Betrag der elektrischen Impedanz $Z_{\rm el}=4~\Omega$ und die Phasenverschiebung $\varphi_{\rm el}=45^\circ$.

Erstellen Sie das Ersatzschaltbild des Wandlers und berechnen Sie die Schaltelemente!



$$\begin{cases}
6 = 50 \text{ Hz} & \text{ bei } 1 = 0 \\
Q = 2
\end{cases}$$

$$\begin{cases}
Y_w = 60
\end{cases}$$

$$\begin{cases}
Y_w =$$

$$\omega_0 = \sqrt{\frac{5}{m}}$$
 $S = \omega_0 m = 44^2 2500 \cdot 5^2 .0.000$

H+A

Übung **4**, Elektroakustik

$$1\frac{S}{k_q} = 1\frac{S \cdot m}{NS^2} = \frac{\Lambda m/s}{\Lambda I}$$

$$\frac{1}{1} = \frac{\omega_0 Q}{5} = \frac{\omega_0 Q}{\omega_0^2 m} = \frac{Q}{\omega_0^2 m}$$

medianisk fest gelsenst: $\hat{y} = 0$ hy $\hat{u}_{w} = 0$ $\frac{1}{2} R j_{w} h$ $\frac{1}{2} R_{e} v = 0$

$$R^{2} = 8 \frac{V^{2}}{A^{2}} \rightarrow R = 2.8352$$

$$\omega^2 L^2 = 8 \frac{V^2}{A^2}$$
 $\omega L = 7.83 \frac{V_5}{A}$ $\rightarrow L = \frac{2.83}{2\pi Aco} \frac{V_5}{A}$

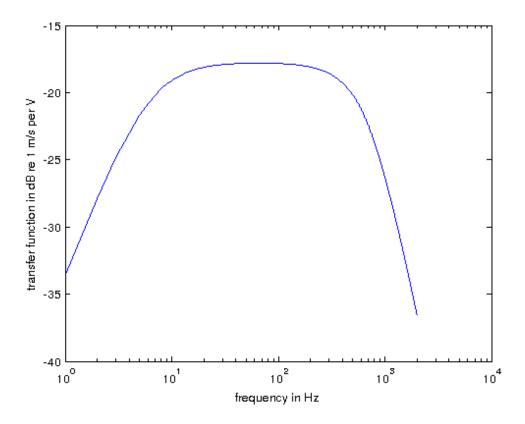
L = 0.37 mit

, in

```
% script file eldynwandler.m
% Copyright (C) 2006-2012 by Matthias Blau
% Author : Matthias Blau <matthias.blau AT jade-hs.de>
% Date : 08 Dec 2006
% Updated: 10 Oct 2012
% This file is free software; you can redistribute it and/or modify
% it under the terms of the GNU General Public License as published
% by the Free Software Foundation; either version 2 of the License,
% or (at your option) any later version.
% See the GNU General Public License for more details:
% http://www.gnu.org/licenses/gpl
%
%
                                                 F=0
%
               -->
   o--|___|--uuuu--o--|
                                        |--0--*---*---
       %
                                             3 | | | |
           u_W | | \ i / \ 0 1/Bl/ \F_W/ |
                                          3 | === | v
| | | V
%
            V
%
                                          |--0--*---*---0
%
  0-----
% / u \ / v \ / v \
% | | = Ages | | = A1*A2*A3 | | u = Ages(1,1)*v
% \ i / \ \F=0/ \ \F=0/
                                             u Ages(1,1)
   %
%
B = 1.2;
m = 0.008;
N = 100; d = 0.02;
f0 = 50; Qmech = 4;
Zel 1200Hz = 4*exp(sqrt(-1)*pi/4); % Zel 1200Hz refers to v=0, i.e. u W=0
                          % thus, Zel_{1200Hz} = R+j*2pi*1200Hz*L
1 = pi*d*N; B1 = B*1;
s = (f0*2*pi)^2*m;
r = s/(f0*2*pi)/Qmech;
R = abs(Zel_1200Hz)/sqrt(2); L = R/(2*pi*1200);
%----- Modell -----
f = 1:2000; w = f*2*pi;
A1 = [1 \ 0; \ 0 \ 1]; \ A2 = [Bl \ 0; \ 0 \ 1/Bl]; \ A3 = [1 \ 0; \ 0 \ 1];
a11 = zeros(1,length(f));
for q = 1:length(f)
 A1(1,2) = R+1j*w(q)*L;
 A3(2,1) = r+1j*w(q)*m+s/(1j*w(q));
```

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```
Ages = A1*A2*A3;
 a11(q) = Ages(1,1);
end
v_re_u = (1)./a11;
%----- Grafik -----
figure();
semilogx(f,log10(abs(v_re_u))*20);
xlabel('frequency in Hz');
ylabel('transfer function in dB re 1 m/s per V');
% noch ein paar Spielereien
%------ elektrische Eingangsimpedanz ------
a21 = zeros(1,length(f));
for q = 1:length(f)
 A1(1,2) = R+1j*w(q)*L;
 A3(2,1) = r+1j*w(q)*m+s/(1j*w(q));
 Ages = A1*A2*A3;
 a21(q) = Ages(2,1);
Zin_el = a11./a21;
```



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