

2025

# Performance Modeling and Improvements on the GRB Source Localization Streaming Pipeline Aboard the ADAPT

*Where the **Bursts** Come From*

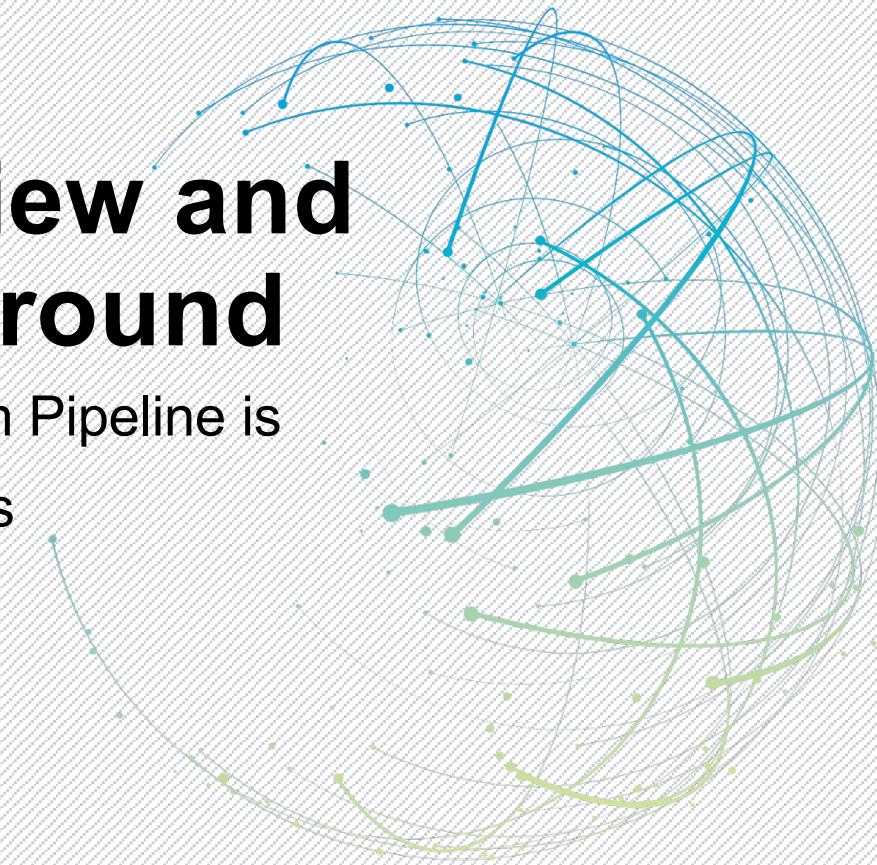


Jack Yang [honghao@wustl.edu](mailto:honghao@wustl.edu)

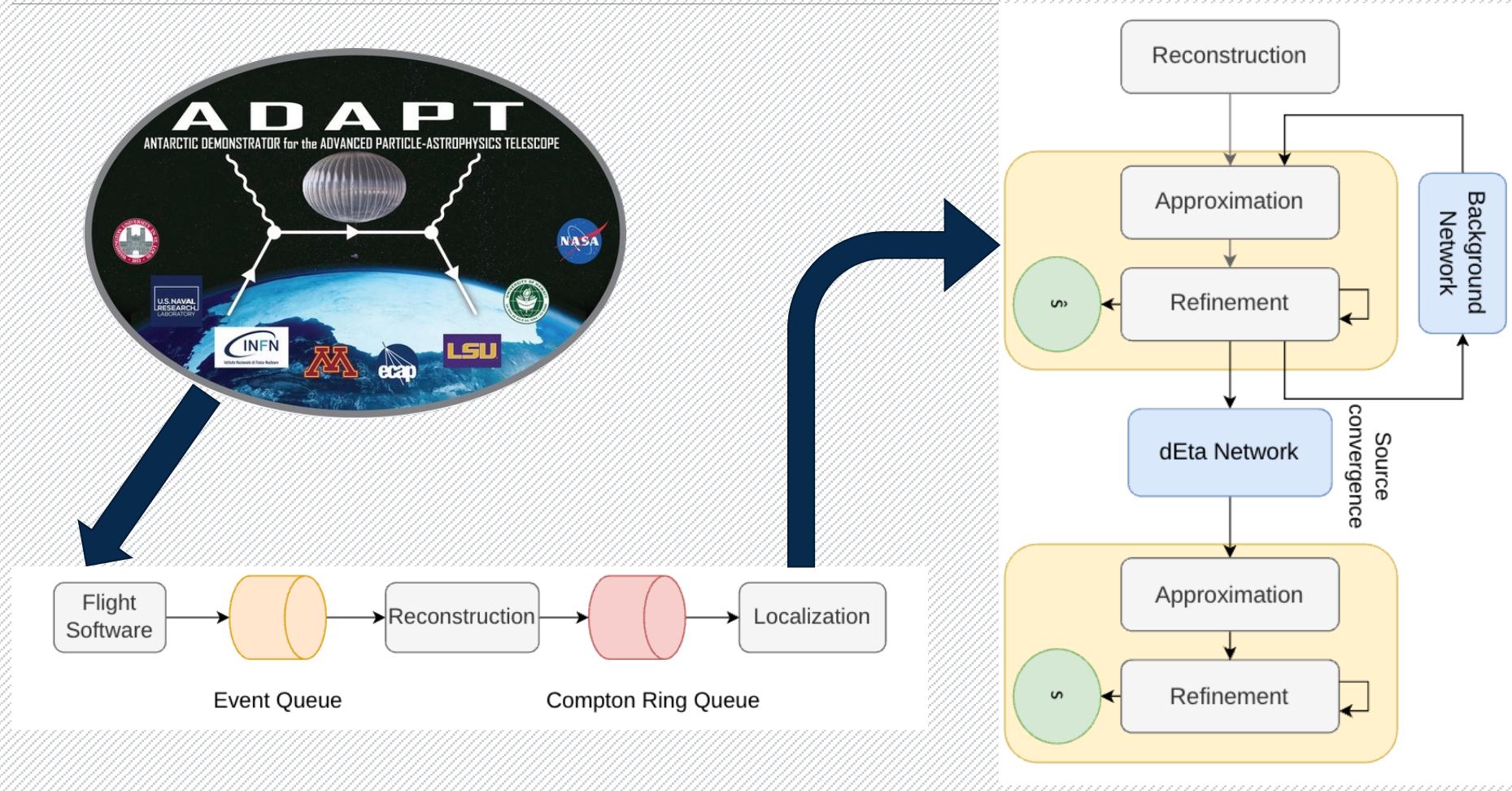
Supervised by Roger Chamberlain and Ye Htet

# 101 Overview and Background

What Stream Pipeline is  
How it Works



# ADAPT & Pipeline Flow



# 102 Working Summary

What did I do



## Performance Modeling

---

$$n_{loc} = \left\lfloor \frac{1 - t_{rec}(n, E)}{t_{loc}(m, R)} \right\rfloor$$

$$w_{min} = \frac{1}{n_{loc}}$$

- $n_{loc}$  computes maximum number of localizations possible during a GRB of length T
- $w_{min}$  is minimum possible time interval between alerts
- $t_{rec}(n, E)$  is execution time of reconstruction kernel on  $E$  Gamma-ray events using  $n$  cores
- $t_{loc}(m, R)$  is execution time of localization kernel on  $R$  Compton rings using  $m$  cores

## **Timing Mechanism**

---



--A standardized timing benchmark

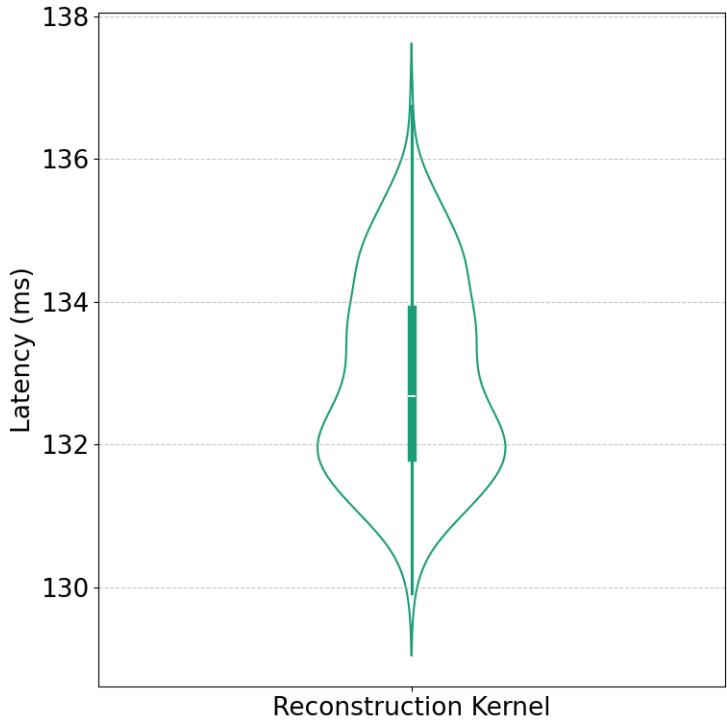
--An easy-to-use timing library



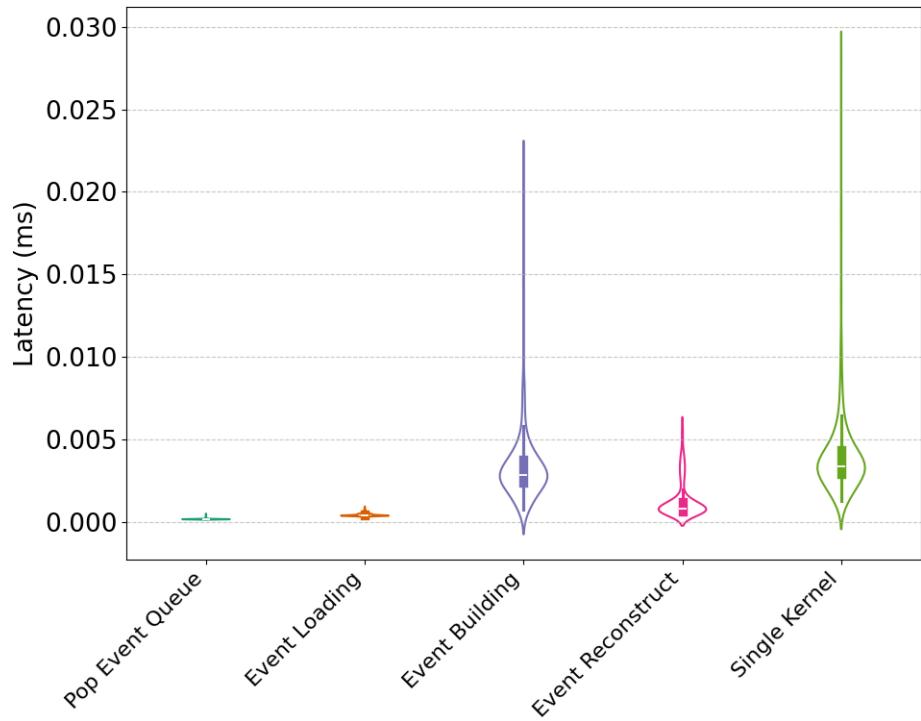
## **Unordered Map vs. Vector vs. Array**

--A manual Stopwatch

## Timing Result: Reconstruction

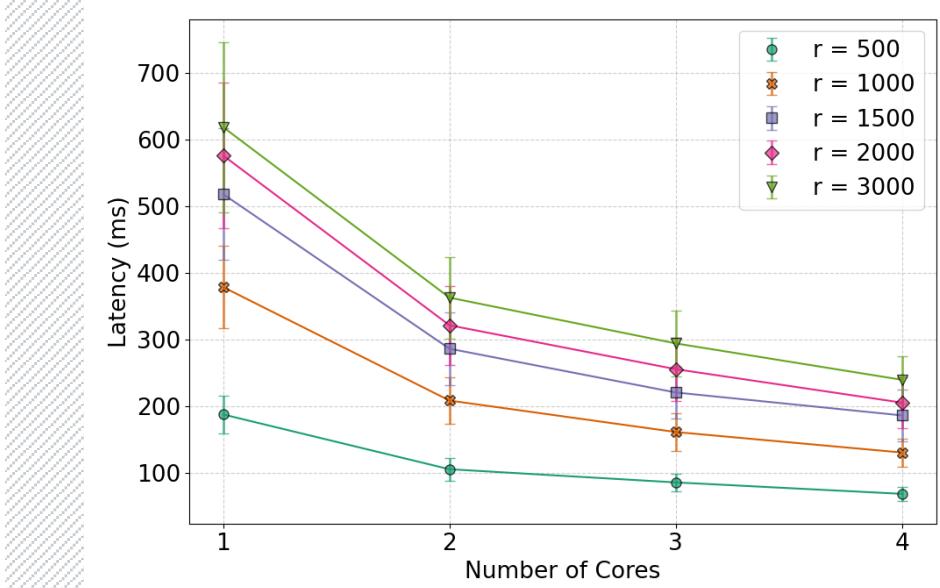
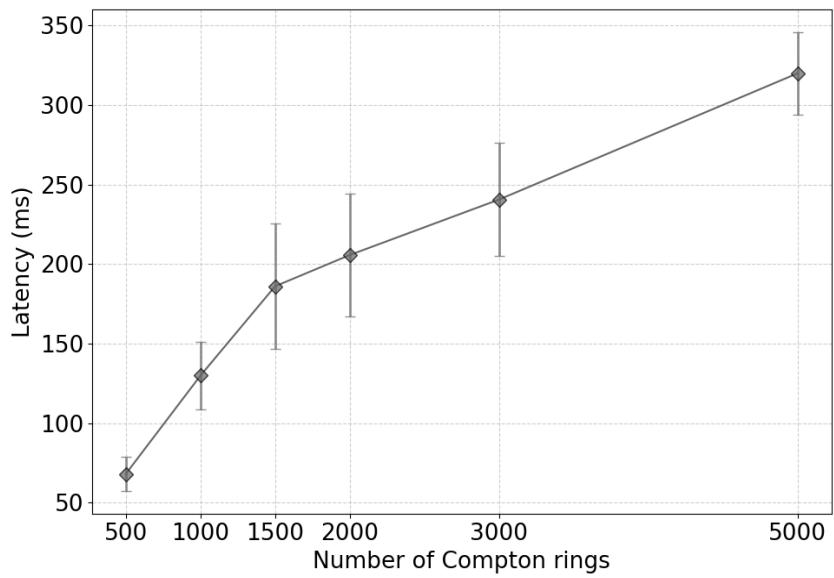


- $t_{rec} (n = 1, E = 31,746) < 140 \text{ ms}$



- `clock_gettime(CLOCK_MONOTONIC)`

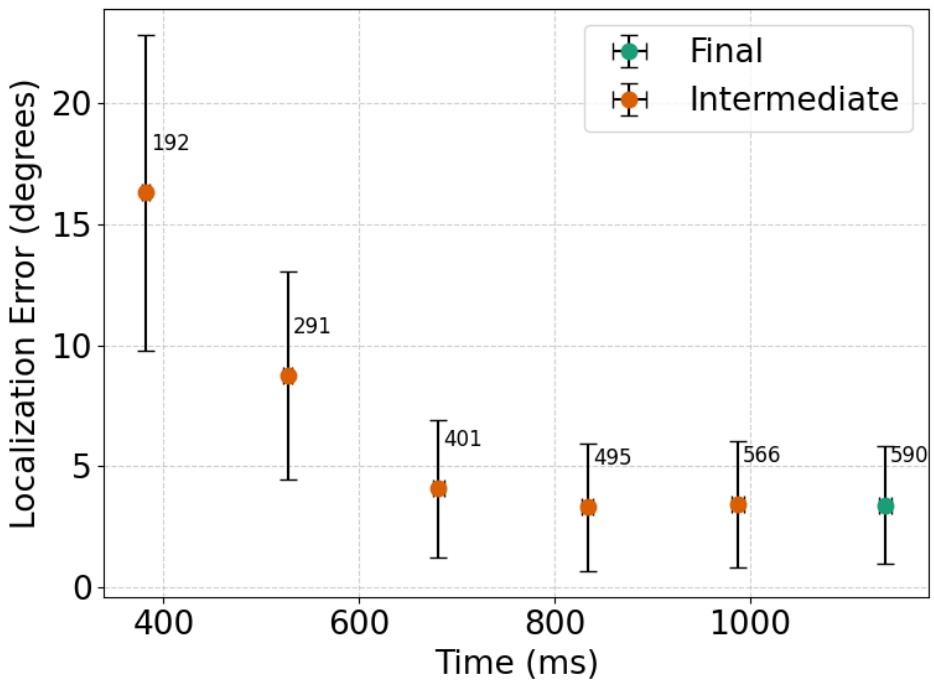
## Timing Result: Localization



- $t_{loc} (m = 4, R = 582) < 100 \text{ ms}$
- Slower increasing rate with more rings

- $t_{loc} (m, R \in \{500, 3000\})$
- Better performance under more threads

## Timing Result: Stream Pipeline



$$n_{loc} = \left\lfloor \frac{1 - 0.14}{0.1} \right\rfloor = 8 \text{ batches}$$

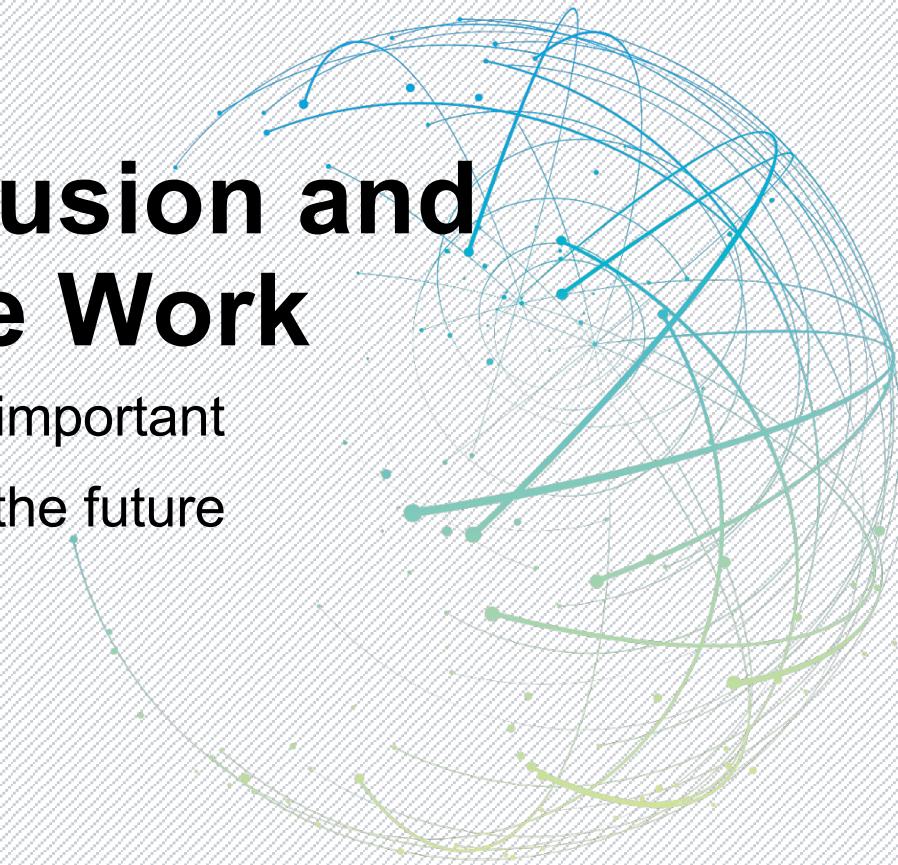
$$w_{min} = \frac{1}{8} = 0.125s = 125 \text{ ms}$$

(set to 150 ms)

# 103 Conclusion and Future Work

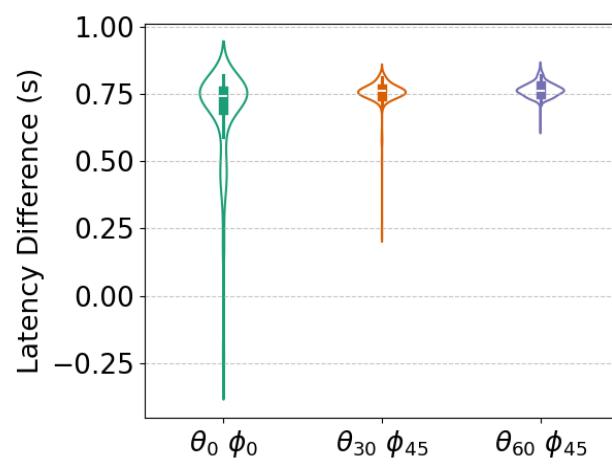
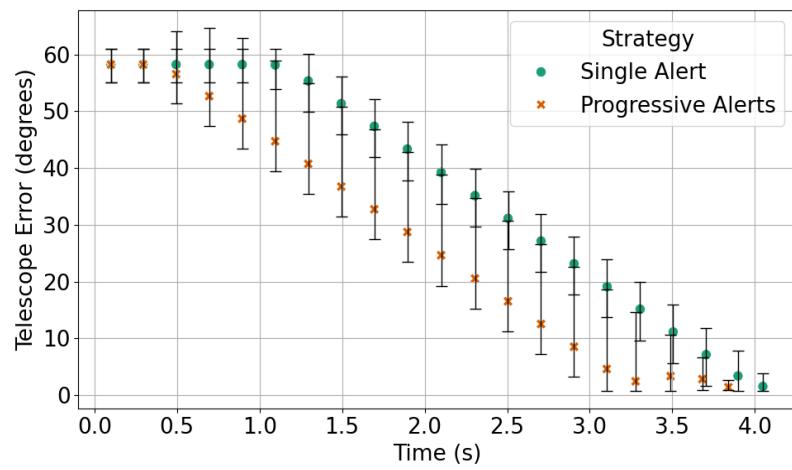
Why this is important

What is for the future

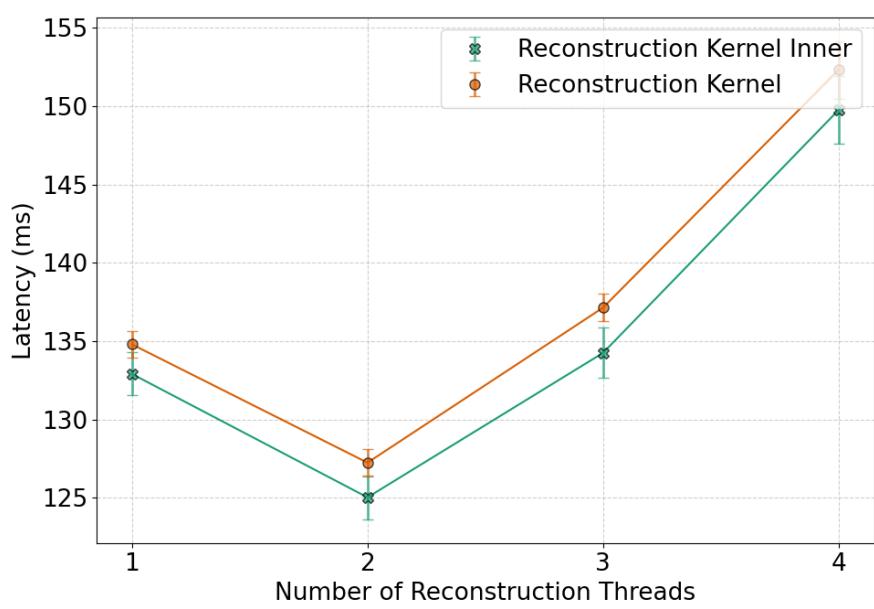


## Conclusion:

- Almost free gain of intermediate results, beneficial for real-time alert on partner telescopes
- Telescope simulation with  $20^\circ/\text{sec}$  slew rate suggests about 0.75 s earlier on-target time using progressive alerts compared to a single alert



## Future Work: Multithreading of Reconstruction



- For each single stage in reconstruction, the latencies are stable for different numbers of threads
- We expect better performance overall using more threads for reconstruction

## Future Work: Batch Processing of Pipeline



- How large is the batch size
- What will be beneficial from the batch process

# Question & Discussion

Jack Yang  
07/30/2025