# Deep learning

Regularisation & Sequential modelling

### Announcements

- Environment
  - It is slower than we want, trying to resolve.
  - If you want, we have created instructions for local development.
    - Docker image updated to 1.1 for today.
- Assignment back on track
  - Deadline 9th of April.
  - Grading will be 0, 1, 2
- Mid-course evaluation.

- (supervised) Machine learning tasks
  - Regression

layer\_dense(unit = 1, activation = "sigmoid") + loss = "binary\_crossentropy"

- Classification
- layer\_dense(unit = 10, activation = "softmax") + loss = "categorical\_crossentropy"

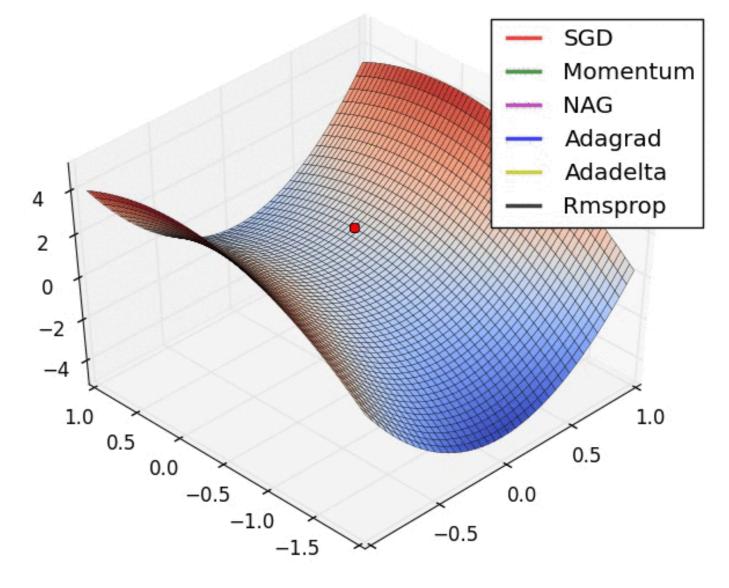
 Multi-class classification

layer\_dense(unit = 1) + loss = "mse"

 Output many things at once!

#### 1.Binary Classification 2. Multiclass Classification 3.Regression NN model Layers Activation Activation NN model Layers NN model Layers input input sigmoid softmax input input input function function input $output = \frac{1}{1 + e^{-v}}$ Dense Dense Dense output output Dense Dense output activate Softmax activate output Sigmoid y=417 output output output error output v1 v2 y=0.9 y1=0.2 y2=0.1 y3=0.7 label error t=520 error label label t=1.0 t1=0.0 t2=0.0 t3=1.0 Cross Entropy(CE) Mean Squared Error(MSE) $L = \frac{1}{2}(t - y)^2$

- Improving networks
  - Optimisers



- Improving networks
  - Batch normalisation

```
Input: Values of x over a mini-batch: \mathcal{B} = \{x_{1...m}\};

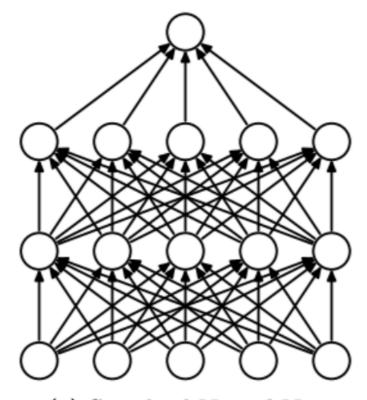
Parameters to be learned: \gamma, \beta

Output: \{y_i = \mathrm{BN}_{\gamma,\beta}(x_i)\}

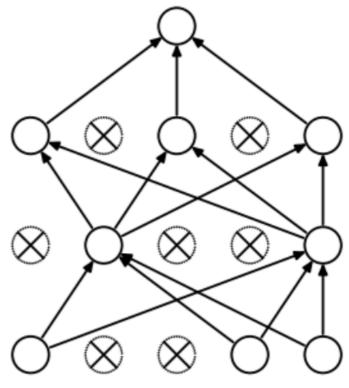
\mu_{\mathcal{B}} \leftarrow \frac{1}{m} \sum_{i=1}^m x_i \qquad \text{// mini-batch mean}
\sigma_{\mathcal{B}}^2 \leftarrow \frac{1}{m} \sum_{i=1}^m (x_i - \mu_{\mathcal{B}})^2 \qquad \text{// mini-batch variance}
\widehat{x}_i \leftarrow \frac{x_i - \mu_{\mathcal{B}}}{\sqrt{\sigma_{\mathcal{B}}^2 + \epsilon}} \qquad \text{// normalize}
y_i \leftarrow \gamma \widehat{x}_i + \beta \equiv \mathrm{BN}_{\gamma,\beta}(x_i) \qquad \text{// scale and shift}
```

Algorithm 1: Batch Normalizing Transform, applied to activation x over a mini-batch.

- Reducing overfitting
  - Dropout



(a) Standard Neural Net



(b) After applying dropout.

### Overview

#### Today we will cover

- Regularisation
  - L2 regularisation
- Practice BN, Dropout and L2
- Sequential modelling
  - Understanding sequential data
  - Basic sequential model (Recurrent Neural Network, RNN)
- Practice working with sequential data

# Reducing overfitting

- What is regularisation?
- Any kind of technique which helps you select one model over another using a structured approach.
- We will add extra terms to the loss function (L2)
- We will add intermediary layers to the network (Dropout)

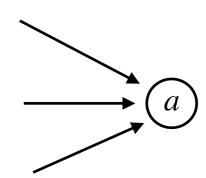
# L2 Regularisation Reducing overfitting

- We add a new term to the total loss function.
- This term adds additional loss to the function which takes the value of the weights into account.
- We then optimise this new loss function instead.
- A new **hyperparameter**,  $\lambda$  is added. This is usually a small value and we will need trial and error to find an acceptable value. It can be considered as a discount factor.

# L2 Regularisation

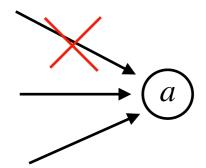
Reducing overfitting

- Why does L2 regularisation work?
- We some cost to the weights, thus making a "more complex" model "more expensive".



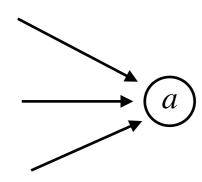
- If some learnt weight is high (say, 10) it "costs more" than a weight with value 1.
- Thus, our model becomes "simpler" by forcing the weights down.
- When some weights are forced to 0, we are effectively "removing connections".

Set weight to 0



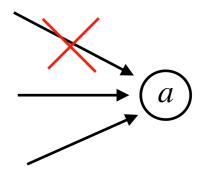
# L2 Regularisation Reducing overfitting

 We use L2 regularisation to fight overfitting, because it makes our model less expressive.



- We use it after we have fitted the data.
- It will increase the training loss during training and hopefully reduce the test loss.
- Also known as weight decay.

Set weight to 0



## L2 Regularisation

Reducing overfitting

Total loss = 
$$J(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^{n} (l(f(x_i, \mathbf{w}), y_i))$$

Now becomes

$$J(w) = \frac{1}{n} \sum_{i=1}^{n} (l(f(x_i, w), y_i) + \frac{\lambda}{2n} \sum_{j=1}^{n} w_j^2)$$

### Hands-on



Go to <a href="https://dba.projects.sda.surfsara.nl/">https://dba.projects.sda.surfsara.nl/</a>

Notebook: 04a-regularisation.ipynb

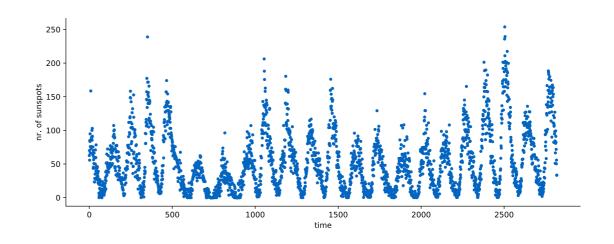
Break at 11:00 / 15:00

Second part at 11:10 / 15:10

## Notebook recap

- We were not really able to improve the baseline much, but made it converge faster.
- We saw that we really need to test if the regularisation technique is helping us.
  - L2 regularisation was not very stable. Dropout was better.
- It depends on the task, architecture, ..., trial and error.

- Data is sequential when the data has some order.
- The whole dataset can consist of a single order (sunspots) or many individual orders (sentences).



the cat sat on the mat the book is open .



in deep learning

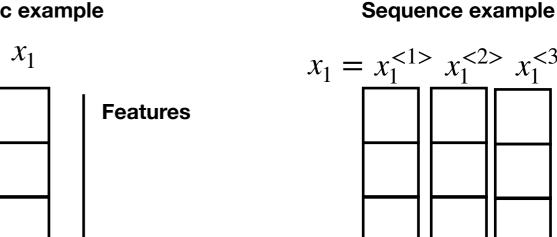
- Machine translation
- Speech recognition
- Music generation
- Sentiment classification
- Video activity recognition

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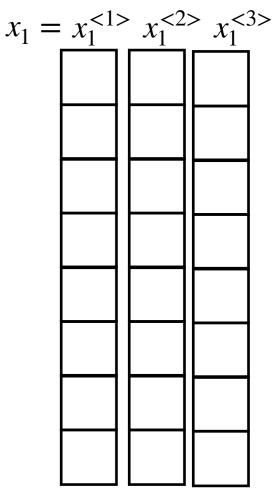


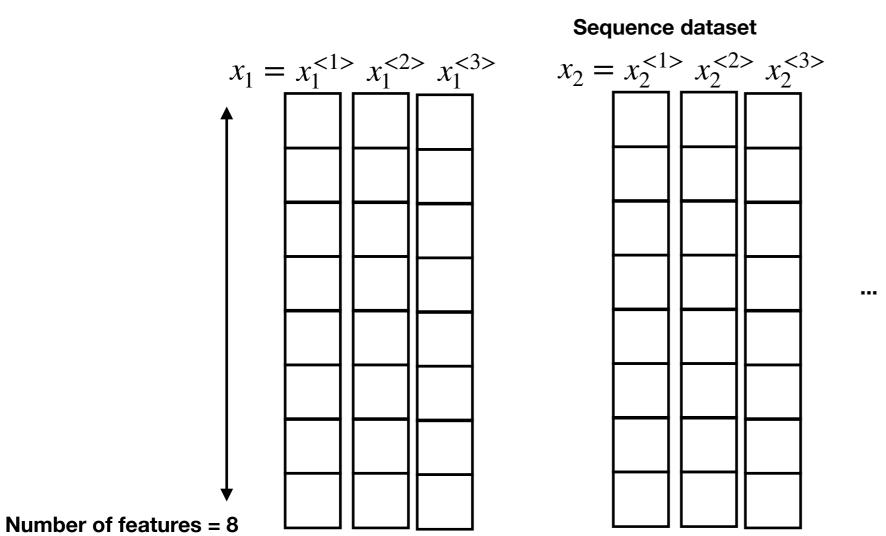
- In previous lectures our data have been made up from a single example.
- A single example can have many features.
  - Temperature, air pressure, etc.
- Now each example is made from a single sequence.
  - "Hi, hoe gaat het?"
- Each sequence has many examples.
  - "Hi", "hoe", "gaat", "het"
- That is, in each iteration we process a single sequence, many examples.

Classic example

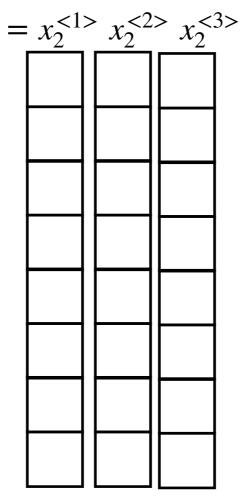


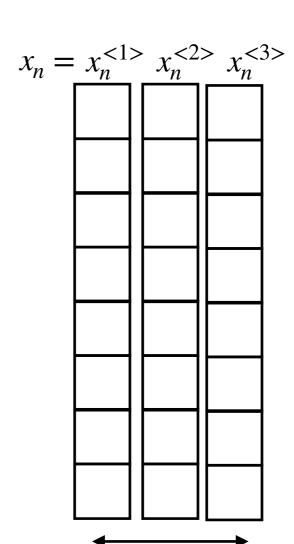
Now is





Sequence dataset



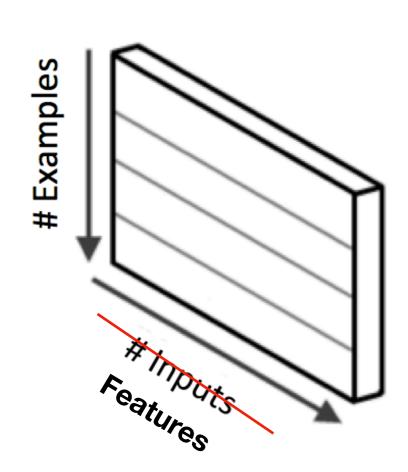


sequence length = 3

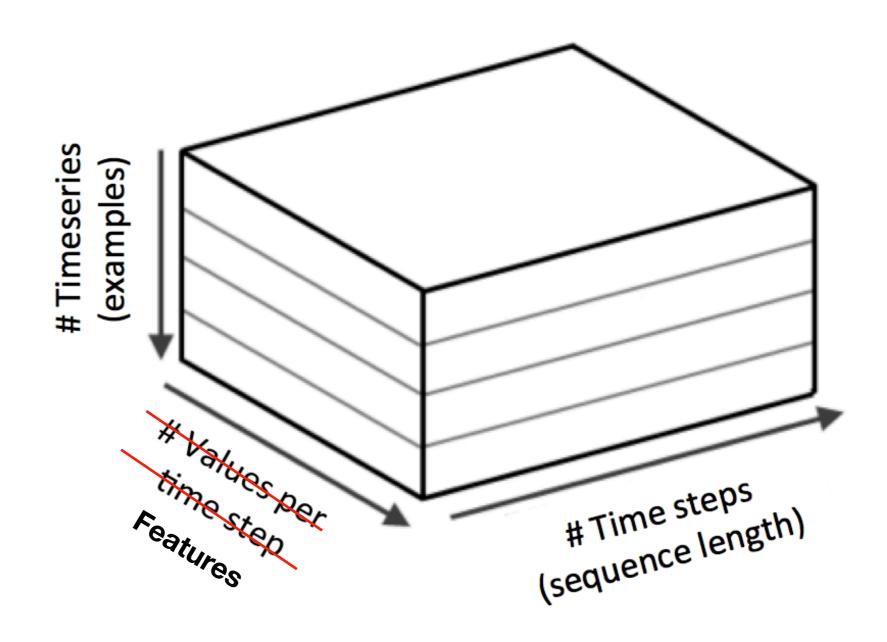
#examples = n

#### Feed-Forward Network Data

#### **Recurrent Network Data**



Data = (examples, features)

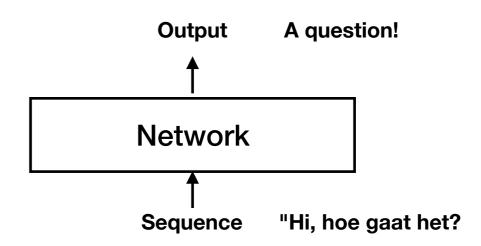


Data = (examples, sequence\_length, features)

Source: https://www.oreilly.com/library/view/deep-learning/9781491924570/ch04.html

### Which task?

- Given a sequence we can try to solve many supervised learning tasks.
  - Regression
    - Predict temperature tomorrow given the last few days.
  - Classification
    - Is this a question?
    - Is the person yelling?
  - Just add the output layer required along with the loss.

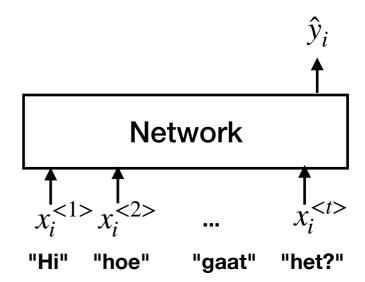


### How to model?

#### Naive model

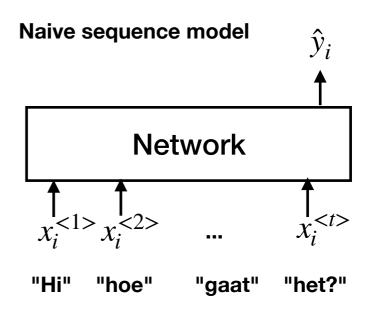
- Why not create a network which accepts multiple inputs at once?
  - For this we will need VERY many parameters.
  - The sequence length might vary between examples.
  - We can often process each element independently and equally.
    - "gaat" is the same word regardless of position in a sentence.

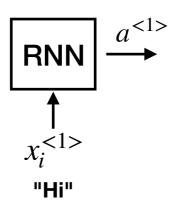
#### Naive sequence model



### How to model?

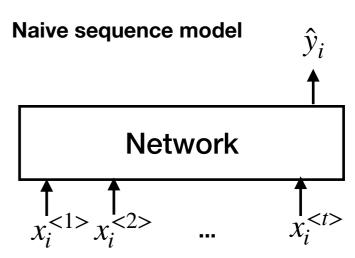
- A more clever approach is to use the same, smaller, network for each element in the sequence.
- Then we pass information to the next time step.
- An RNN cell.



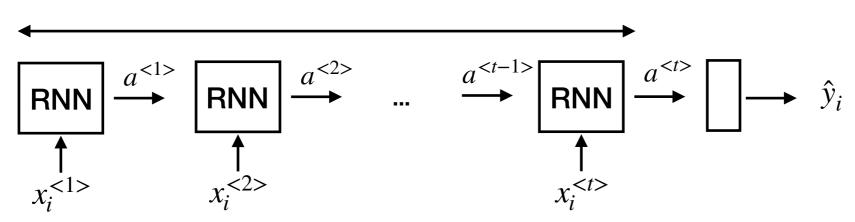


#### passing information

- Read the sequence, step by step.
- Until the sequence has been read.

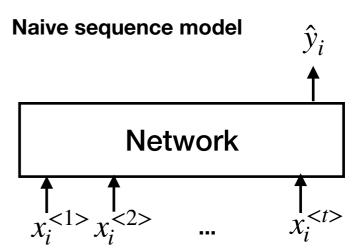




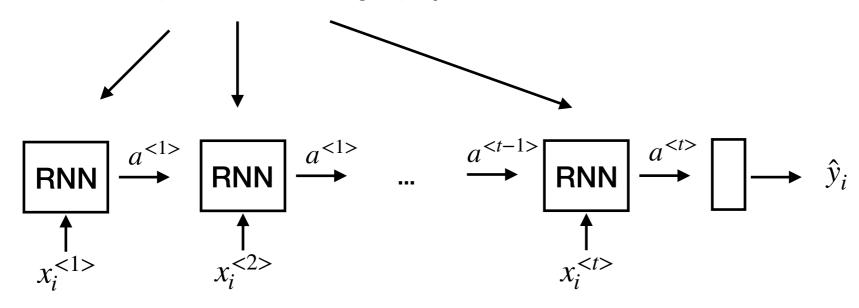


#### passing information

- Use the same network for each time-step.
- RNN cell contains the parameters



The same network, with the same weights, replicated

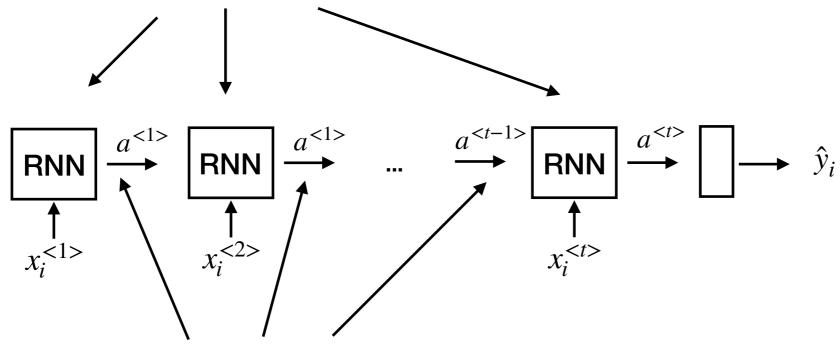


passing information

- Pass information forward in a "memory".
- "Memory" is updated each step.

Naive sequence model  $\hat{y}_i$ Network  $\uparrow$   $\chi_i^{<1>}\chi_i^{<2>}$ ...  $\chi_i^{<t>}$ 

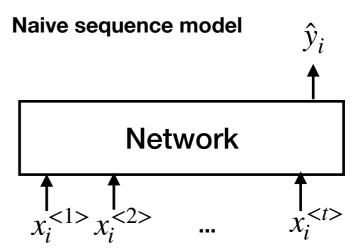
The same network, with the same weights, replicated

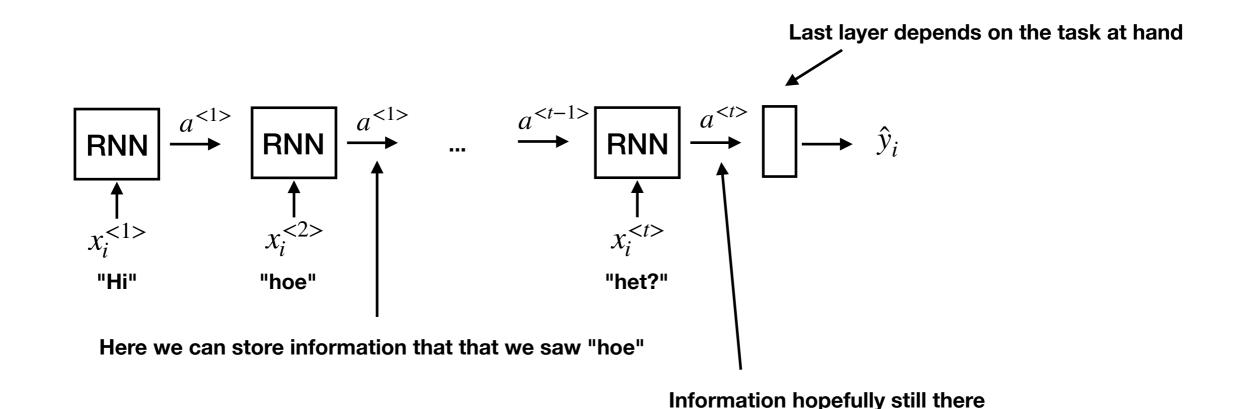


Passing a vector with information forward "memory"

passing information

- Hopefully good information is stored.
- Task is just the last layer.

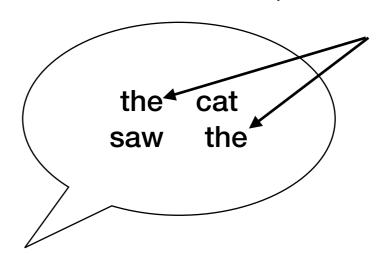


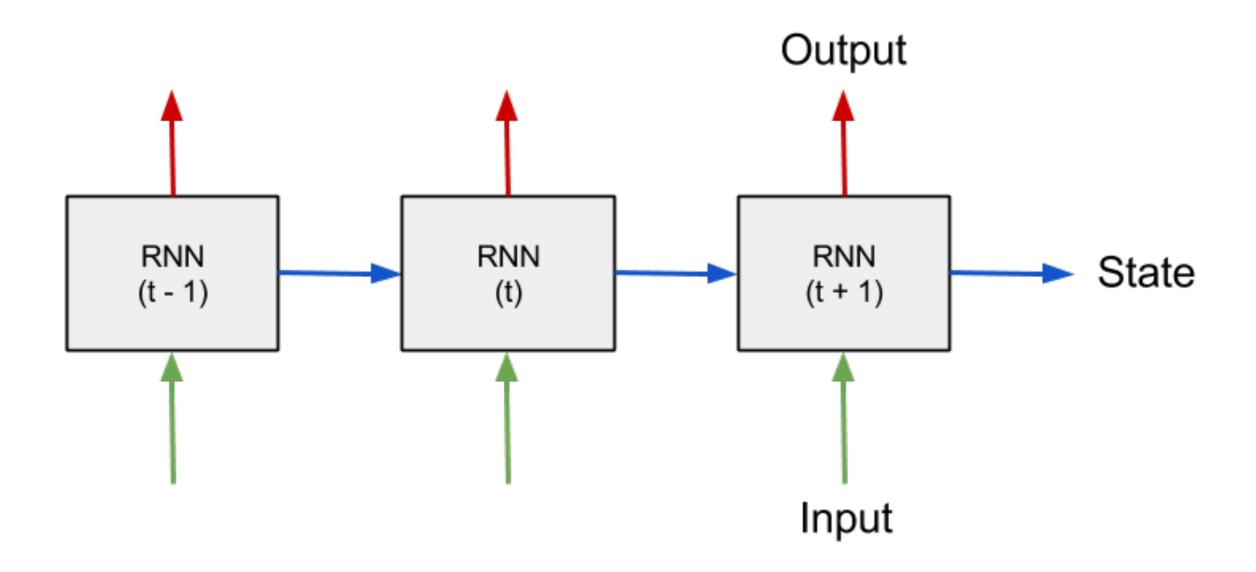


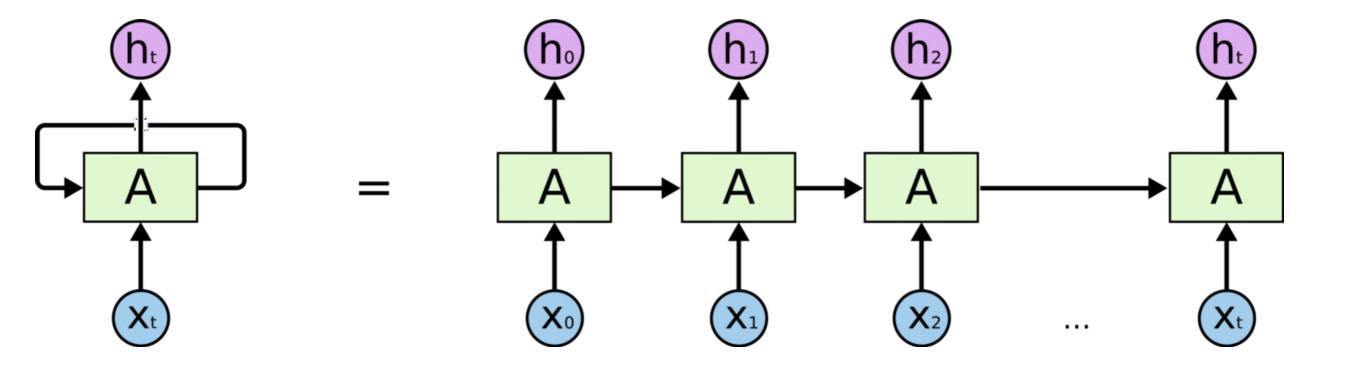
#### sharing parameters

- For each time-step we use the same network, it just gets different "memory" passed to it.
- This allows us to share parameters in different locations of the model.
- Sharing parameters reduces the number of parameters in the model.
- More intuitive and works better.
- The idea behind an RNN.

We process "the" in the same way.





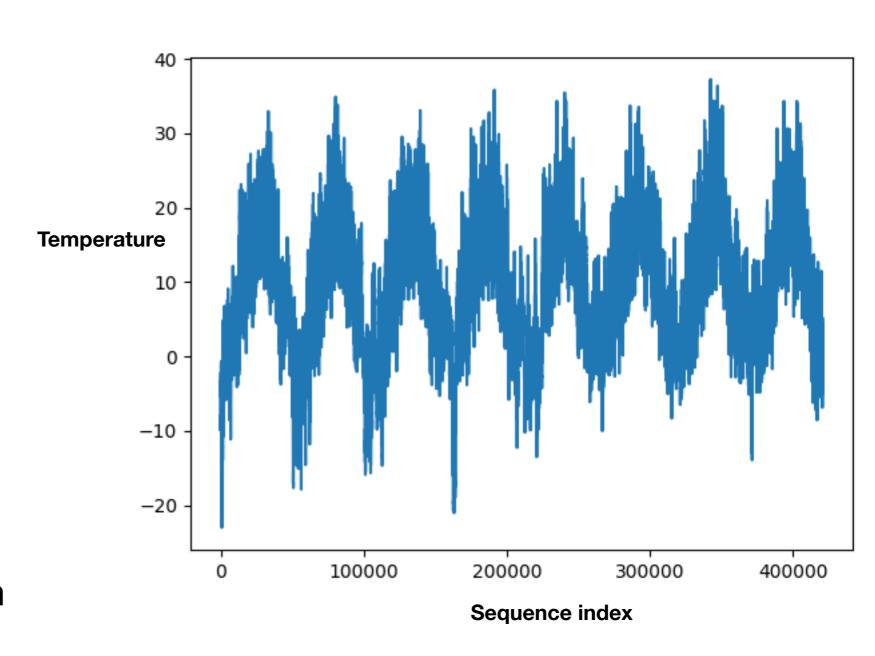


# Summary

- Sequential data is ordered to it.
- Sequential data needs to be processed using dimensions, (examples, sequence length, features).
- We feed each time-step of the sequence into the same RNN cell and remember what we have seen.
- The last layer still takes care of the task.
- Allows us to share parameters.

### Notebook

- The Jena weather dataset.
- A long sequence of weather measurements.
- Each measurement consists of 15 variables.
- We see a timedependent pattern in the data.



### Hands-on



Go to <a href="https://dba.projects.sda.surfsara.nl/">https://dba.projects.sda.surfsara.nl/</a>

Notebook: 04b-time-series-prediction.ipynb

Wrap-up at 12:20 / 16:20

# Summary

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