```
In [5]: import os
    os.environ["KMP_DUPLICATE_LIB_OK"] = "TRUE"
    import torch
    import torch.nn as nn
    import torch.nn.functional as F
    from d21 import torch as d21
```

模型搭建

```
In [19]: from torchvision import models

class ResNet18(nn.Module):
    def __init__(self):
        super(ResNet18, self).__init__()
    # 加载预训练的 ResNet18 模型
        self.model = models.resnet18(pretrained=True)
    # 替换最后的全连接层,适配猫狗分类任务(输出2个类别)
        num_features = self.model.fc.in_features
        self.model.fc = nn.Linear(num_features, 2)

def forward(self, x):
    return self.model(x)
```

```
In [20]: x=torch.randn(2,3,224,224)
    model = ResNet18()
    y = model(x)
    y.shape
```

Out[20]: torch.Size([2, 2])

训练

```
In [34]: from torch.optim import lr scheduler
         from torchvision import datasets, transforms
         from torch.utils.data import Dataset, DataLoader
         root_train = "data/train"
         root_test = "data/val"
         #将图像的像素值归一化到[-1,1]之间
         #由于使用的是 torchvision.models 的预训练模型,所以用 ResNet 训练时的标准化参数
         normalize = transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224,
         train transform = transforms.Compose([
            transforms.Resize((224,224)),
            transforms.RandomHorizontalFlip(),
            transforms.RandomRotation(15), # 随机旋转
            transforms.ColorJitter(brightness=0.2, contrast=0.2, saturation=0.2, hue=0.1
            transforms.RandomAffine(5, translate=(0.1, 0.1)), # 随机仿射变换
            transforms.ToTensor(),
            normalize])
         val transform = transforms.Compose([
```

```
transforms.Resize((224,224)),
   transforms.ToTensor(),
   normalize])
train dataset = datasets.ImageFolder(root train, train transform)
val_dataset = datasets.ImageFolder(root_test, val_transform)
batch_size=64
train_dataloader = DataLoader(train_dataset, batch_size=batch_size, shuffle=True
val_dataloader = DataLoader(val_dataset, batch_size=batch_size, shuffle=True)
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
model = ResNet18().to(device)
#定义损失函数
loss_fn = nn.CrossEntropyLoss()
#定义优化器(Adam)
optimizer = torch.optim.Adam(model.parameters(), lr=1e-4)
#调整学习率,每隔10epoch,变为原来的0.5
lr_scheduler = lr_scheduler.StepLR(optimizer, step_size=10, gamma=0.5)
#训练批次
epoch=20
```

定义训练函数

```
In [35]: def train(dataloader, model, loss_fn, optimizer):
             loss, current, n = 0.0, 0.0, 0
             for batch_idx, (X, targets) in enumerate(dataloader):
                 images, targets = X.to(device), targets.to(device)
                 outputs = model(images)
                 cur_loss = loss_fn(outputs, targets)
                 _, pred = outputs.max(dim=1)
                 cur_acc = torch.sum(pred == targets)/ outputs.shape[0]
                 #反向传播
                 optimizer.zero_grad()
                 cur loss.backward()
                 optimizer.step()
                 loss += cur loss.item()
                 current += cur_acc.item()
                 n = n + 1
             train acc = current / n
             train_loss = loss / n
             print("train loss: %.4f, train acc: %.4f" % (train_loss, train_acc))
             return train_loss, train_acc
```

定义验证函数

```
In [36]: def val(dataloader, model, loss fn, optimizer):
             model.eval()
             loss, current, n = 0.0, 0.0, 0
             with torch.no_grad():
                 for batch_idx, (X, targets) in enumerate(dataloader):
                     images, targets = X.to(device), targets.to(device)
                     outputs = model(images)
                     cur_loss = loss_fn(outputs, targets)
                     _, pred = outputs.max(dim=1)
                     cur_acc = torch.sum(pred == targets)/ outputs.shape[0]
                     loss += cur_loss.item()
                     current += cur_acc.item()
                     n = n + 1
             val_acc = current / n
             val_loss = loss / n
             print("val loss: %.4f, val acc: %.4f" % (val_loss, val_acc))
             return val loss, val acc
```

查看模型在训练中的梯度和权重分布

开始训练

```
In [37]: loss_train_list=[]
         acc_train_list=[]
         loss_val_list=[]
         acc_val_list=[]
         # 定义模型保存的文件夹
         folder = 'save model'
         if not os.path.exists(folder):
             os.makedirs(folder)
         \max acc = 0
         for t in range(epoch):
             lr_scheduler.step()
             print('Epoch %d/%d-----' % (t + 1, epoch))
             train_loss, train_acc = train(train_dataloader, model, loss_fn, optimizer)
             val_loss, val_acc = val(val_dataloader, model, loss_fn, optimizer)
             loss train list.append(train loss)
             acc_train_list.append(train_acc)
             loss val list.append(val loss)
             acc_val_list.append(val_acc)
             if val_acc > max_acc:
                 max_acc = val_acc
                 torch.save(model, os.path.join(folder, 'resnet18_best.pt'))
                 print(f'Saving model, 第{t + 1}轮...')
         # 在最后一次训练结束后保存模型
         torch.save(model, os.path.join(folder, 'resnet18_last.pt'))
         print('最高精确值:',max_acc)
         print("Done!")
```

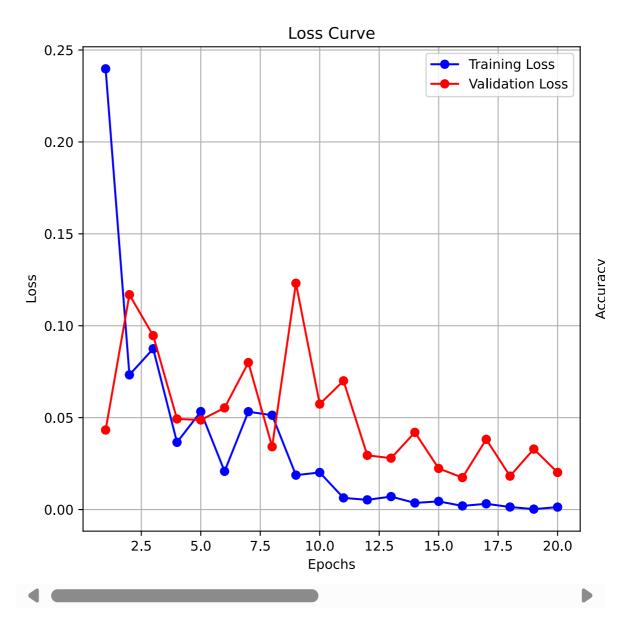
Epoch 1/20----train loss: 0.2398, train acc: 0.9028 val loss: 0.0433, val acc: 0.9812 Saving model, 第1轮... Epoch 2/20----train loss: 0.0733, train acc: 0.9714 val loss: 0.1169, val acc: 0.9625 Epoch 3/20----train loss: 0.0875, train acc: 0.9661 val loss: 0.0946, val acc: 0.9615 Epoch 4/20----train loss: 0.0366, train acc: 0.9887 val loss: 0.0493, val acc: 0.9792 Epoch 5/20----train loss: 0.0533, train acc: 0.9748 val loss: 0.0487, val acc: 0.9781 Epoch 6/20----train loss: 0.0208, train acc: 0.9922 val loss: 0.0553, val acc: 0.9906 Saving model, 第6轮... Epoch 7/20----train loss: 0.0532, train acc: 0.9835 val loss: 0.0800, val acc: 0.9625 Epoch 8/20----train loss: 0.0513, train acc: 0.9783 val loss: 0.0342, val acc: 0.9906 Epoch 9/20----train loss: 0.0187, train acc: 0.9948 val loss: 0.1231, val acc: 0.9760 Epoch 10/20----train loss: 0.0202, train acc: 0.9922 val loss: 0.0574, val acc: 0.9917 Saving model, 第10轮... Epoch 11/20----train loss: 0.0064, train acc: 0.9991 val loss: 0.0700, val acc: 0.9854 Epoch 12/20----train loss: 0.0053, train acc: 0.9983 val loss: 0.0295, val acc: 0.9938 Saving model, 第12轮... Epoch 13/20----train loss: 0.0071, train acc: 0.9974 val loss: 0.0280, val acc: 0.9938 Epoch 14/20----train loss: 0.0036, train acc: 0.9991 val loss: 0.0420, val acc: 0.9906 Epoch 15/20----train loss: 0.0045, train acc: 0.9991 val loss: 0.0224, val acc: 0.9969 Saving model, 第15轮... Epoch 16/20----train loss: 0.0020, train acc: 1.0000 val loss: 0.0174, val acc: 0.9906 Epoch 17/20----train loss: 0.0031, train acc: 0.9991 val loss: 0.0382, val acc: 0.9885 Epoch 18/20----train loss: 0.0014, train acc: 1.0000 val loss: 0.0182, val acc: 0.9969 Epoch 19/20-----

```
train loss: 0.0002, train acc: 1.0000 val loss: 0.0329, val acc: 0.9938 Epoch 20/20------
train loss: 0.0013, train acc: 1.0000 val loss: 0.0202, val acc: 0.9938 最高精确值: 0.996875 Done!
```

绘制训练曲线

```
In [41]: import matplotlib.pyplot as plt
         def plot_training_curves(loss_train_list, acc_train_list, loss_val_list, acc_val
            绘制训练过程中的损失值曲线和精确度曲线
            epochs = range(1, len(loss_train_list) + 1) # x 轴: 训练轮次
            # 绘制损失值曲线
            plt.figure(figsize=(12, 6))
            plt.subplot(1, 2, 1) # 第一张子图
            plt.plot(epochs, loss_train_list, label="Training Loss", marker='o', color='
            plt.plot(epochs, loss_val_list, label="Validation Loss", marker='o', color='
            plt.title("Loss Curve")
            plt.xlabel("Epochs")
            plt.ylabel("Loss")
            plt.legend()
            plt.grid(True)
            # 绘制精确度曲线
            plt.subplot(1, 2, 2) # 第二张子图
            plt.plot(epochs, acc_train_list, label="Training Accuracy", marker='o', cold
            plt.plot(epochs, acc_val_list, label="Validation Accuracy", marker='o', colo
            plt.title("Accuracy Curve")
            plt.xlabel("Epochs")
            plt.ylabel("Accuracy")
            plt.legend()
            plt.grid(True)
            #显示图形
            plt.tight layout()
            plt.show()
```

In [42]: plot_training_curves(loss_train_list, acc_train_list, loss_val_list, acc_val_lis



测试模型

```
In [45]:
        import random
        # 定义一个函数,绘制图像和标题
        def show_images_with_predictions(imgs, preds, labels, num_rows, num_cols, classe
            """绘制图像列表,并显示预测结果与真实标签"""
            figsize = (num_cols * scale, num_rows * scale)
            _, axes = plt.subplots(num_rows, num_cols, figsize=figsize)
            axes = axes.flatten() # 将 axes 从二维数组转换为一维数组
            for i, (ax, img, pred, label) in enumerate(zip(axes, imgs, preds, labels)):
                # 反归一化后转换为 numpy
                img = img.permute(1, 2, 0).numpy() # (C, H, W) -> (H, W, C)
                ax.imshow(img)
                ax.axes.get_xaxis().set_visible(False) # 隐藏 X 轴
                ax.axes.get_yaxis().set_visible(False) # 隐藏 Y 轴
                ax.set_title(f"Truth: {classes[label]} \nPred: {classes[pred]}")
            plt.tight_layout()
            plt.show()
        # 加载已训练的模型
        model = torch.load('save_model/resnet18_best.pt')
        model = model.to(device)
        classes = ['cat', 'dog']
```

```
model.eval()
imgs, preds, labels = [], [], []
# 批量处理数据
with torch.no grad():
   for _ in range(10): # 获取前 10 张图片
       i=random.randint(0, len(val_dataset)-1)
       img, label = val_dataset[i][0], val_dataset[i][1]
       img_with_batch = img.unsqueeze(0).to(device) #添加 batch 维度
       output = model(img_with_batch) # 模型推理
       pred = torch.max(output, 1)[1].item() # 获取预测类别索引
       imgs.append(img) # 原始图像(张量)
       preds.append(pred) # 预测结果
       labels.append(label) # 真实标签
# 显示图片及预测结果
num rows = 2
num_cols = 5
show_images_with_predictions(imgs, preds, labels, num_rows, num_cols, classes)
```

C:\Users\SUN\AppData\Local\Temp\ipykernel_24708\836601485.py:20: FutureWarning: Y ou are using `torch.load` with `weights_only=False` (the current default value), which uses the default pickle module implicitly. It is possible to construct mali cious pickle data which will execute arbitrary code during unpickling (See http s://github.com/pytorch/pytorch/blob/main/SECURITY.md#untrusted-models for more de tails). In a future release, the default value for `weights_only` will be flipped to `True`. This limits the functions that could be executed during unpickling. Ar bitrary objects will no longer be allowed to be loaded via this mode unless they are explicitly allowlisted by the user via `torch.serialization.add_safe_globals . We recommend you start setting `weights_only=True` for any use case where you don't have full control of the loaded file. Please open an issue on GitHub for an y issues related to this experimental feature. model = torch.load('save_model/resnet18_best.pt') Clipping input data to the valid range for imshow with RGB data ([0..1] for float s or [0..255] for integers). Clipping input data to the valid range for imshow with RGB data ([0..1] for float s or [0..255] for integers). Clipping input data to the valid range for imshow with RGB data ([0..1] for float s or [0..255] for integers). Clipping input data to the valid range for imshow with RGB data ([0..1] for float s or [0..255] for integers). Clipping input data to the valid range for imshow with RGB data ([0..1] for float s or [0..255] for integers). Clipping input data to the valid range for imshow with RGB data ([0..1] for float s or [0..255] for integers). Clipping input data to the valid range for imshow with RGB data ([0..1] for float s or [0..255] for integers). Clipping input data to the valid range for imshow with RGB data ([0..1] for float s or [0..255] for integers). Clipping input data to the valid range for imshow with RGB data ([0..1] for float s or [0..255] for integers). Clipping input data to the valid range for imshow with RGB data ([0..1] for float s or [0..255] for integers).

Truth: cat Pred: cat



Truth: dog Pred: dog



Truth: cat Pred: cat



Truth: cat Pred: cat



Truth: dog Pred: dog



Truth: dog Pred: dog



Truth: cat Pred: cat



Truth: dog Pred: dog



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