

基于差异矩阵和矩阵度量的行人重识别方法

Person Re-identification via Discrepancy Matrix and Matrix Metric



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研究背景



研究动机和方法



实验结果和分析



查找周克华

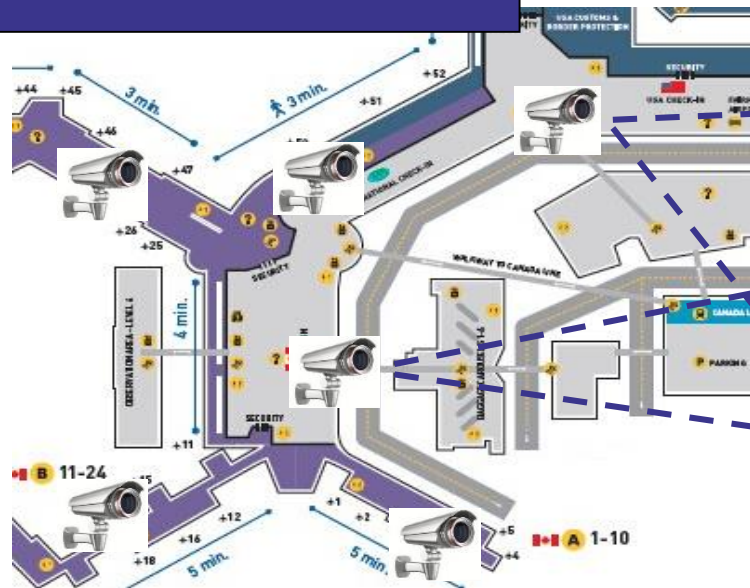


1500 个警员, 1个月时间

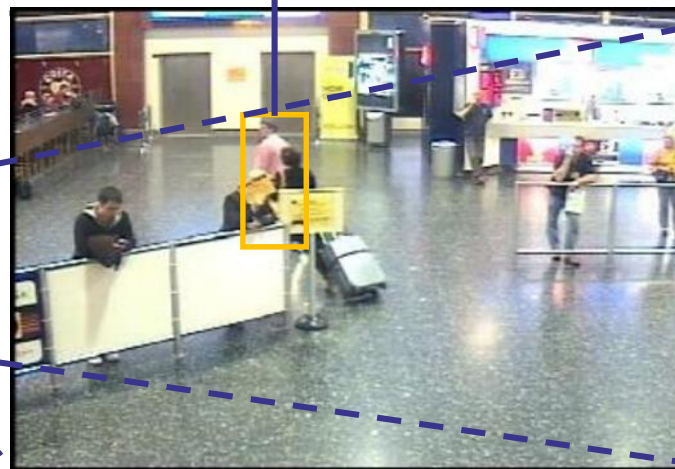


329 段视频片段

Person Re-identification



是同一人吗?



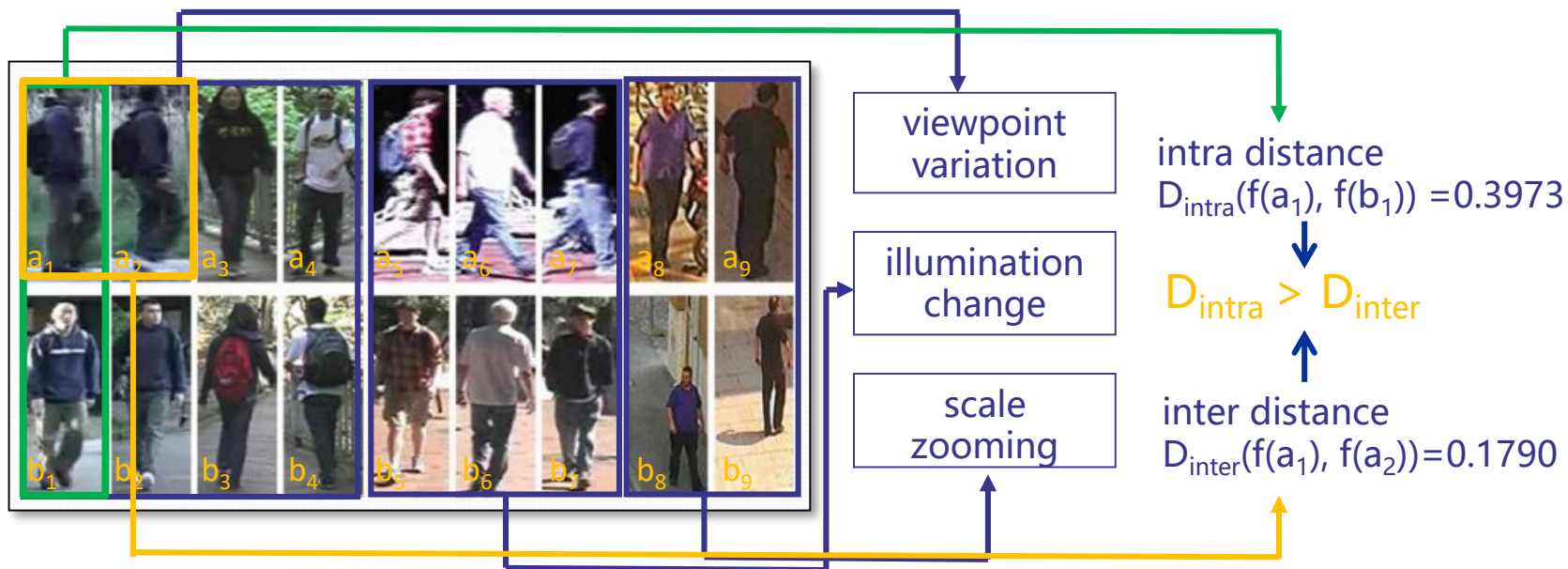
摄像头 a



摄像头 b



挑战



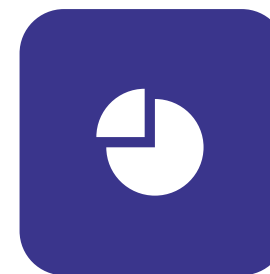
研究方向



行人表征



距离度量



排序优化



行人表征

- **Zheng Wang**, Ruimin Hu, et al., Scale-adaptive Low-resolution Person Re-identification via Learning A Discriminating Surface, International Joint Conference on Artificial Intelligence (**IJCAI**), pp.2669-2675, Aug, 2016
- **Zheng Wang**, Ruimin Hu, et al., Multi-Level Fusion for Person Re-identification with Incomplete Marks, ACM international Conference on Multimedia (**ACM MM**), pp.1267-1270, Oct, 2015
- Mang Ye, Chao Liang, **Zheng Wang**, et al., Specific Person Retrieval via Incomplete Text Description, ACM International Conference on Multimedia Retrieval (**ICMR**), pp.547-550, Jun, 2015



A vertical vector x_p^A with N_f elements, represented by a column of 10 light blue squares.



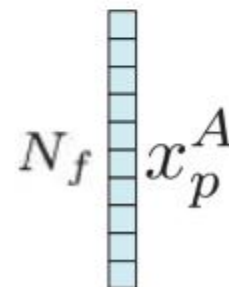
x_q^B



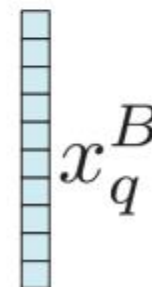
距离度量

- **Zheng Wang**, Ruimin Hu, Yi Yu, Junjun Jiang, Jiayi Ma, Shin'ichi Satoh, Statistical Inference of Gaussian-Laplace Distribution for Person Verification, ACM international Conference on Multimedia (**ACM MM**), 2017
- **Zheng Wang**, Ruimin Hu, et al. , Zero-Shot Person Re-identification via Cross-View Consistency, **IEEE Transactions on Multimedia**, Vol 18, No 2, pp.260-272, Feb, 2016
- **Zheng Wang**, Ruimin Hu, et al., TAICHI Distance for Person Re-identification, International Conference on Acoustics, Speech and Signal Processing (**ICASSP**), Mar, 2017
- Jin Wang, **Zheng Wang**, et al., DeepList: Learning Deep Features with Adaptive Listwise Constraint for Person Re-identification, **IEEE Transactions on Circuits and Systems for Video Technology**, Vol 27, No 3, pp.513 - 524, Mar, 2017

Camera A



Camera B



$$d(x_p^A, x_q^B) = (x_p^A - x_q^B)^\top \mathbf{M} (x_p^A - x_q^B)$$

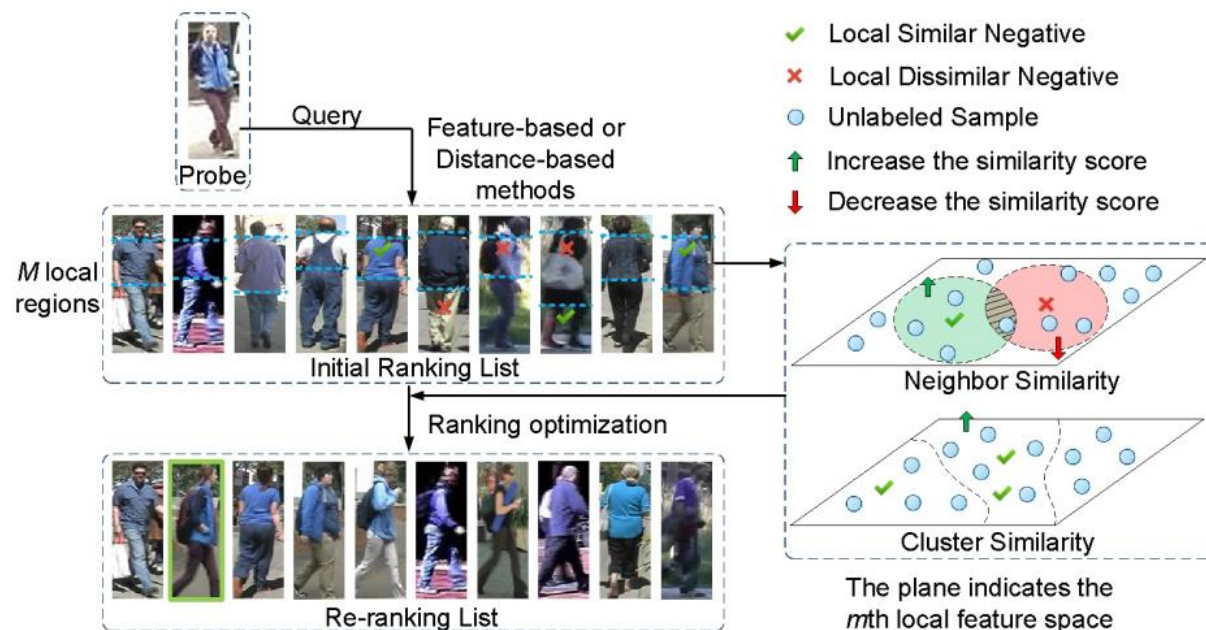
$$\mathbf{M} = \mathbf{L}^\top \mathbf{L}$$

$$d(x_p^A, x_q^B) = \|\mathbf{L}(x_p^A - x_q^B)\|^2$$



排序优化

- **Zheng Wang**, Ruimin Hu, et al., Region-based Interactive Ranking Optimization For Person Re-identification, Pacific-Rim Conference on Multimedia (**PCM**), pp.1-10, Dec, 2014 (最佳论文奖)
- Mang Ye, Chao Liang, **Zheng Wang**, et al., Ranking Optimization for Person Re-identification via Similarity and Dissimilarity, ACM international Conference on Multimedia (**ACM MM**), pp.1239-1242, Oct, 2015
- Mang Ye, Chao Liang, Yi Yu, **Zheng Wang**, et al., Person Re-identification via Ranking Aggregation of Similarity Pulling and Dissimilarity Pushing, **IEEE Transactions on Multimedia**, Vol 18, No 12, pp.2553-2566, Dec, 2016



Region-based Interactive Re-ranking



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实验结果和分析



从特性表示到差异表示

by characteristic



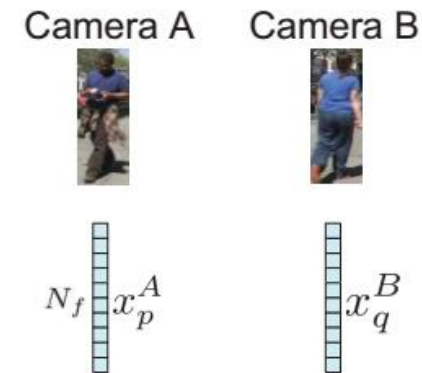
猜想:

- (1) 抵消了摄像头变化?
- (2) 能突出细节?

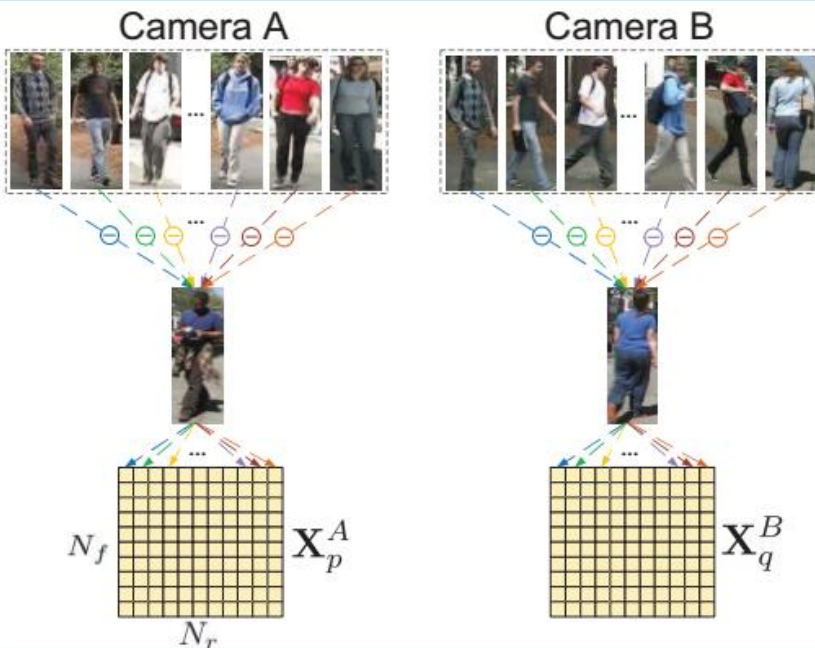


差异表示更好

Traditional Methods



The Proposed Method



$$f_i^A - f_i^B = v + \sigma_i$$

$$\mathbf{X}_p^A = [x_p^A - f_1^A; x_p^A - f_2^A; \dots; x_p^A - f_{N_r}^A]$$

$$\mathbf{X}_q^B = [x_q^B - f_1^B; x_q^B - f_2^B; \dots; x_q^B - f_{N_r}^B]$$

跨摄像头的成像变化

行人个体差异

$$f_p^A - f_q^B = v + \sigma$$

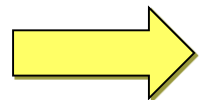
$$\mathbf{X}_p^A - \mathbf{X}_q^B = [\sigma - \sigma_1; \sigma - \sigma_2; \dots; \sigma - \sigma_{N_r}]$$

Method (rank@)	1	2	3	4	5	6	7	8	9	10
hand-crafted feature vector	21.3	29.7	34.6	39.4	43.9	47.5	49.9	53.3	55.6	57.6
hand-crafted discrepancy matrix	22.9	33.4	39.5	43.7	46.5	49	51.9	54.7	56.9	59.7
deep-learned feature vector	29.3	37.9	44.5	49.5	53.5	57.6	61.0	62.9	65.6	67.7
deep-learned discrepancy matrix	31.8	43.1	49.8	54.2	57.9	61.1	63.2	65.3	68.3	69.7



从一个投影到两个投影

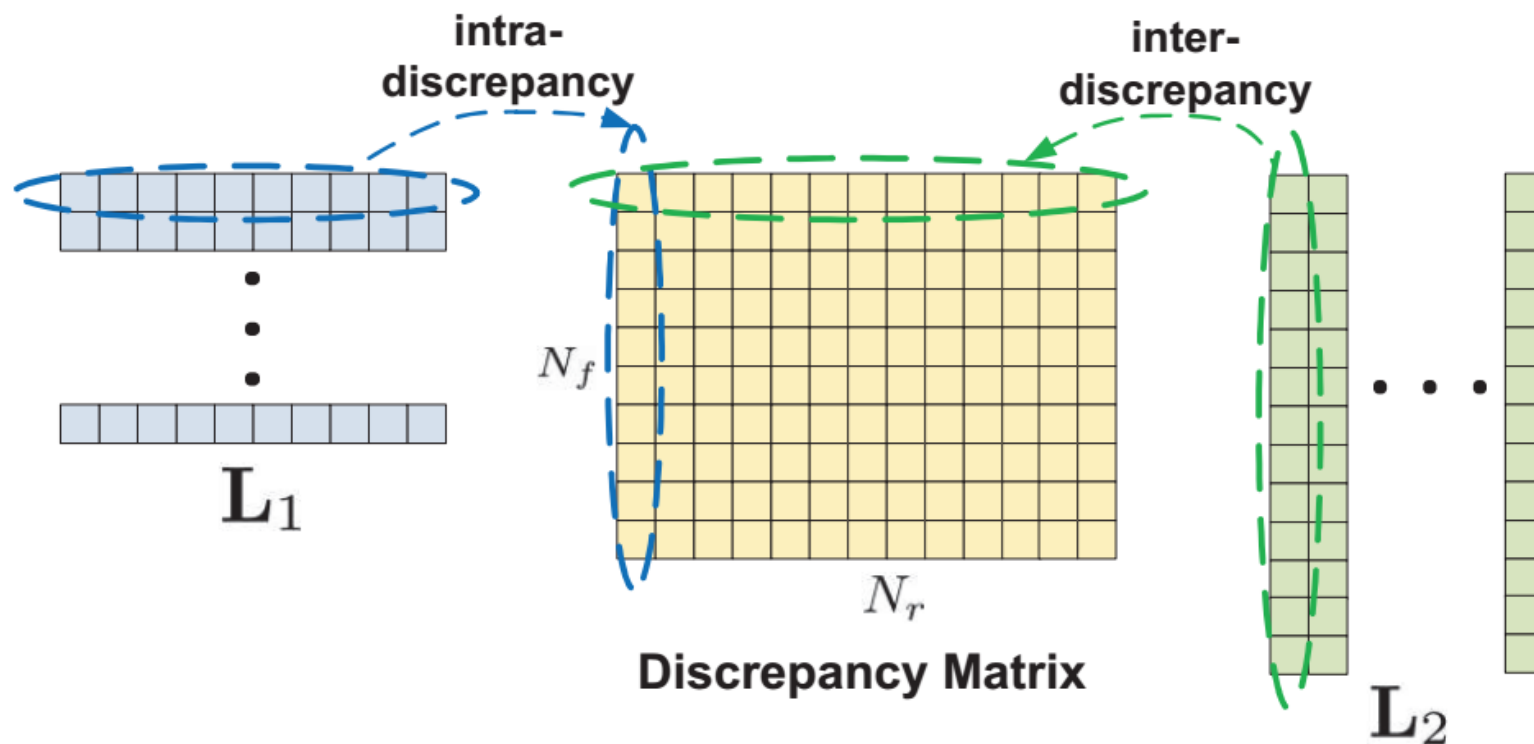
$$d(x_p^A, x_q^B) = \|\mathbf{L}(x_p^A - x_q^B)\|^2$$

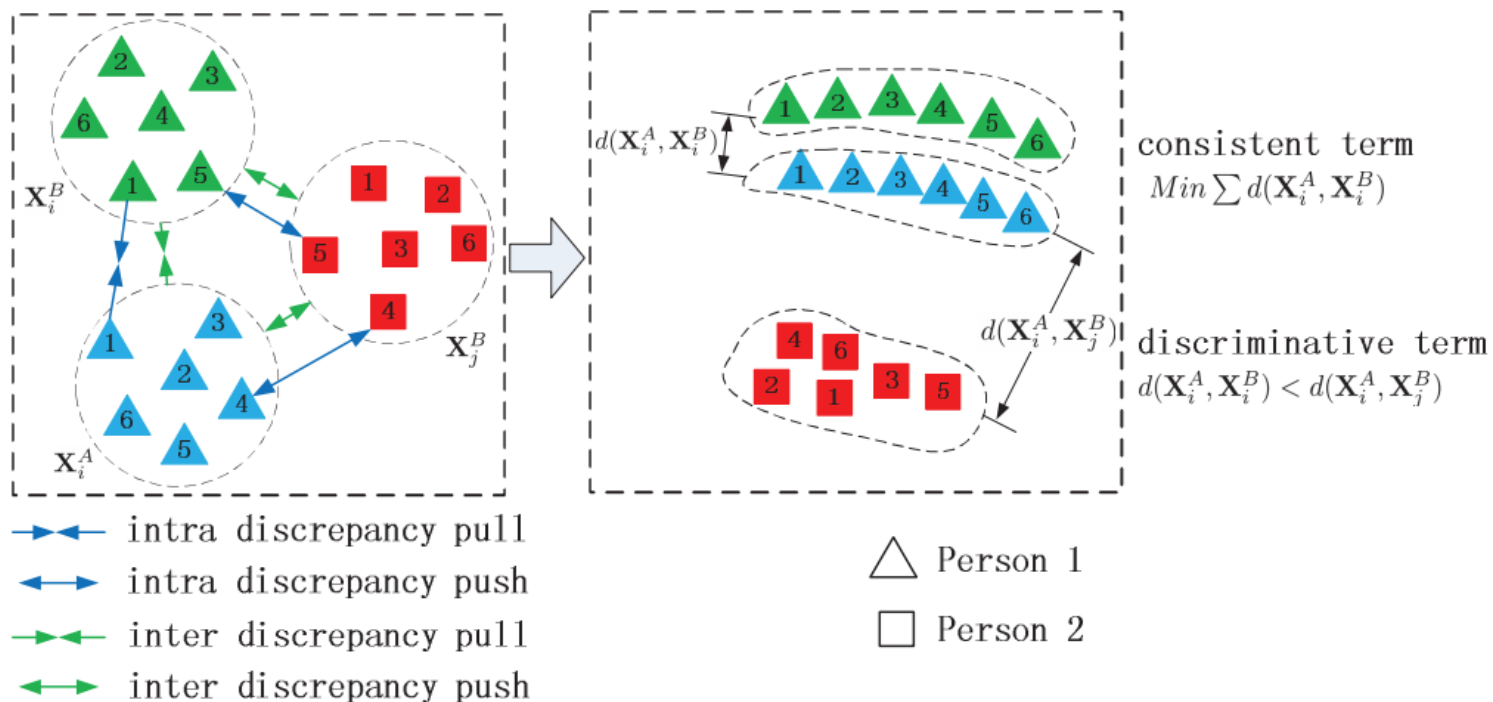


$$d(\mathbf{X}_p^A, \mathbf{X}_q^B) = \|\mathbf{L}_1(\mathbf{X}_p^A - \mathbf{X}_q^B)\mathbf{L}_2\|_F^2$$

差异内投影矩阵

差异间投影矩阵





$$E_{con}(\mathbf{L}_1, \mathbf{L}_2) = \frac{1}{M} \sum_{i=1}^M d(\mathbf{X}_i^A, \mathbf{X}_i^B)$$

$$E_{dis}(\mathbf{L}_1, \mathbf{L}_2) = \frac{1}{S} \sum_{k=1}^S l_{\beta}(e(s_k))$$

$$e(s_k) = d(\mathbf{X}_i^A, \mathbf{X}_i^B) - d(\mathbf{X}_i^A, \mathbf{X}_j^B)$$

$$l_{\beta}(z) = \frac{1}{\beta} \log(1 + e^{\beta z})$$

$$E_{spr}(\mathbf{L}_2) = \|\mathbf{L}_2\|_{2,1}$$

$$E(\mathbf{L}_1, \mathbf{L}_2) = E_{con}(\mathbf{L}_1, \mathbf{L}_2) + E_{dis}(\mathbf{L}_1, \mathbf{L}_2) + \mu E_{spr}(\mathbf{L}_2)$$

一致項

判別項

L_2 稀疏項



迭代交替优化

$$\frac{\partial E(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_1} = \frac{\partial E_{con}(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_1} + \frac{\partial E_{dis}(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_1}$$

$$\frac{\partial E(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_2} = \frac{\partial E_{con}(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_2} + \frac{\partial E_{dis}(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_2} + \mu \frac{\partial E_{spr}(\mathbf{L}_2)}{\partial \mathbf{L}_2}$$

$$\frac{\partial E_{con}(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_1} = \frac{2}{M} \sum_{i=1}^M \mathbf{L}_1 \mathbf{Z}_i \mathbf{L}_2 \mathbf{L}_2^\top \mathbf{Z}_i^\top$$

$$\frac{\partial E_{con}(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_2} = \frac{2}{M} \sum_{i=1}^M \mathbf{Z}_i^\top \mathbf{L}_1^\top \mathbf{L}_1 \mathbf{Z}_i \mathbf{L}_2$$

$$\frac{\partial E_{dis}(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_1} = \frac{2}{S} \sum_{k=1}^S g(e(s_k)) (\mathbf{L}_1 \mathbf{U}_k \mathbf{L}_2 \mathbf{L}_2^\top \mathbf{U}_k^\top - \mathbf{L}_1 \mathbf{V}_k \mathbf{L}_2 \mathbf{L}_2^\top \mathbf{V}_k^\top)$$

$$\frac{\partial E_{dis}(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_2} = \frac{2}{S} \sum_{k=1}^S g(e(s_k)) (\mathbf{U}_k^\top \mathbf{L}_1^\top \mathbf{L}_1 \mathbf{U}_k \mathbf{L}_2 - \mathbf{V}_k^\top \mathbf{L}_1^\top \mathbf{L}_1 \mathbf{V}_k \mathbf{L}_2)$$

$$\frac{\partial E_{spr}(\mathbf{L}_2)}{\partial \mathbf{L}_2} = 2\mathbf{D}\mathbf{L}_2$$

Algorithm 1 Learning the matrix metric \mathbf{L}_1 and \mathbf{L}_2

Input: The training data: Positive samples with pair form $\{(\mathbf{X}_i^A, \mathbf{X}_i^B)\}$, and Negative Samples with triple form $\{(\mathbf{X}_i^A, \mathbf{X}_i^B, \mathbf{X}_j^B)_k\}$.

Output: The optimal matrix \mathbf{L}_1^* and \mathbf{L}_2^* .

- 1: Initialize \mathbf{L}_1 and \mathbf{L}_2 ;
- 2: **for** $n = 1$ to $MaxIter$ **do**
- 3: Fix \mathbf{L}_2^n ;
- 4: Compute $\nabla E(\mathbf{L}_1) = \frac{\partial E(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_1}$ as Eq. 8, Eq. 10, and Eq. 12;
- 5: Choose a proper step λ_1 as [61];
- 6: Compute $\mathbf{L}_1^{n+1} = \mathbf{L}_1^n - \lambda_1 \nabla E(\mathbf{L}_1)$;
- 7: Fix \mathbf{L}_1^{n+1} ;
- 8: Compute $\nabla E(\mathbf{L}_2) = \frac{\partial E(\mathbf{L}_1, \mathbf{L}_2)}{\partial \mathbf{L}_2}$ as Eq. 9, Eq. 11, and Eq. 13;
- 9: Choose a proper step λ_2 as [61];
- 10: Compute $\mathbf{L}_2^{n+1} = \mathbf{L}_2^n - \lambda_2 \nabla E(\mathbf{L}_2)$;
- 11: **if** converge **then**
- 12: break;
- 13: **end if**
- 14: **end for**



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研究动机和方法



实验结果和分析



(a) VIPeR dataset

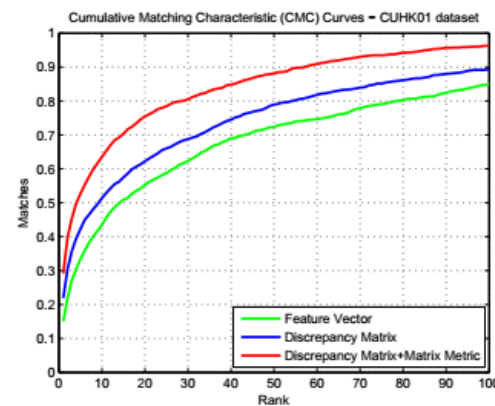
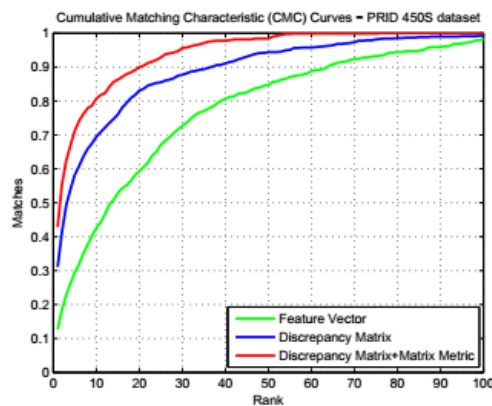
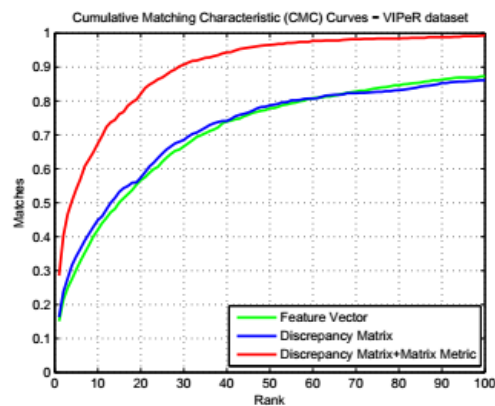


(b) PRID 450S dataset

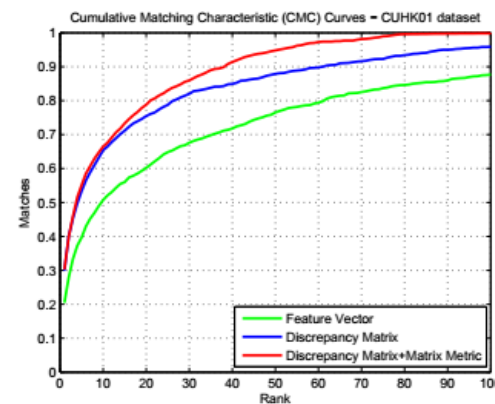
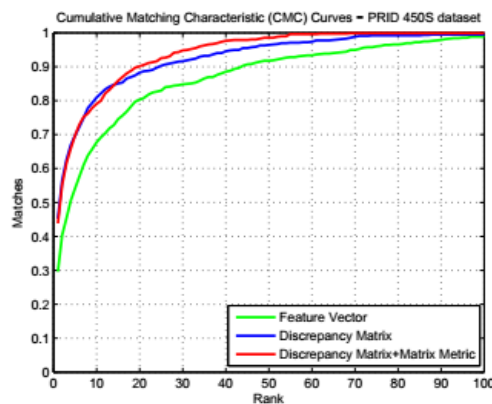
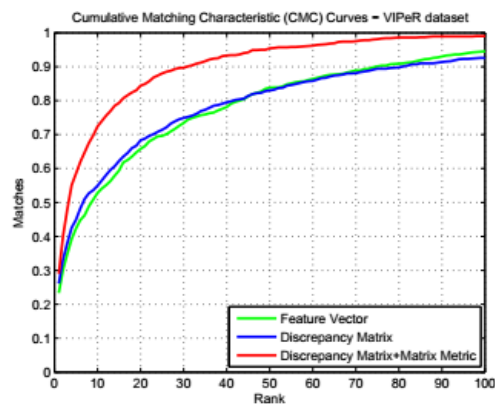


(c) CUHK01 dataset

GoG



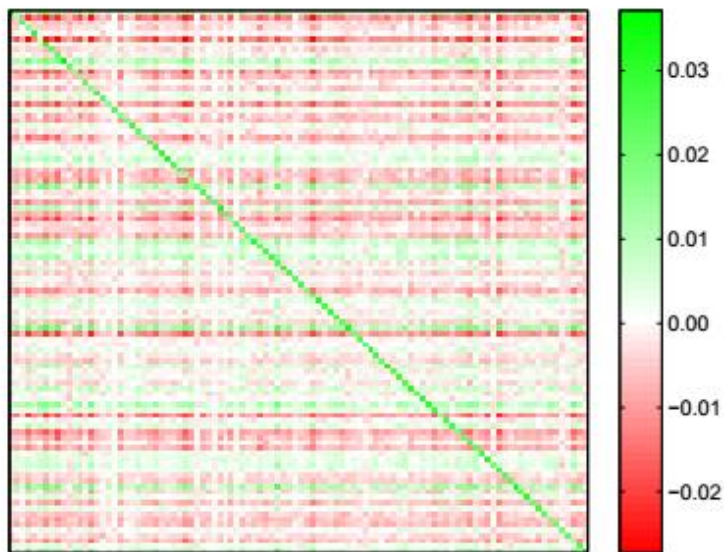
FTCNN



(1) 差异矩阵
(2) 矩阵度量投影
都有用

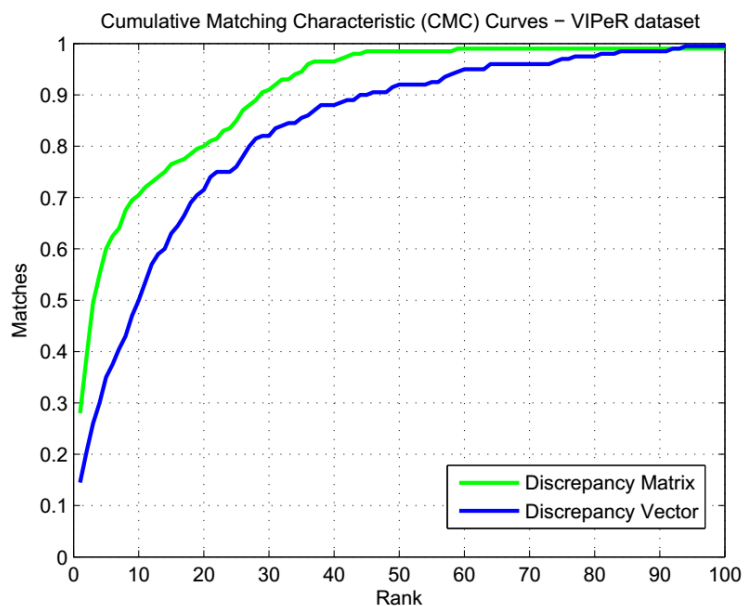


差异间投影的稀疏性

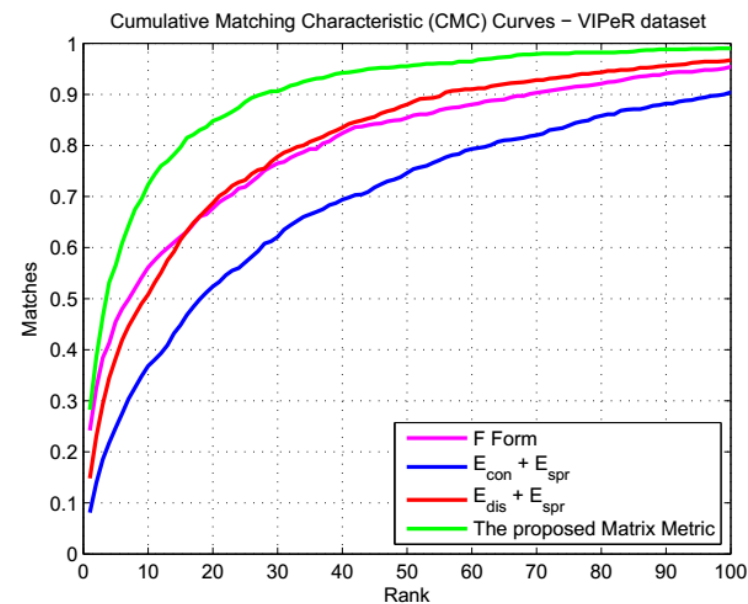


	Selected reference persons with high weights	Selected reference persons with low weights
Camera A		
Camera B		

向量 V.S. 矩阵



判别项和一致项





与前沿方法的比较

ViPER

Method (rank@)	1	5	10	20
ELF [22]	12.0	-	43.0	60.0
BiCov [39]	20.6	43.2	56.1	68.0
SDALF [23]	19.9	38.4	49.4	66.0
eSDC [42]	26.3	46.4	58.6	72.8
MidFilter [64]	29.1	52.5	65.9	79.9
SCNCD [24]	37.8	68.5	81.2	90.4
RD [37]	33.3	65.1	78.3	88.5
PRDC [19]	15.7	38.4	53.9	70.1
KISSME [33]	19.6	48.0	62.2	77.0
PCCA [49]	19.3	48.9	64.9	80.3
LADF [34]	30.0	64.0	80.0	92.0
LOMO+XQDA [25]	40.0	68.5	80.5	91.0
DeepMetric [65]	28.2	59.3	73.4	86.4
DeepRanking [66]	38.4	69.2	81.3	90.4
DeepFeature+RDC [28]	40.5	60.8	70.4	84.4
DeepList [30]	40.5	69.1	80.1	91.2
LOMO+NFST [51]	42.2	71.4	82.9	92.0
(1) GoG [26]+XQDA	37.3	67.4	77.2	89.6
(2) FTCNN [56]+XQDA	31.2	59.8	74.0	83.5
(3) FTCNN+DM ³	37.3(↑6.1)	67.4(↑7.6)	80.3(↑6.3)	89.5(↑6.0)
Combine (1) and (2)	38.3	67.2	77.0	89.3
Combine (1) and (3)	42.7	74.3	85.1	93.1

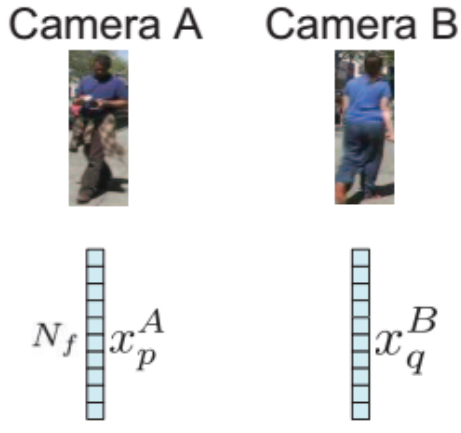
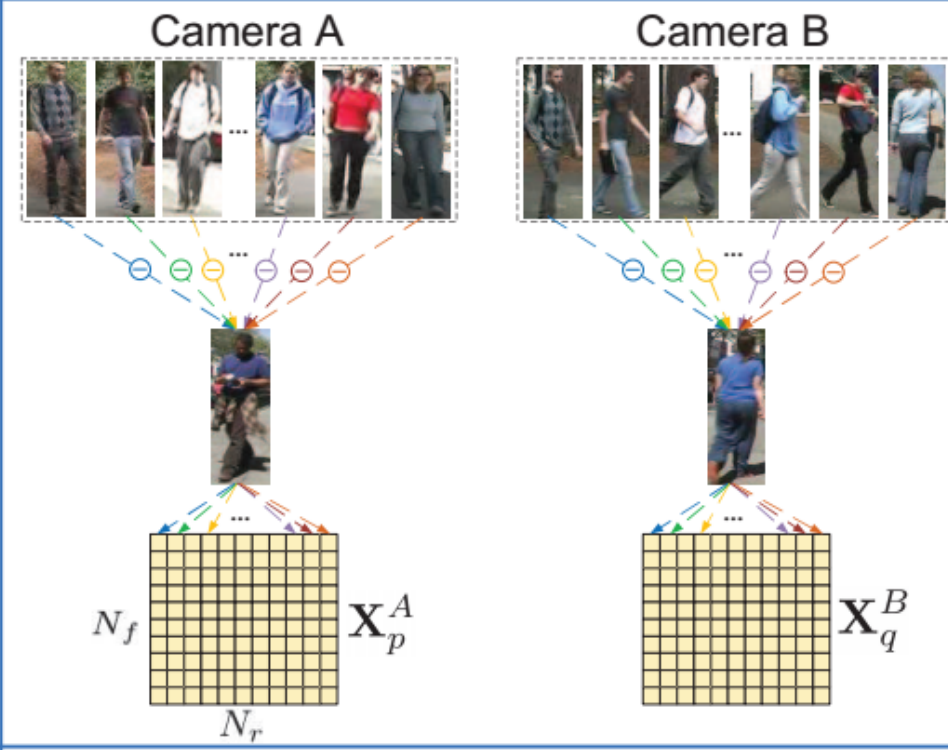
PRID 450S

Method (rank@)	1	5	10	20
SCNCD [24]	41.6	68.9	79.4	87.8
KISSME [33]	33.0	59.8	71.0	79.0
CBRA [67]	26.4	57.1	71.0	83.2
CSL [68]	44.4	71.6	82.2	89.8
Mirror [69]	55.4	79.3	87.8	93.9
DRML [70]	56.4	-	82.2	90.2
(1) GoG [26]+XQDA	51.6	76.8	88.8	94.2
(2) FTCNN [56]+XQDA	50.2	74.2	84.8	93.7
(3) FTCNN+DM ³	56.7(↑6.5)	83.1(↑8.9)	88.4(↑3.6)	94.7(↑1.0)
Combine (1) and (2)	51.8	76.9	87.0	94.2
Combine (1) and (3)	61.0	85.8	92.0	96.7

CUHK01

Method (rank@)	1	5	10	20
SDALF [23]	9.9	22.6	30.3	41.0
TML [63]	20.0	43.5	56.0	69.3
SalMatch [71]	28.4	45.8	55.7	67.9
MidFilter [64]	34.3	55.1	65.0	74.9
RD [37]	31.1	-	68.5	79.1
ImprovedDeep [72]	47.5	71.0	80.0	-
(1) GoG [26]+XQDA	44.5	71.1	78.1	89.0
(2) FTCNN [56]+XQDA	41.1	63.5	73.6	85.8
(3) FTCNN+DM ³	43.7(↑2.6)	70.1(↑6.6)	77.4(↑3.8)	88.7(↑2.9)
Combine (1) and (2)	42.1	70.1	78.3	89.6
Combine (1) and (3)	49.7	77.3	86.1	91.4



	Traditional Methods	The Proposed Method
Feature description	<p>Camera A Camera B</p>  <p>N_f x_p^A x_q^B</p>	<p>Camera A Camera B</p>  <p>N_f \mathbf{X}_p^A \mathbf{X}_q^B N_r</p>
Distance metric	$d(x_p^A, x_q^B) = \ \mathbf{L}(x_p^A - x_q^B)\ ^2$	$d(\mathbf{X}_p^A, \mathbf{X}_q^B) = \ \mathbf{L}_1(\mathbf{X}_p^A - \mathbf{X}_q^B)\mathbf{L}_2\ _F^2$

从特性向量到差异矩阵

从向量度量到矩阵度量

谢谢！