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import matplotlib.pyplot as plt
class TwoLayerNet(object):
 A two-layer fully-connected neural network. The net has an input dimension of
 N, a hidden layer dimension of H, and performs classification over C classes.
 We train the network with a softmax loss function and L2 regularization on the
 weight matrices. The network uses a ReLU nonlinearity after the first fully
 connected layer.
 In other words, the network has the following architecture:
 input - fully connected layer - ReLU - fully connected layer - softmax
 The outputs of the second fully-connected layer are the scores for each class.
 def __init__(self, input_size, hidden_size, output_size, std=1e-4):
   Initialize the model. Weights are initialized to small random values and
   biases are initialized to zero. Weights and biases are stored in the
   variable self.params, which is a dictionary with the following keys:
   W1: First layer weights; has shape (H, D)
   b1: First layer biases; has shape (H,)
   W2: Second layer weights; has shape (C, H)
   b2: Second layer biases; has shape (C,)
   Inputs:
   - input_size: The dimension D of the input data.
   - hidden_size: The number of neurons H in the hidden layer.
   - output_size: The number of classes C.
   self.params = {}
   self.params['W1'] = std * np.random.randn(hidden_size, input_size)
   self.params['b1'] = np.zeros(hidden_size)
   self.params['W2'] = std * np.random.randn(output_size, hidden_size)
   self.params['b2'] = np.zeros(output_size)
 def loss(self, X, y=None, reg=0.0):
   Compute the loss and gradients for a two layer fully connected neural
   network.
   Inputs:
   X: Input data of shape (N, D). Each X[i] is a training sample.
   - y: Vector of training labels. y[i] is the label for X[i], and each y[i] is
     an integer in the range 0 \le y[i] < C. This parameter is optional; if it
     is not passed then we only return scores, and if it is passed then we
     instead return the loss and gradients.
   - reg: Regularization strength.
   Returns:
   If y is None, return a matrix scores of shape (N, C) where scores[i, c] is
   the score for class c on input X[i].
   If y is not None, instead return a tuple of:
   - loss: Loss (data loss and regularization loss) for this batch of training
     samples.
   - grads: Dictionary mapping parameter names to gradients of those parameters
     with respect to the loss function; has the same keys as self.params.
   # Unpack variables from the params dictionary
   W1, b1 = self.params['W1'], self.params['b1']
   W2, b2 = self.params['W2'], self.params['b2']
   N, D = X_shape
   # Compute the forward pass
   scores = None
   # YOUR CODE HERE:
   # Calculate the output scores of the neural network. The result
      should be (N, C). As stated in the description for this class,
      there should not be a ReLU layer after the second FC layer.
      The output of the second FC layer is the output scores. Do not
      use a for loop in your implementation.
   relu = lambda x: np.maximum(0, x)
   z1 = X @ W1.T + b1
   a1 = relu(z1)
   z2 = a1 @ W2 T + b2
   scores = z2
   # END YOUR CODE HERE
   # If the targets are not given then jump out, we're done
   if y is None:
     return scores
   # Compute the loss
   loss = None
   # YOUR CODE HERE:
   # Calculate the loss of the neural network. This includes the
      softmax loss and the L2 regularization for W1 and W2. Store the
     total loss in teh variable loss. Multiply the regularization
     loss by 0.5 (in addition to the factor reg).
   # ================================= #
   # Softmax Loss Calc
   softmax_loss = np.sum(np.log(np.sum(np.exp(scores), axis = 1)) - scores[np.arange(N), y])
   # L2 regularization
   l2\_reg = 0.5 * reg * (np.linalg.norm(W1)**2 + np.linalg.norm(W2)**2)
   # Final Loss
   loss = softmax_loss / N + l2_reg
   # END YOUR CODE HERE
   # =================== #
   grads = {}
   # YOUR CODE HERE:
   # Implement the backward pass. Compute the derivatives of the
   # weights and the biases. Store the results in the grads
   # dictionary. e.g., grads['W1'] should store the gradient for
      W1, and be of the same size as W1.
   # Used denominator layout
   # Loss dL/dz2
   dL_dz2 = np.exp(scores) / np.sum(np.exp(scores), axis=1, keepdims=True)
   dL_dz2[np.arange(N), y] -= 1
   dL_dz2 = dL_dz2/N \# normalize by samples
   # Loss dL/da1 = dz2/da1 * dL/dz2
   dL_da1 = (W2.T @ dL_dz2.T).T
   # Loss dL/dz1 = da1/dz1 * dL/da1
   dL_dz1 = (z1 > 0) * dL_da1
   grads['W2'] = dL_dz2.T @ a1 + (reg * W2) # dL/dW2
   grads['b2'] = np.sum(dL_dz2,axis=0)
                                                 # dL/db2
   grads['W1'] = (X_T @ dL_dz1)_T + (reg * W1) # dL/dW1
   grads['b1'] = np.sum(dL_dz1,axis=0)
                                              # dL/db1
   # END YOUR CODE HERE
   return loss, grads
 def train(self, X, y, X_val, y_val,
          learning_rate=1e-3, learning_rate_decay=0.95,
          reg=1e-5, num_iters=100,
          batch_size=200, verbose=False):
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   Train this neural network using stochastic gradient descent.
   Inputs:

    X: A numpy array of shape (N, D) giving training data.

   - y: A numpy array f shape (N,) giving training labels; y[i] = c means that
    X[i] has label c, where 0 <= c < C.
   X_val: A numpy array of shape (N_val, D) giving validation data.

    y_val: A numpy array of shape (N_val,) giving validation labels.

    learning_rate: Scalar giving learning rate for optimization.

   - learning_rate_decay: Scalar giving factor used to decay the learning rate
     after each epoch.
   reg: Scalar giving regularization strength.
   - num_iters: Number of steps to take when optimizing.
   batch_size: Number of training examples to use per step.

    verbose: boolean; if true print progress during optimization.

   num_train = X.shape[0]
   iterations_per_epoch = max(num_train / batch_size, 1)
   # Use SGD to optimize the parameters in self.model
   loss_history = []
   train_acc_history = []
   val_acc_history = []
   for it in np.arange(num_iters):
     X_batch = None
     y batch = None
     # YOUR CODE HERE:
     # Create a minibatch by sampling batch_size samples randomly.
     samples = np.random.choice(X.shape[0], batch_size)
     X_batch = X[samples,:]
     y_batch = y[samples]
     # END YOUR CODE HERE
     # Compute loss and gradients using the current minibatch
     loss, grads = self.loss(X_batch, y=y_batch, reg=reg)
     loss_history.append(loss)
     # YOUR CODE HERE:
       Perform a gradient descent step using the minibatch to update
        all parameters (i.e., W1, W2, b1, and b2).
     # Gradient descent step
     self.params['W1'] -= learning_rate * grads['W1']
     self.params['W2'] -= learning_rate * grads['W2']
     self.params['b1'] -= learning_rate * grads['b1']
     self.params['b2'] -= learning_rate * grads['b2']
     # END YOUR CODE HERE
     if verbose and it % 100 == 0:
      print('iteration {} / {}: loss {}'.format(it, num_iters, loss))
     # Every epoch, check train and val accuracy and decay learning rate.
     if it % iterations_per_epoch == 0:
       # Check accuracy
       train_acc = (self.predict(X_batch) == y_batch).mean()
       val_acc = (self.predict(X_val) == y_val).mean()
       train_acc_history.append(train_acc)
       val_acc_history.append(val_acc)
      # Decay learning rate
       learning_rate *= learning_rate_decay
   return {
     'loss_history': loss_history,
     'train_acc_history': train_acc_history,
     'val_acc_history': val_acc_history,
 def predict(self, X):
   Use the trained weights of this two-layer network to predict labels for
   data points. For each data point we predict scores for each of the C
   classes, and assign each data point to the class with the highest score.
   Inputs:

    X: A numpy array of shape (N, D) giving N D-dimensional data points to

     classify.
   Returns:
   - y_pred: A numpy array of shape (N,) giving predicted labels for each of
     the elements of X. For all i, y_pred[i] = c means that X[i] is predicted
     to have class c, where 0 <= c < C.
   y_pred = None
   # YOUR CODE HERE:
     Predict the class given the input data.
   # Forward prop and argmax of scores
   z1 = X @ self.params['W1'].T + self.params['b1']
   a1 = np.maximum(0,z1)
   z2 = a1 @ self.params['W2'].T + self.params['b2']
   y_pred = np.argmax(z2, axis=1)
   # END YOUR CODE HERE
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import numpy as np

return y\_pred