



연세대학교

Yonsei Where we make History

Maker Space Lecture

Week 1 – What is Arduino?



YONSEI, where we make *history*

<https://github.com/SunghaWoo/Arduino-Seminar>

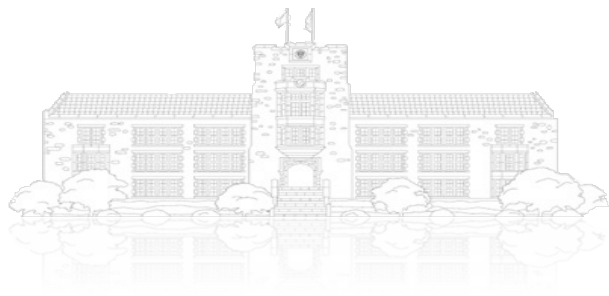
연세대학교 기계공학과 우성하

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연세대학교

Yonsei Where we make History



YONSEI, where we make *history*

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1. Introduction to Arduino
2. Arduino Grammar
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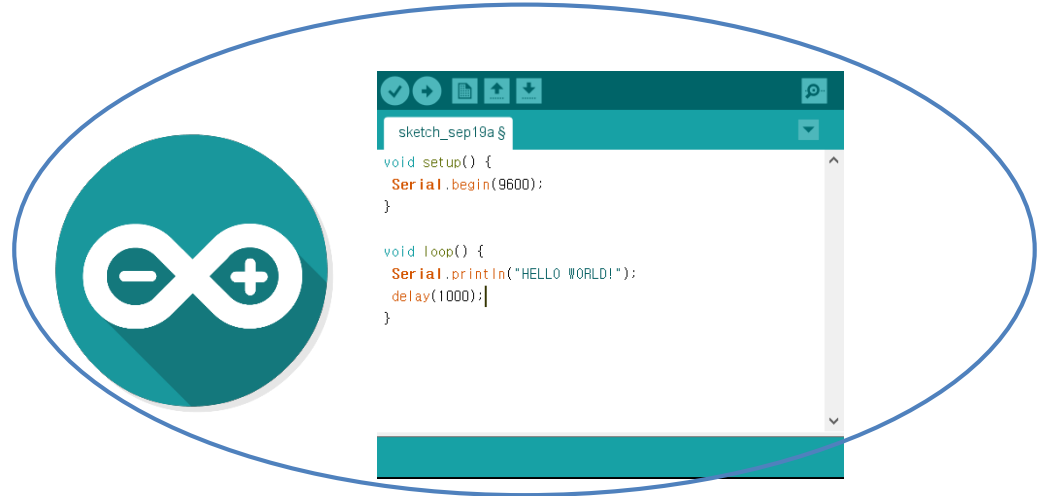
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Definition of Arduino

→ Easy to share code, library, and even hardware!

Arduino is an **open-source** electronics platform based on easy-to-use **hardware** and **software**.

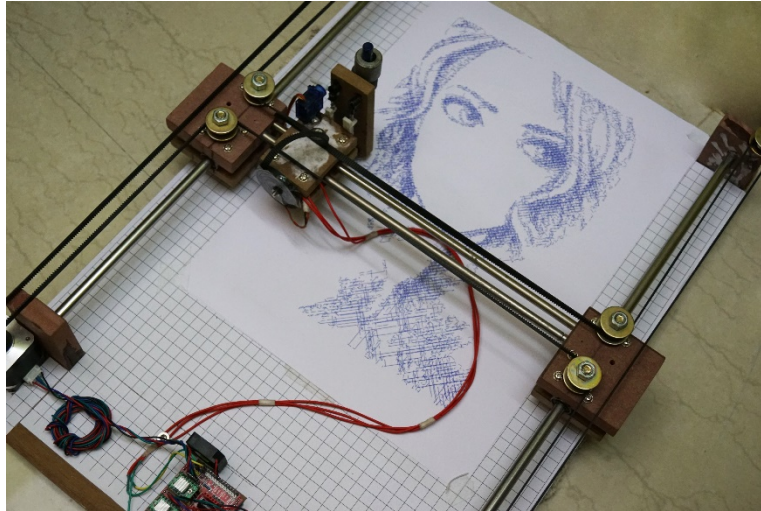
To use it, you use the Arduino programming language, and the **Arduino Software(IDE)**.



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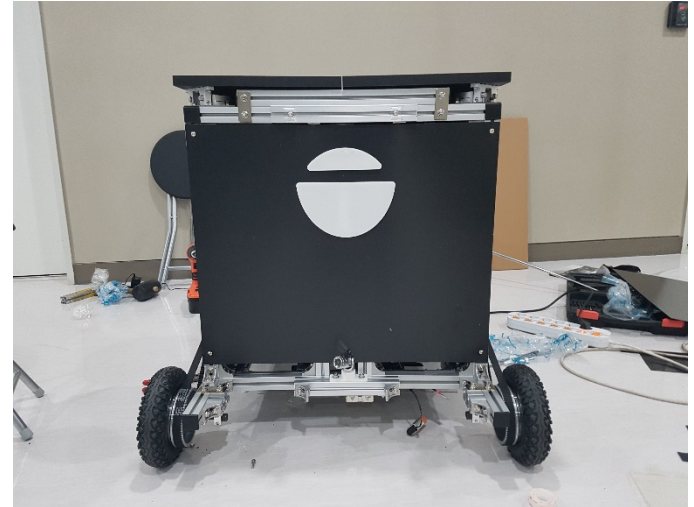
Applications of Arduino

<https://www.youtube.com/watch?v=S6bjZ5kTxyM>



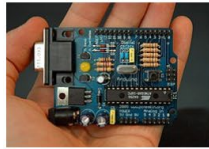
Arduino CNC Drawing Machine

Index-<http://www.arnabkumardas.com/product/arduino-cnc-drawing-machine/>



BOB-Delivery Robot with Table and Chairs

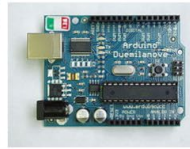
Types of Arduino



Arduino RS232^[32]
(male pins)



Arduino Diecimila



Arduino Duemilanove^[34]
(rev 2009b)



Arduino Uno R2^[35]



Arduino Uno SMD
R3^[37]



Arduino Leonardo^[38]



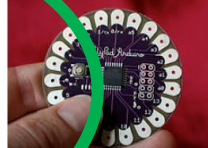
Arduino Pro^[39]
(No USB)



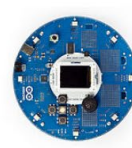
Arduino Mega^[40]



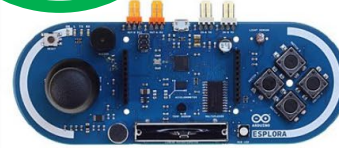
Arduino
Nano^[41]
(50
footprint
)



Arduino LilyPad 00^[42]
(rev 2007) (No USB)



Arduino Robot^[43]



Arduino Esplora^[44]



Arduino Ethernet^[45]
(AVR + W5100)



Arduino Yun^[46]
(AVR + AR9331)

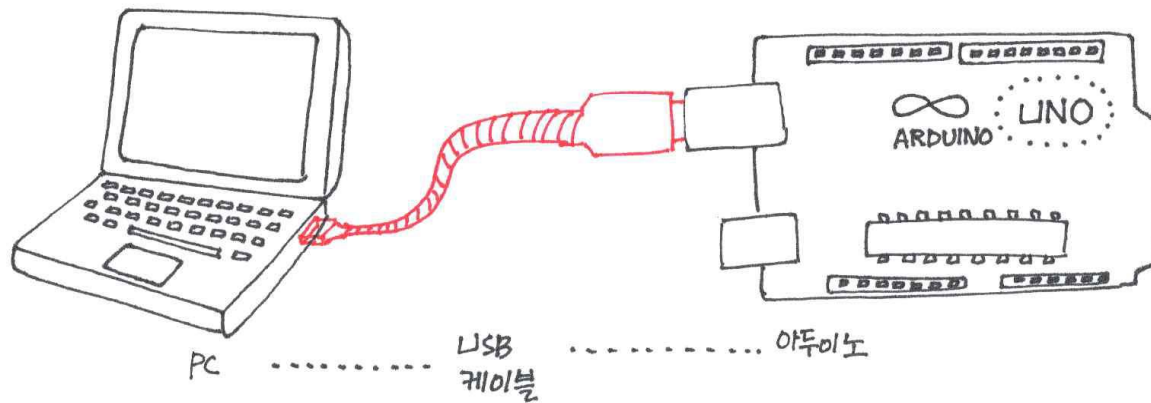


Arduino Due^[47]
(ARM Cortex-M3 core)

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Arduino Connection

Step 1.
Connect as the picture

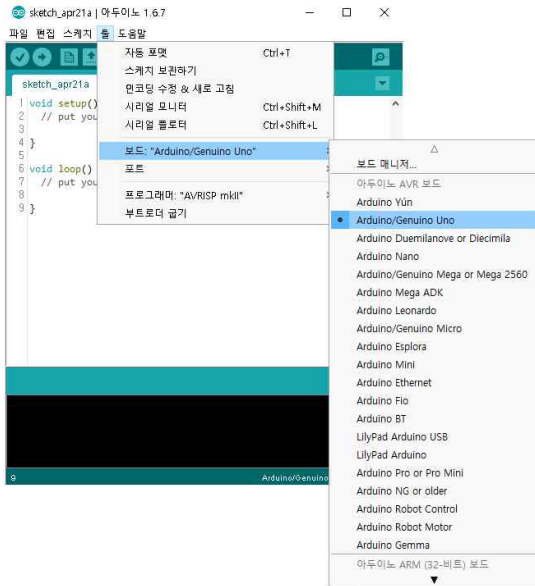




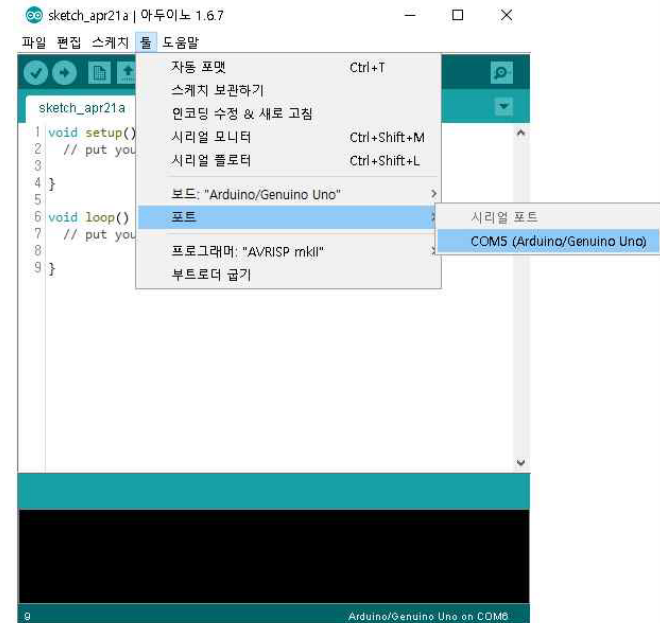
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Arduino Connection

Step 2.
Tool-Board setting



Step 3.
Tool-Port setting





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Basic Structure

```
void setup() {  
  // put your setup code here, to run once:  
  
}  
  
void loop() {  
  // put your main code here, to run repeatedly:  
  
}
```

setup()

: Initial setting function

loop()

: Real working & repeated function



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Practice 0 - HELLO WORLD!

```
sketch_sep19a$  
  
void setup() {  
  Serial.begin(9600);  
}  
  
void loop() {  
  Serial.println("HELLO WORLD!");  
  delay(1000);  
}
```

Serial.begin()
: Start serial communication

Serial.println("")
: Print sentence on the serial monitor and add a newline

delay()
: Wait () milli seconds

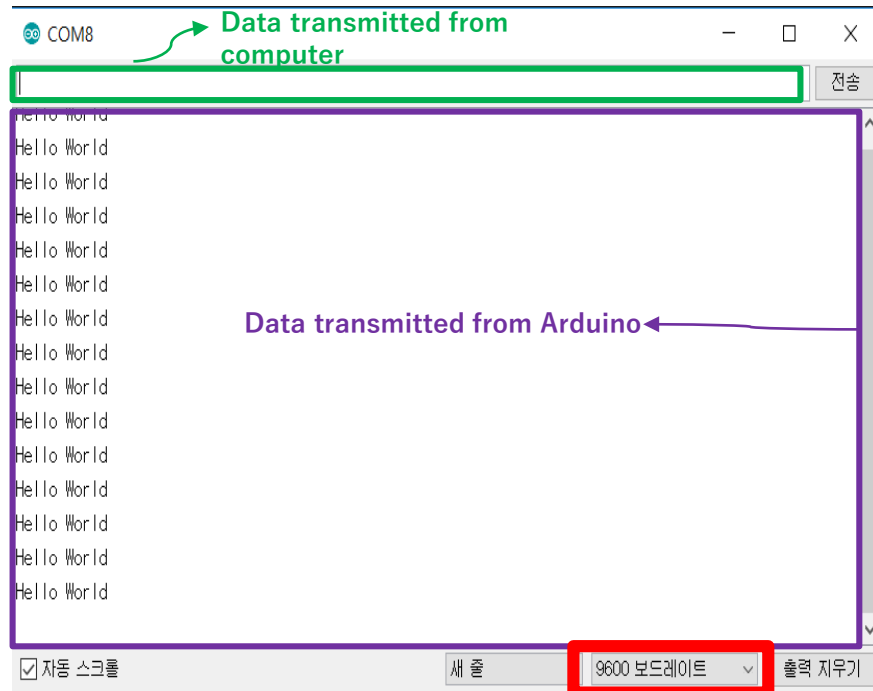
Serial Communication?
<https://m.blog.naver.com/yuyyulee/220301424499>

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1 : Upload 2 : Click Serial monitor



3 : Set the baud rate

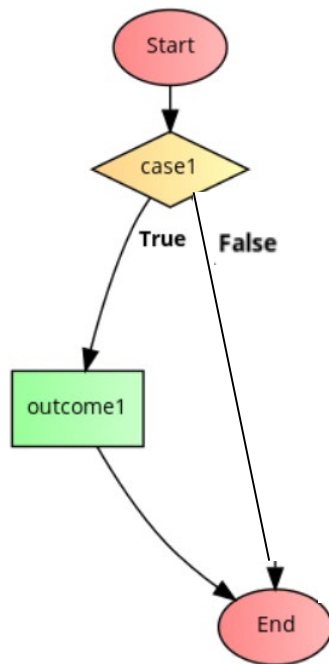




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if statement

```
if(case1){  
    outcome1  
}
```



-if the condition in the () is true, then the following outcome in the {} will run

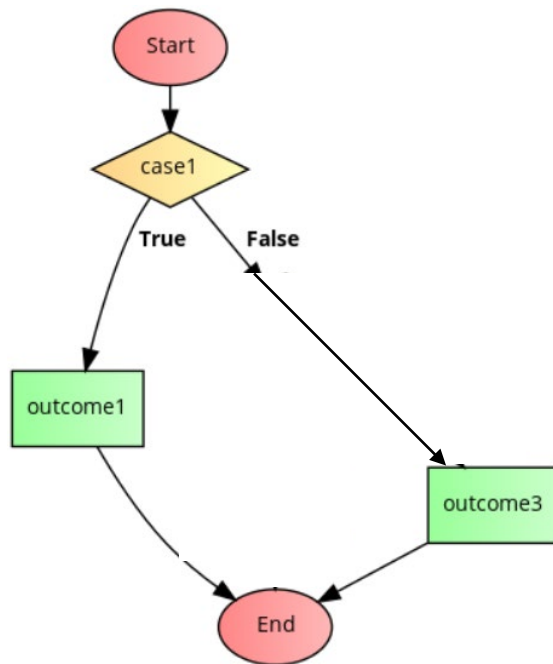


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if statement

```
if(case1){
    outcome1
}
```

```
else(){
    outcome3
}
```

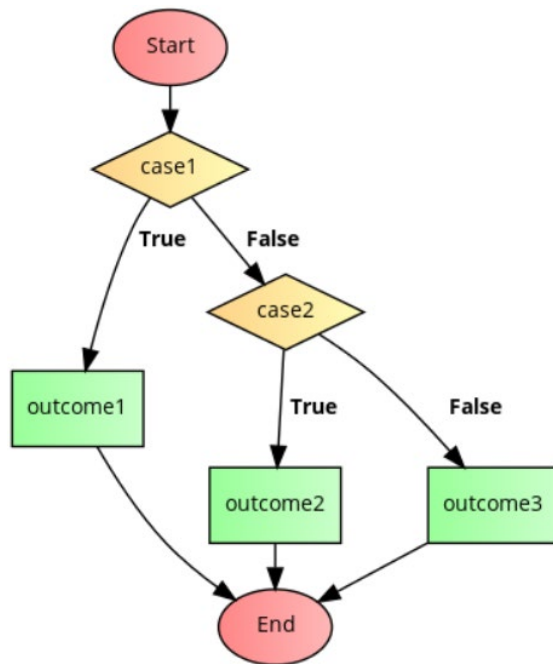


-if the condition in the () is true, then the following outcome in the {} will run

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if statement

```
if(case1){
    outcome1
}
else if(case2){
    outcome2
}
else(){
    outcome3
}
```



-if the condition in the () is true, then the following outcome in the {} will run

-you can skip “else” and “else if” if you want

-“else if” can be written as many times as you want

cf.

1 means ‘ON’, ‘True’, and ‘HIGH’

0 means ‘OFF’, ‘False’, and ‘LOW’



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variable

-A variable is a place to store a piece of data. It has a **name**, a **value**, and a **type**. For example, this statement

```
int pin = 13;
```

is a typical variable declaration(선언) format.

And this creates a variable whose name is **pin**, whose value is **13**, and whose type is **int**.

-variable **name** can be written with A~Z, a~z, 0~9, _ (but number cannot written at the first)

-type of variable integer(정수형) : int, long
real number(실수형) : float
character(문자형) : char

(you should put a proper value according to the variable)

Type?

<http://www.3demp.com/community/boardDetails.php?cbID=212>



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Function

```
sketch_jan16a $
```

```
return_type function_name( parameter_list ) {  
    body of the function  
    return output;  
}
```

```
sketch_apr16a $
```

```
void happy() {  
    //주석이여서 아무 효과 없어요~  
    /*  
    이렇게 쓰면  
    여러 줄을 주석으로 쓸 수 있습니다.  
    */  
    Serial.println("HELLO WORLD!");  
}
```

return_type

The data type of "the value the function returns"(=output)

You can use "int", "float", "char", "void" ...

When performing the desired operations without returning a value, the return_type is the "void"

function_name

The actual name of the function

NO 한글 & "Built In functions' names"

parameters

The input to use for the desired operations

A function may contain no parameters → ()

return

Return the desired value after executing the function

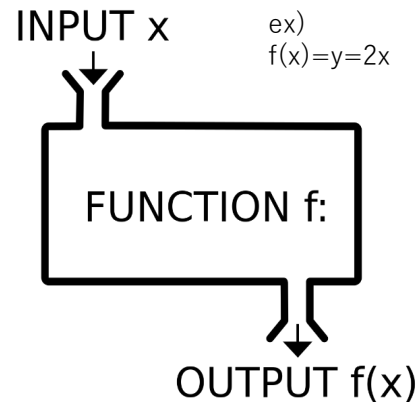
The output's data type must be the same as return_type

When return_type is the "void", omit "return" or use "return;"

{ } Paragraph

; End a statement

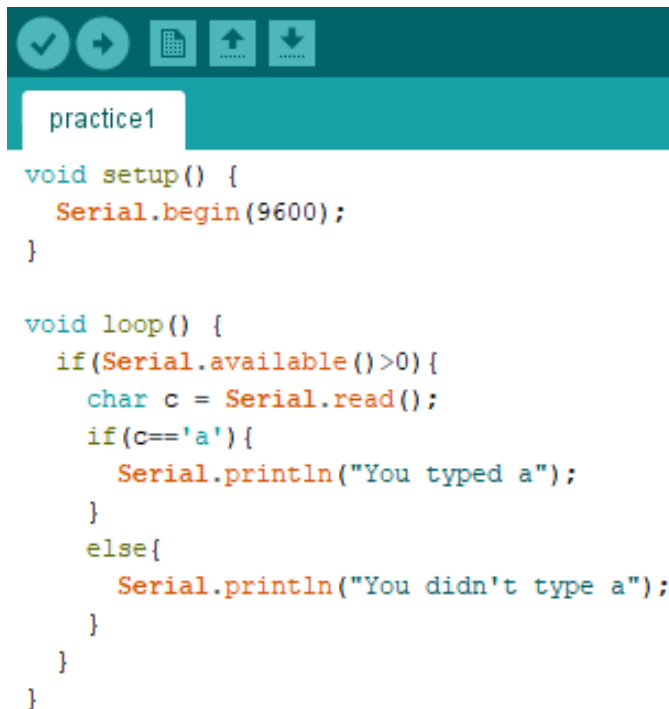
Blockcomment // for one line /* */ for multiple lines





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Practice 1



```
void setup() {  
  Serial.begin(9600);  
}  
  
void loop() {  
  if(Serial.available()>0){  
    char c = Serial.read();  
    if(c=='a'){  
      Serial.println("You typed a");  
    }  
    else{  
      Serial.println("You didn't type a");  
    }  
  }  
}
```

Serial.available()

: Get the number of bytes available for reading from serial port

: If data does exist, then its value is more than zero

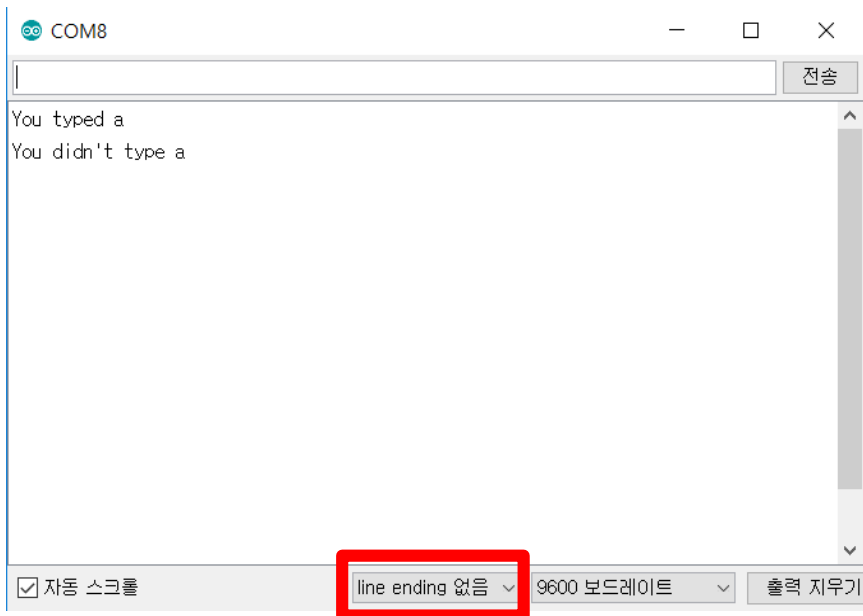
Serial.read()

: Reads incoming serial data and returns the first byte of incoming serial data available (or -1 if no data is available)



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Practice 1



Error case :

-If you type any character and see that Serial.available() runs again as you see in the image to the left, then you should click 'no line ending'



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Practice 2 – About Numbers



```
sketch_apr21a
void setup() {
  Serial.begin(9600);
}
void loop() {
  if(Serial.available()){
    long c = Serial.parseInt();
    long d = Serial.parseInt();
    Serial.println(c*d);
  }
}
```

업로드 완료.

`Serial.parseInt()`

: We cannot use `Serial.read`

: Simply click 'space bar' between integers when you write the numbers

: if input is number, returns long type number, if not, returns 0



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Practice 2 – About Numbers

COM8

15 8

전송

120

☒ 자동 스크롤

line ending 없음 ▾

9600 보드레이트 ▾

출력 지우기



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Practice 3 – User-defined Function

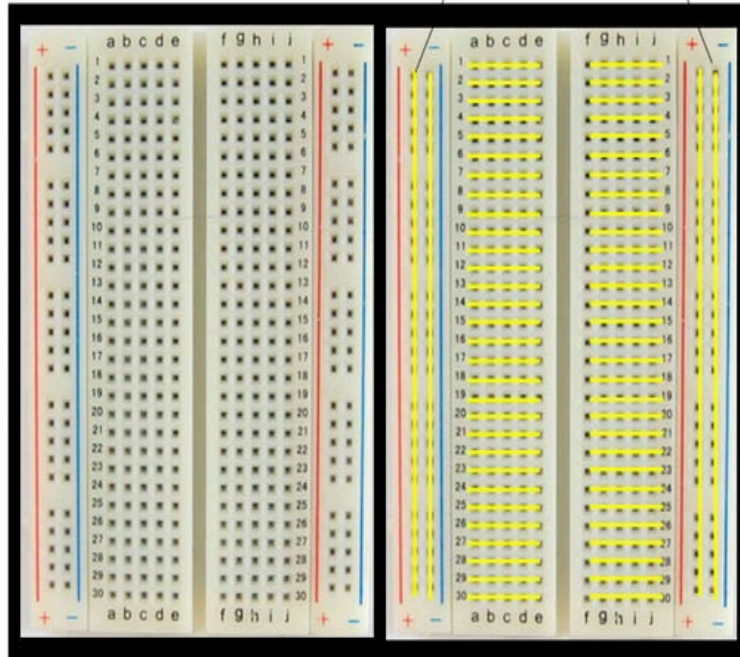
```
sketch_may04a $  
  
void setup() {  
  Serial.begin(9600);  
  Serial.println("Start");  
}  
  
int a = 0;  
int b = 0;  
  
void loop() {  
  if(Serial.available()){  
    a = Serial.parseInt();  
    b = Serial.parseInt();  
    int c = Sum(a,b);  
    Serial.println(c);  
  }  
}  
  
int Sum(int x1, int x2){  
  return x1+x2;  
}
```

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Breadboard(빵판)

Power bus

Ground bus



Directions for the use

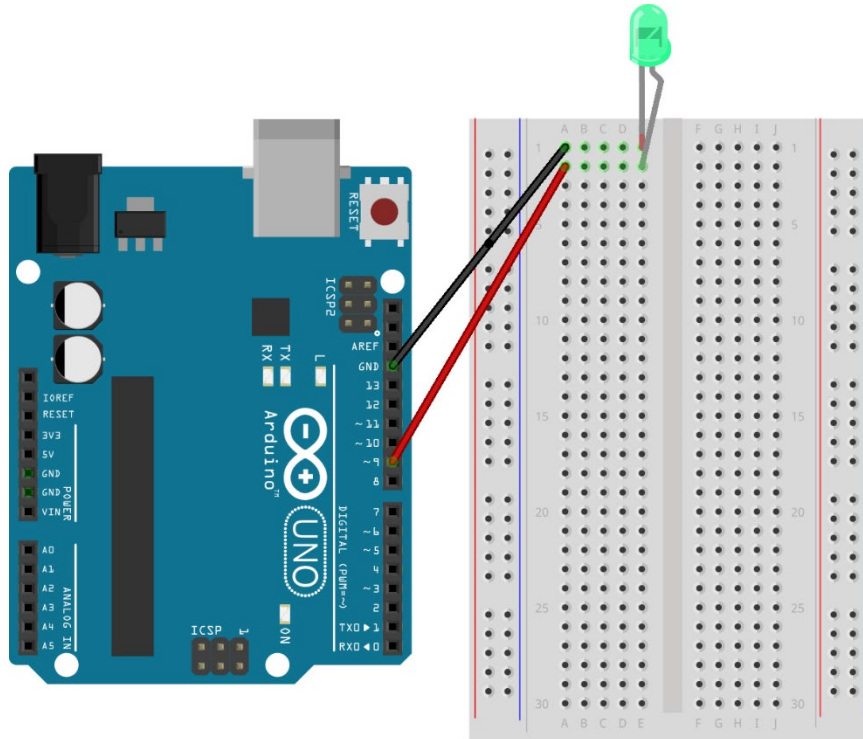
Connection

: Always disconnect an Arduino from external power sources (laptop, battery, etc.) before making an electrical circuit.

: When the Arduino is connected with external power sources and you want to connect electronic components or jumper cables..
→ Connect -(ground) first!

and you want to disconnect electronic components or jumper cables..
→ Disconnect +(power) first!

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fritzing

Led

Long lead : + (plus)
Short lead : - (minus)



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Practice 4 – Blink

```
practice4_Blink $
#define LED 9
|
void setup(){
  pinMode(LED,OUTPUT);
  Serial.begin(9600);
  Serial.println("Start");
}

void loop(){
  digitalWrite(LED,HIGH);
  Serial.println("LED ON");
  delay(2000);
  digitalWrite(LED,LOW);
  Serial.println("LED OFF");
  delay(2000);
}

업로드 완료.
```

#define

: Give a name to a constant
: #define constantName value

pinMode()

: Configures the specified pin to behave either as an input or an output

: pinMode(pin, mode)
pin – the number of the pin whose mode you wish to set
mode – INPUT or OUTPUT

digitalWrite()

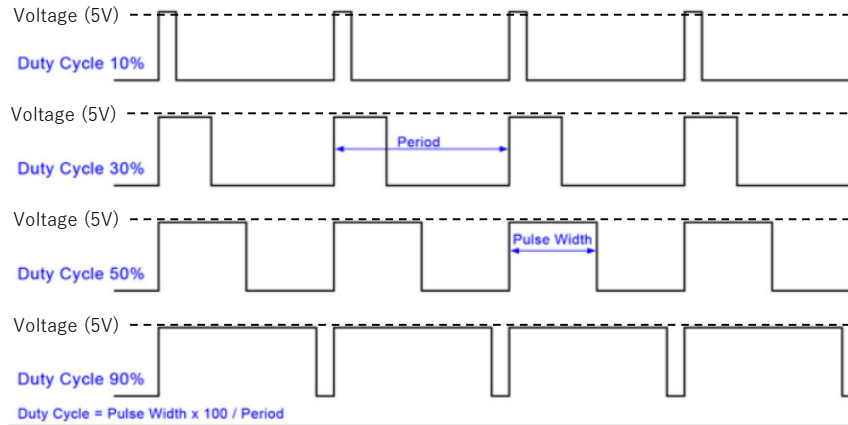
: Write a HIGH or a LOW value to a digital pin

: digitalWrite(pin, mode)
pin – the pin number
value – HIGH or LOW

PWM (Pulse Width Modulation)

1. 한 주기(Period)안에서 신호가 'ON' 상태인 시간을 지속시간 (Pulse Width)
2. 'ON'시간과 'OFF'시간의 비율을 Duty Cycle.

** 주기의 경우(t) 1/f 로 표현된다. $t=1/f$ (주파수)



Digital signals

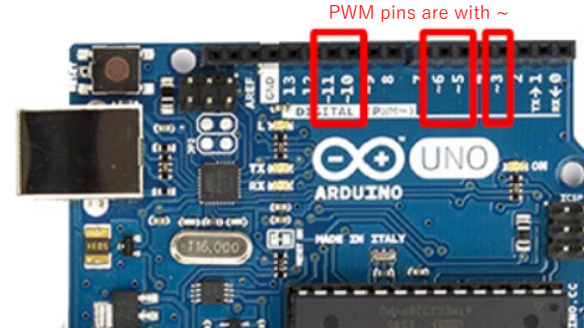
: ON or OFF (interpreted in shorthand as 1 or 0)

Analog signals

: infinite number of positions between 0 and 1

PWM

: A way to control analog devices with a digital output. You can output a modulating signal from a digital device such as an Arduino to drive an analog device.



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for statement

-The for statement is used to repeat a block of statements enclosed in curly braces{}. An increment counter is usually used to increment and terminate the loop. The for statement is useful for any repetitive operation.

-The initialization happens first and exactly once. Each time through the loop, the condition is tested; if it is true, the statement block, and the increment are executed. Then the condition is tested again. When the condition becomes false, the loop ends.

```
: for(initialization; condition; increment){  
    statement (s);  
}
```

Examples

```
: for(int i=0; i<=255; i++){  
    statement (s);  
}
```

```
: for(int i=255; i>=0; i--){  
    statement (s);  
}
```

cf.

i++ is equal to i=i+1;

i-- is equal to i=i-1;



Practice 5 – Brightness

```
practice5_Brightness
#define LED 9
void setup() {
  //pinMode(LED,OUTPUT);
  Serial.begin(9600);
  Serial.println("Start");
}
void loop() {
  for(int i=0; i<=255; i++){
    analogWrite(LED,i);
    Serial.print("LED : ");
    Serial.println(i);
    delay(10);
  }
  /*for(int i=255; i>=0; i--){
    analogWrite(LED,i);
    Serial.print("LED : ");
    Serial.println(i);
    delay(10);
  }*/
}
```

analogWrite()

: Writes an analog value (PWM wave) to a pin. Can be used to light a LED at varying brightnesses or drive a motor at various speeds

: analogWrite(pin, value)

pin – the pin to write to

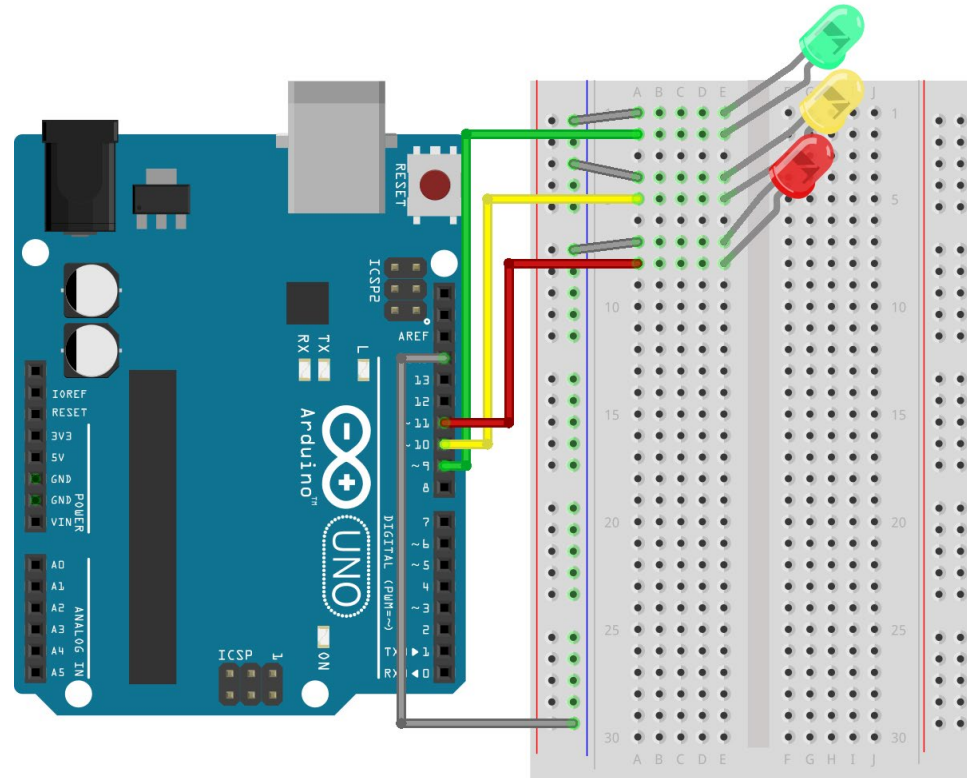
value – the duty cycle between 0 (always off) and 255 (always on)

Serial.print("")

: Print sentence on the serial monitor (no new line)



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fritzing



Practice 6 – Traffic light

```
practice6_trafficlight $
```

```
#define Green 9
#define Yellow 10
#define Red 11
void setup() {
  pinMode(Green, OUTPUT);
  pinMode(Yellow, OUTPUT);
  pinMode(Red, OUTPUT);
  digitalWrite(Green, LOW);
  digitalWrite(Yellow, LOW);
  digitalWrite(Red, LOW);
  Serial.begin(9600);
  Serial.println("Start");
}
```

```
void loop() {
  digitalWrite(Green, HIGH);
  delay(3000);
  digitalWrite(Green, LOW);
  digitalWrite(Yellow, HIGH);
  delay(1000);
  digitalWrite(Yellow, LOW);
  digitalWrite(Red, HIGH);
  delay(3000);
  digitalWrite(Red, LOW);
}
```



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References

<https://codingrun.com/65>

<https://forum.arduino.cc/>

<https://dokkodai.tistory.com/188>

If you have any questions, then email me (sungha.woo@yonsei.ac.kr)

You can also refer to the articles on <https://www.arduino.cc/reference/ko/>