Term Project

ULTRA-SONIC WAVE RADAR

초음파 레이더

PERFORMED BY

노준호 & 주성민



O1 INTRO A. TEAM NAME



O1 INTRO

B. TEAM ROLE



Cooperation

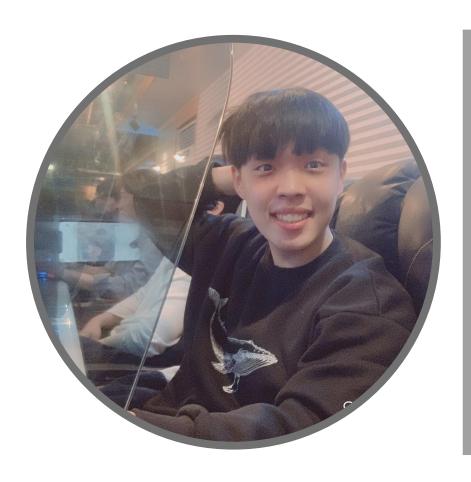
- A. Radar operation Algorithm
- B. FPGA (Rework Driver)

Personal Tasks

- A. Data Frame, Print Screen
- B. Screen Brightness Control
- C. Detection & Alarm
- D. Error Correction
- E. Make a Presentation

O1 INTRO

B. TEAM ROLE



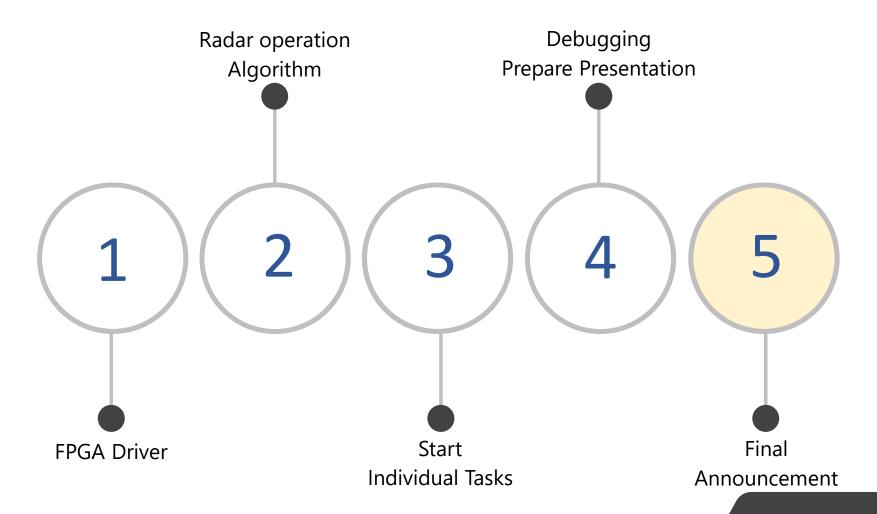
Cooperation

- A. Radar operation Algorithm
- B. FPGA (Rework Driver)

Personal Tasks

- A. Design & Optimization
- B. Touch-Event Handling
- C. Radar Realization
- D. PWM Control
- E. Multi Process Programing

INTRO C. PROJECT SCHEDULE



O1 INTRO

C. PROJECT SCHEDULE









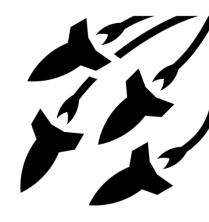


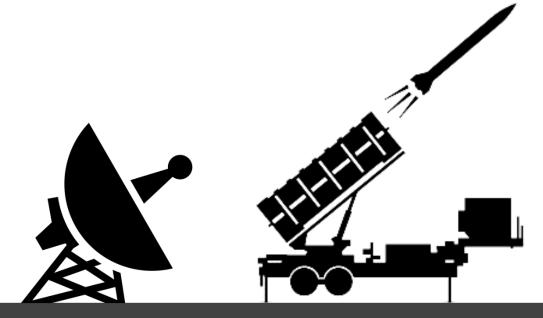


- A. NECESSITY
- B. DIFFERENCE
- C. MODULE
- D. SYSTEM



A. NECESSITY





OZ ABOUT PROJE

A. NECESSITY

국방/외교 ▼

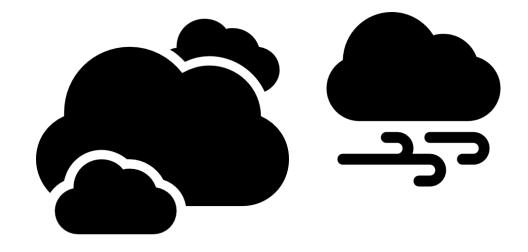
"AESA레이더 현재 기술수준 미국의 75%"

최신기사

한국 레이더체계 기술 수준, 세계 12위 중진국권(종합2 보)

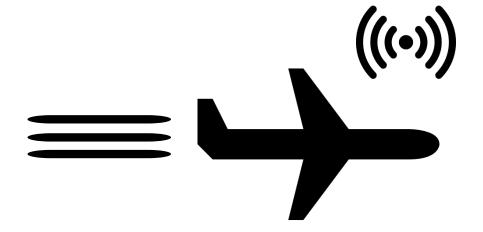


A. NECESSITY





A. NECESSITY







A. NECESSITY

Overall rank	Country	Total score	Policy and legislation		Technology & innovation		Infrastructure		Consumer acceptance	
			Rank	Score	Rank	Score	Rank	Score	Rank	Score
1	The Netherlands	27.73	3	7.89	4	5.46	1	7.89	2	6.49
2	Singapore	26.08	1	8.49	8	4.26	2	6.72	1	6.63
3	United States	24.75	10	6.38	1	6.97	7	5.84	4	5.5
4	Sweden	24.73	8	6.83	2	6.44	6	6.04	6	5.4
5	United Kingdom	23.99	4	7.55	5	5.28	10	5.31	3	5.8
6	Germany	22.74	5	7.33	3	6.15	12	5.17	12	4.0
7	Canada	22.61	7	7.12	6	4.97	11	5.22	7	5.3
8	United Arab Emirates	20.89	6	7.26	14	2.71	5	6.12	8	4.7
9	New Zealand	20.75	2	7.92	12	3.26	16	4.14	5	5.4
10	South Korea	20.71	14	5.78	9	4.24	4	6.32	11	4.3
11	Japan	20.28	12	5.93	7	4.79	3	6.55	16	3.0
12	Austria	20.00	9	6.73	11	3.69	8	5.66	13	3.9
13	France	19.44	13	5.92	10	4.03	13	4.94	10	4.5
14	Australia	19.40	11	6.01	13	3.18	9	5.43	9	4.7
15	Spain	14.58	15	4.95	16	2.21	14	4.69	17	2.7
16	China	13.94	16	4.38	15	2.25	15	4.18	15	3.1
4.7	0	717	20	0.02	10	0.00	10	100	44	2.4

2.58

19 0.54

18

2.28

20

18

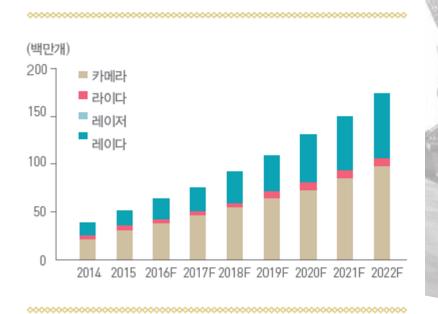
2.35

1.91

Russia

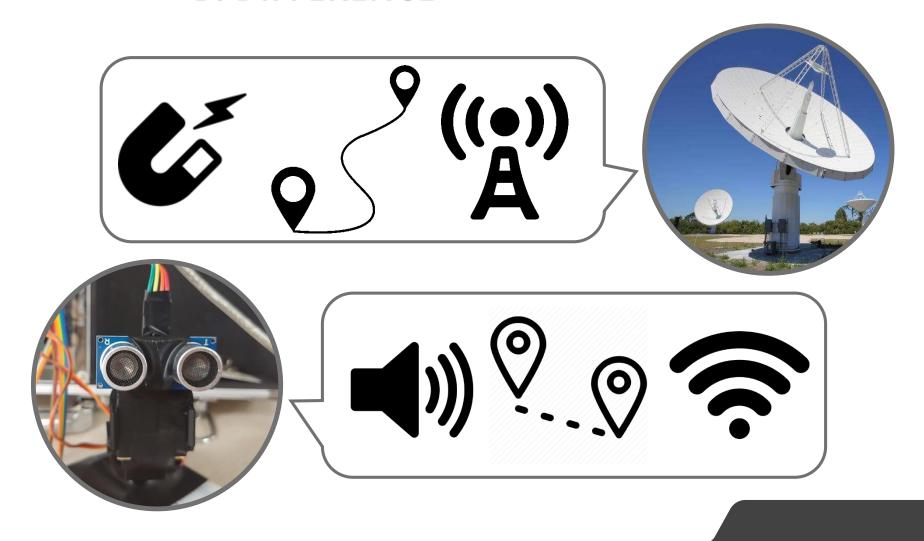
India

글로벌 ADAS용 센서 시장 전망

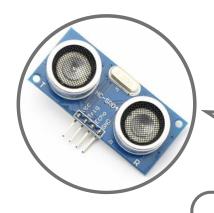


자료: IHS, 신한금융투자 추정

B. DIFFERENCE



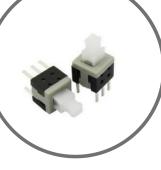
C. MODULE



Detection

Movement

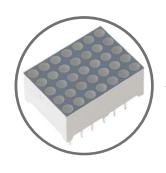




Controller

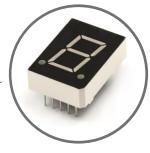
Q2 ABOUT PROJECT

C. MODULE



Detecting Direction

Detected Distance





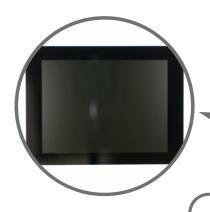
Danger Close Alarm

Show Record Order



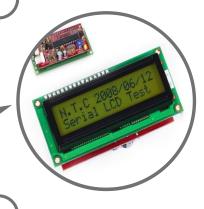
Q2 ABOUT PROJECT

C. MODULE



Show Detection Info.
Setting Output

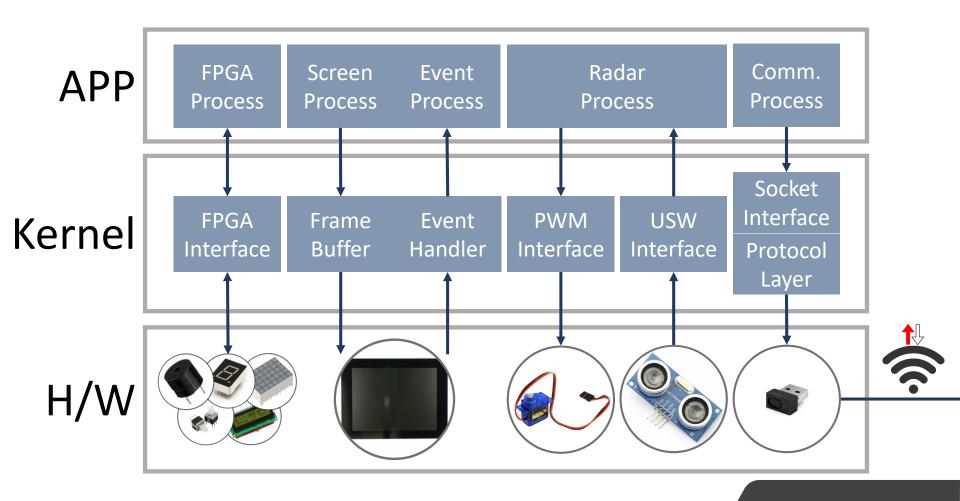
Show Setting Option Show Data's Time Info.

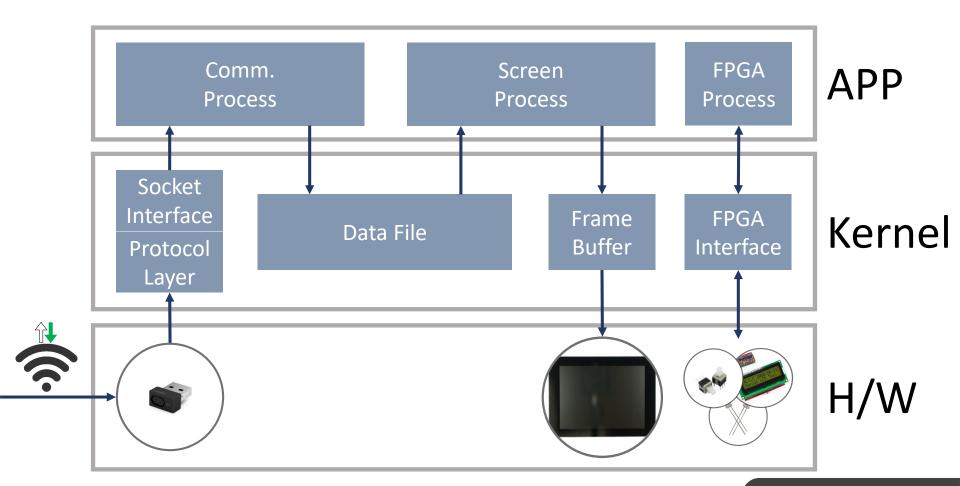


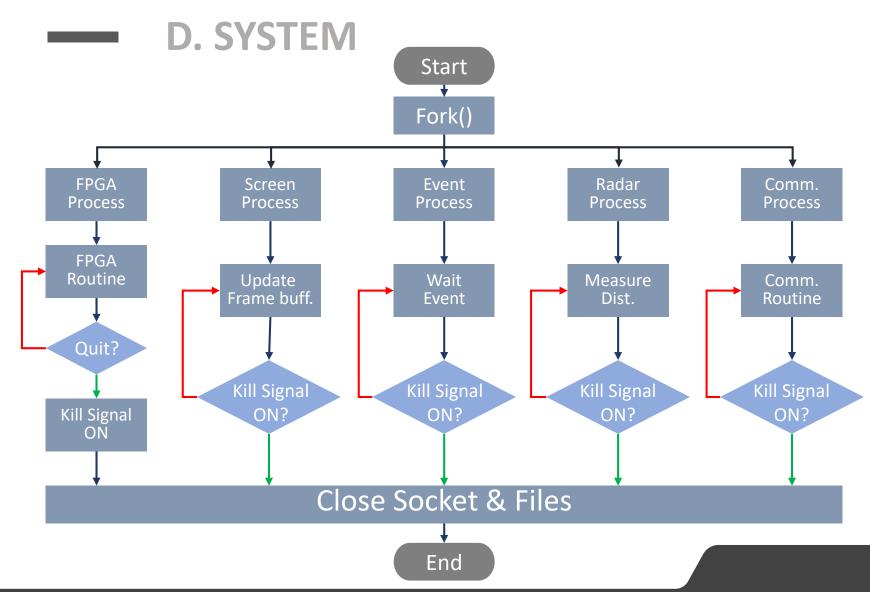


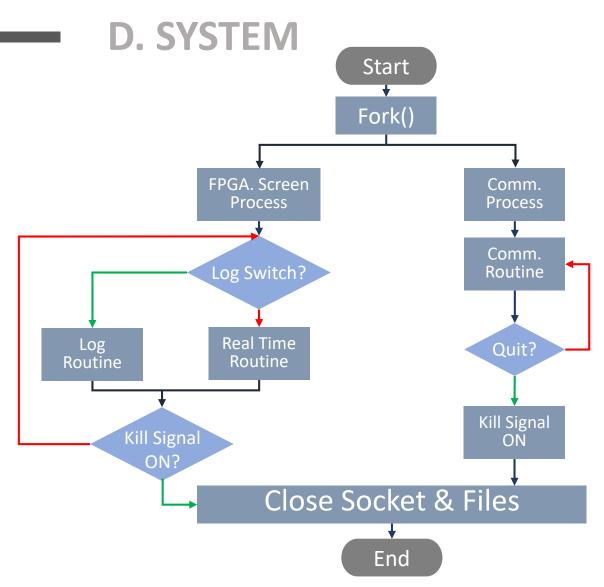
Data Transmission

D. SYSTEM











DEMOFILM HOW THE RADAR WORKS



https://youtu.be/e_Ej8C35qMA



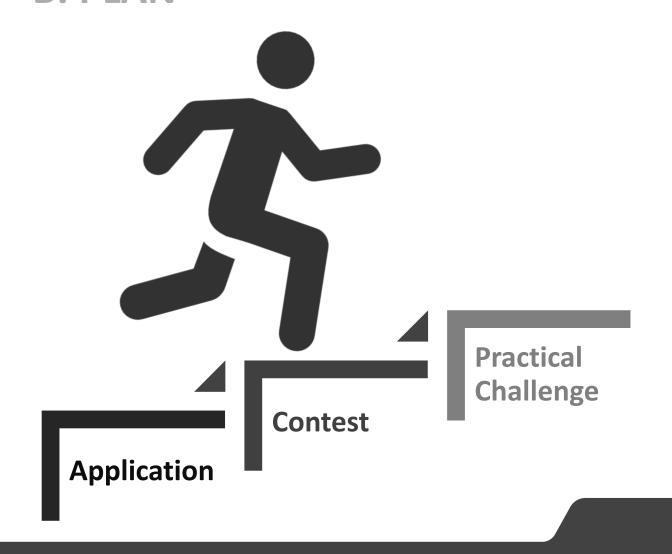
- A. IMPROVEMENT
- B. PLAN
- C. OPINION
- D. EPILOGUE



04 OUTRO A. IMPROVEMENT

- 1 Speed & Precision
 - 2 Vibration-induced Error
 - 3 Frame Buffer Optimization
- 4 Two-way Comm.

04 OUTRO B. PLAN



04 OUTRO C. OPINION

Window Environment



Linux Environment

- Experience Work-Level
- Real Radar

04 outro

D. EPILOGUE



THANKS FOR LISTENING