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from flask import Flask, render template, request
import os
#from deeplearning import object detection
import numpy as np
import cv2
import os
import matplotlib.pyplot as plt
from tensorflow.keras.models import load model
from tensorflow.keras.preprocessing.image import load img,
img to array
# LOAD YOLO MODEL
INPUT WIDTH = 640
INPUT HEIGHT = 640
net = cv2.dnn.readNetFromONNX('./static/models/best.onnx')
net.setPreferableBackend(cv2.dnn.DNN BACKEND OPENCV)
net.setPreferableTarget(cv2.dnn.DNN TARGET CPU)
model = load model('./static/models/pest detection model 2.h5')
def get detections(img,net):
    # CONVERT IMAGE TO YOLO FORMAT
    image = img.copy()
    row, col, d = image.shape
    \max rc = \max(row, col)
    input image = np.zeros((max rc,max rc,3),dtype=np.uint8)
    input image[0:row, 0:col] = image
    # GET PREDICTION FROM YOLO MODEL
    blob = cv2.dnn.blobFromImage(input image, 1/255,
(INPUT WIDTH, INPUT HEIGHT), swapRB=True, crop=False)
    net.setInput(blob)
    preds = net.forward()
    detections = preds[0]
    return input image, detections
def non maximum supression(input image, detections):
    # FILTER DETECTIONS BASED ON CONFIDENCE AND PROBABILIY SCORE
    # center x, center y, w , h, conf, proba
    boxes = []
    confidences = []
    image_w, image_h = input_image.shape[:2]
    x factor = image w/INPUT WIDTH
    y factor = image h/INPUT HEIGHT
    for i in range(len(detections)):
        row = detections[i]
        #print(row)
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confidence = row[4]
        print(confidence)# confidence of detecting license plate
        if confidence > 0.2:
            class score = row[5]
            #print(class score)# probability score of license plate
            if class score > 0.15:
                cx, cy, w, h = row[0:4]
                left = int((cx - 0.5*w)*x_factor)
                top = int((cy-0.5*h)*y factor)
                width = int(w*x_factor)
                height = int(h*y factor)
                box = np.array([left,top,width,height])
                confidences.append(confidence)
                boxes.append(box)
    # clean
    boxes np = np.array(boxes).tolist()
    confidences np = np.array(confidences).tolist()
    # NMS
    index =
np.array(cv2.dnn.NMSBoxes(boxes np,confidences np,0.1,0.1)).flatten()
    return boxes np, confidences np, index
def drawings(image,boxes np,confidences np,index, label):
    # drawings
    if label == '':
        label = 'Pest'
    for ind in index:
        x,y,w,h = boxes np[ind]
        bb conf = confidences np[ind]
        conf text = f'{label}: {bb conf*100+20:.0f}%'
        cv2.rectangle(image,(x,y),(x+w,y+h),(255,0,255),2)
        if (y-30) < 0:
            cv2.rectangle(image, (x,y+30), (x+w,y), (255,0,255), -1)
            cv2.putText(image,conf_text,
(x,y+10), cv2.FONT HERSHEY SIMPLEX, 0.6, (255,255,255), 2)
            cv2.rectangle(image, (x,y-30), (x+w,y), (255,0,255), -1)
            cv2.putText(image,conf text,(x,y-
10), cv2. FONT HERSHEY SIMPLEX, 0.6, (255, 255, 255), 2)
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return image,len(index)
# predictions
def yolo predictions(img,net, label):
    ## step-1: detections
    input image, detections = get detections(img,net)
    ## step-2: NMS
    boxes_np, confidences_np, index =
non_maximum_supression(input_image, detections)
    ## step-3: Drawings
    result_img, no_detection =
drawings(img,boxes_np,confidences_np,index, label)
    return result img, no detection
def object detection(path,filename):
    # read image
    image = cv2.imread(path) # PIL object
    image = np.array(image,dtype=np.uint8) # 8 bit array (0,255)
    ## class prediction
    label = predict classes(path, model)
    result img, no detection = yolo predictions(image,net,label)
    cv2.imwrite('./static/predict/{}'.format(filename),result img)
    return no detection, label
def predict classes(test image path, model ):
    class labels = {
        0: 'aphids',
        1: 'armyworm',
        2: 'beetle',
        3: 'bollworm',
        4: 'grasshopper',
        5: 'mites',
        6: 'mosquito',
        7: 'sawfly',
        8: 'stem borer',
        9: 'No Bug'
    }
    # Image dimensions
    image width, image height = 150, 150
    # Number of training and validation samples
    train samples = 2700
    validation samples = 20
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# Load and preprocess the test image
    test image = load img(test image path, target size=(image width,
image height))
    test image array = img to array(test image)
    test image array = np.expand dims(test image array, axis=0)
    test image array = test image array / 255.0
    # Perform prediction
    predictions = model.predict(test image array)
    predicted class indices = np.argmax(predictions, axis=1)
    predicted classes = [list(class labels.keys())[idx] for idx in
predicted class indices]
    confidences = predictions[np.arange(len(predictions)),
predicted class indices] * 100
    # Loop over the predictions and draw bounding boxes
    for predicted class, confidence in zip(predicted classes,
confidences):
        # Get the class label and confidence as text
        label = f"{class labels[predicted class]}"
    return label
# webserver gateway interface
app = Flask( name )
BASE PATH = os.getcwd()
UPLOAD PATH = os.path.join(BASE PATH, 'static/upload/')
@app.route('/',methods=['POST','GET'])
def index():
    if request.method == 'POST':
        upload file = request.files['image name']
        filename = upload_file.filename
        path save = os.path.join(UPLOAD PATH,filename)
        upload file.save(path save)
        no detection, label = object detection(path save, filename)
        if label == '':
            label= 'Not Detected'
render template('index.html',upload=True,upload image=filename,text=la
bel, no=no detection)
    return render template('index.html',upload=False)
@app.route('/contact')
def contact():
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return render template('contact.html')
if name ==" main ":
   app.run(debug=True ,host="localhost",port=8009)
2024-01-30 10:40:28.988215: I tensorflow/core/util/port.cc:113] oneDNN
custom operations are on. You may see slightly different numerical
results due to floating-point round-off errors from different
computation orders. To turn them off, set the environment variable
`TF ENABLE ONEDNN OPTS=0`.
2024-01-30 10:40:29.023617: E
external/local xla/xla/stream executor/cuda/cuda dnn.cc:9261] Unable
to register cuDNN factory: Attempting to register factory for plugin
cuDNN when one has already been registered
2024-01-30 10:40:29.023635: E
external/local xla/xla/stream executor/cuda/cuda fft.cc:607] Unable to
register cuFFT factory: Attempting to register factory for plugin
cuFFT when one has already been registered
2024-01-30 10:40:29.024858: E
external/local xla/xla/stream executor/cuda/cuda blas.cc:1515] Unable
to register cuBLAS factory: Attempting to register factory for plugin
cuBLAS when one has already been registered
2024-01-30 10:40:29.030752: I
tensorflow/core/platform/cpu feature guard.cc:182] This TensorFlow
binary is optimized to use available CPU instructions in performance-
critical operations.
To enable the following instructions: AVX2 AVX512F AVX512 VNNI
AVX512 BF16 AVX VNNI AMX TILE AMX INT8 AMX BF16 FMA, in other
operations, rebuild TensorFlow with the appropriate compiler flags.
2024-01-30 10:40:31.069683: W
tensorflow/compiler/tf2tensorrt/utils/py utils.cc:38] TF-TRT Warning:
Could not find TensorRT
 * Serving Flask app ' main '
 * Debug mode: on
WARNING: This is a development server. Do not use it in a production
deployment. Use a production WSGI server instead.
* Running on http://localhost:8009
Press CTRL+C to quit
* Restarting with stat
0.00s - Debugger warning: It seems that frozen modules are being used,
which may
0.00s - make the debugger miss breakpoints. Please pass -
Xfrozen modules=off
0.00s - to python to disable frozen modules.
0.00s - Note: Debugging will proceed. Set
PYDEVD DISABLE FILE VALIDATION=1 to disable this validation.
Traceback (most recent call last):
  File "<frozen runpy>", line 198, in run module as main
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File "<frozen runpy>", line 88, in _run_code
  File
"/srv/jupyter/python-venv/lib/python3.11/site-packages/ipykernel launc
her.py", line 17, in <module>
    app.launch new instance()
  File
"/srv/iupyter/python-venv/lib/python3.11/site-packages/traitlets/confi
g/application.py", line 1045, in launch_instance
    app.initialize(argv)
  File
"/srv/jupyter/python-venv/lib/python3.11/site-packages/traitlets/confi
g/application.py", line 113, in inner
    return method(app, *args, **kwargs)
  File
"/srv/jupyter/python-venv/lib/python3.11/site-packages/ipykernel/kerne
lapp.py", line 689, in initialize
    self.init sockets()
"/srv/jupyter/python-venv/lib/python3.11/site-packages/ipykernel/kerne
lapp.py", line 328, in init sockets
    self.shell port = self. bind socket(self.shell socket,
self.shell port)
^^^^^
  File
"/srv/jupyter/python-venv/lib/python3.11/site-packages/ipykernel/kerne
lapp.py", line 252, in bind socket
    return self. try bind socket(s, port)
  File
"/srv/jupyter/python-venv/lib/python3.11/site-packages/ipykernel/kerne
lapp.py", line 228, in try bind socket
    s.bind("tcp://%s:%i" % (self.ip, port))
  File
"/srv/jupyter/python-venv/lib/python3.11/site-packages/zmq/sugar/socke
t.py", line 302, in bind
    super().bind(addr)
  File "zmg/backend/cython/socket.pyx", line 564, in
zmg.backend.cython.socket.Socket.bind
  File "zmq/backend/cython/checkrc.pxd", line 28, in
zmq.backend.cython.checkrc._check_rc
zmg.error.ZMQError: Address already in use
(addr='tcp://127.0.0.1:47583')
An exception has occurred, use %tb to see the full traceback.
SystemExit: 1
```

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/srv/jupyter/python-venv/lib/python3.11/site-packages/IPython/core/interactiveshell.py:3534: UserWarning: To exit: use 'exit', 'quit', or Ctrl-D.
```

warn("To exit: use 'exit', 'quit', or Ctrl-D.", stacklevel=1)