

Understanding Deep Neural Networks

Chapter Six

Unsupervised Learning

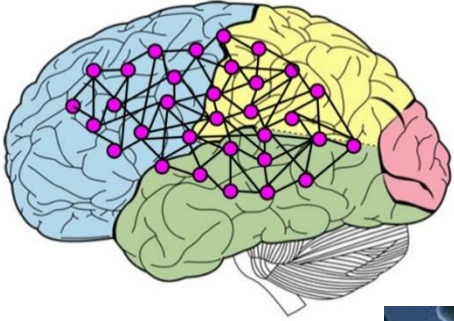
深度学习引论2020

Zhang Yi, *IEEE Fellow*
Autumn 2020

Outline

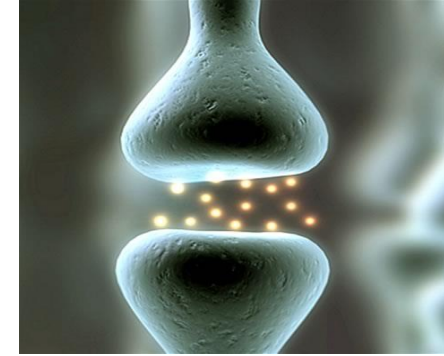
- Learning in Neural Networks
- Supervised Learning
- Unsupervised Learning
- Autoencoder Neural Networks
- Generative Adversarial Networks
- Assignment

Learning in Neural Networks



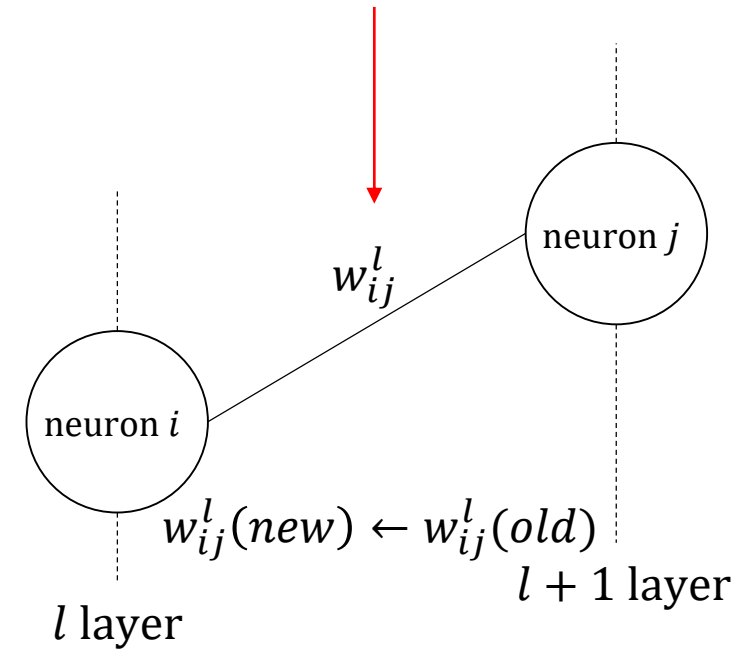
Neural Network

The brain is a learning system. The brain can learn by some supervisor or by itself. Thus, there are **Supervised Learning** and **Unsupervised Learning**.



Learning is the changing of connection strength between two connected neurons

The knowledge is stored in connections weight.

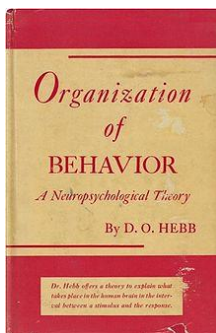


Learning in Neural Networks

Hebb's Postulate

When an axon of cell A is near enough to excite a cell B and repeatedly or persistently takes part in firing it, some growth process or metabolic change takes place in one or both cells such that A's efficiency, as one of the cells firing B, is increased.

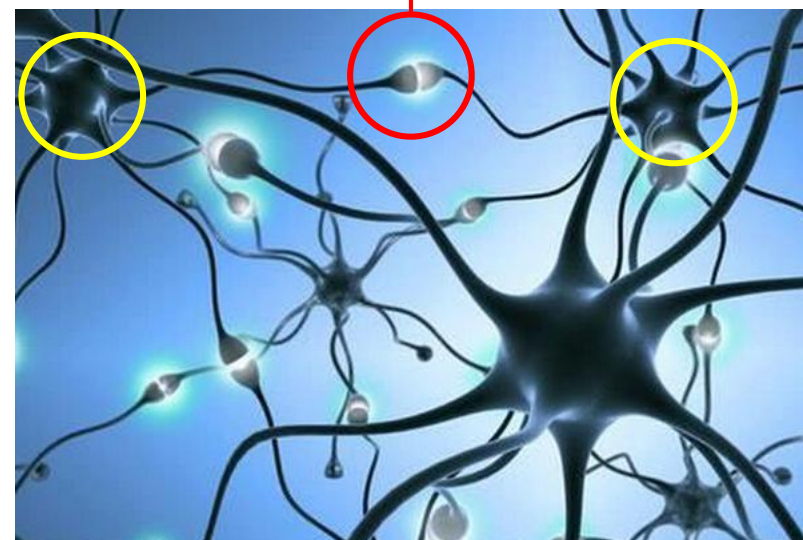
— D.O Hebb, 1949



D. O. Hebb
Father of Cognitive Psychobiology
1904-1985



Synapse



Learning in Neural Networks

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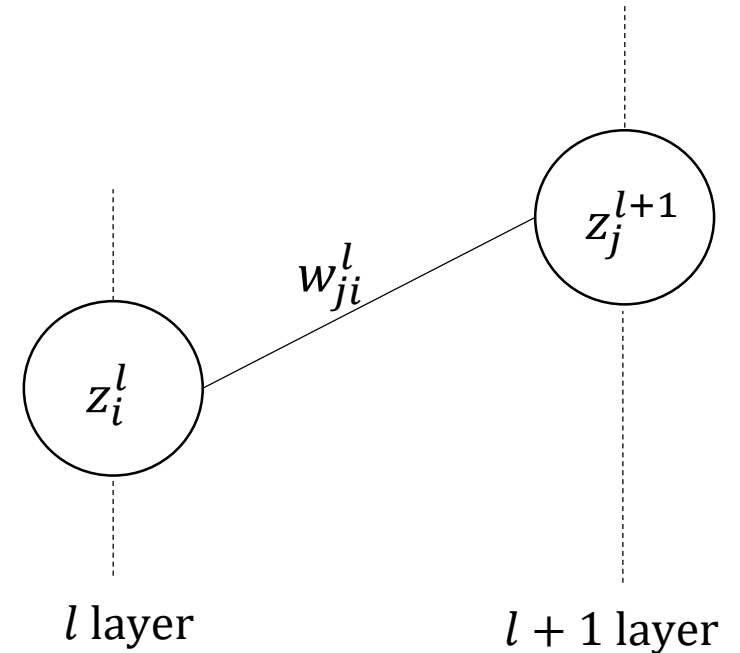


If two neurons of either side of a synapse are activated simultaneously, the strength of the synapse will increase.

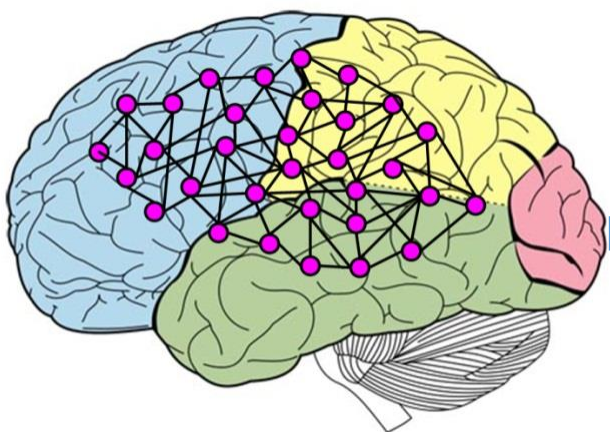


Hebbian Learning

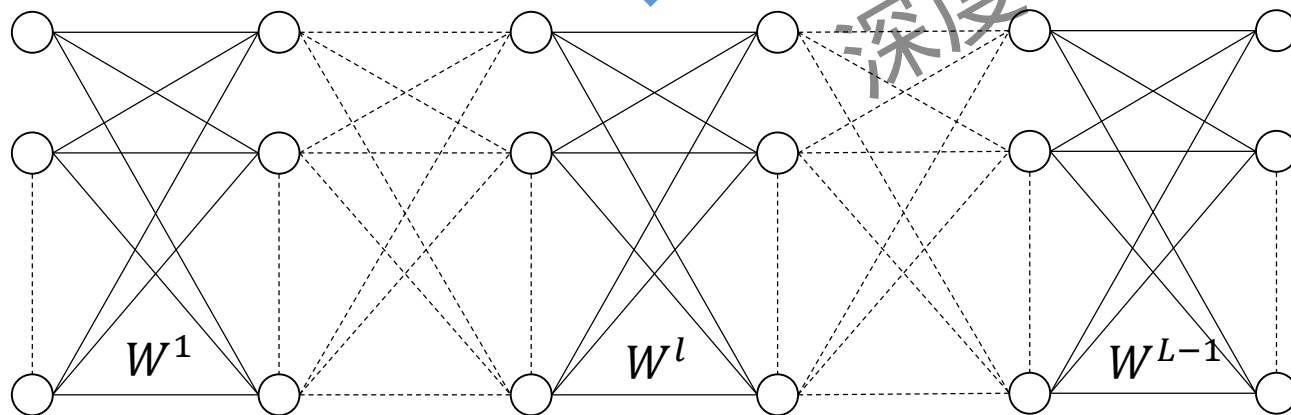
$$w_{ji}^l \leftarrow w_{ji}^l + F(z_j^{l+1}, z_i^l)$$



Learning in Neural Networks



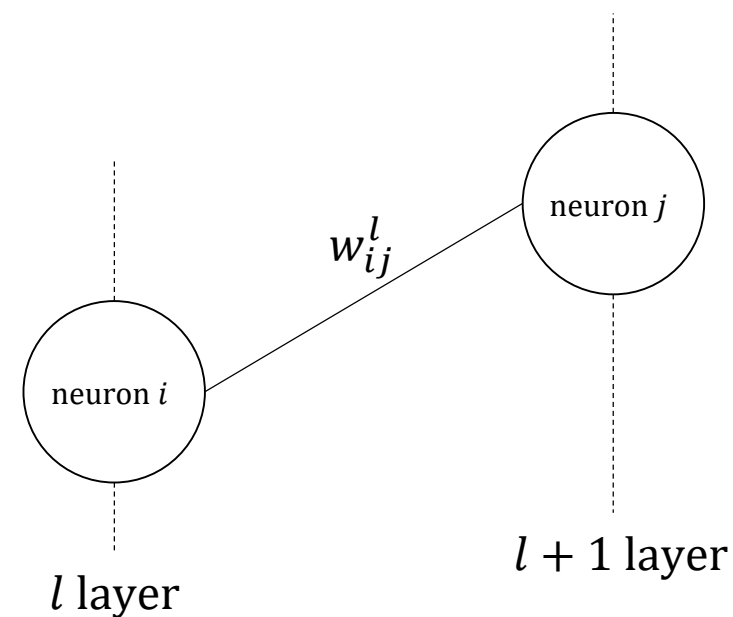
Neural Network



The network stores only knowledge, it does not store original data.

Learning is the updating of connection weight between two connected neurons

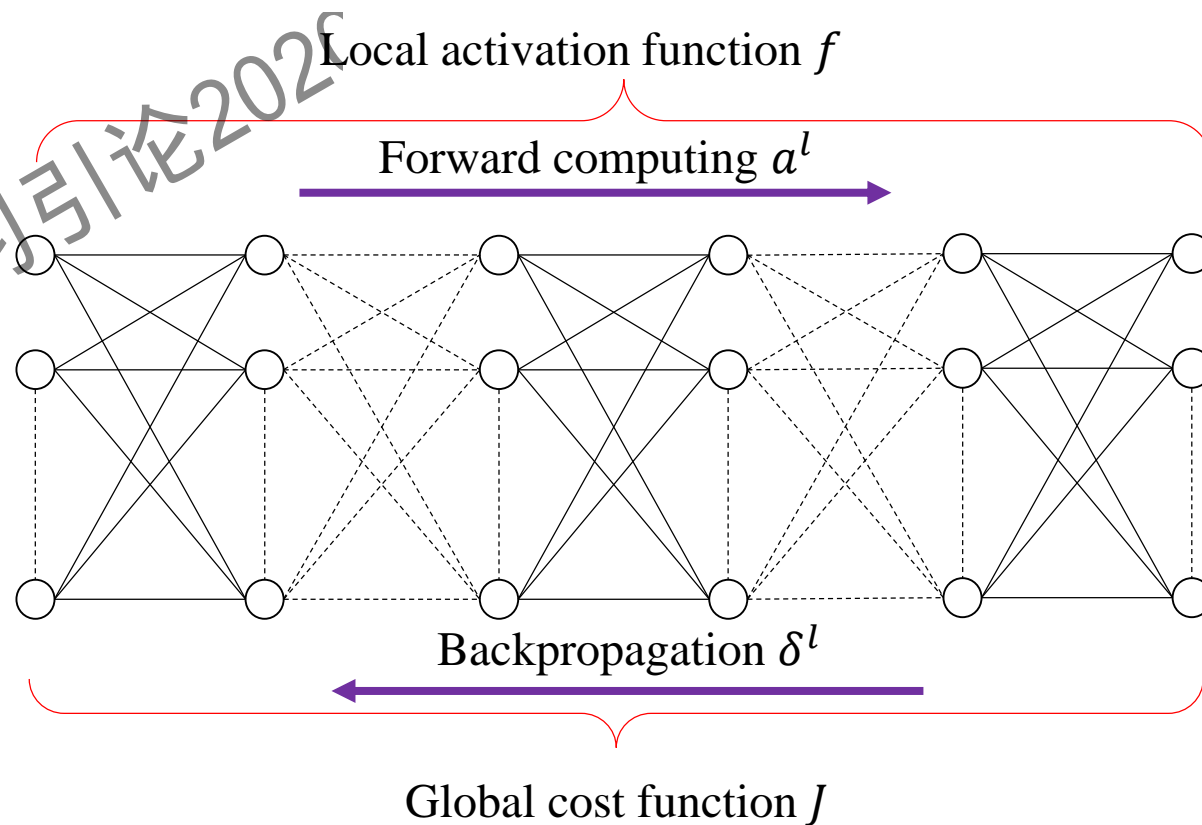
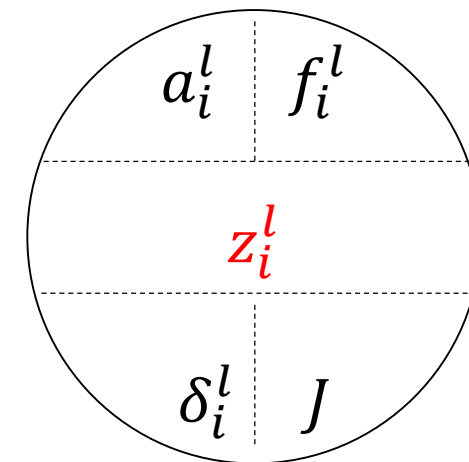
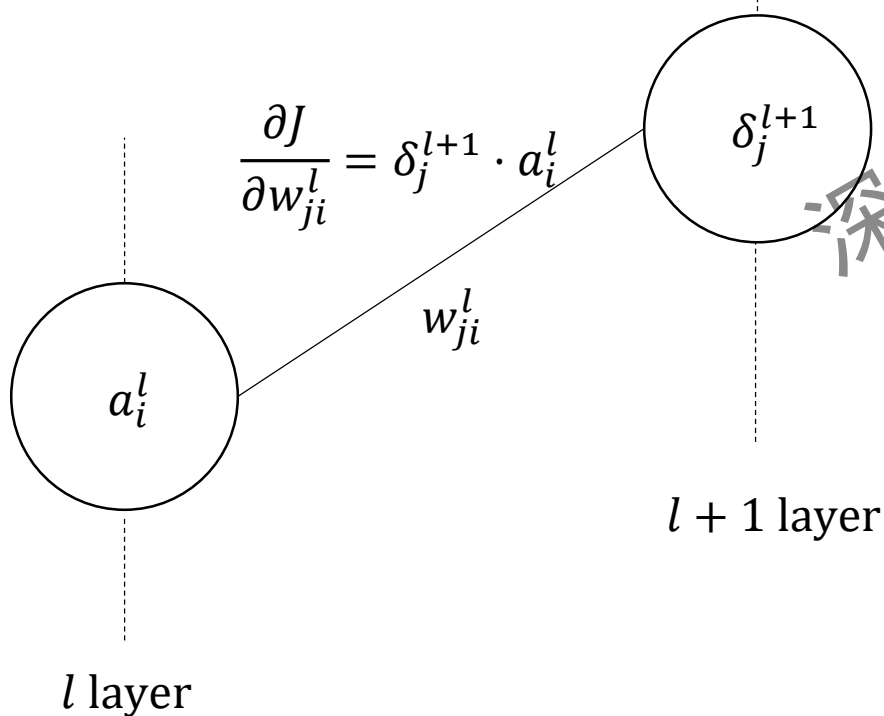
$$w_{ij}^l(new) \leftarrow w_{ij}^l(old)$$



Learning in Neural Networks

BP Learning Algorithm

$$w_{ij}^l \leftarrow w_{ij}^l - \alpha \cdot (\delta_j^{l+1} \cdot a_i^l)$$
$$w_{ji}^l \leftarrow w_{ji}^l - \alpha \cdot \left(\frac{\partial J}{\partial z_j^{l+1}} \right) \cdot f(z_i^l)$$



On the Network Learning Rule

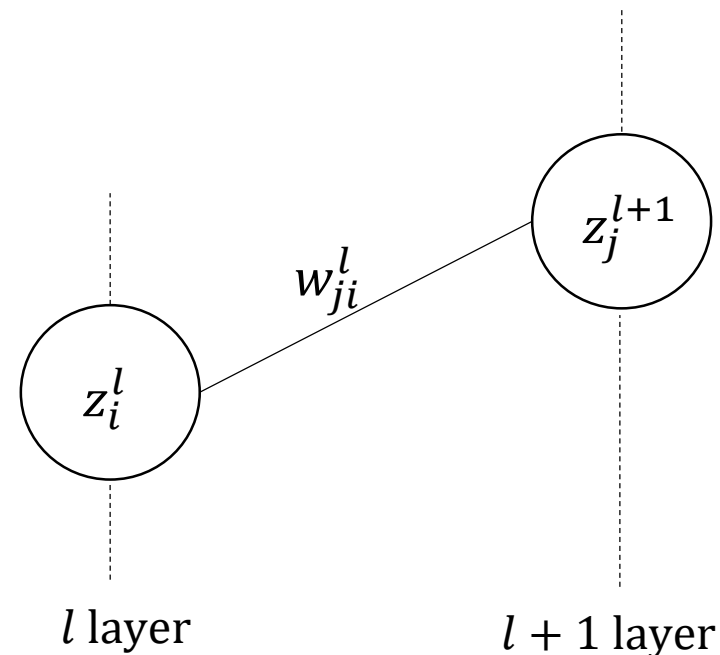
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Hebbian Learning

$$w_{ji}^l \leftarrow w_{ji}^l + F(z_j^{l+1}, z_i^l)$$

BP Learning

$$w_{ji}^l \leftarrow w_{ji}^l - \alpha \cdot \left(\frac{\partial J}{\partial z_j^{l+1}} \right) \cdot f(z_i^l)$$



$$F(z_j^{l+1}, z_i^l) = -\alpha \cdot \left(\frac{\partial J}{\partial z_j^{l+1}} \right) \cdot f(z_i^l)$$

Outline

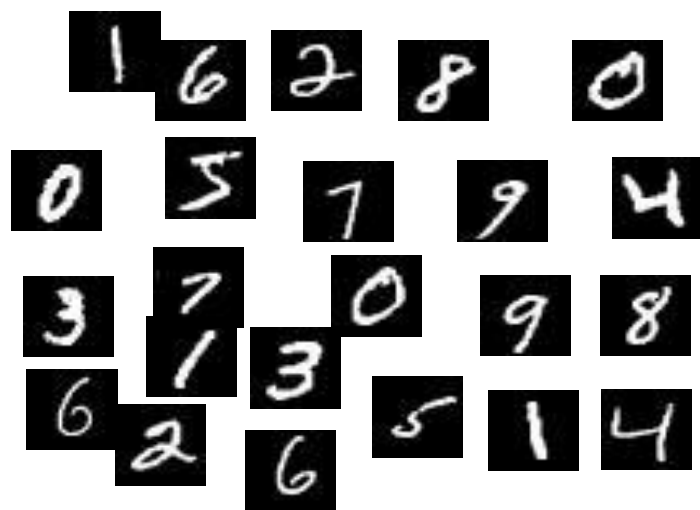
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Supervised Learning

■ Supervised Learning

- Learning with a supervisor
- The supervisor knows the correct answer
- Each training sample must contain input and target

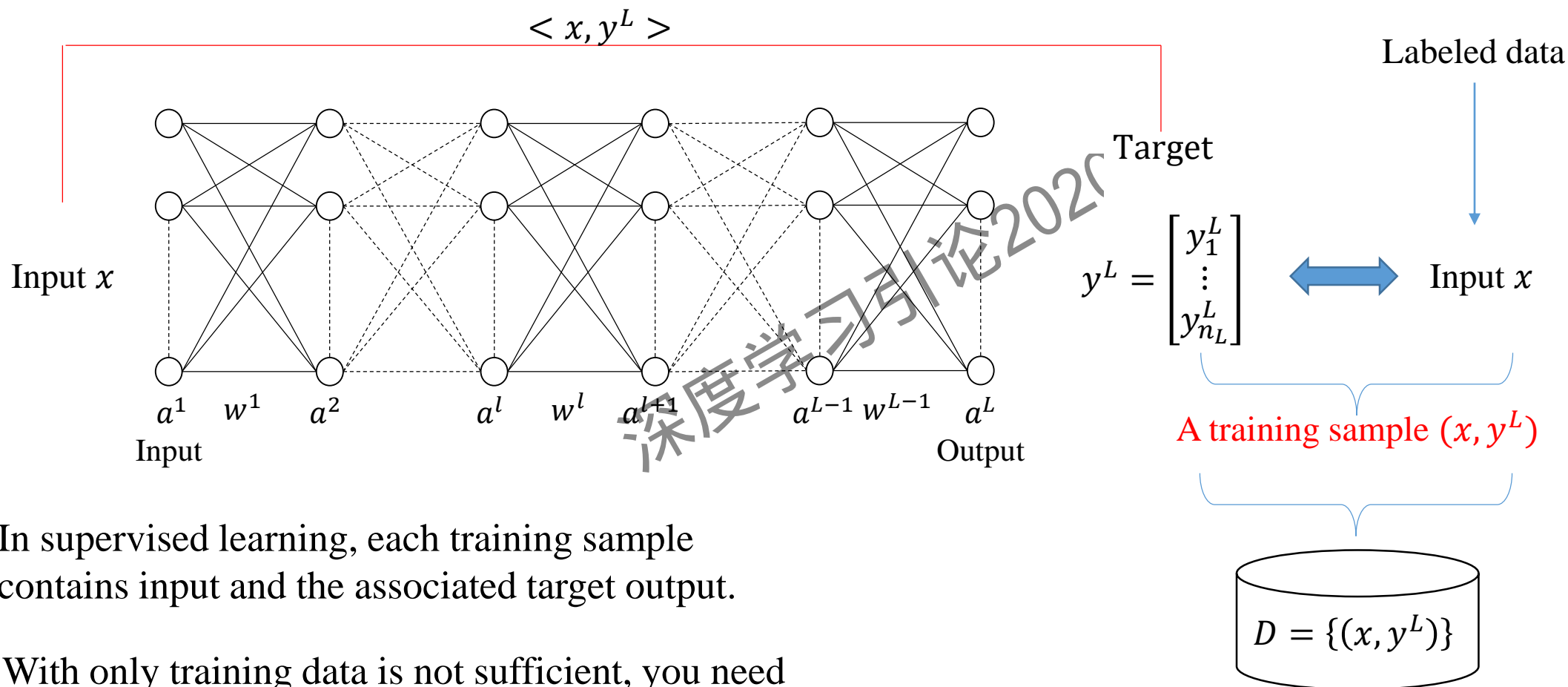
Learn from supervisor



Learn from parent



Supervised Learning



In supervised learning, each training sample contains input and the associated target output.

With only training data is not sufficient, you need a learning algorithm to update the knowledge, i.e., updating the connection weights in the network.

A training data set is a set composed by training samples

Supervised Learning

The well known BP algorithm is a supervised learning algorithm.

$$D = \{(x, y^L)\}$$

Network prediction

Target

$$a^L = \begin{bmatrix} a_1^L \\ \vdots \\ a_{n_L}^L \end{bmatrix} \quad y^L = \begin{bmatrix} y_1^L \\ \vdots \\ y_{n_L}^L \end{bmatrix}$$

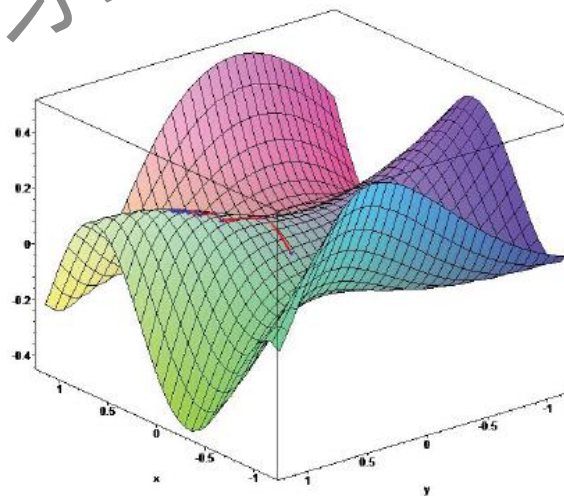
Cost function (Energy Function)

$$J = J(w^1, \dots, w^{L-1})$$

$$\frac{\partial J}{\partial w_{ji}^l} = \delta_j^{l+1} \cdot a_i^l$$

Forward computing a^l

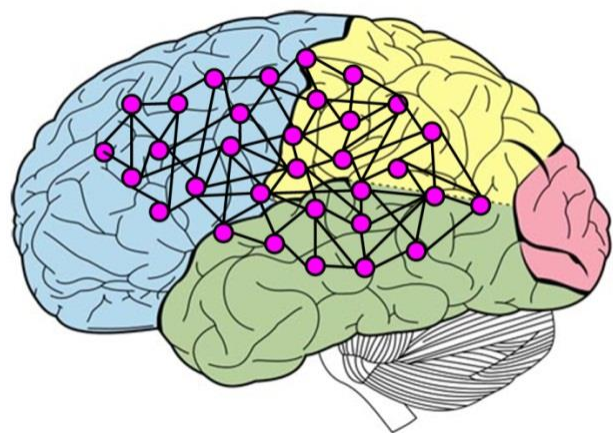
Backpropagation δ^l



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- **Unsupervised Learning**
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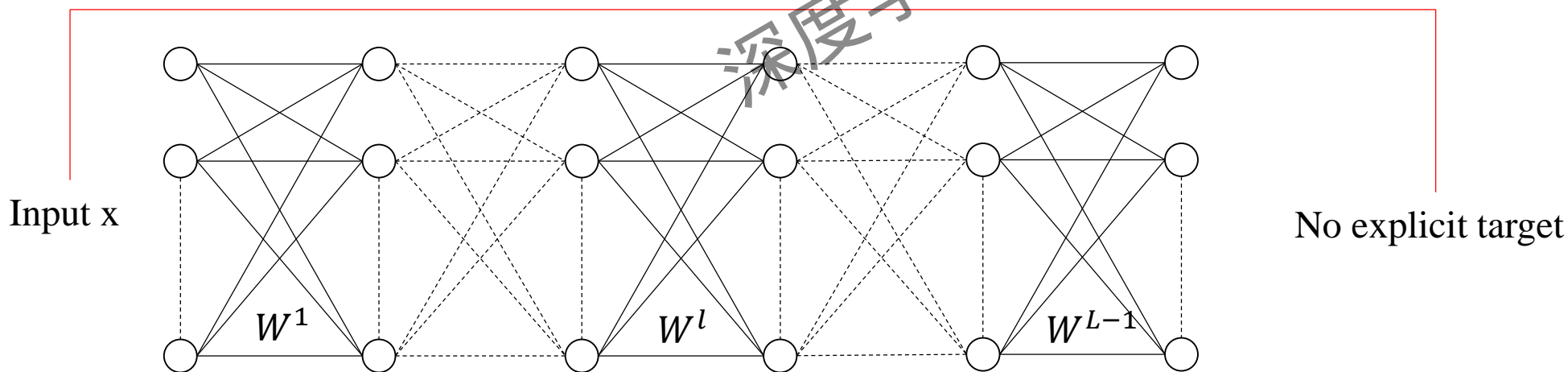
Unsupervised Learning



■ Unsupervised Learning

- Learning without supervisor
- Each training sample do not have any explicit target

Neural Network



Problem: How can I learn without a supervisor?

Unsupervised Learning: Feature Extraction

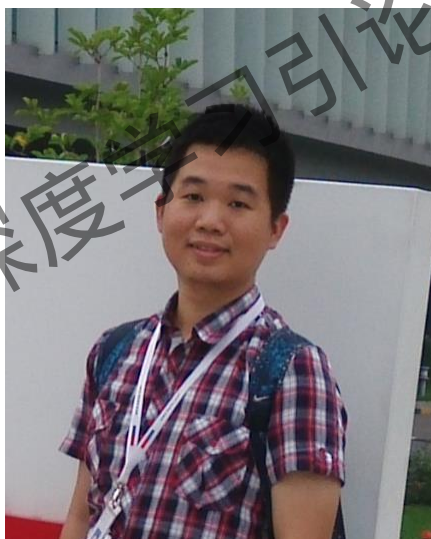
Can we learn something without a supervisor?



What's this?!

No body can tell the student what this is.

Unsupervised Learning: Feature Extraction

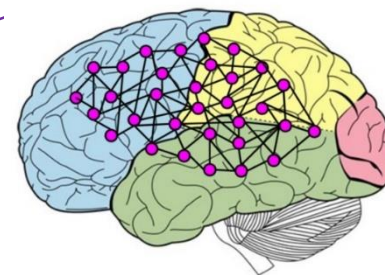


Haha, I saw it
yesterday.

Unsupervised Learning: Feature Extraction

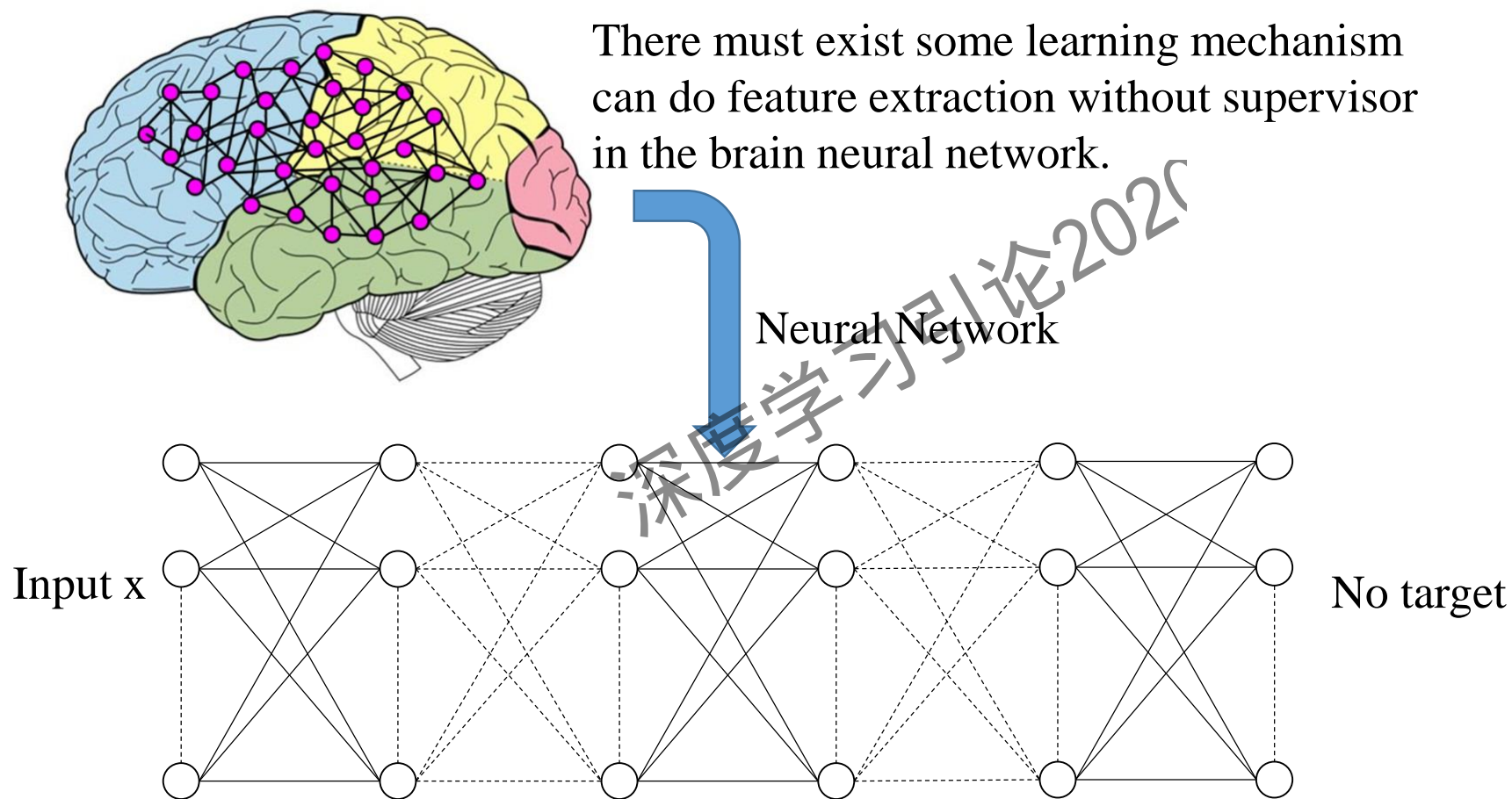


They are not the same one.
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Without a supervisor, how can
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Unsupervised Learning: Feature Extraction

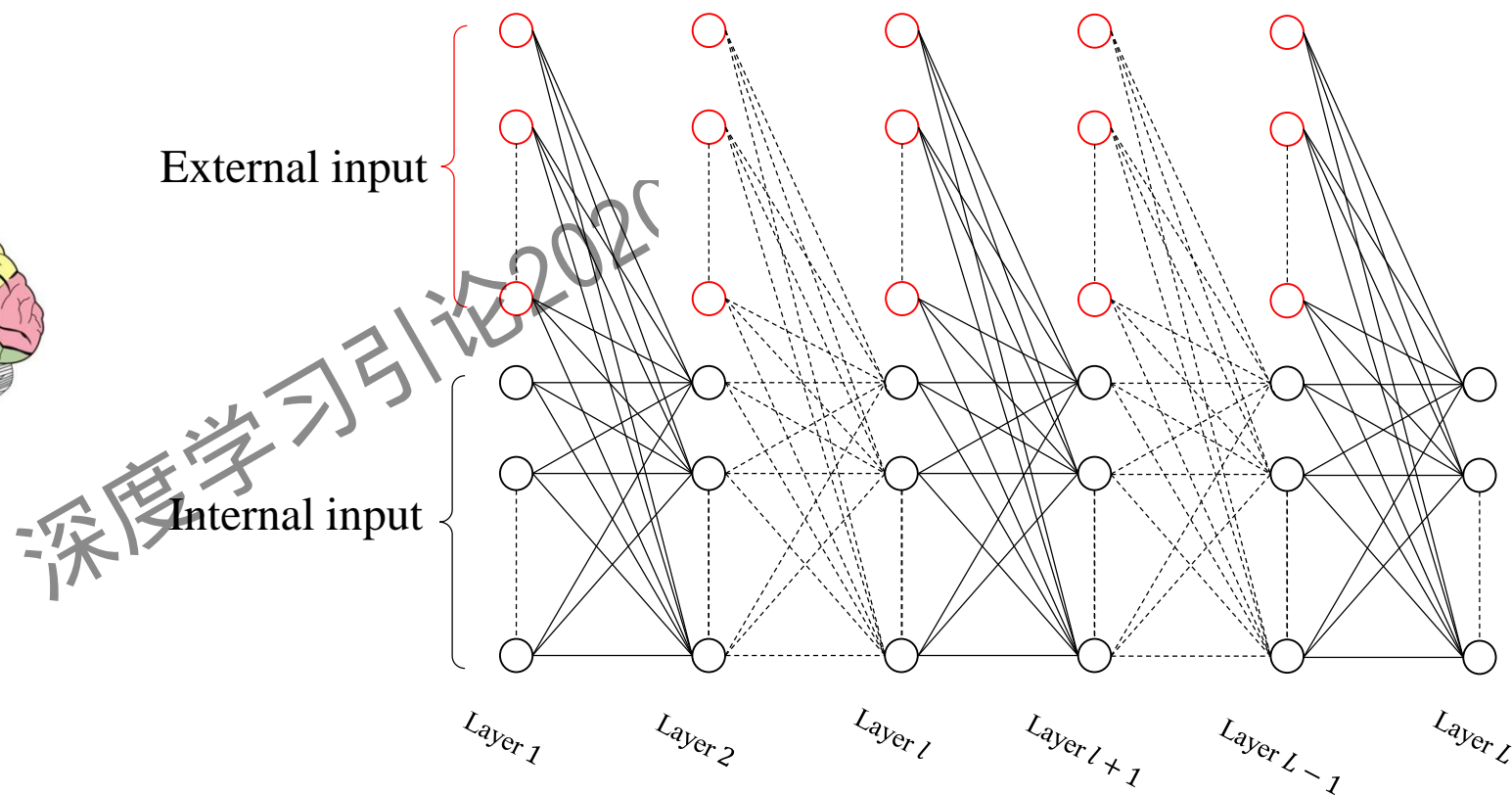
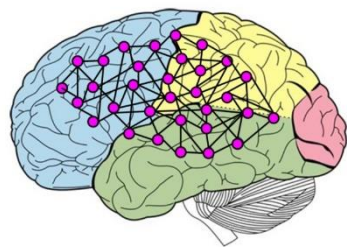


Problem: How to develop algorithms such that an artificial network can learn without any supervisor?

Outline

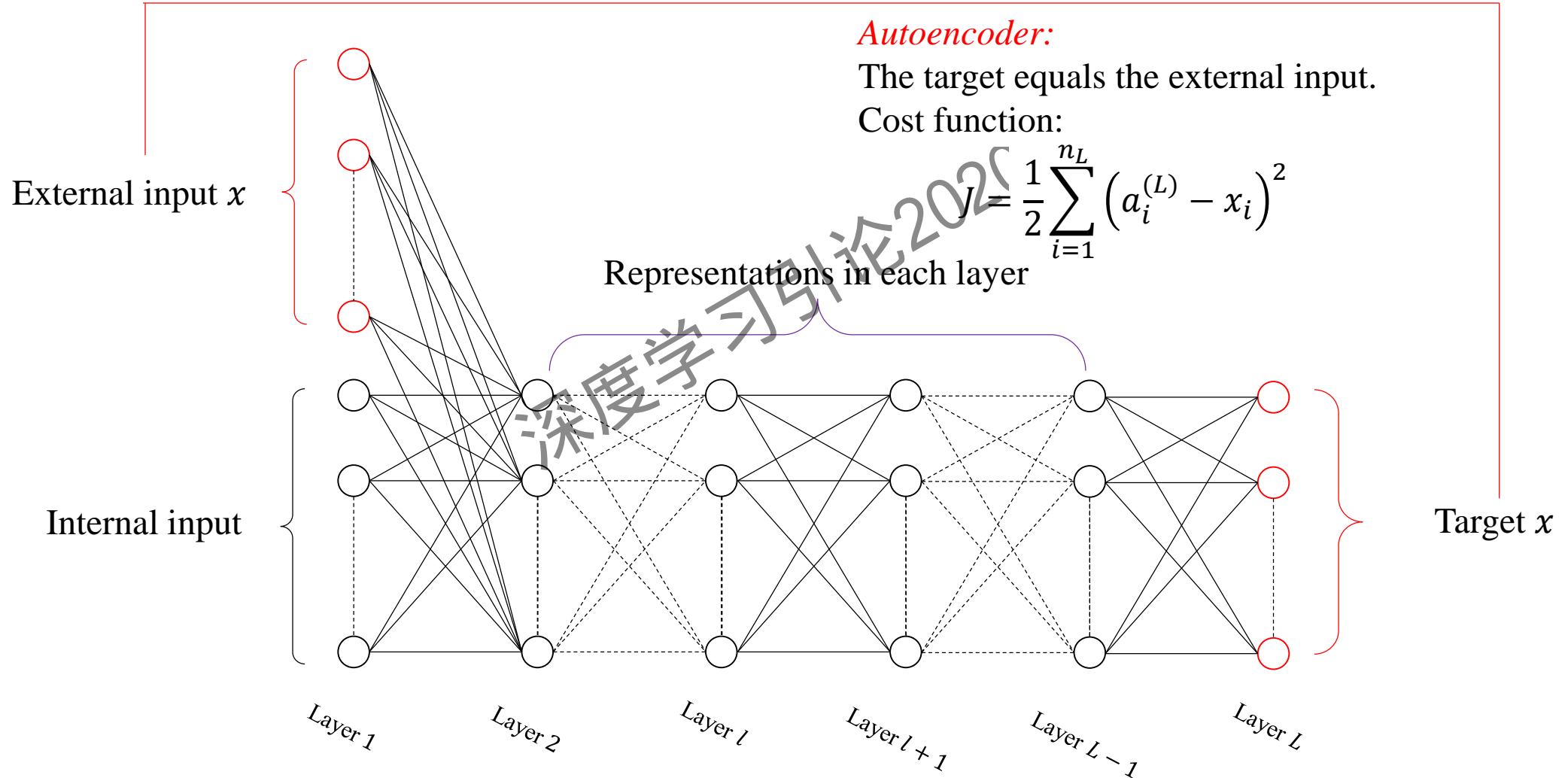
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Autoencoder Neural Networks

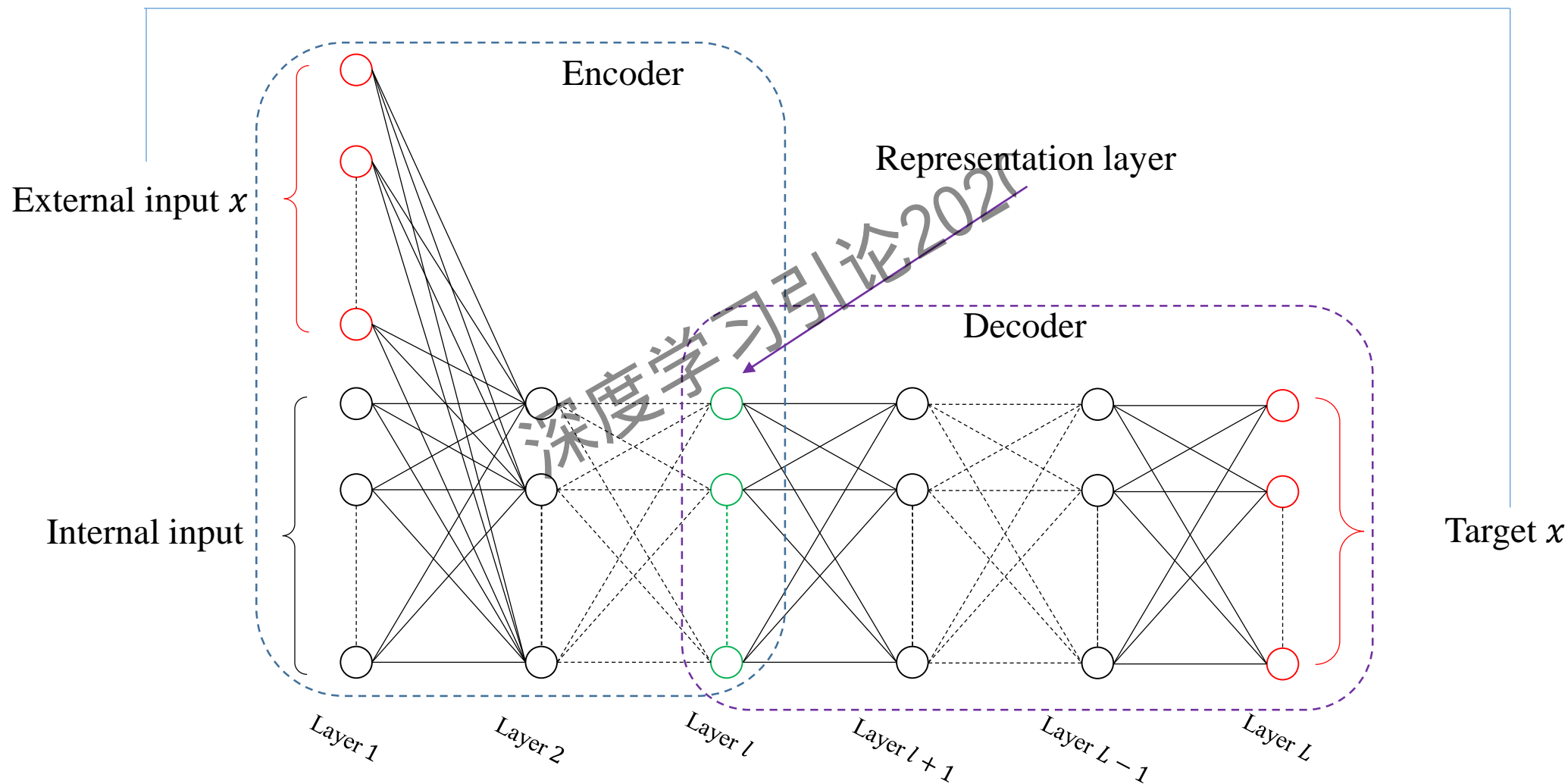


The well-known network structure

Autoencoder Neural Networks



Autoencoder Neural Networks



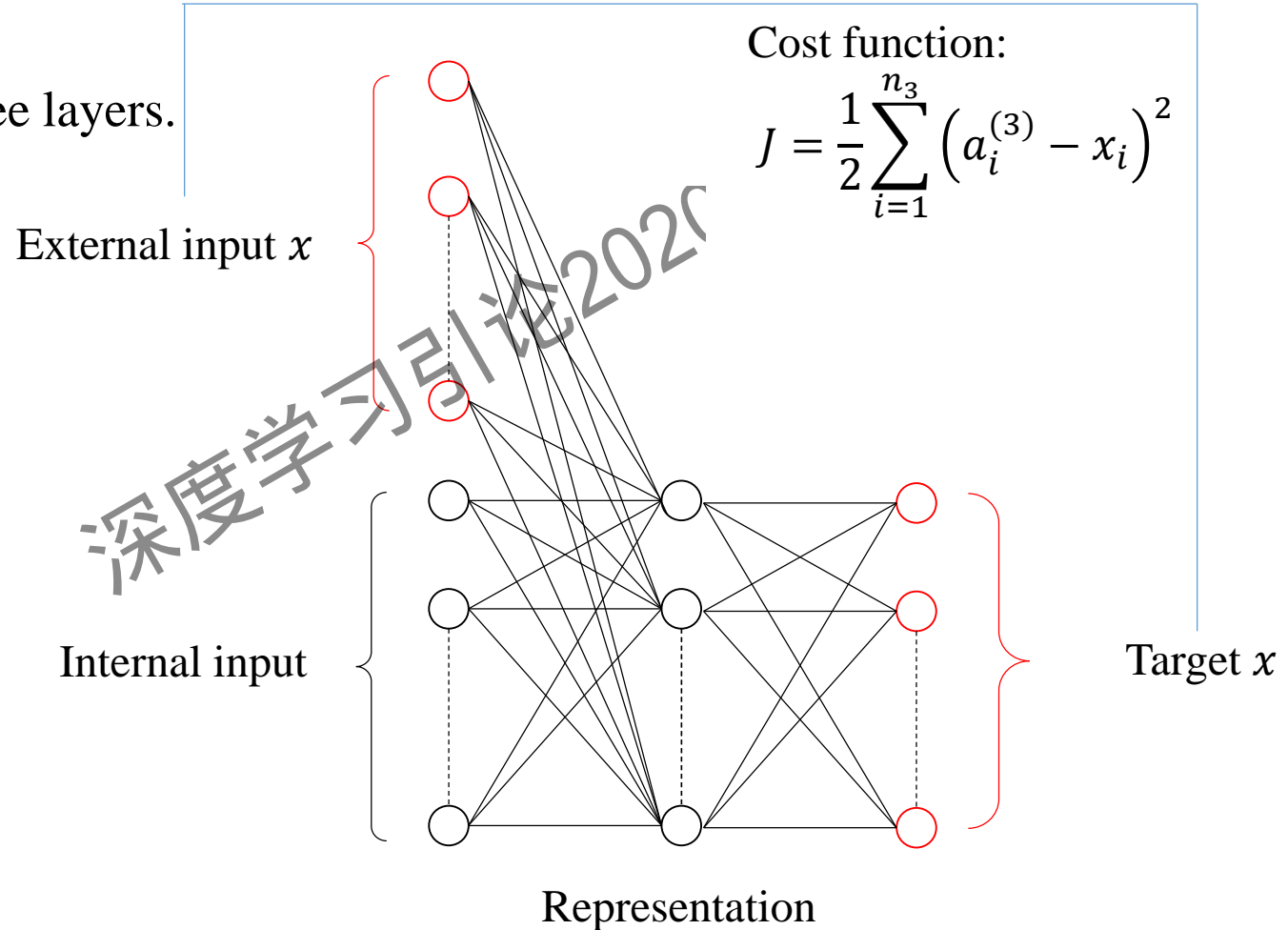
Autoencoder Neural Networks

Simplest Autoencoder:

The simplest autoencoder contains three layers.

$$a_i^{(2)} = f\left(\sum_{j=1}^{n_1} w_{ij}^{(1)} a_j^{(1)}\right)$$

$$a_i^{(3)} = f\left(\sum_{j=1}^{n_2} w_{ij}^{(2)} a_j^{(2)}\right)$$



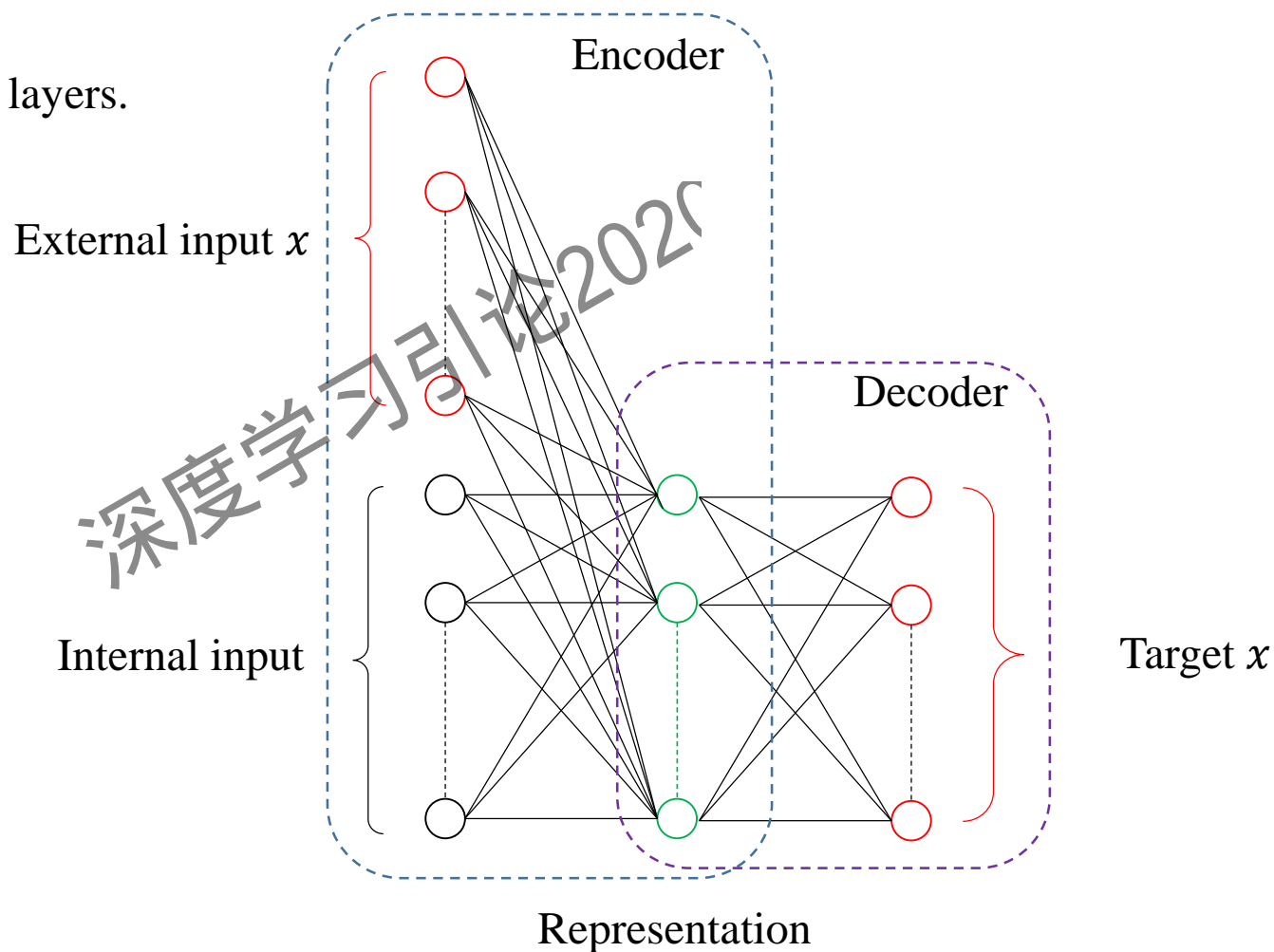
Autoencoder Neural Networks

Simplest Autoencoder:

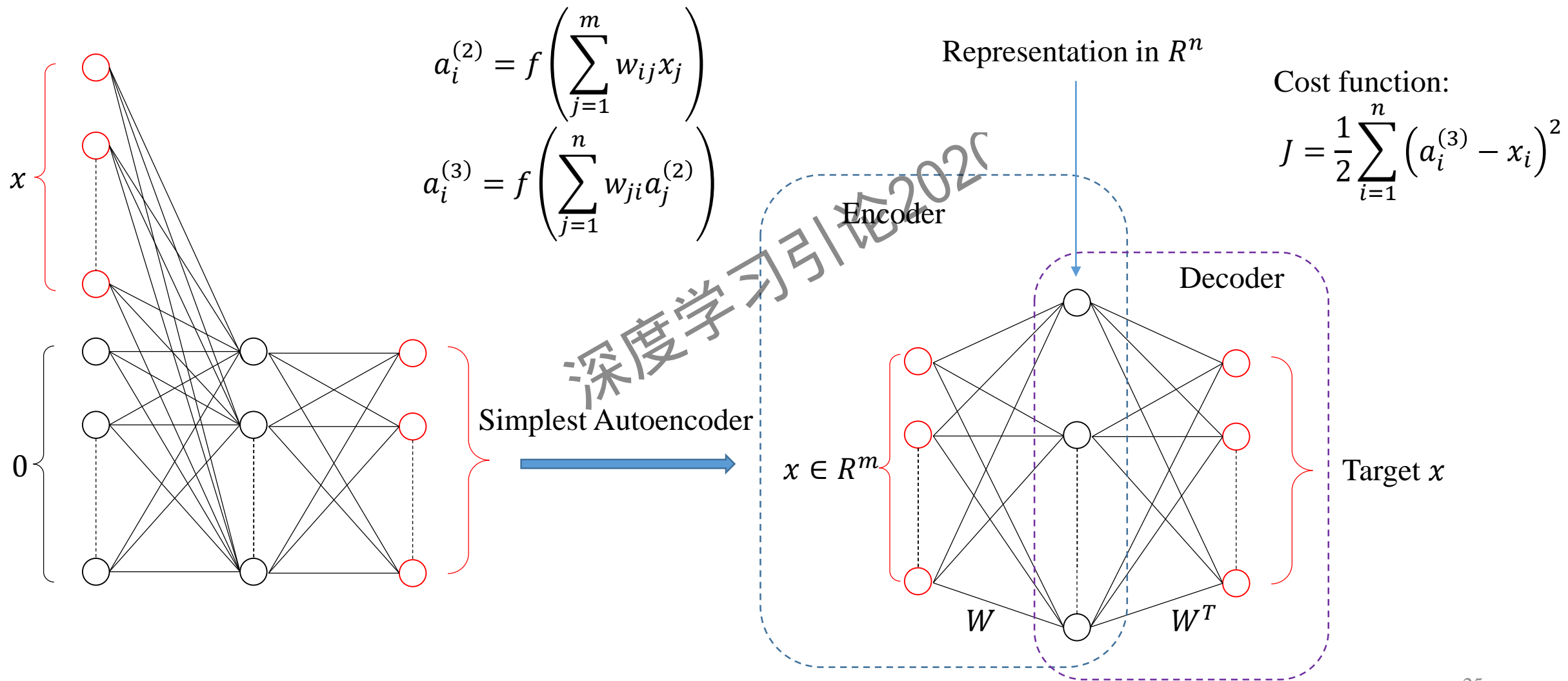
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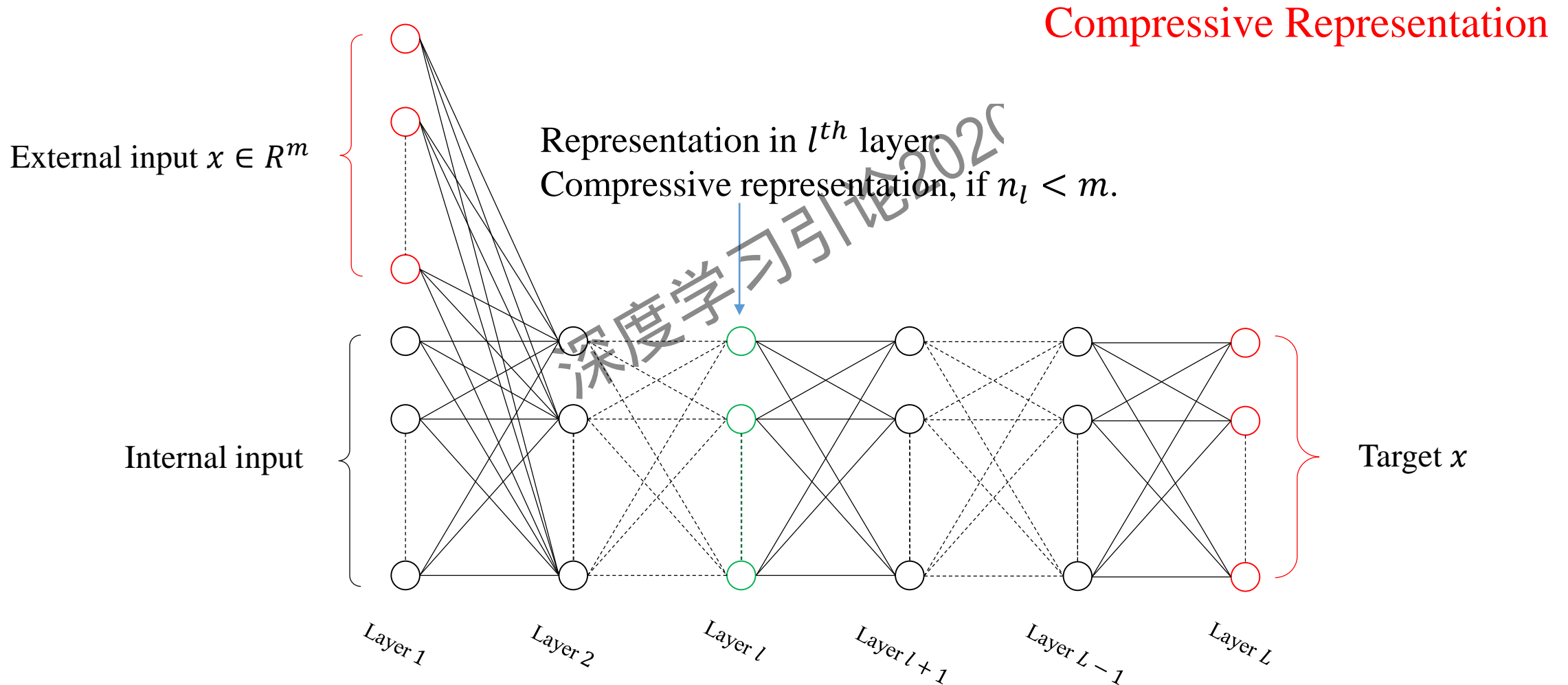
Autoencoder Neural Networks



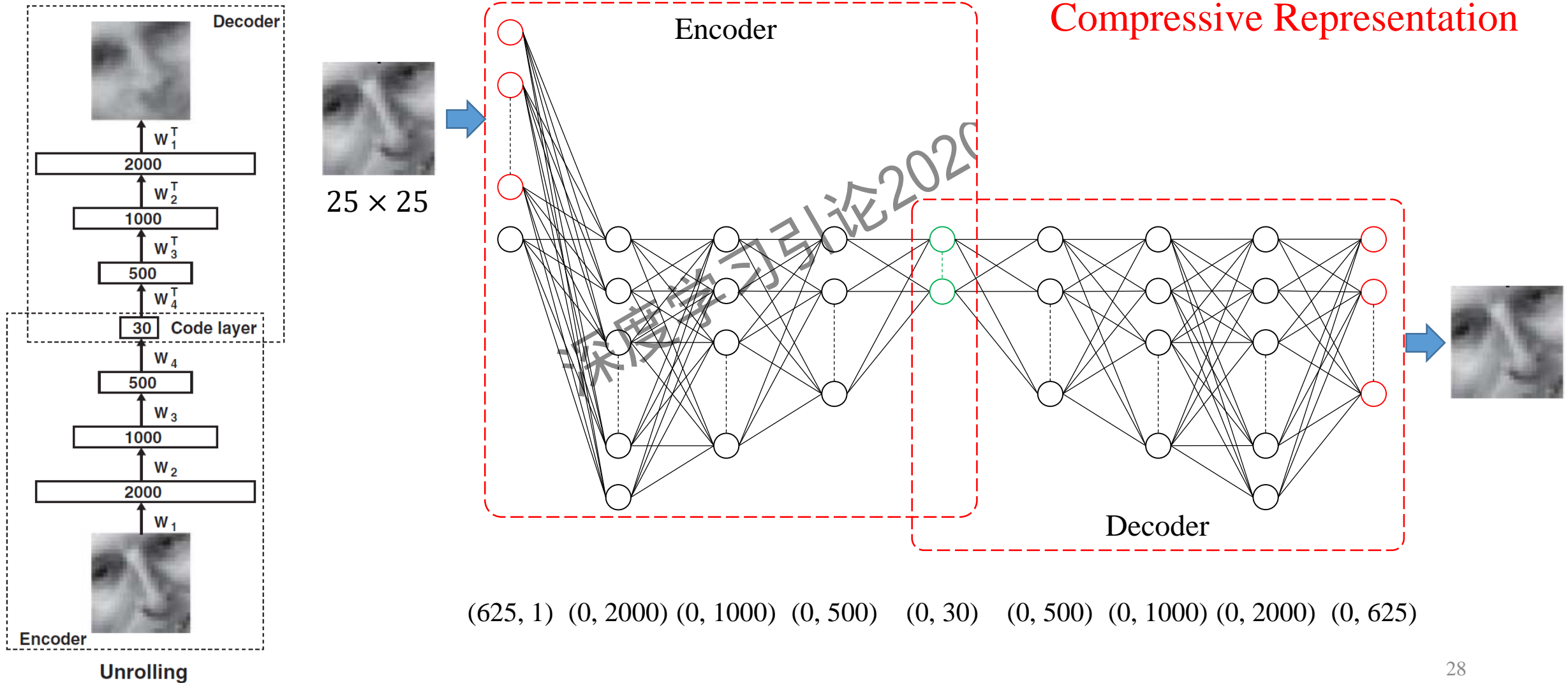
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Autoencoder Neural Networks



Autoencoder Neural Networks

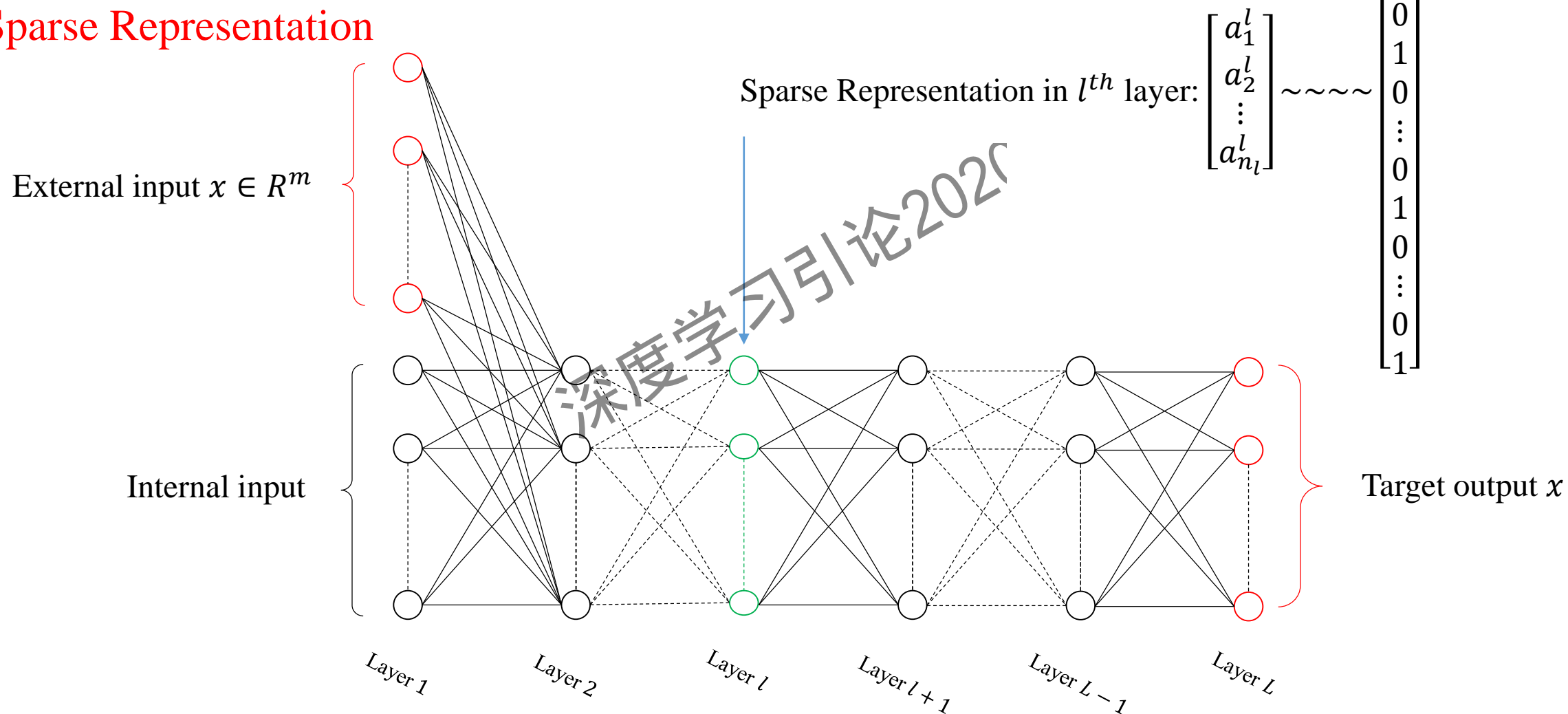


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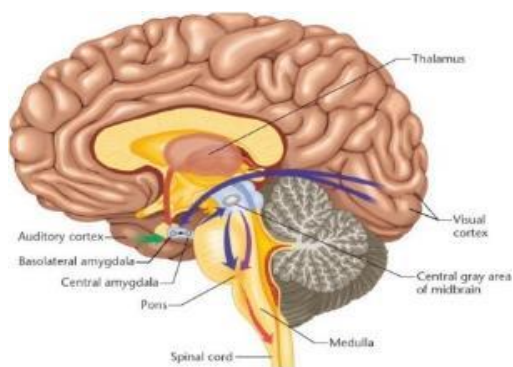
Sparse Representation



Autoencoder Neural Networks

Sparse Representation

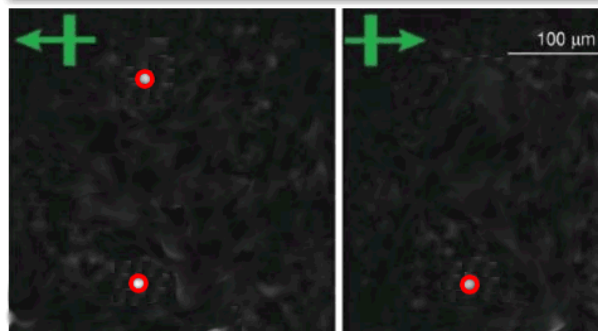
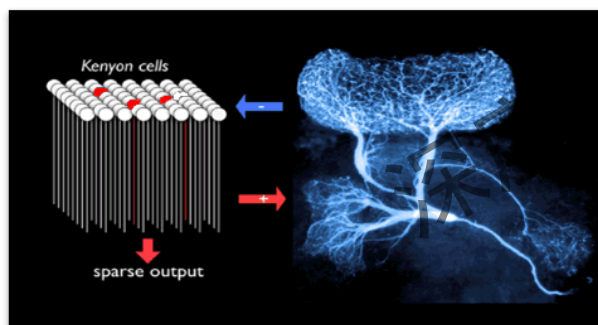
The brain represents information in sparsity way.



nature

Emergence of simple-cell receptive field properties by learning a sparse code for natural images

Bruno A. Olshausen and David J. Field
Nature **381**, 607 - 609 (13 June 1996);
doi:10.1038/381607a0

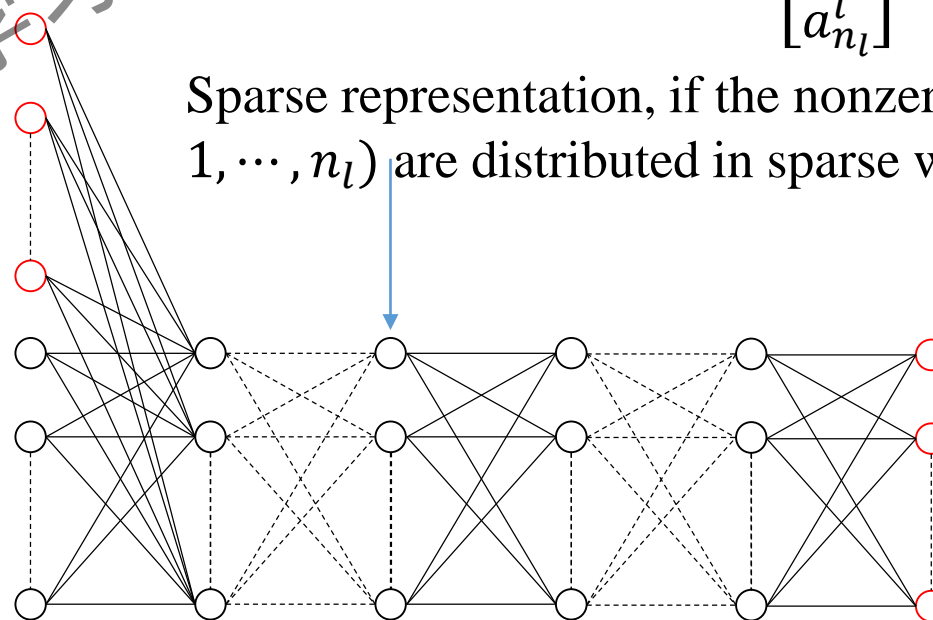


Problem:

How to get sparse representation?

Representation in l^{th} layer: $\begin{bmatrix} a_1^l \\ a_2^l \\ \vdots \\ a_{n_l}^l \end{bmatrix}$

Sparse representation, if the nonzero $a_i^l (i = 1, \dots, n_l)$ are distributed in sparse way.



Autoencoder Neural Networks

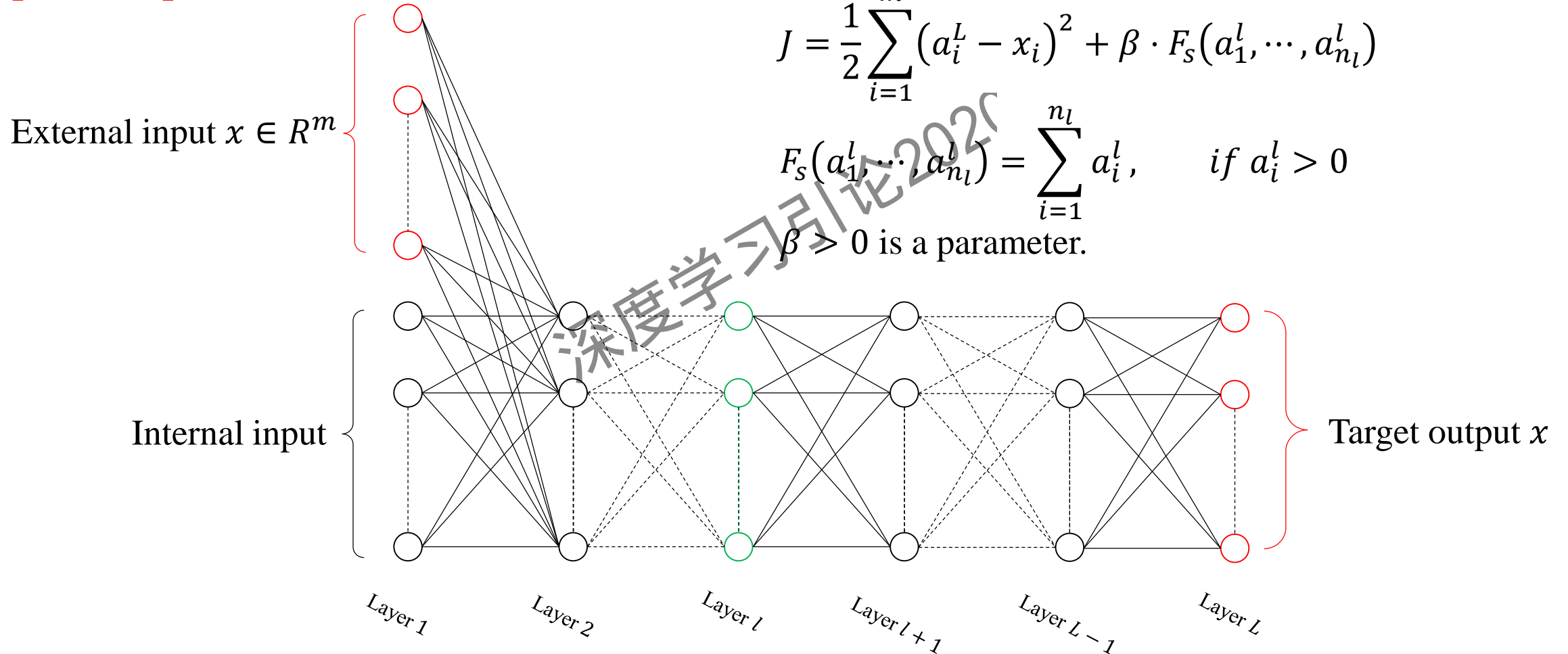
Sparse Representation

■ Cost function:

$$J = \frac{1}{2} \sum_{i=1}^m (a_i^L - x_i)^2 + \beta \cdot F_s(a_1^l, \dots, a_{n_l}^l)$$

$$F_s(a_1^l, \dots, a_{n_l}^l) = \sum_{i=1}^{n_l} a_i^l, \quad \text{if } a_i^l > 0$$

$\beta > 0$ is a parameter.



Autoencoder Neural Networks

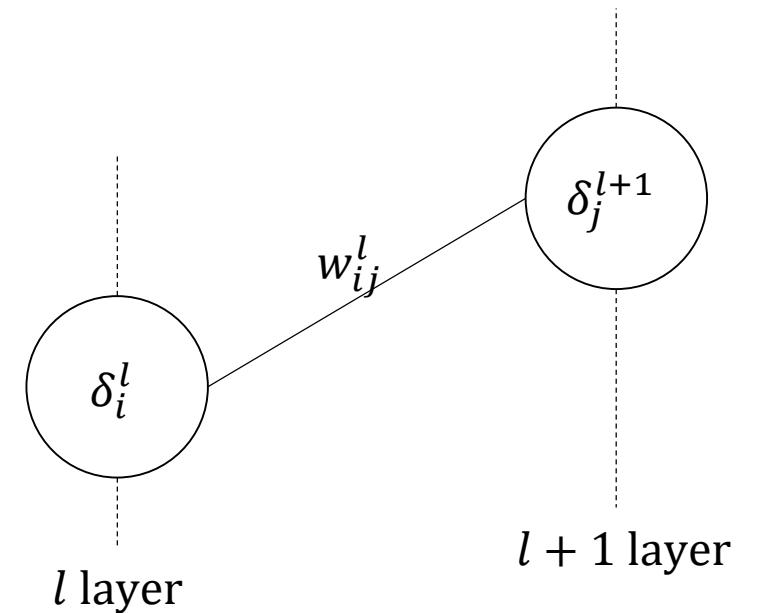
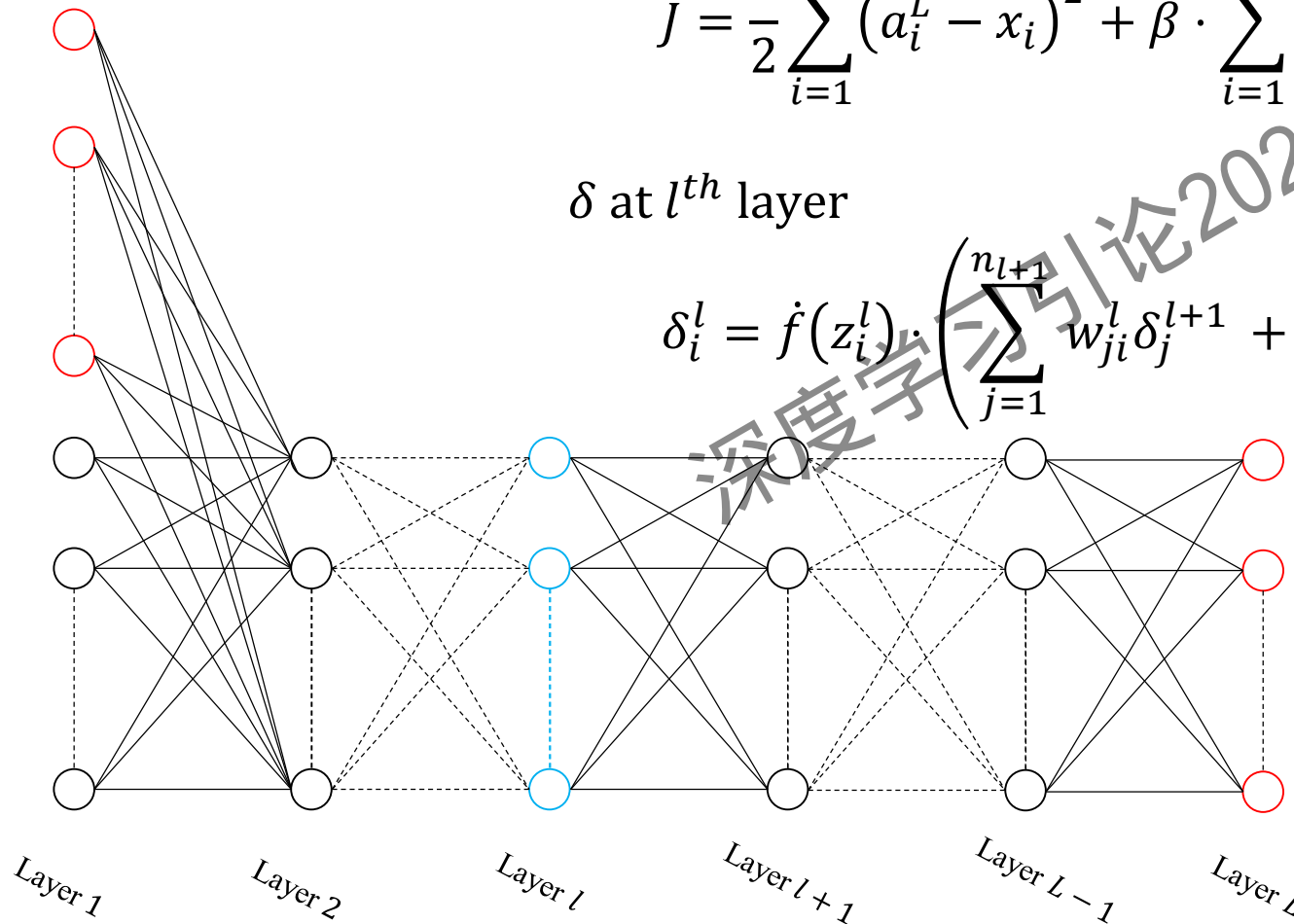
Sparse Representation

Cost function

$$J = \frac{1}{2} \sum_{i=1}^m (a_i^L - x_i)^2 + \beta \cdot \sum_{i=1}^{n_l} a_i^l$$

δ at l^{th} layer

$$\delta_i^l = \dot{f}(z_i^l) \cdot \left(\sum_{j=1}^{n_{l+1}} w_{ji}^l \delta_j^{l+1} + \beta \right)$$



l layer i^{th} neuron

$$\frac{a_i^l = f(z_i^l)}{\delta_i^l = \frac{\partial J}{\partial z_i^l}}$$

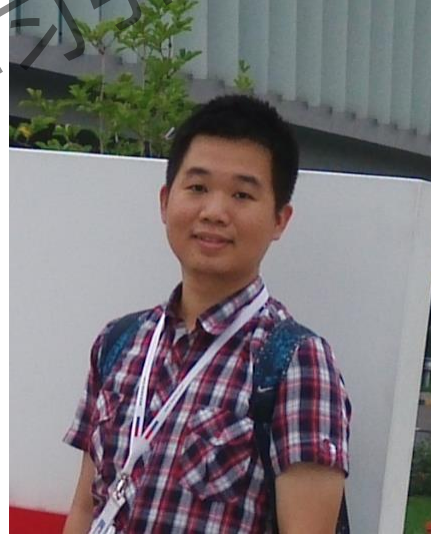
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Autoencoder Neural Networks

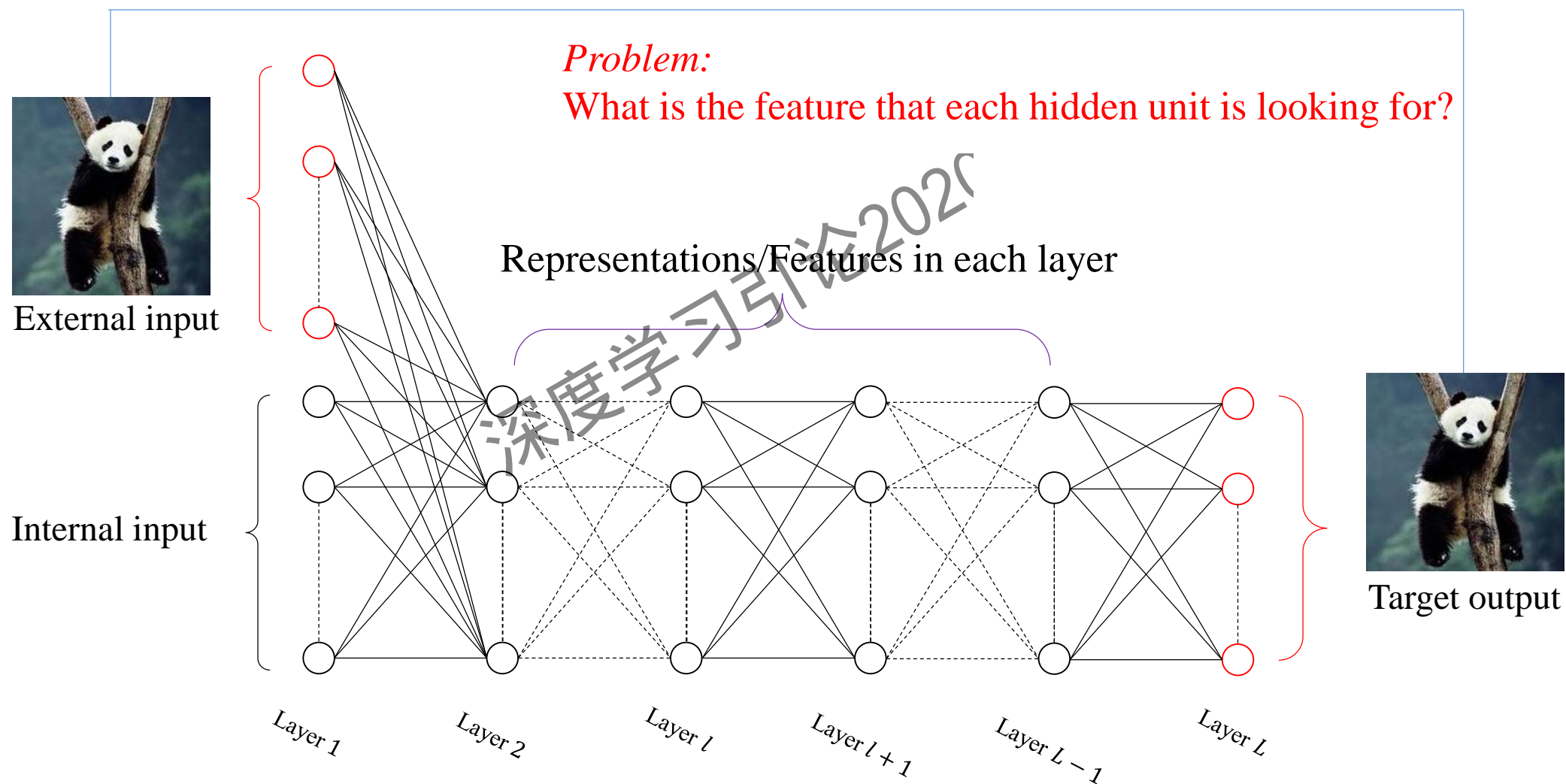


They are not the same one.
The student successfully
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Without a supervisor, how can
the student learn that the fruits in
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Autoencoder Neural Networks



Autoencoder Neural Networks

Problem:

What is the feature that hidden neuron i is looking for?

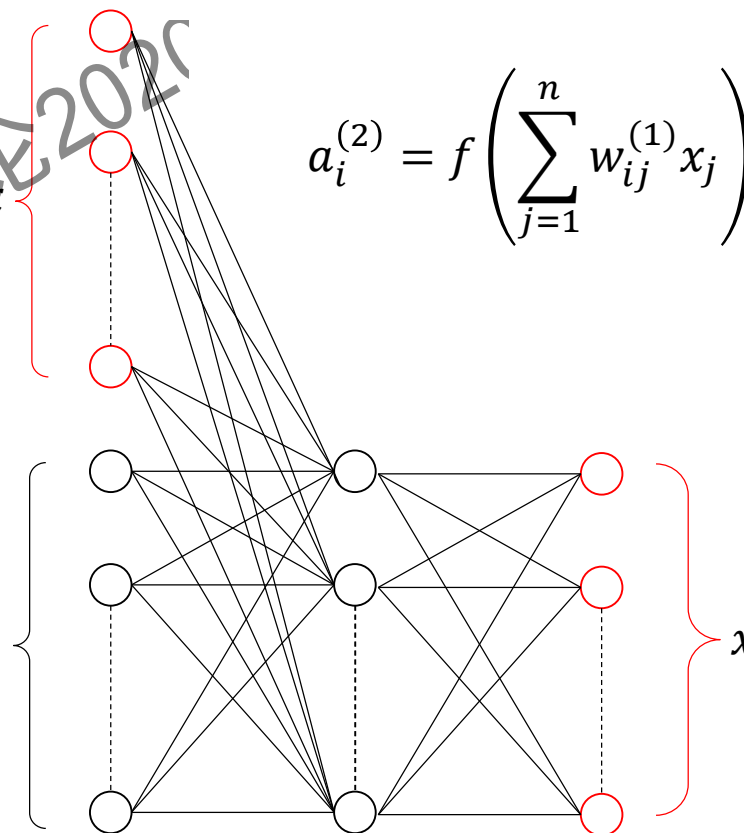
In other words, what input image x cause $a_i^{(2)}$ to be maximally activated?

$$\begin{cases} \max \sum_{i=1}^n w_{ij}^{(1)} x_j \\ \text{s. t. } \sum_{i=1}^n x_i^2 \leq 1 \end{cases}$$

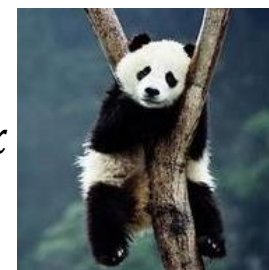
$$x_j = \frac{w_{ij}^{(1)}}{\sqrt{\sum_{j=1}^n (w_{ij}^{(1)})^2}}, (j = 1, \dots, n)$$



Internal input
 $a_i^{(1)} = 0$



$$a_i^{(2)} = f\left(\sum_{j=1}^n w_{ij}^{(1)} x_j\right)$$



Exercise: How to solve this problem?

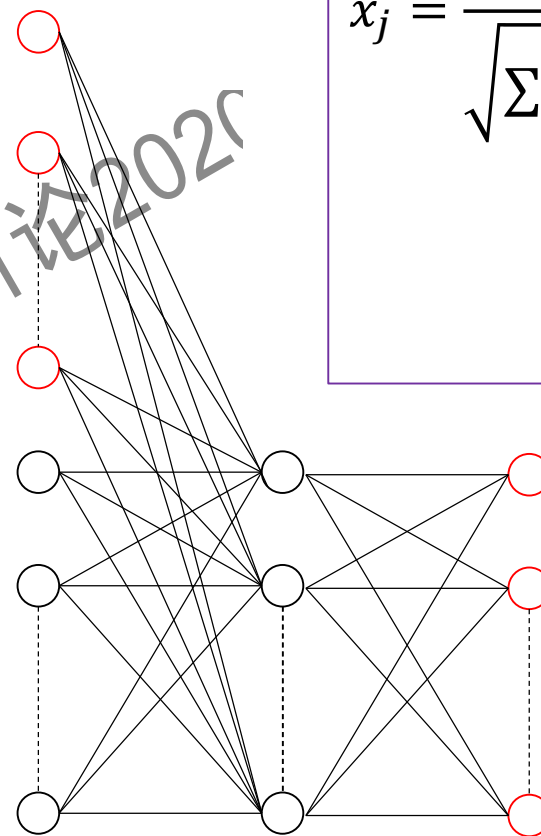
Autoencoder Neural Networks

Problem:

What is the feature that hidden neuron i is looking for?



Train the Net



$$x_j = \frac{w_{ij}^{(1)}}{\sqrt{\sum_{j=1}^n (w_{ij}^{(1)})^2}}, (j = 1, \dots, n)$$

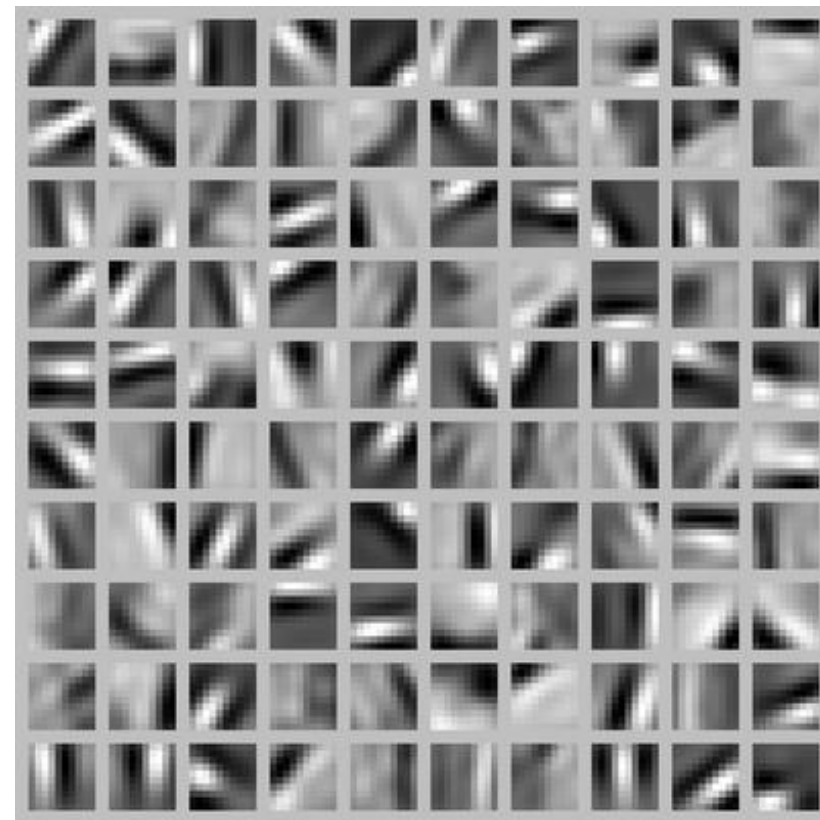
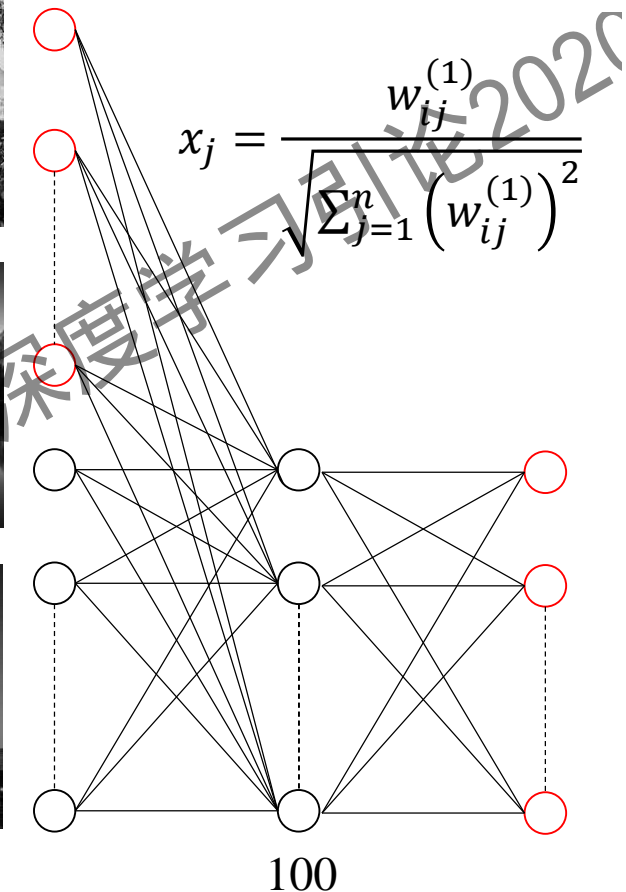
?

Autoencoder Neural Networks

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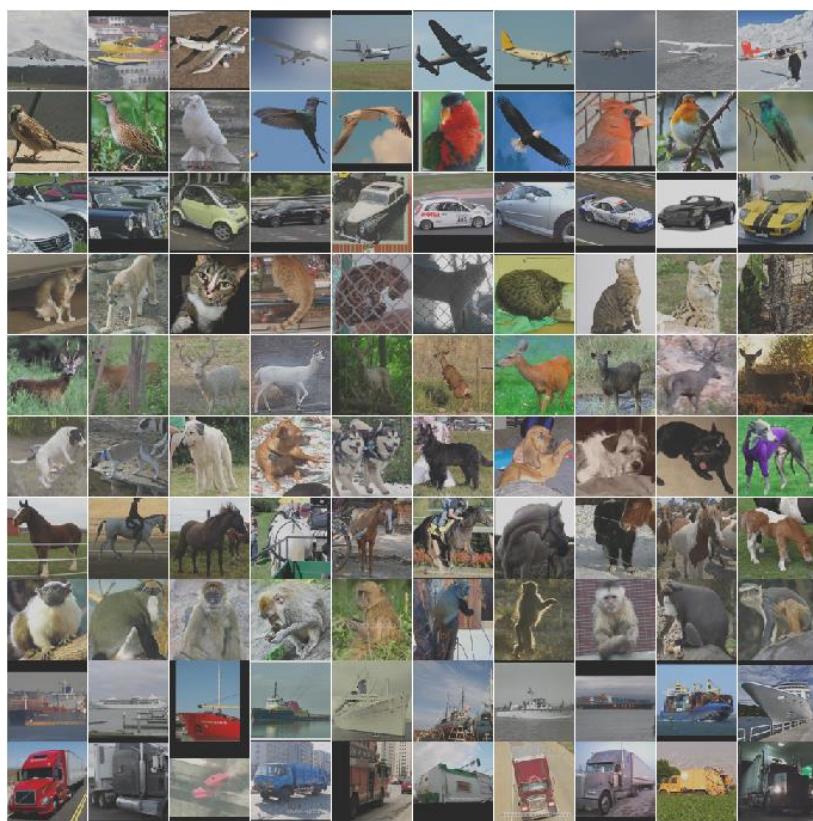
Edges at different positions and orientations



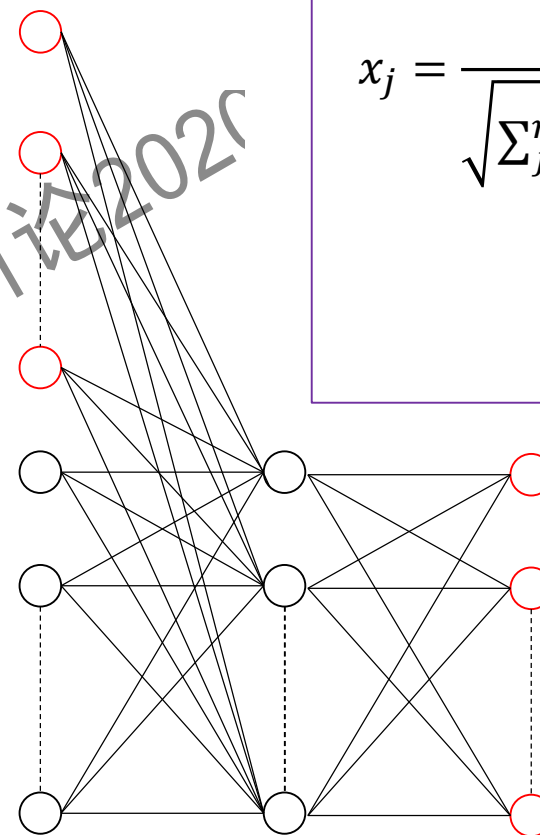
Autoencoder Neural Networks

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Train the Net



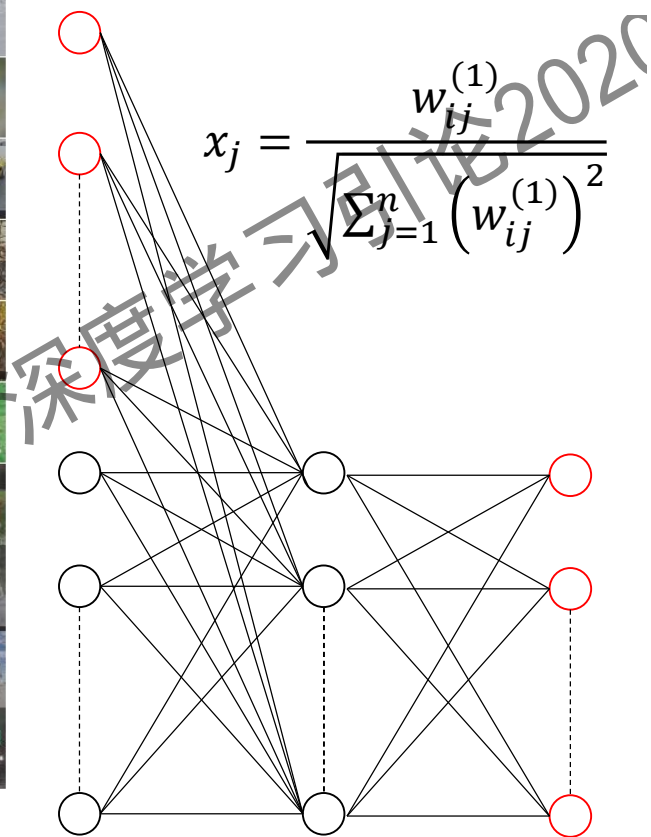
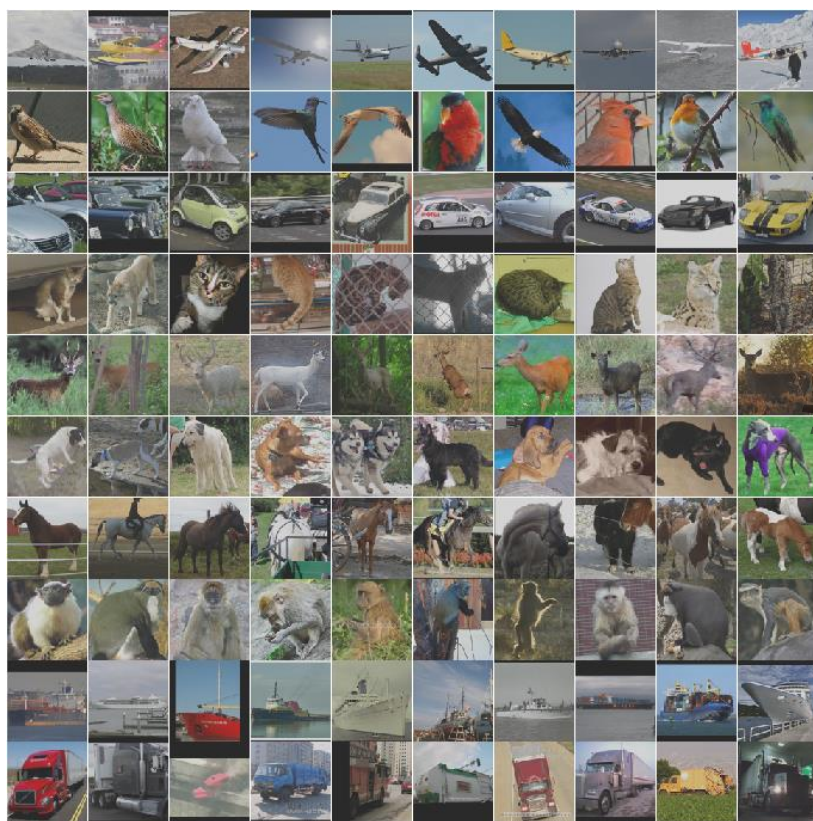
$$x_j = \frac{w_{ij}^{(1)}}{\sqrt{\sum_{j=1}^n (w_{ij}^{(1)})^2}}, (j = 1, \dots, n)$$

?

Autoencoder Neural Networks

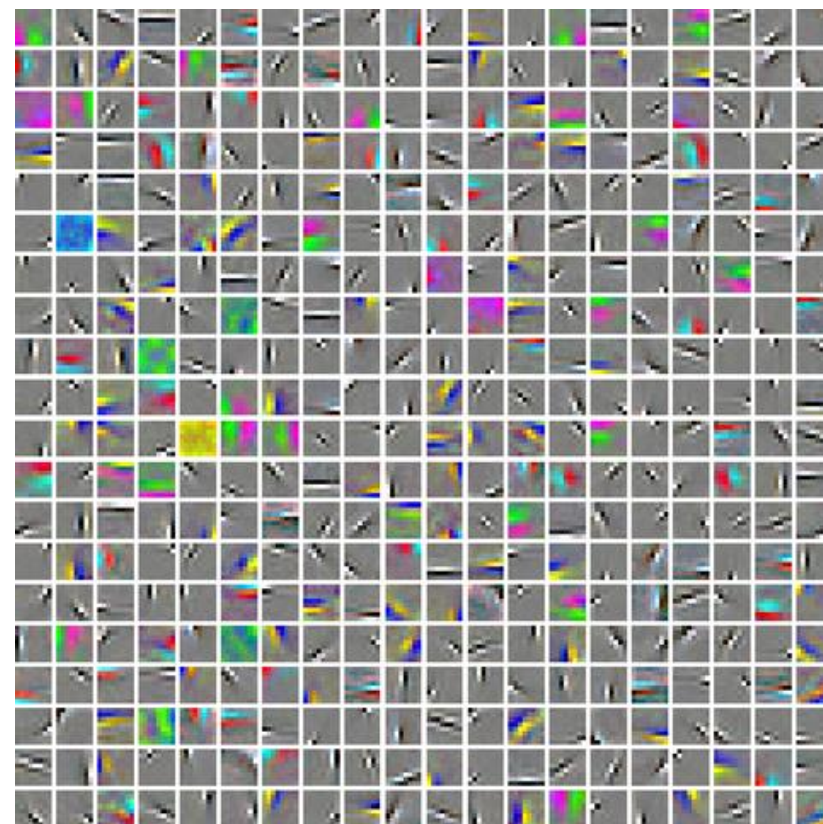
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$$x_j = \frac{w_{ij}^{(1)}}{\sqrt{\sum_{j=1}^n (w_{ij}^{(1)})^2}}$$

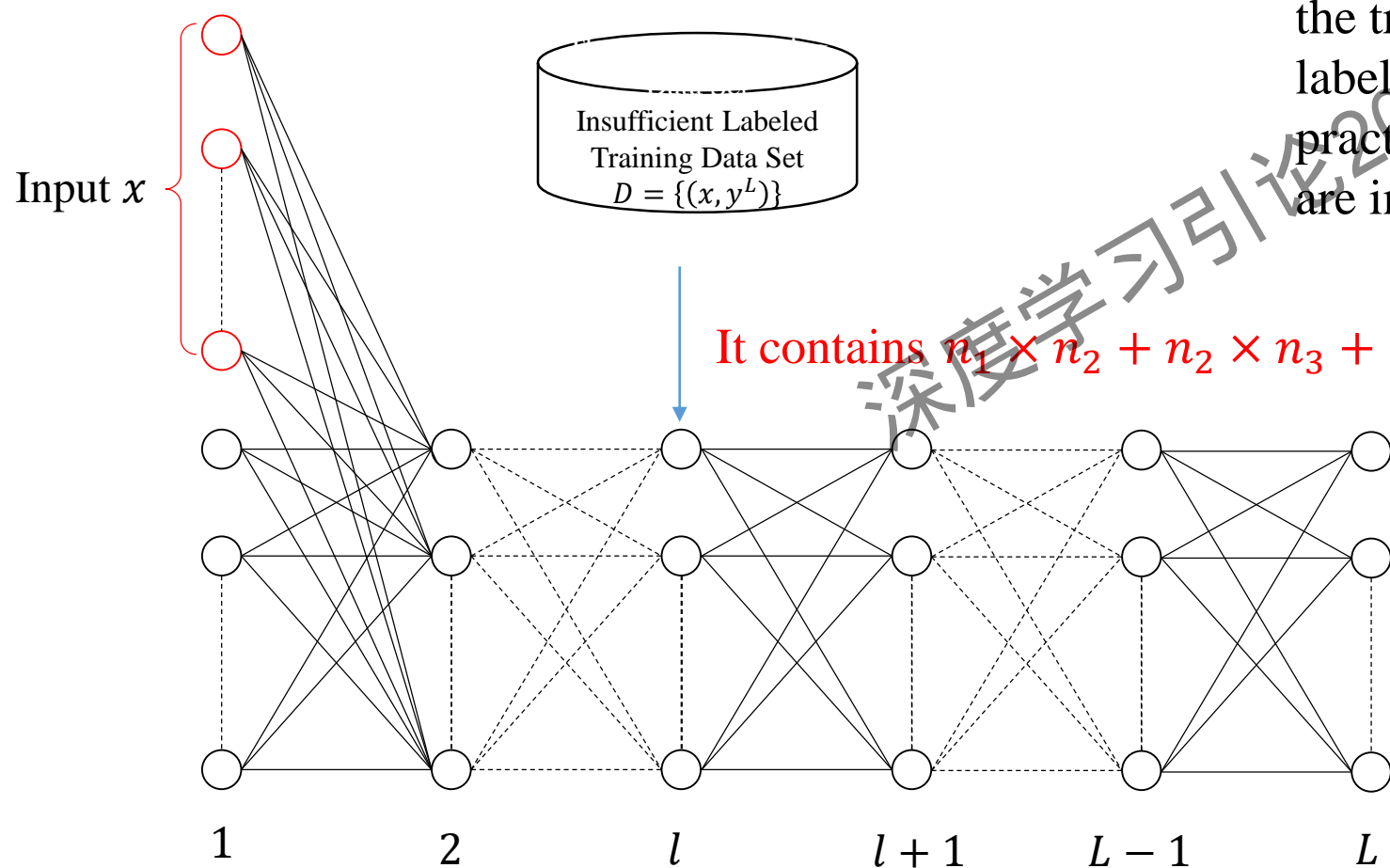
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Application to Supervised Learning

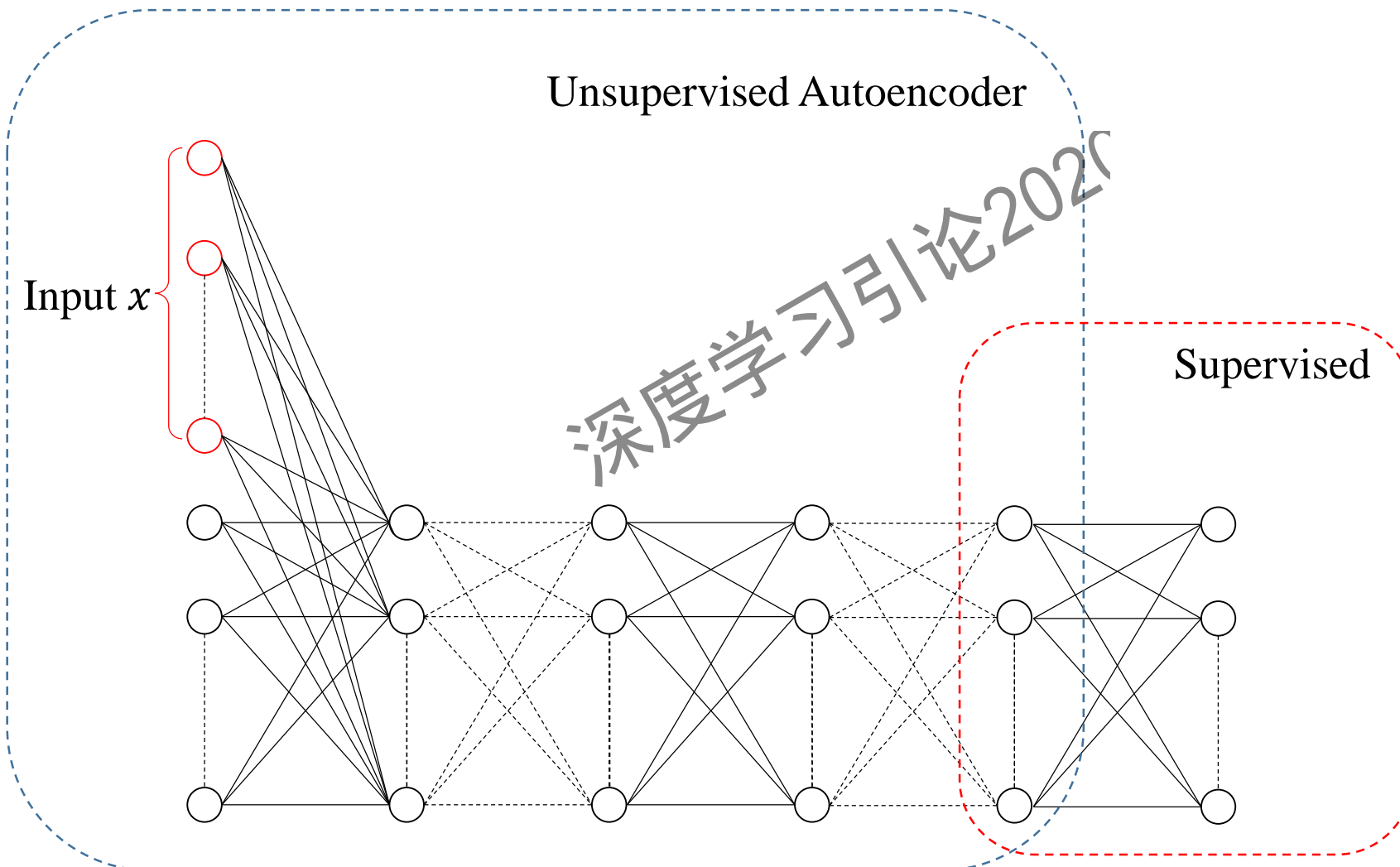


In supervised learning, to train the network, the training data set should contain sufficient labeled training data. However, in many practice applications, the labeled training data are insufficient. How to solve this problem?

Target

$$y^L = \begin{bmatrix} y_1^L \\ \vdots \\ y_{n_L}^L \end{bmatrix}$$

Application to Supervised Learning



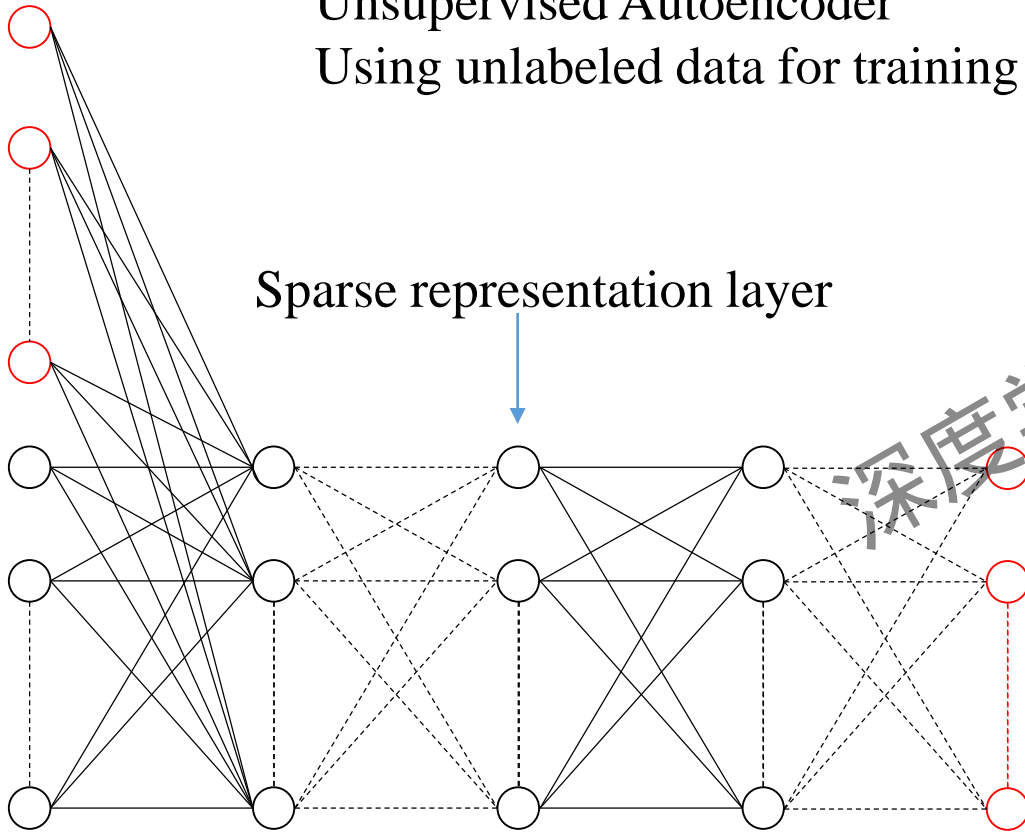
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Application to Supervised Learning

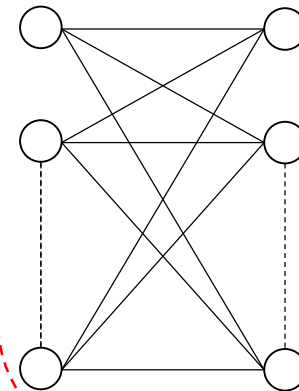
Unsupervised Autoencoder
Using unlabeled data for training

Sparse representation layer



l layer

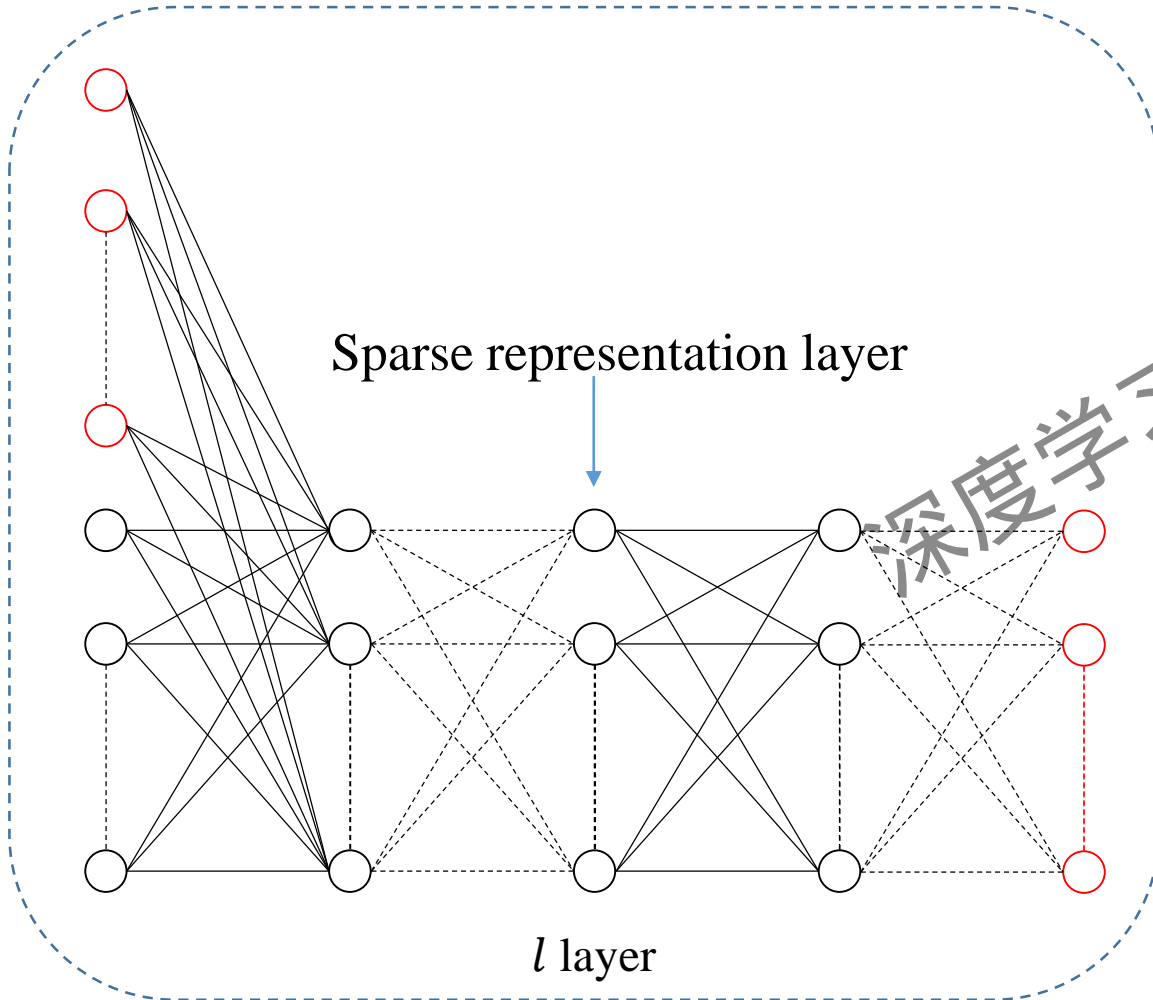
Supervised Two Layer Network
It contains $n^{L-1} \times n^L$ parameters.
Using labeled data for training



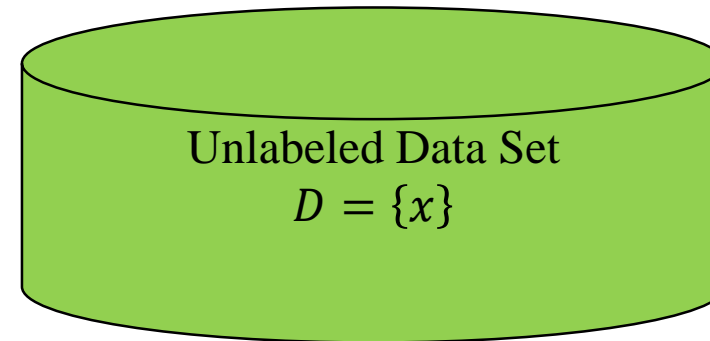
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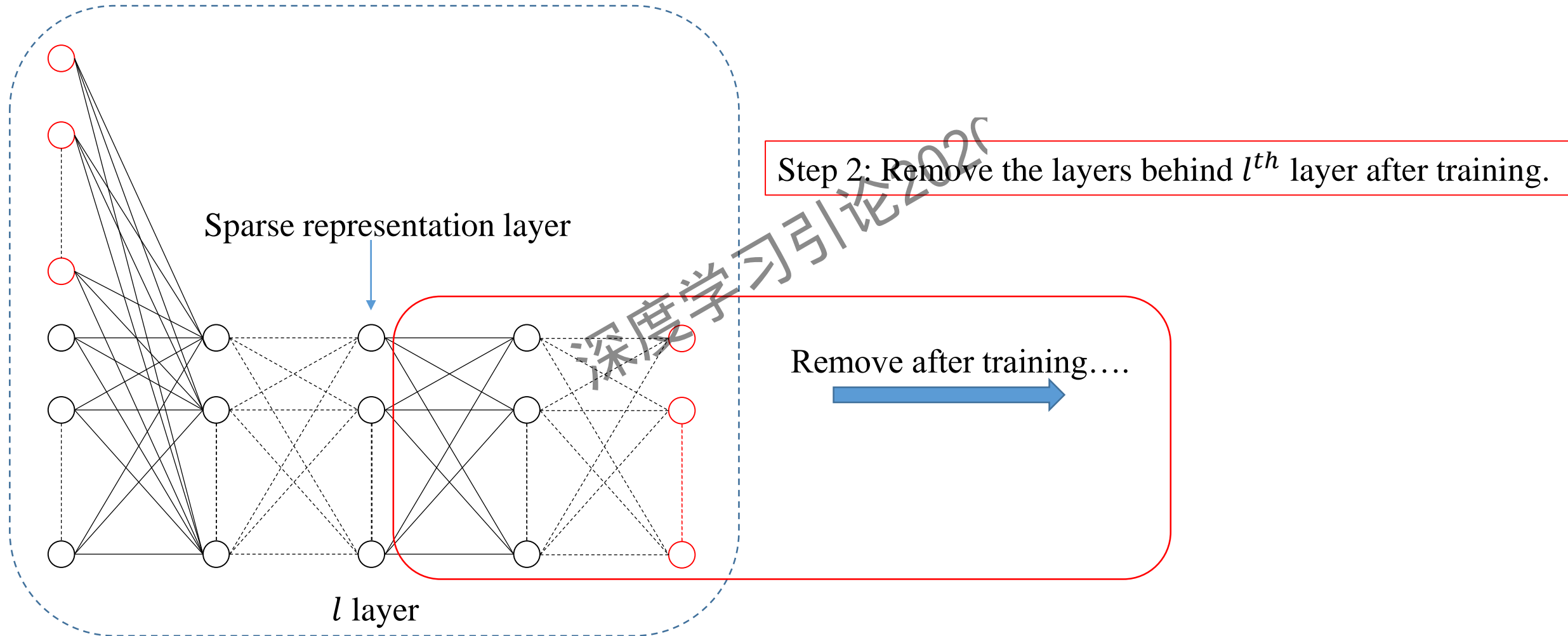
Application to Supervised Learning



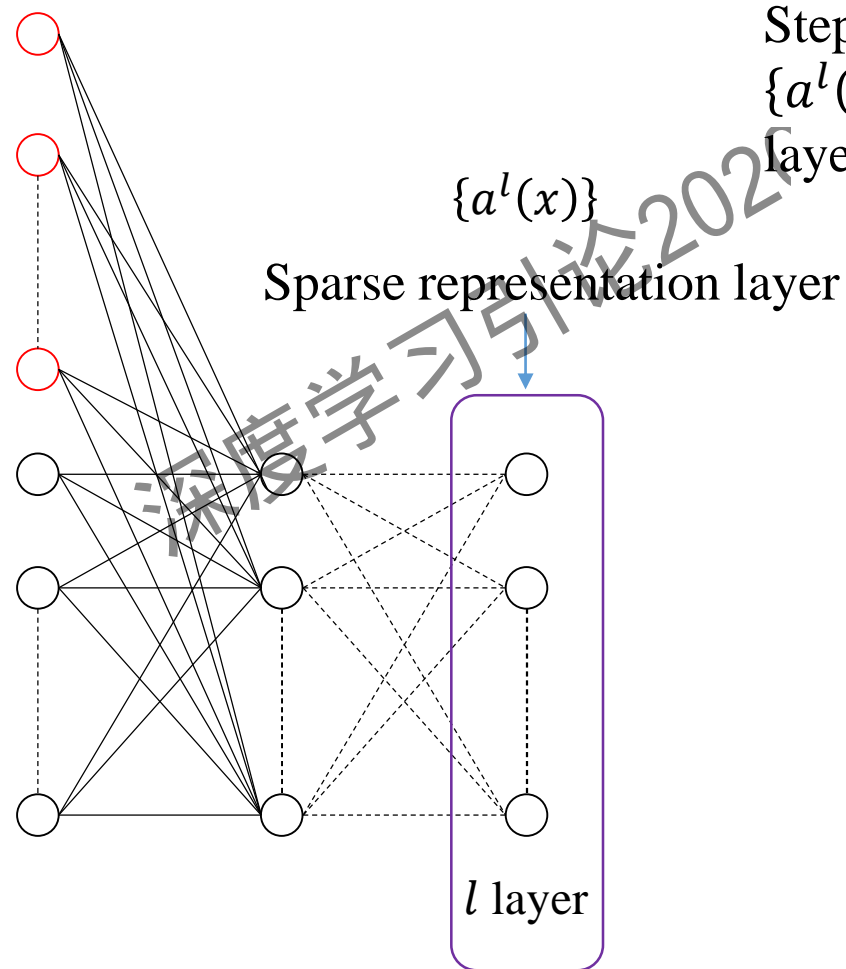
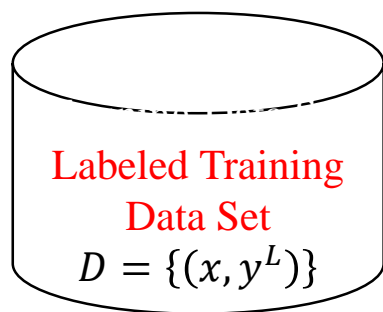
Step 1: Train the autoencoder by **using unlabeled data**.



Application to Supervised Learning



Application to Supervised Learning

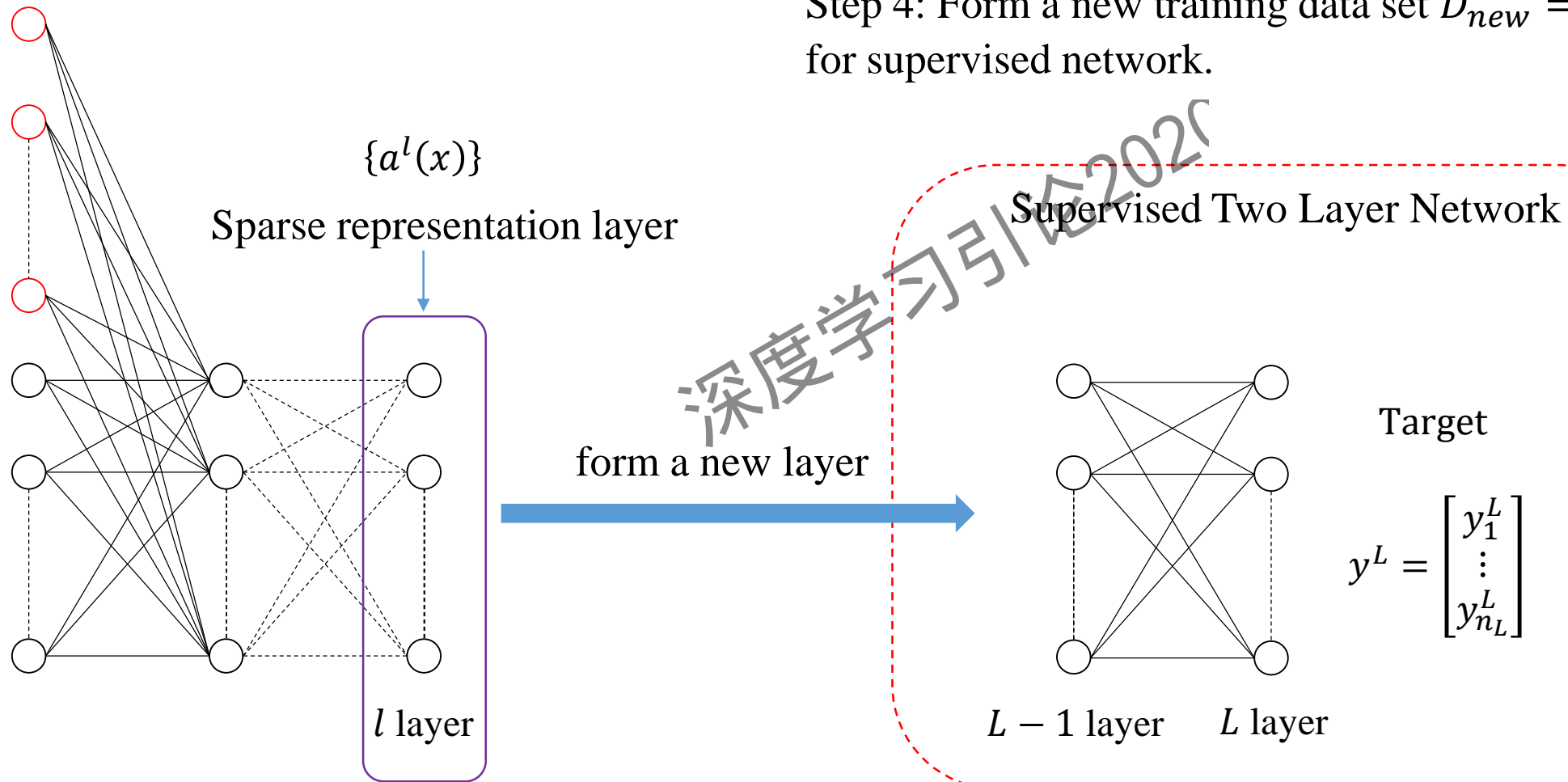


Step 3: Form a new data set $\{a^l(x)\}$ in sparse representation layer by using the labeled data set.



Application to Supervised Learning

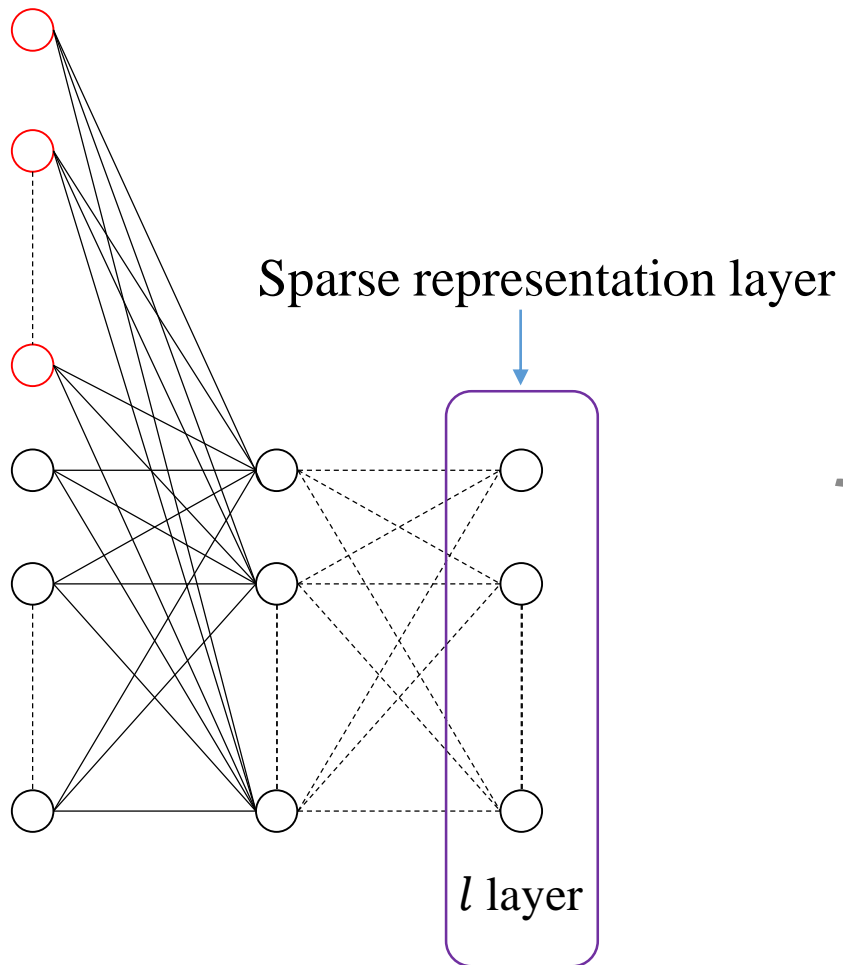
Step 4: Form a new training data set $D_{new} = \{(a^l(x), y^L)\}$ for supervised network.



Application to Supervised Learning

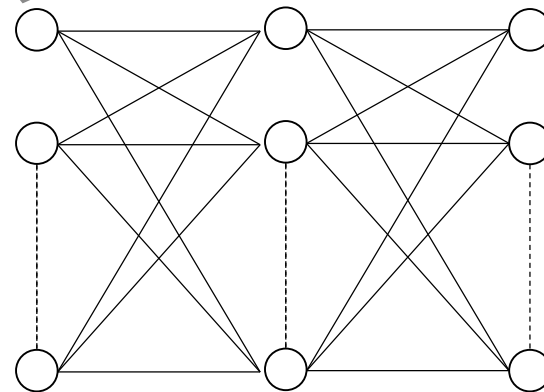
Step 5: Training the network by using the new data set

$$D_{new} = \{(a^l(x), y^L)\}$$



Supervised Three Layers Network

It contains $n_l \times n_{L-1} + n_{L-1} \times n_L$ parameters.

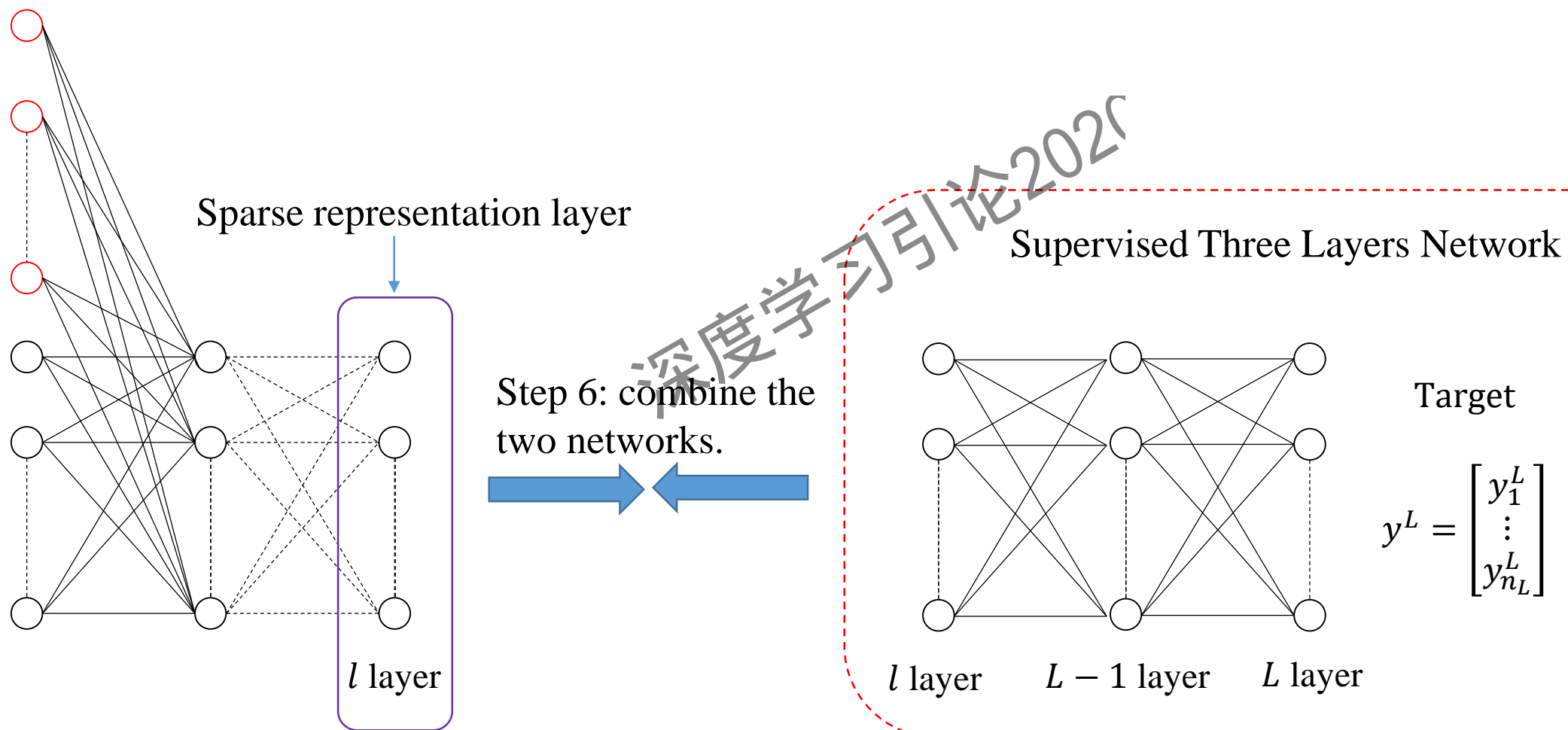


Target

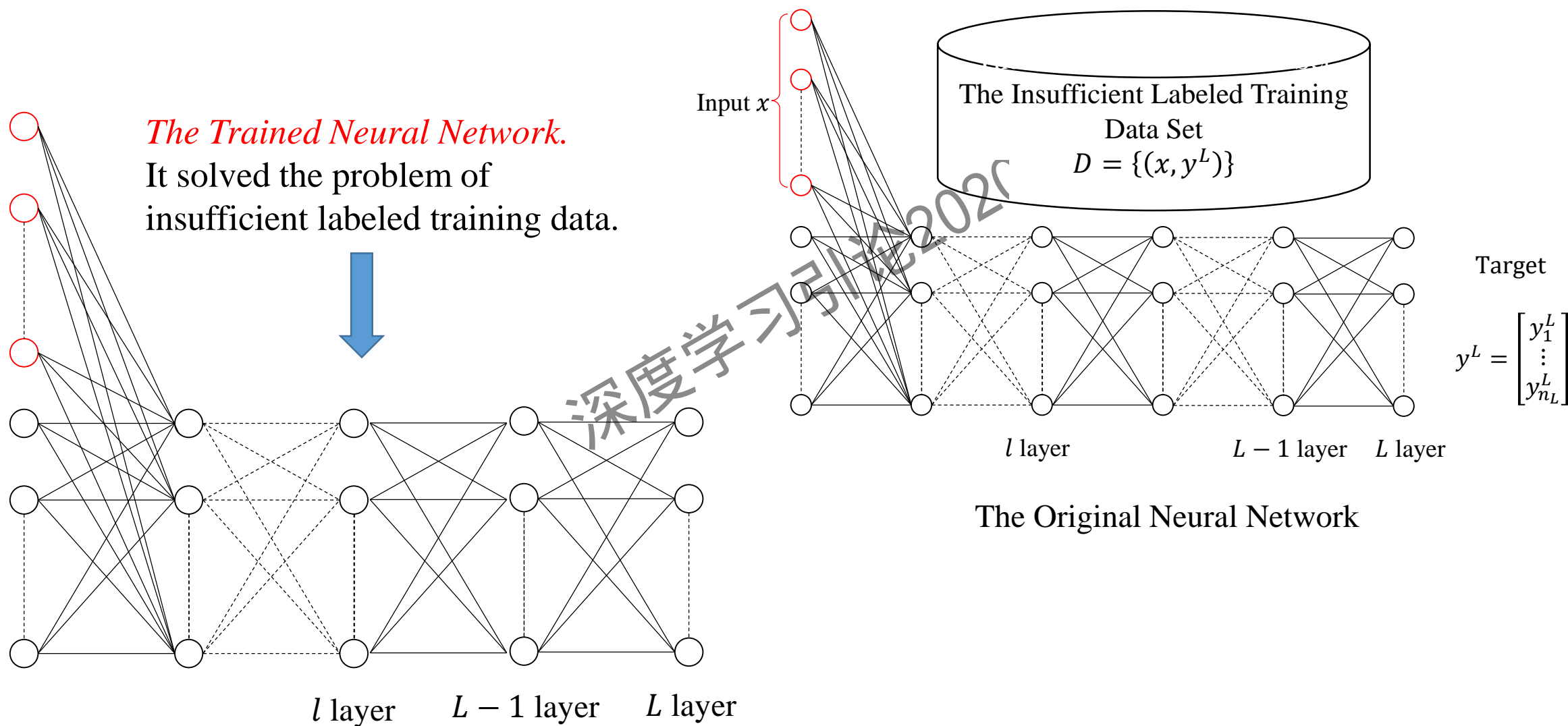
$$y^L = \begin{bmatrix} y_1^L \\ \vdots \\ y_{n_L}^L \end{bmatrix}$$

l layer L - 1 layer L layer

Application to Supervised Learning



Application to Supervised Learning



Outline

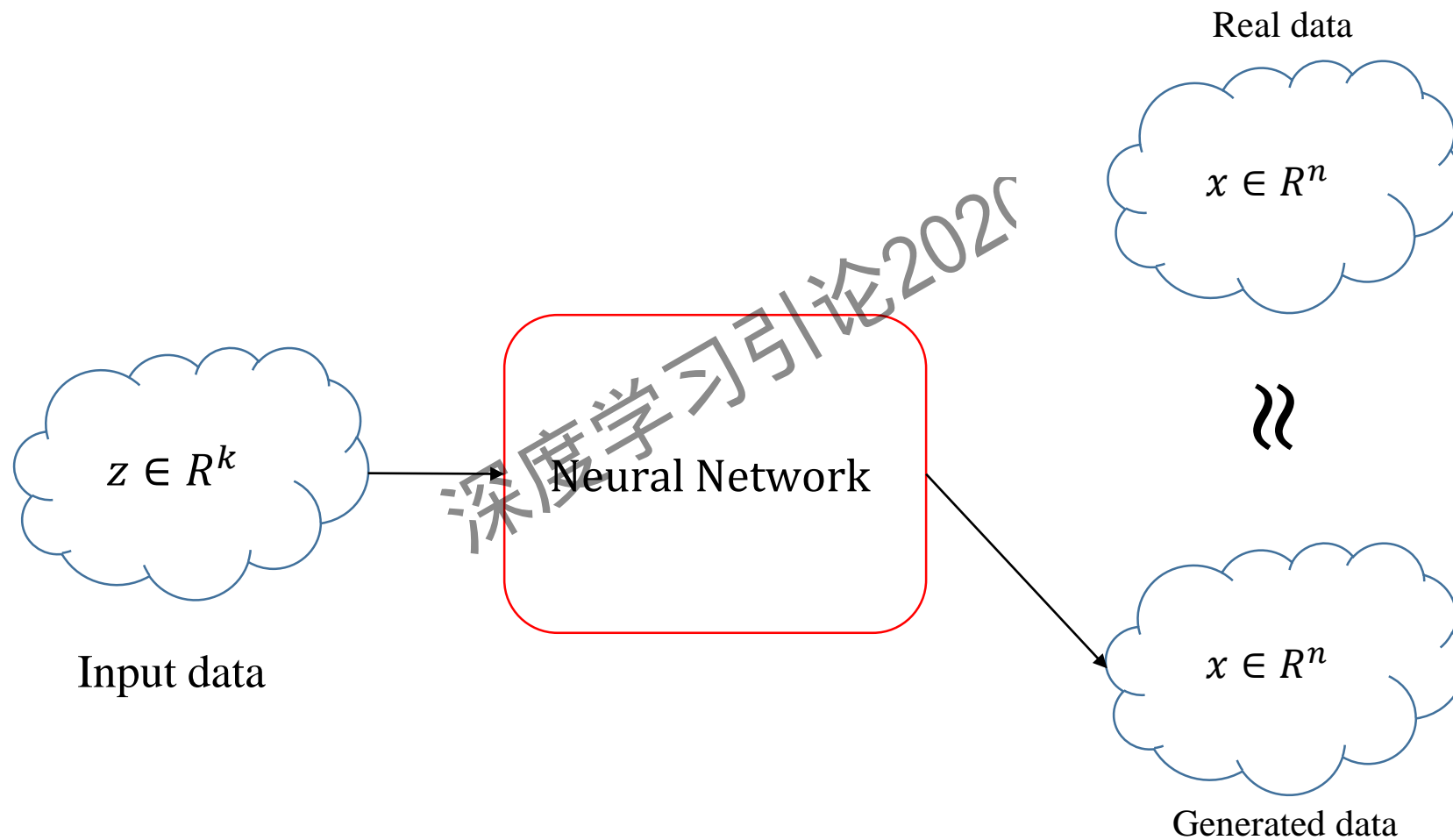
- Learning in Neural Networks
- Supervised Learning
- Unsupervised Learning
- *Autoencoder Neural Networks*
 - The Network Structure
 - Compressive Representation
 - Sparse Representation
 - Feature Learning
 - Application to Supervised Learning
- Generative Adversarial Networks
- Assignment

Generative Adversarial Networks

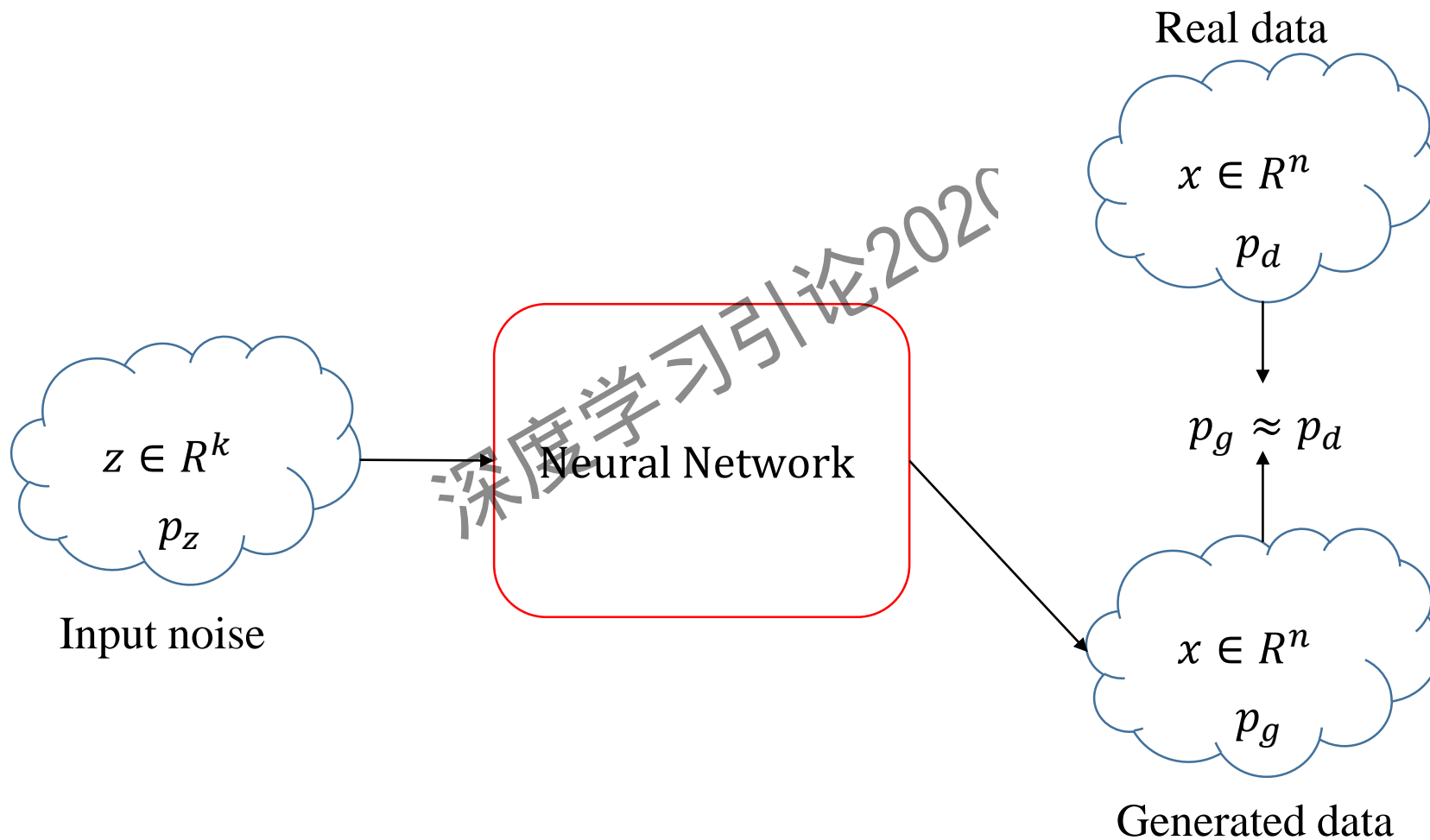
Can we generate similar images by using neural networks?



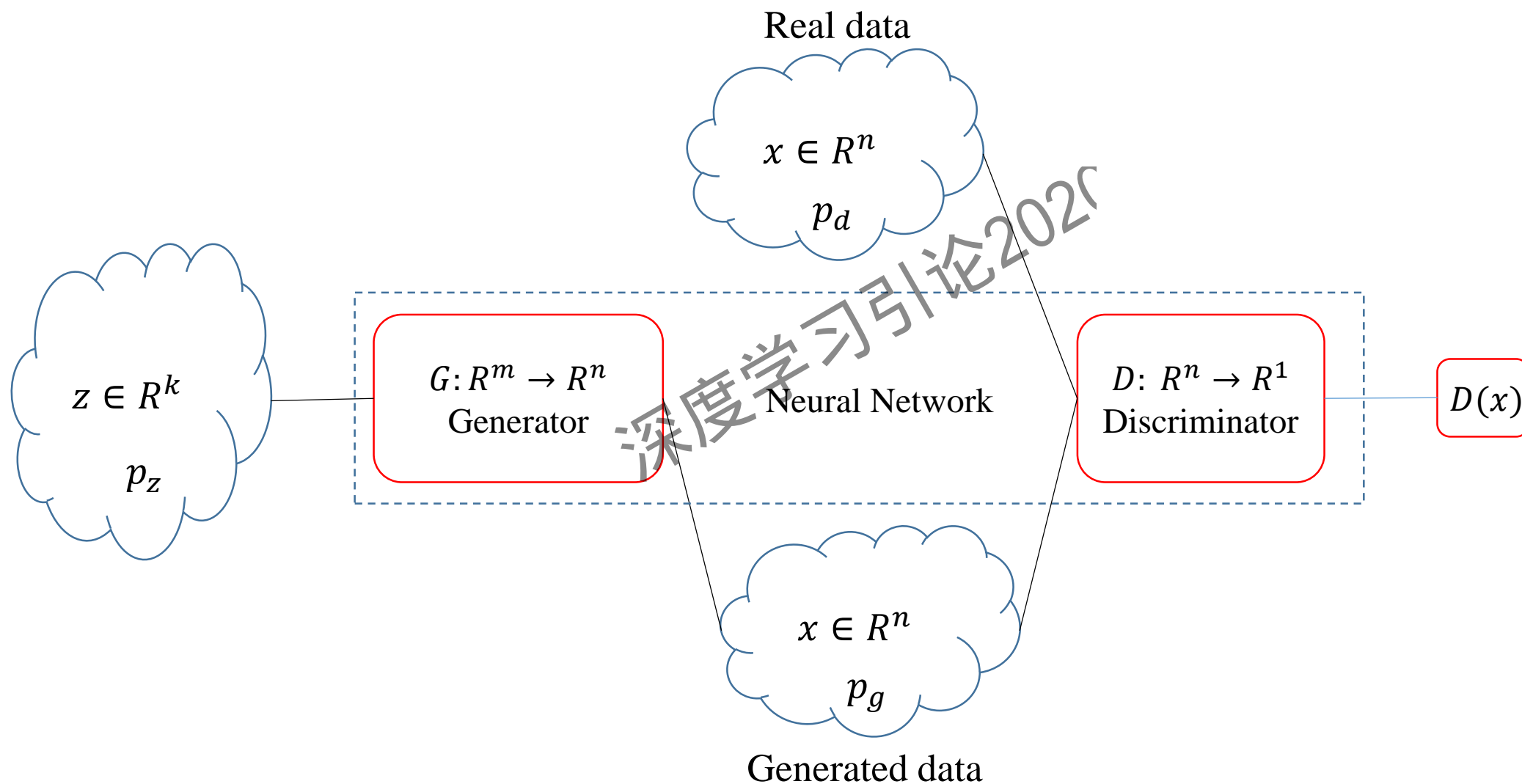
Generative Adversarial Network



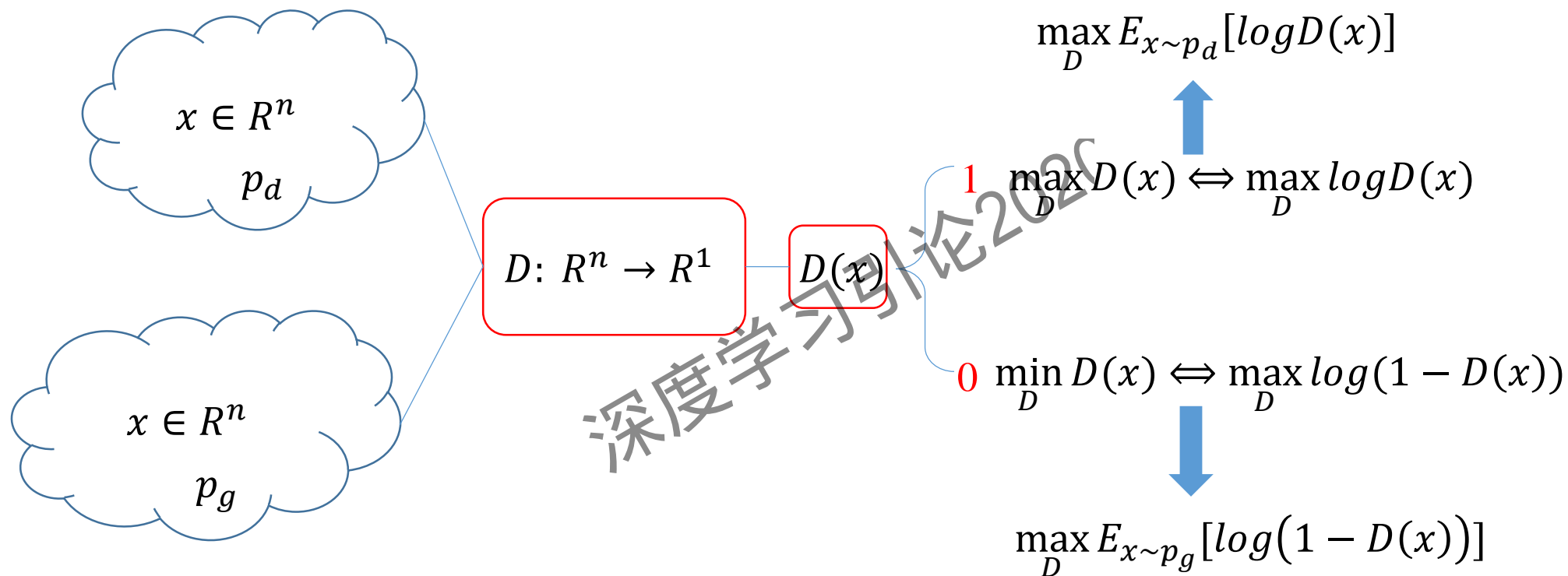
Generative Adversarial Network



Generative Adversarial Network

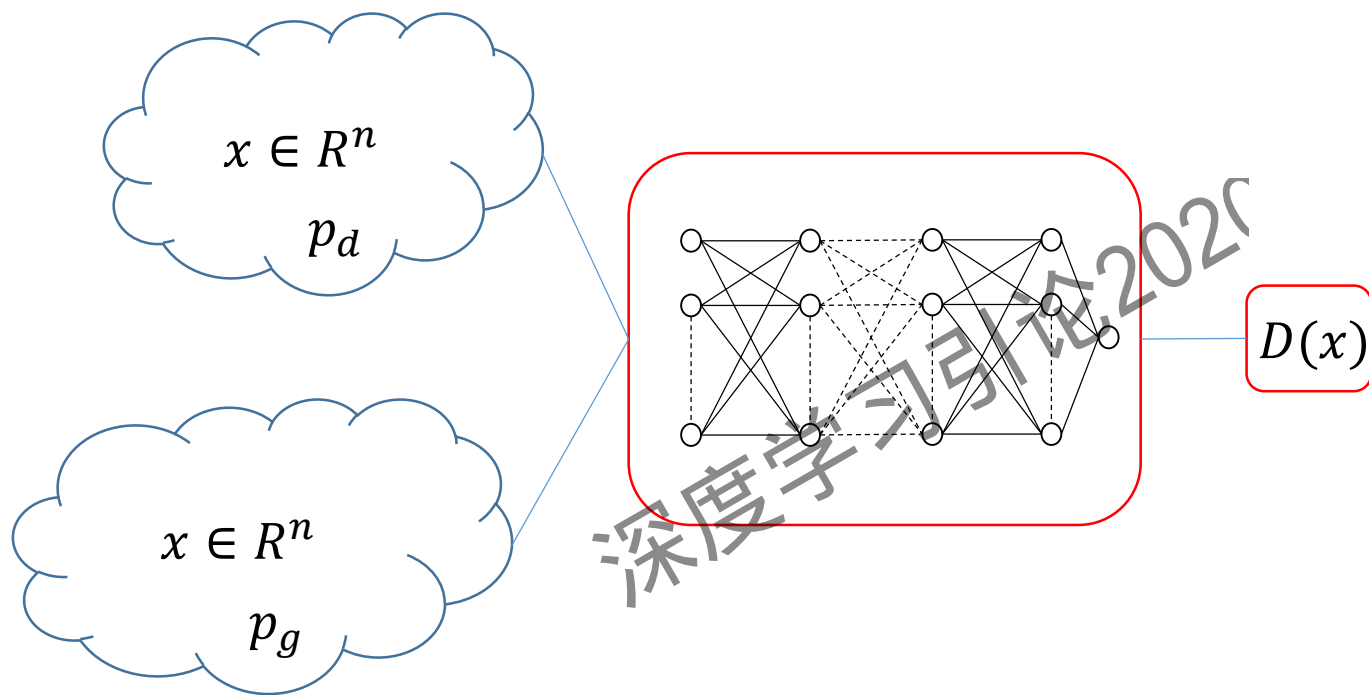


Discriminative Model



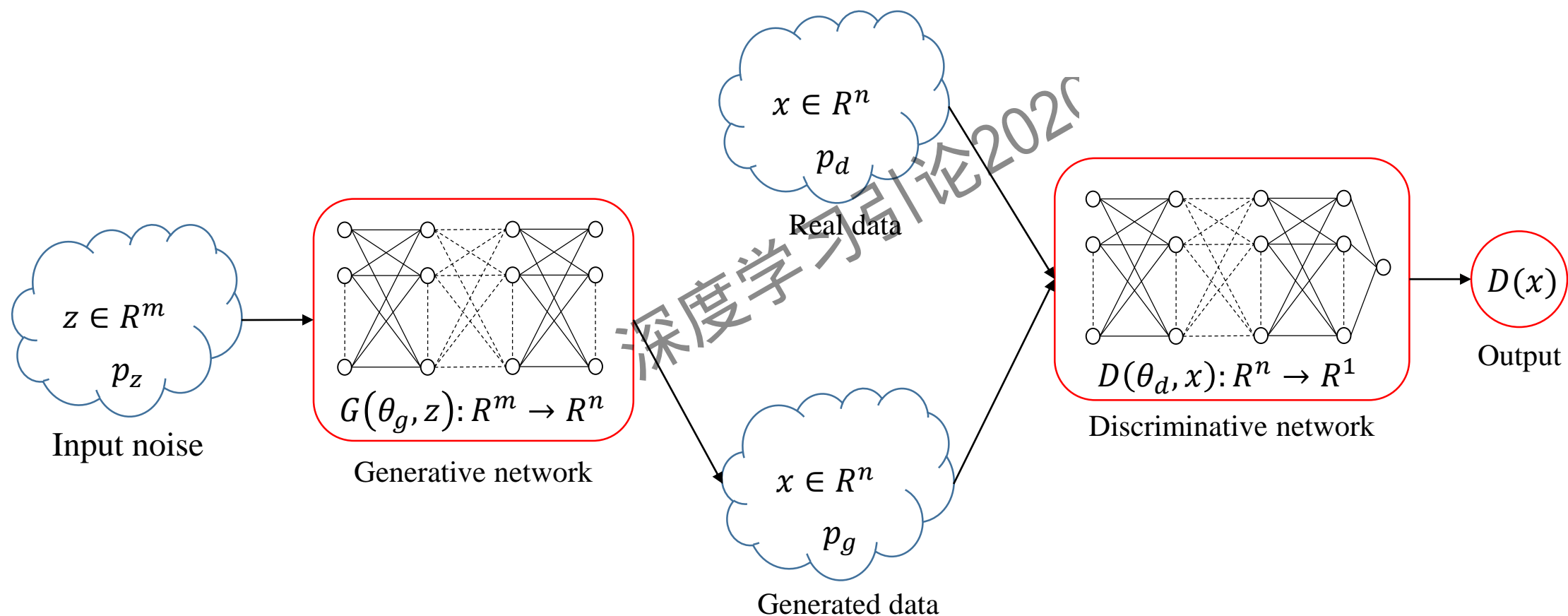
$$\max_D E_{x \sim p_d} [\log D(x)] + E_{x \sim p_g} [\log(1 - D(x))]$$

Discriminative Model

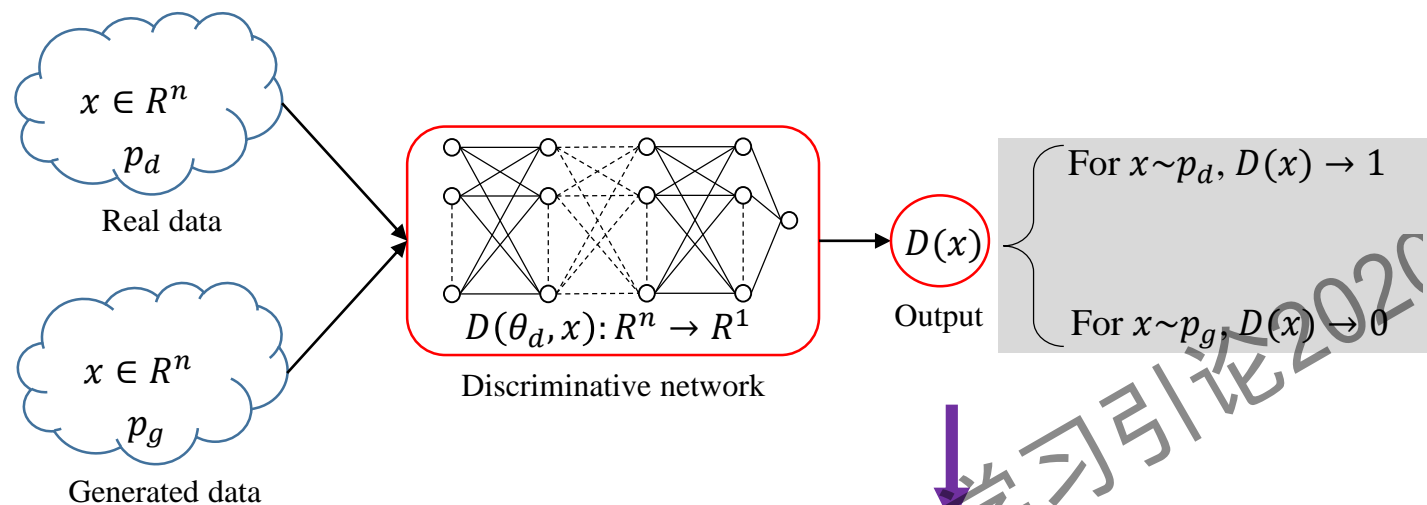


$$\max_D E_{x \sim p_d} [\log D(x)] + E_{x \sim p_g} [\log(1 - D(x))]$$

Generative Adversarial Network

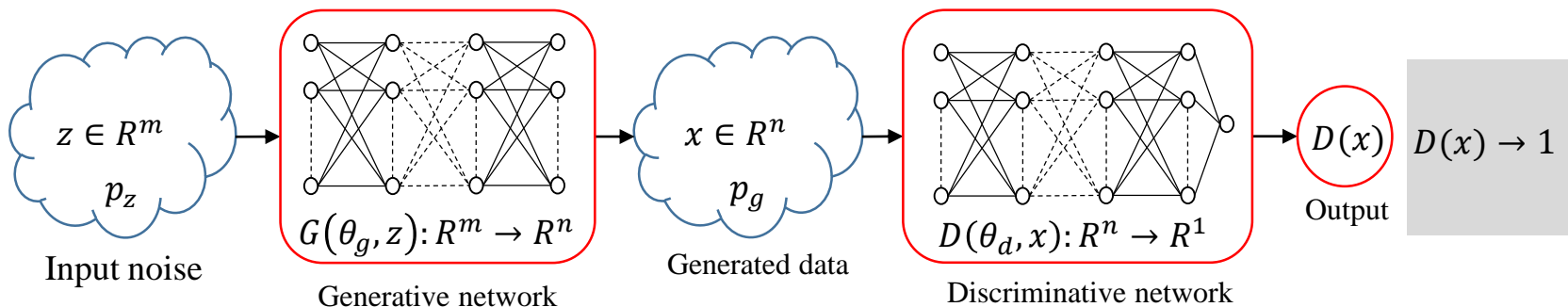


Generative Adversarial Network



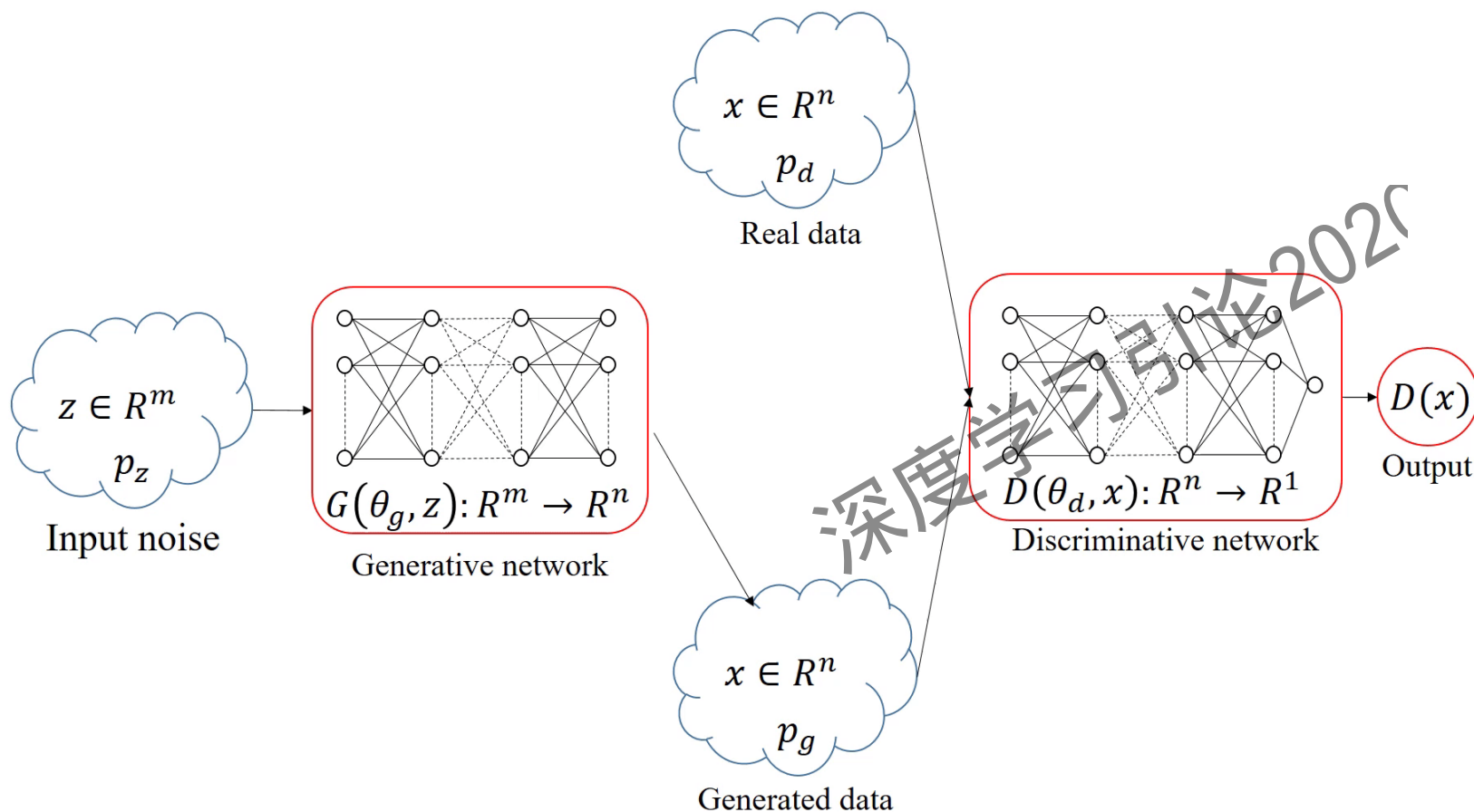
■ Discriminative network (D) aims to discriminate the real and generated data

VS



■ Generative network (G) aims to cheat the discriminative network

Generative Adversarial Networks



Algorithm

Step 1. Sample t noise samples

$$\{z^1, \dots, z^t\} \text{ from } p_z$$

Step 2. Generate t samples $\{x^1, \dots, x^t\}$ from p_g by using $\{z^1, \dots, z^t\}$

Step 3. Update **discriminative** network

$$\nabla_{\theta_d} \frac{1}{t} \sum_{i=1}^t [\log D(x^i) + \log (1 - D(G(z^i)))]$$

Step 4. Sample t noise samples

$$\{z^1, \dots, z^t\} \text{ from } p_z$$

Step 5. Update **generative** network

$$\nabla_{\theta_g} \frac{1}{t} \sum_{i=1}^t \log (1 - D(G(z^i)))$$

Human Face Generation Examples



Original images



Generated images

Outline

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Assignment 1

1. Given the cost function

$$J = \frac{1}{2} \sum_{i=1}^m (a_i^L - x_i)^2 + \beta \cdot \sum_{i=1}^{n_l} a_i^l$$

Prove that

$$\delta_i^l = \dot{f}(z_i^l) \cdot \left(\sum_{j=1}^{n_{l+1}} w_{ji}^l \delta_j^{l+1} + \beta \right)$$

2. Given the optimization problem

$$\begin{cases} \max \sum_{i=1}^n w_{ij}^{(1)} x_j \\ \text{s. t. } \sum_{i=1}^n x_i^2 \leq 1 \end{cases}$$

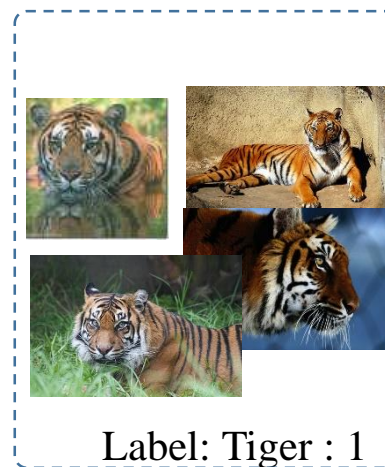
Prove that

$$x_j = \frac{w_{ij}^{(1)}}{\sqrt{\sum_{j=1}^n (w_{ij}^{(1)})^2}}, (j = 1, \dots, n)$$

Assignment 2

Assignment:

In this example, the labeled training data are insufficient to train a classifier by using BP directly. However, a good classifier can be developed by using the autoencoder method. Please do it.



Q & A
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The End

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