



The Study of Unmanned Twin-body Asymmetric Flying-Wing Aircraft for Monitoring Air Quality

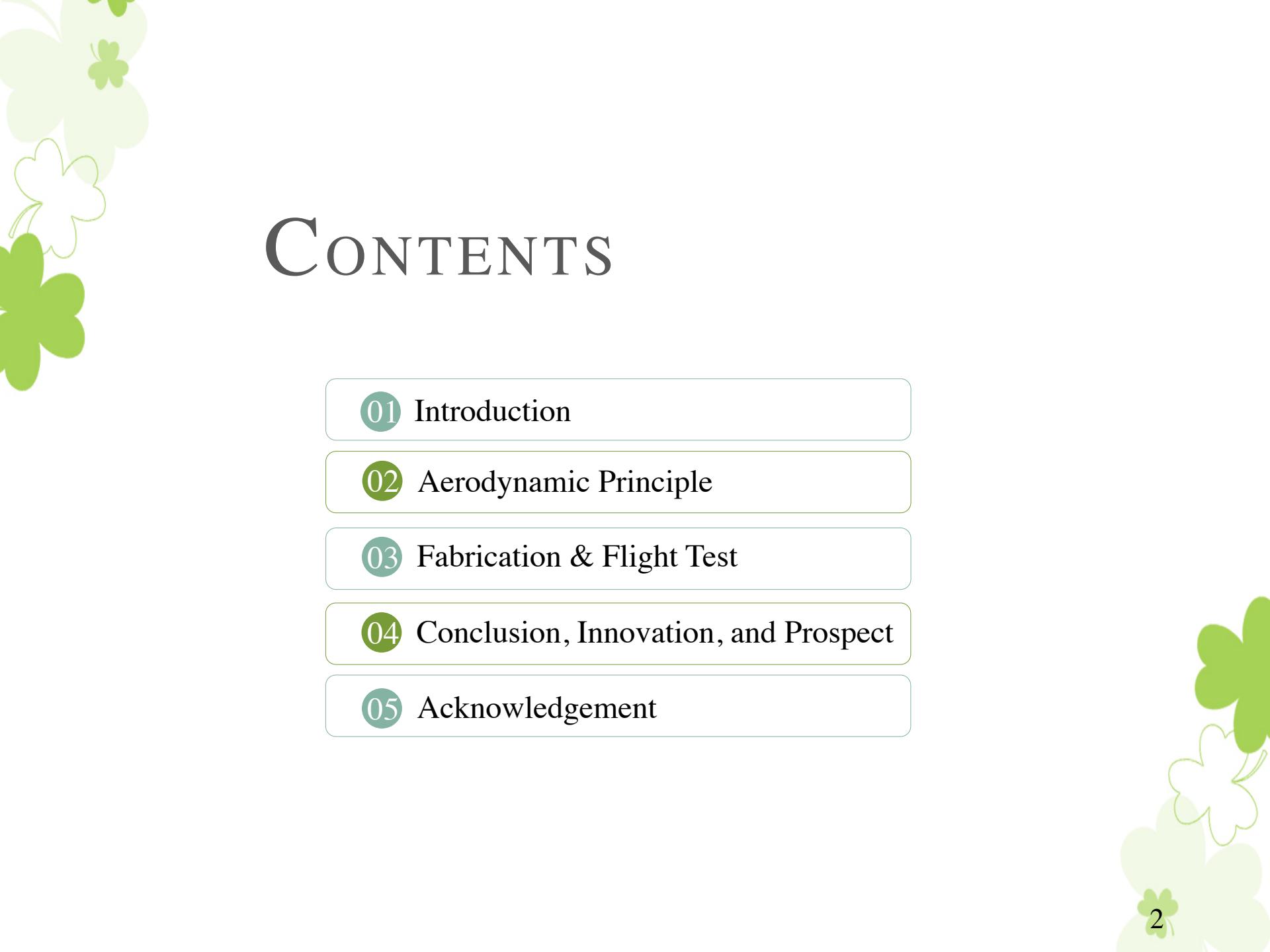


By: Guo Xinze

Instructor: Huang Jun, Fan Bozhao

Beijing National Day school, Beijing, China





CONTENTS

01 Introduction

02 Aerodynamic Principle

03 Fabrication & Flight Test

04 Conclusion, Innovation, and Prospect

05 Acknowledgement

1

Introduction

- Traditional automatic air monitoring station
- Current Unmanned Aerial Vehicle (UAV)
- Twin-body Asymmetric Flying-Wing Aircraft (TAFA)

Traditional automatic air monitoring station

- Costly (labors, periodic maintenance...)
- Difficult to carry out large-scale measurement.
- Observation point is not representative.



Long endurance, high loading unmanned aerial vehicle(UAV)

Current Unmanned Aerial Vehicle (UAV)



(a) Monoplane



(b) Twin-body Aircraft



(c) Asymmetric
Twin-body Aircraft

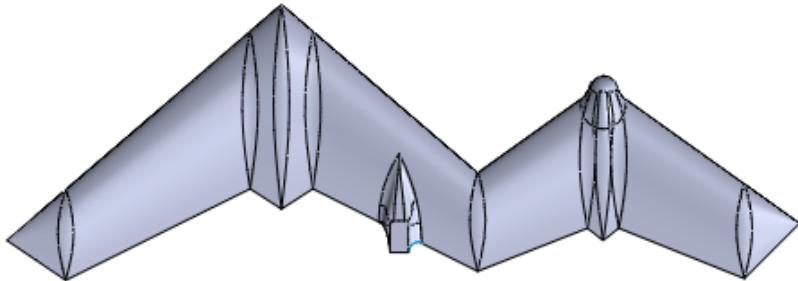


(d) Flying-Wing Aircraft

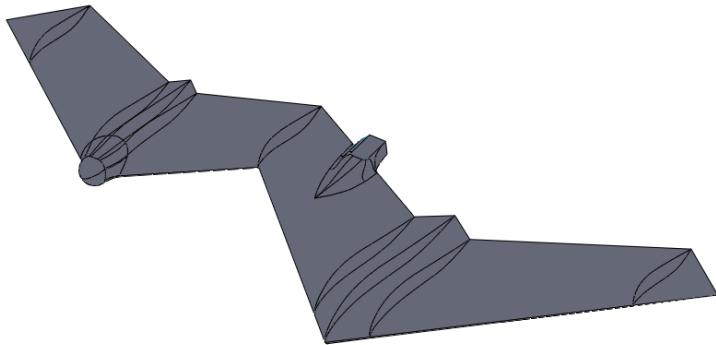
Problem:
Low load
Low voyage
Low Endurance
Low efficiency



Twin-body Asymmetric Flying-Wing Aircraft (TAFA)



TAFA



Advantage: high lift, high voyage, and high endurance.

Twin-body

Disadvantage: high mid-wing strength requirement, no usable airport, loading interfere with each other.

Asymmetric Arrangement

Solve the interference problem and no usable airport problem.

Flying-Wing Layout

Increase lift, voyage, and endurance, reinforce the mid-wing strength.

2

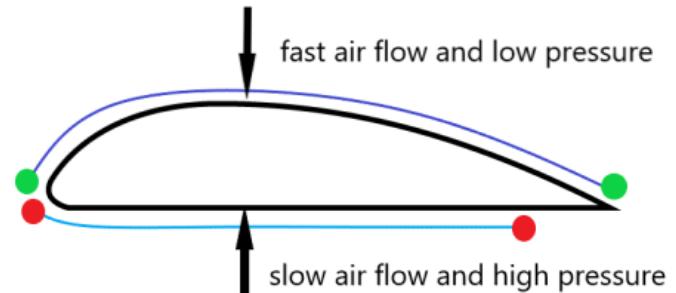
Aerodynamic Principle

- Theory
- Design Process
- Simulation
- Results and Discussion

Theory

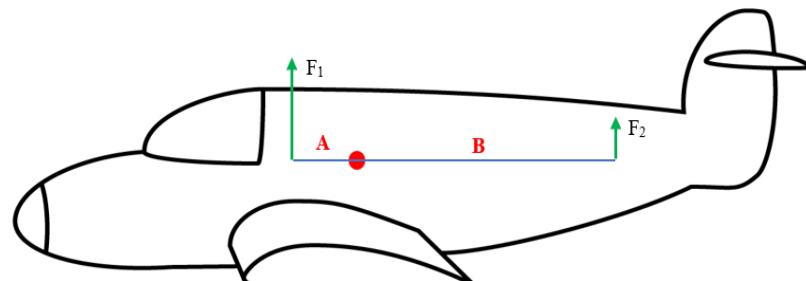
- **Principle of Flight Lift Generation**

- $\frac{1}{2}\rho u_1^2 + \rho g z_1 + p_1 = \frac{1}{2}\rho u_2^2 + \rho g z_2 + p_2$
- $\frac{1}{2}\rho u_1^2 + p_1 = \frac{1}{2}\rho u_2^2 + p_2$
- The lift is proportional to the wing area.

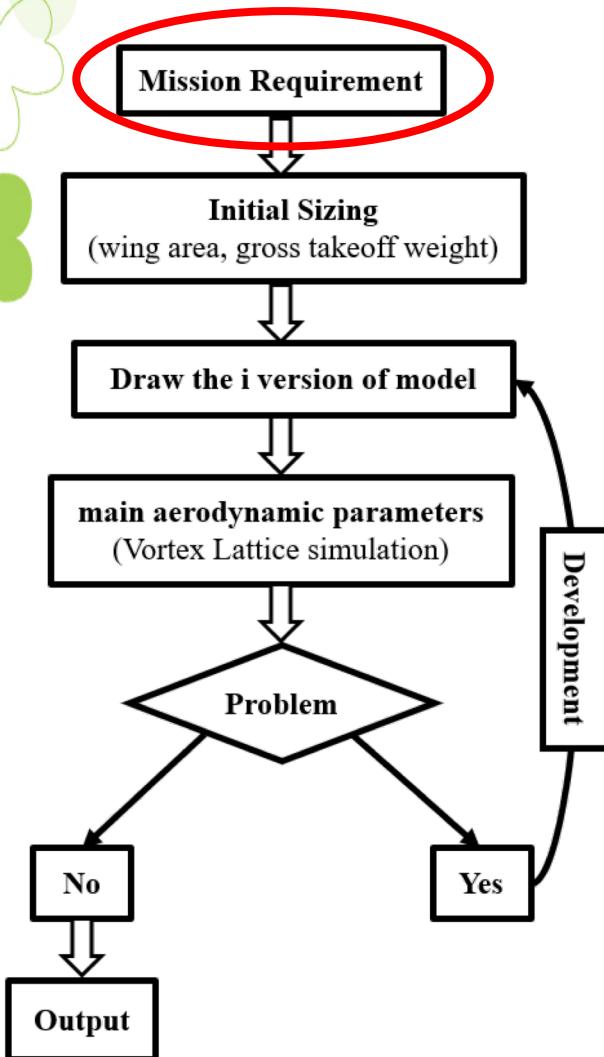


- **Balance Control of Aircraft**

- $F_1 \times A = F_2 \times B$
- Put the engine on the center mass



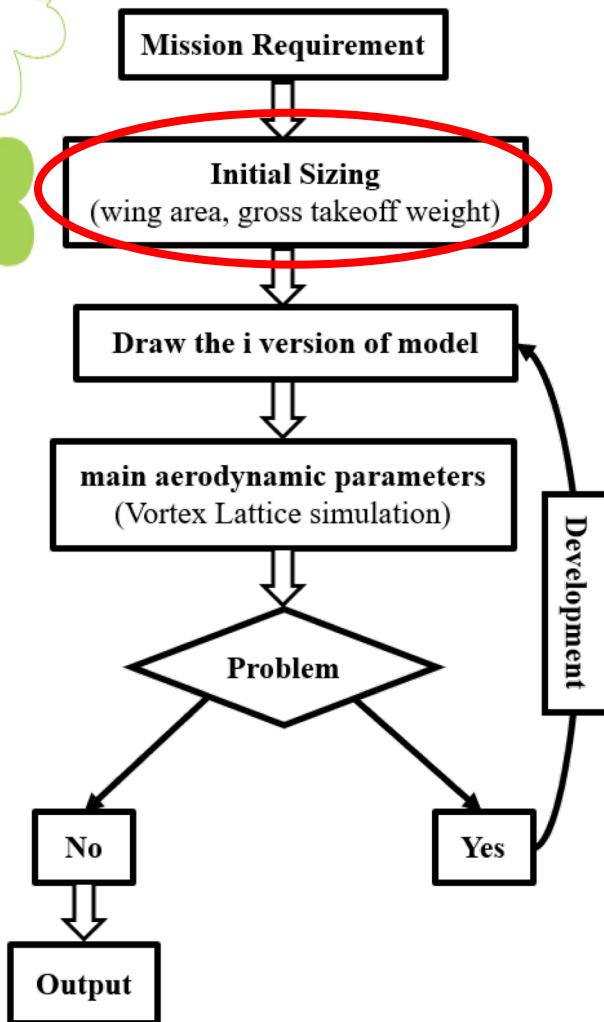
Design Process



| Flight Requirements | |
|---------------------|-----------------------|
| Payload weight | 9.24kg |
| Endurance | 8h(battery)/24h(fuel) |
| Loiter Speed | 25m/s |

| Payload Requirements | |
|----------------------|--------------------------|
| Radar | 203*165*76mm, 2.44kg |
| Antenna | 127*127*38mm, 0.29kg |
| Imaging processor | 152.5*152.5*76mm, 1.41kg |
| Lidar | 142*70*230mm, 2.2kg |
| Data link | 290*179*161mm, 1.5kg |
| Multispectral camera | 127*177.1mm, 1.4kg |
| Engine | 60*161*93mm, 0.62 kg |

Design Process



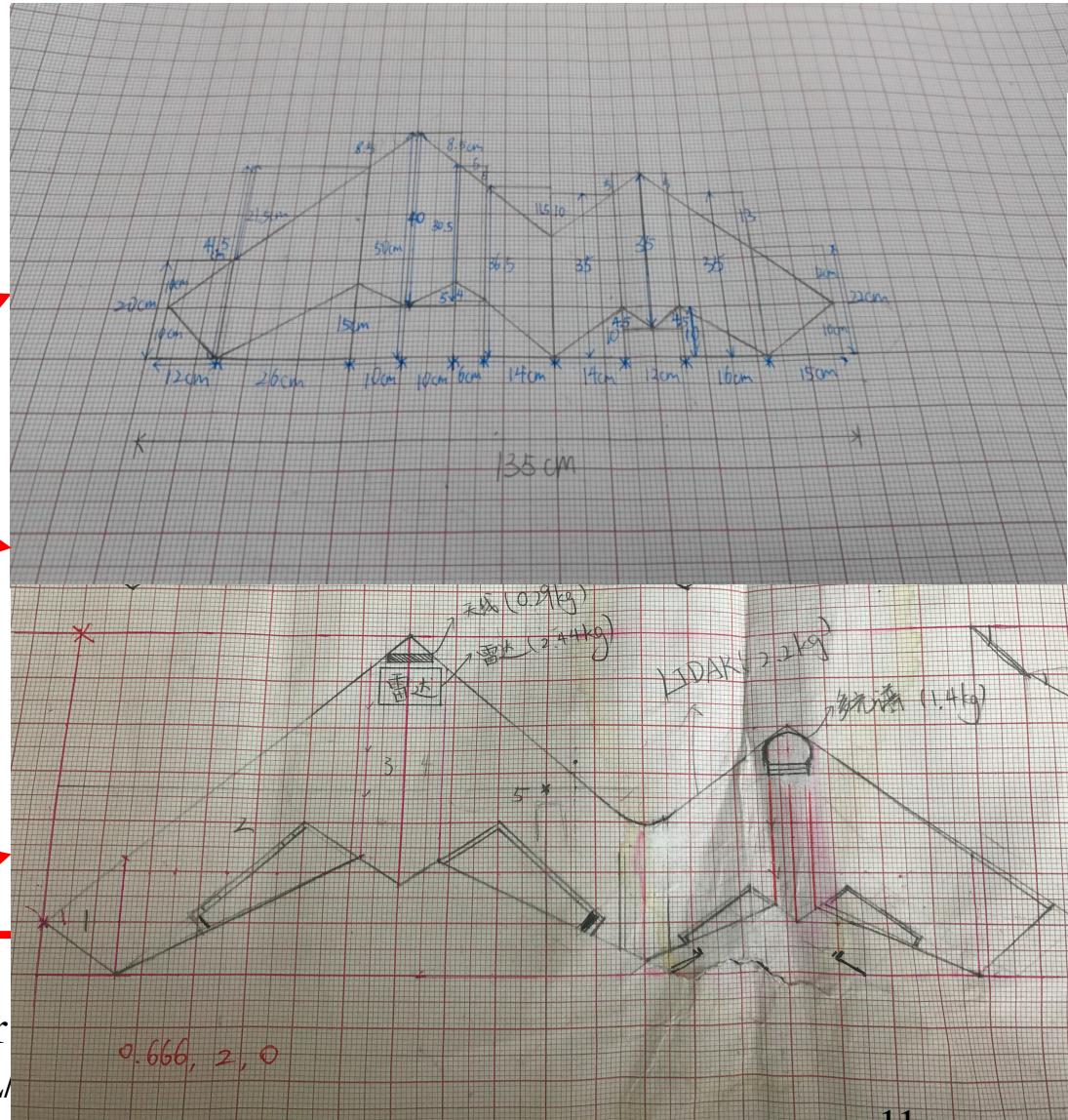
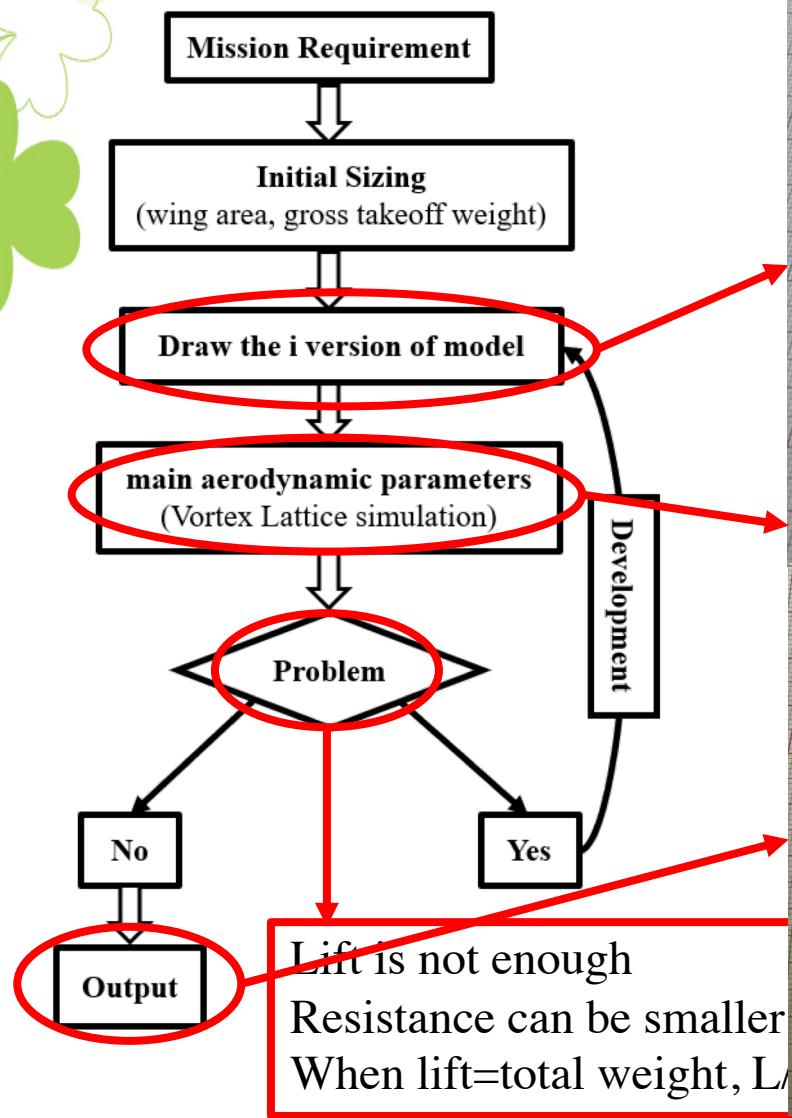
Total loading weight: 9.24 kg

Estimate takeoff weight: 36kg

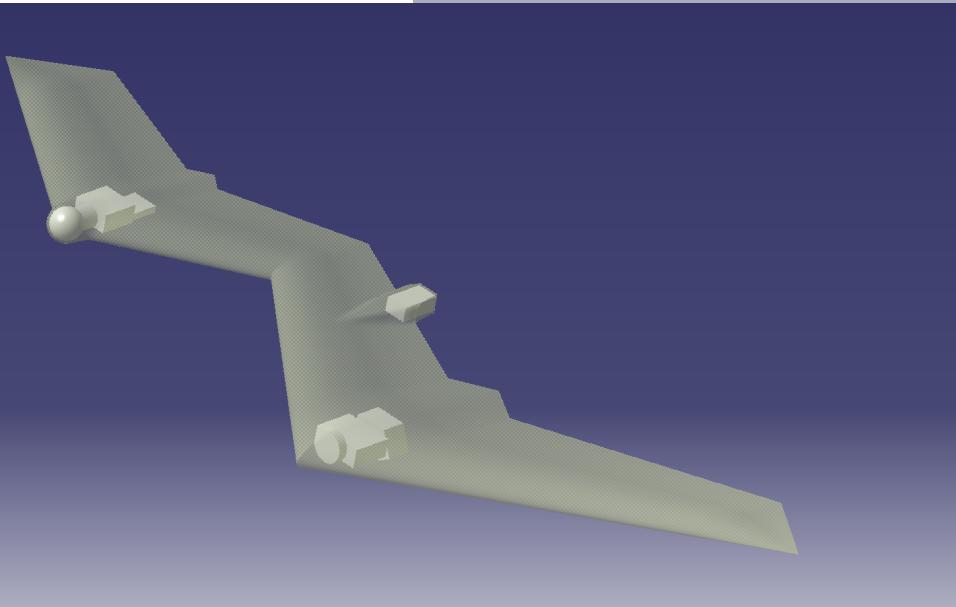
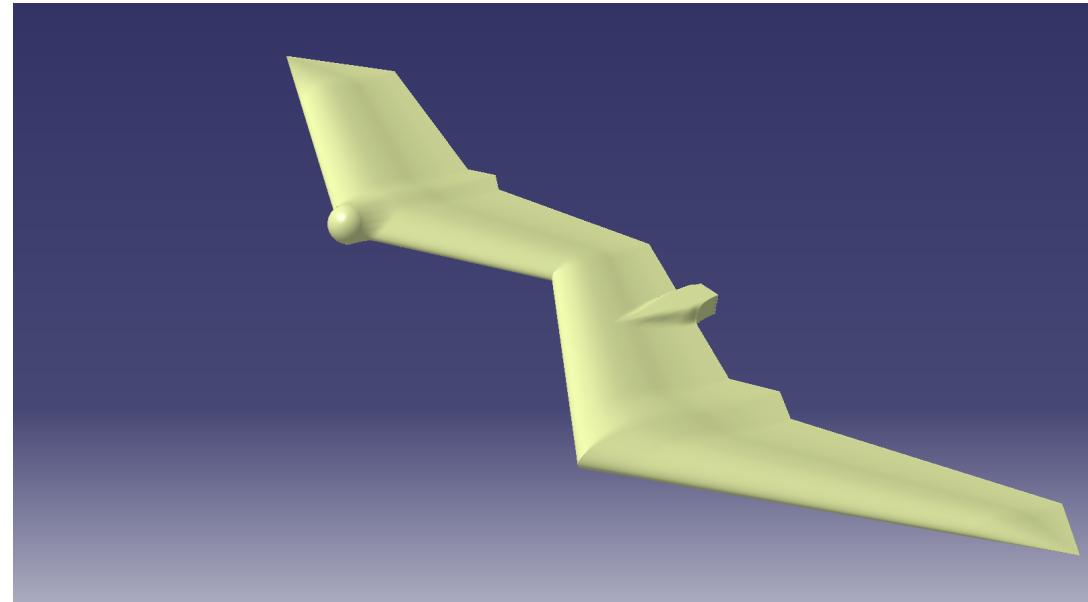
$$L = \frac{1}{2} C_y \rho v^2 S$$

Wing area = 2.39m²

Design Process

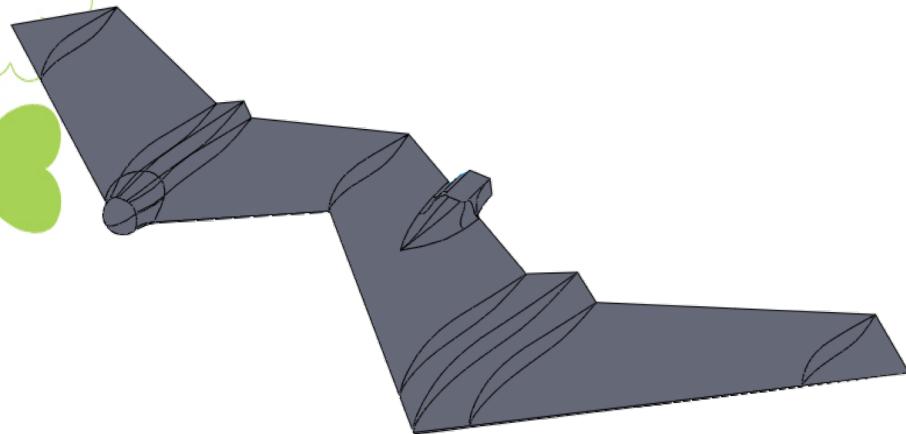


Modeling

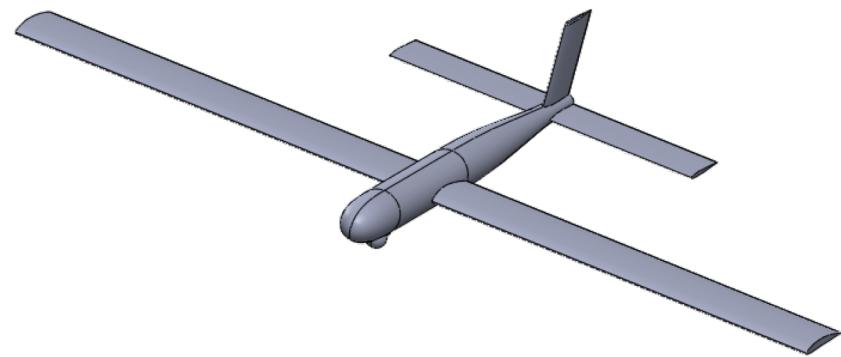




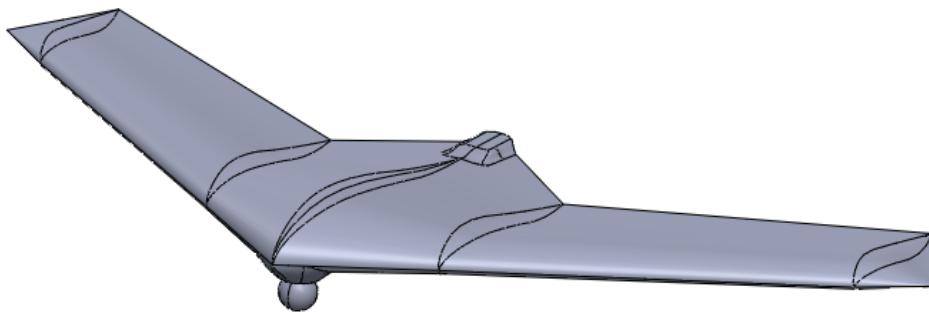
Models



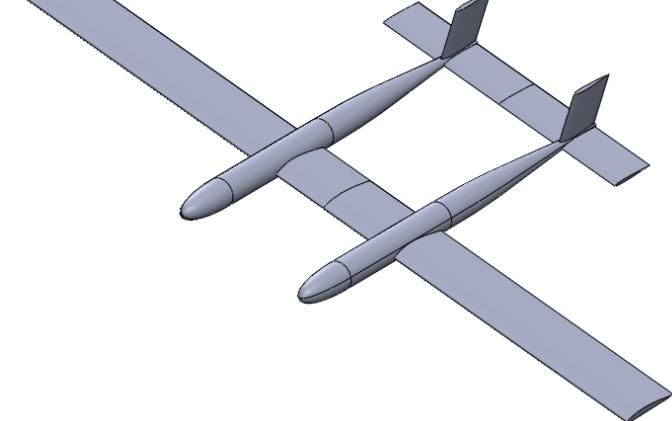
(a) TAFA



(b) Normal Aircraft



(c) Flying-Wing Aircraft



(d) Twin-Body Symmetric Airplane

Simulation

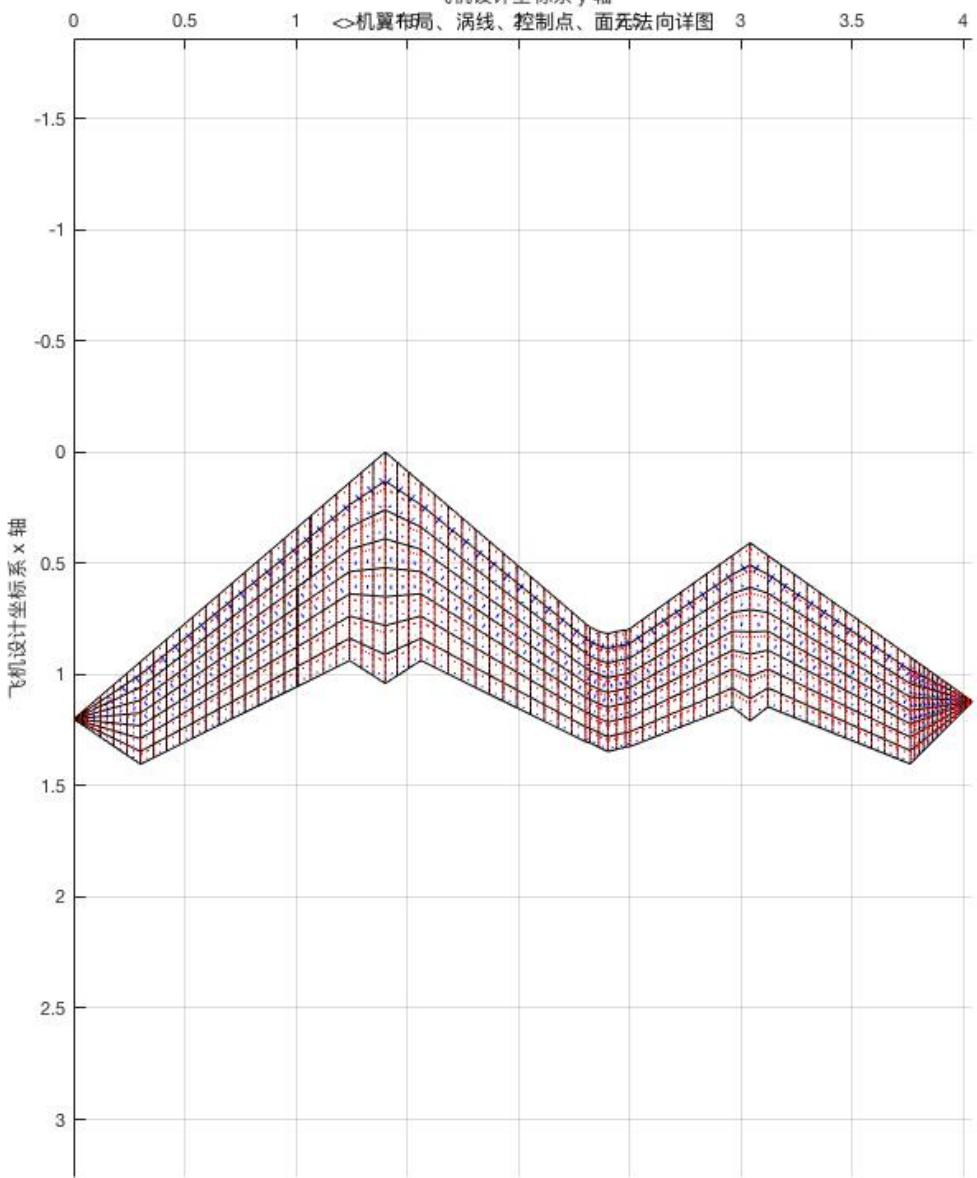
- Vortex lattice method

$$\omega(x, y) = -\frac{1}{4\pi} \iint_S \frac{(x - \xi)\gamma(\xi, \eta) + (y - \eta)\delta(\xi, \eta)}{[(x - \xi)^2 + (y - \eta)^2]^{3/2}} d\xi d\eta - \frac{1}{4\pi} \iint_W \frac{(y - \eta)\delta_\omega(\xi, \eta)}{[(x - \xi)^2 + (y - \eta)^2]^{3/2}} d\xi d\eta$$

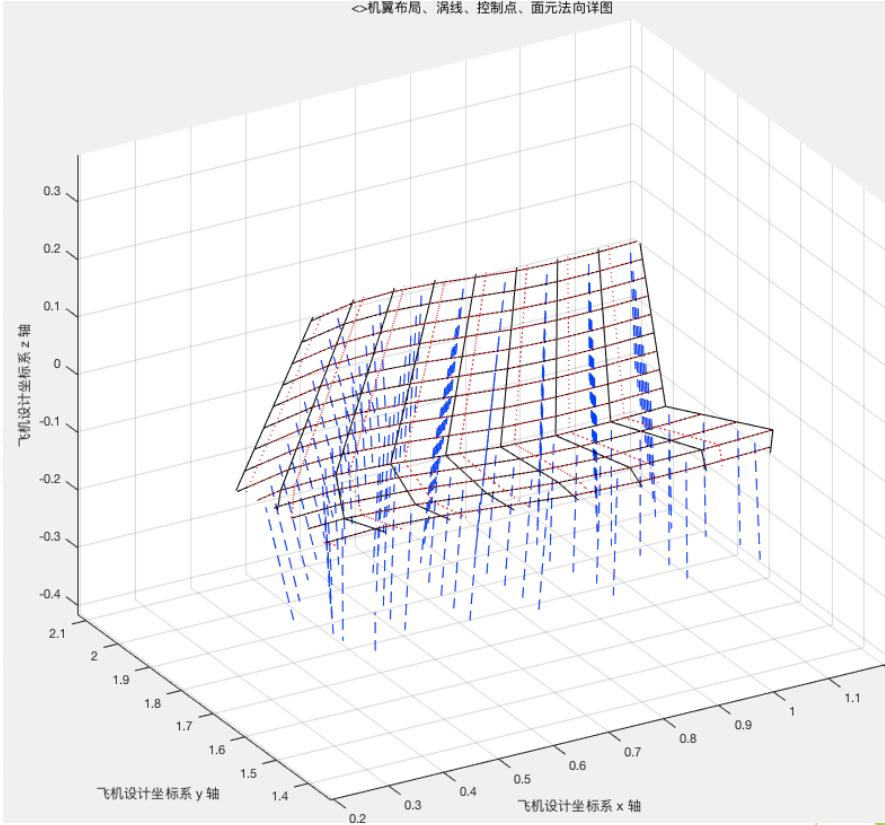
- Computational Fluid Dynamics (CFD)

$$\left\{ \begin{array}{l} \rho \frac{Du}{Dt} = -\frac{\partial p}{\partial x} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + \rho f_x \\ \rho \frac{Dv}{Dt} = -\frac{\partial p}{\partial y} + \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + \rho f_y \\ \rho \frac{Dw}{Dt} = -\frac{\partial p}{\partial z} + \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} + \rho f_z \end{array} \right.$$

飞机设计坐标系 y 轴

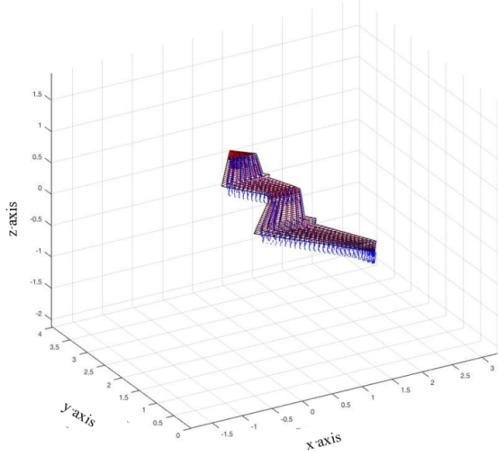


<>机翼布局、涡线、控制点、面无法向详图

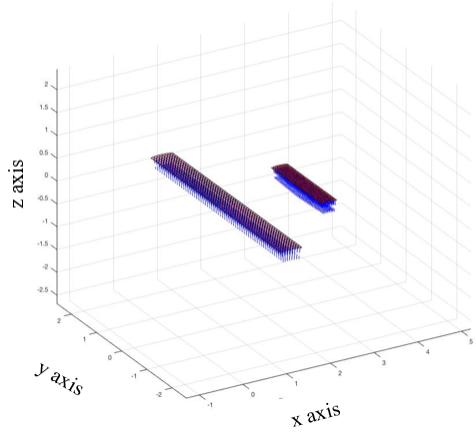


Results and Discussion

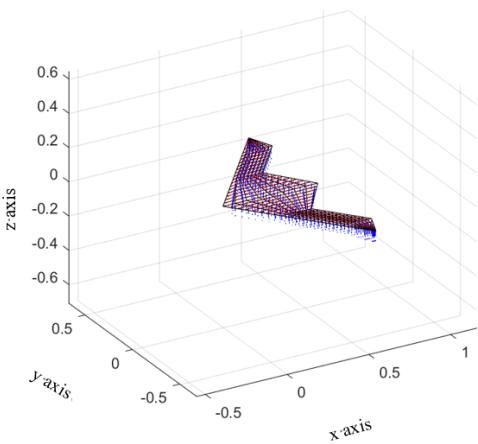
Vortex Lattice Method Data



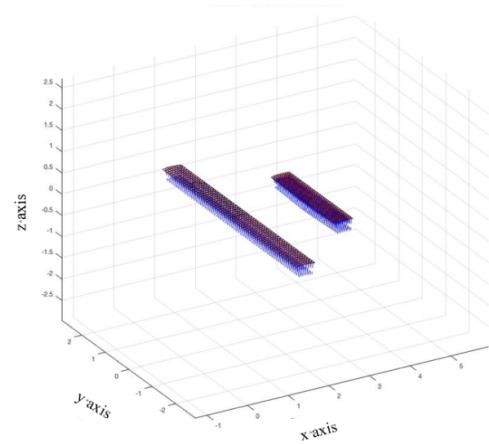
(a) TAFA



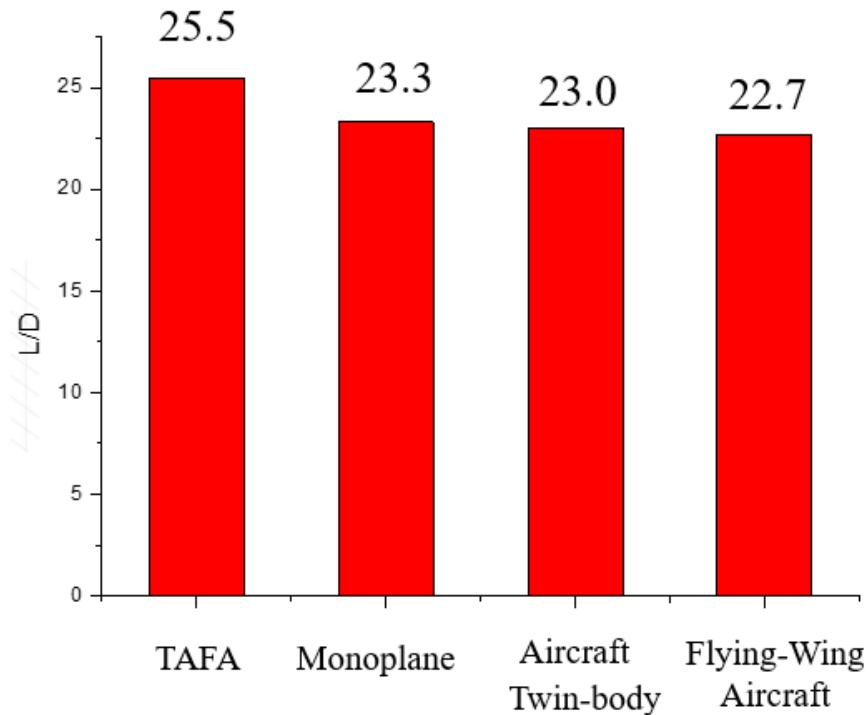
(b) Monoplane



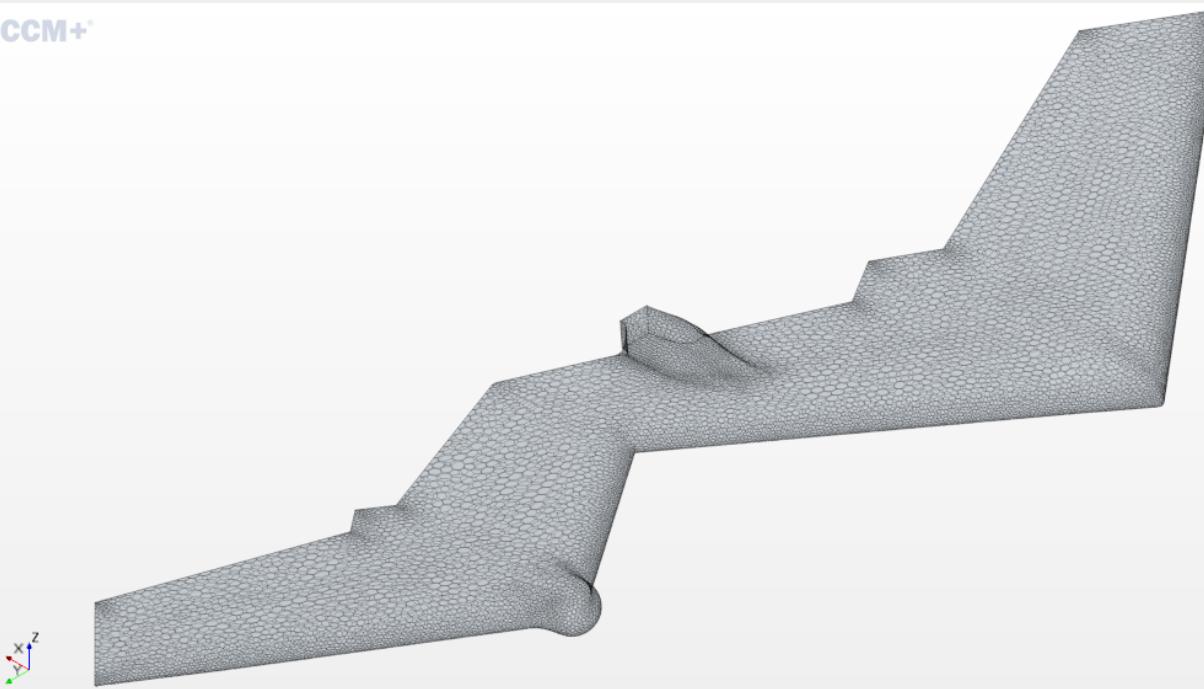
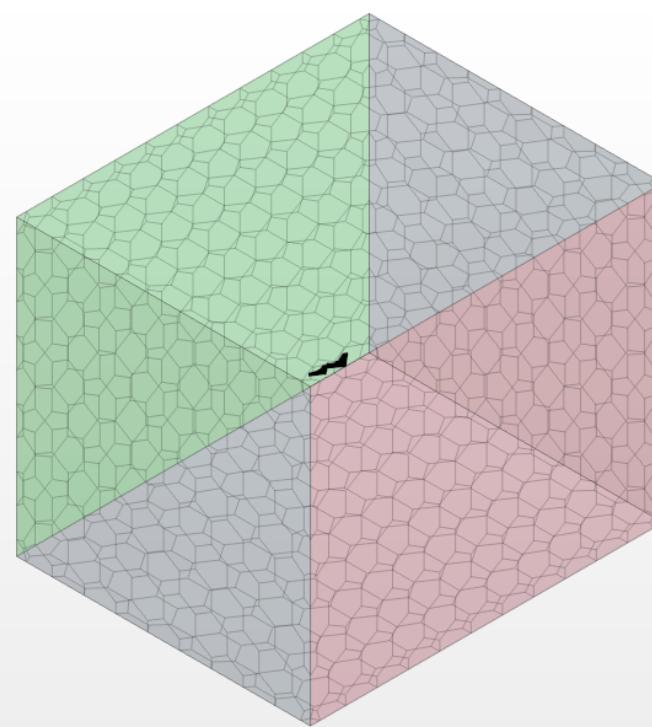
(c) Flying-Wing Aircraft



(d) Twin-body Aircraft

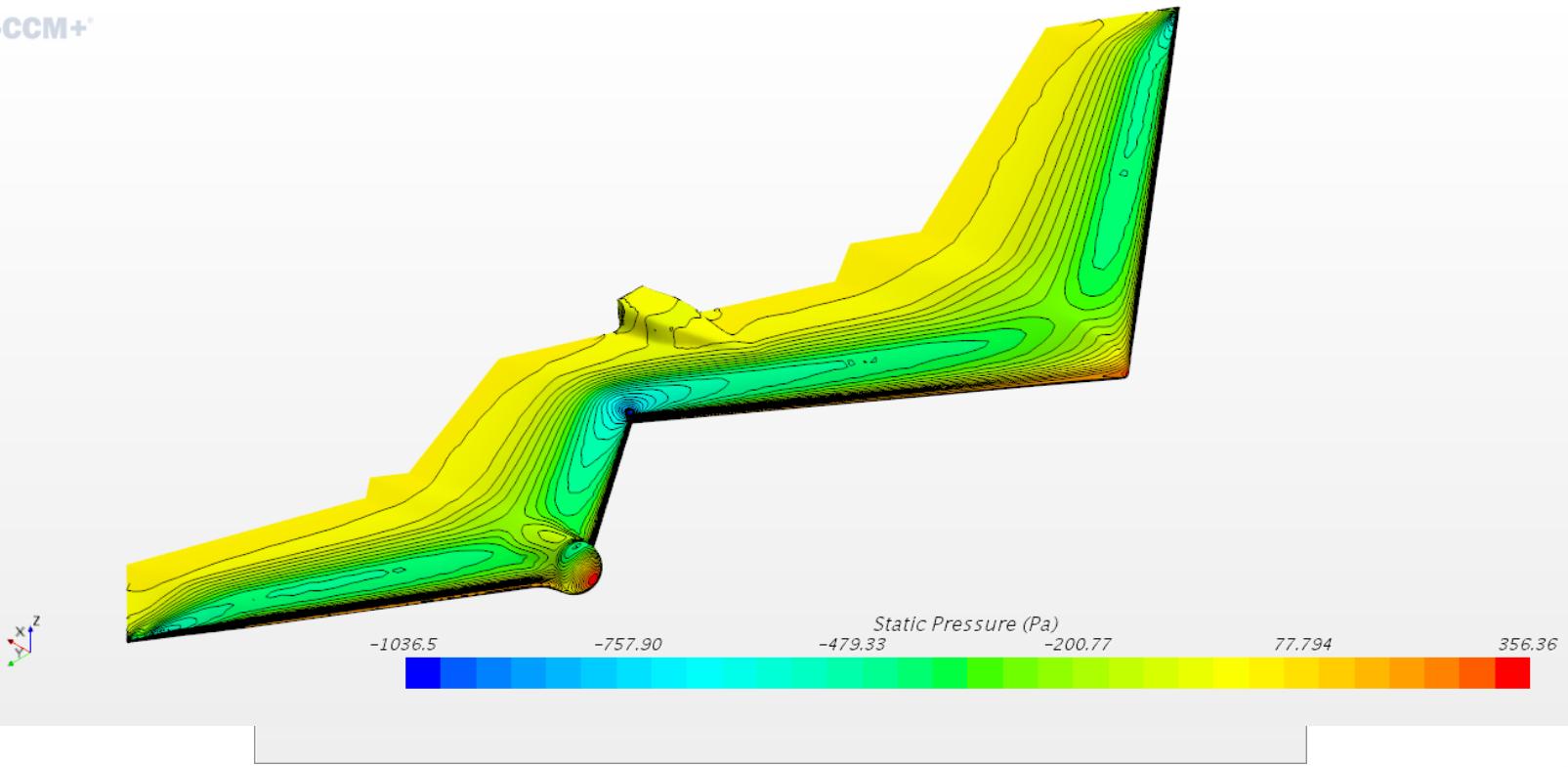


TAFA is the most efficient plane



Results and Discussion

CFD Simulation Pressure Distributing Figure



- No large scale flow separation
- No stalled problem
- No obvious design problems

Results and Discussion

CFD Simulation Data

| | L (N) | D (N) | L/D |
|----------------------|----------|----------|----------|
| TAFA | 329.2787 | 19.50406 | 16.88257 |
| Flying-wing Aircraft | 335.3814 | 24.20468 | 13.85709 |
| Twin-body Aircraft | 320.5712 | 24.93343 | 12.85709 |
| Monoplane | 321.6086 | 26.47643 | 12.14698 |

TAFA has the highest lift-drag ratio



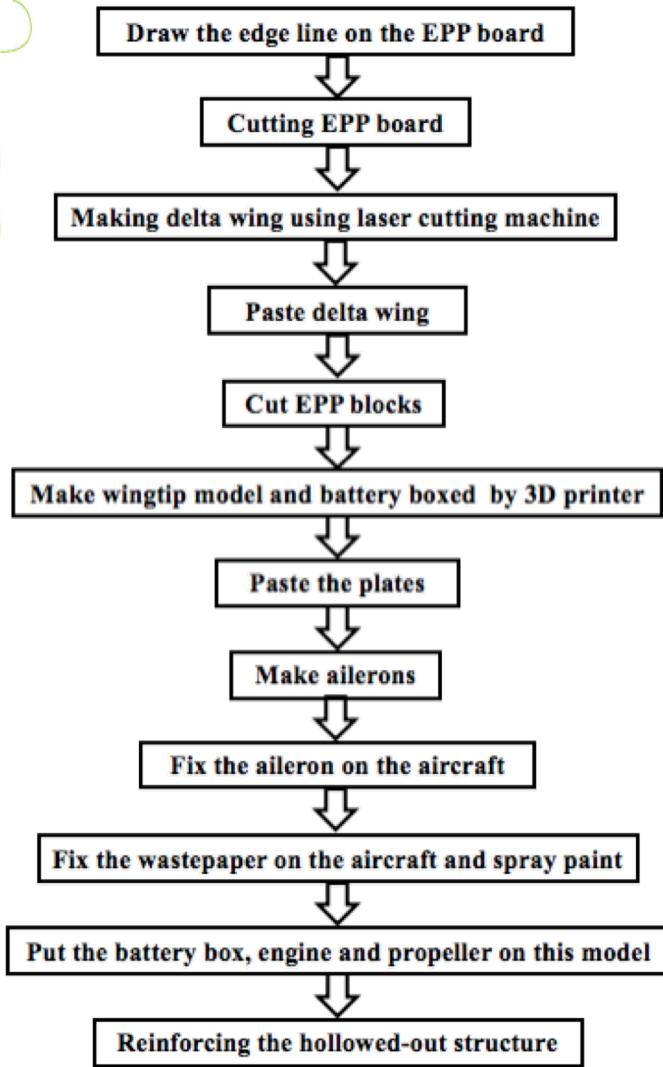
TAFA has the best flight performance

3

Fabrication & Flight Test

- Fabrication
- Flight Test

Fabrication



Flight Test

- ✓ Beijing University of Aeronautics and Astronautics
- ✓ Stable and controllable
- ✓ Control is sensitive and efficient
- ✓ **Successful and feasible**



4

Conclusion, Innovation, and Prospect

- Conclusion
- Innovation
- Prospect



Conclusion

- (1) The combination of the three features can improve the lift, endurance, and efficiency of the twin-body aircraft.
 - (2) TAFA and other three aircraft models are designed and simulated. TAFA model is manufactured, and experimented. The results show that TAFA is well designed.
- 



Innovation

- (1) A new type of UAV
- (2) Increase lift, endurance, and efficiency.
- (3) Reinforce the structural strength of the mid-wing.
- (4) Solve the equipment interference problem.



Prospect

- Applied into other tasks.
- Environmental-friendly.

5

Acknowledgement

- Acknowledgement



Acknowledgement

Thank you to Professor Huang Jun and Dr. Xie Jingfeng from Beijing university of aeronautics and astronautics. In addition, Thank you to Instructor Fan Bozhao and Dr. Dou Xiangmei from Beijing National Day's School.





THANK YOU

