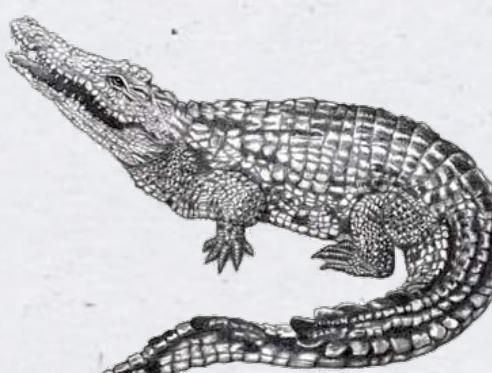


SUNOIKISIS DIGITAL CLASSICS 2016

SESSION 7: 3D SCANNING, IMAGING AND PRINTING

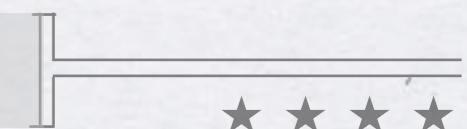
Eleni Bozia, Sara Gonzalez, Valeria Vitale

<https://github.com/SunoikisisDC/SunoikisisDC-2016>



OVERVIEW OF 3D IMAGING TECHNOLOGIES

Valeria Vitale, King's College London



Why using 3D imaging for ancient cultural heritage?

- * Enhancement (for example: writing, engravings, scratches, tool marks, damages)
- * Manipulation
- * Virtual restoration and/or unification
- * Testing hypotheses and develop variants
- * Rescue archaeology
- * Public engagement
- * ...

A brief technological overview

Time of Flight Laser Scanners

- * Good geometric fidelity
- * Suitable for large areas
- * Expensive (60k\$)
- * Massive data set
- * Slow process
- * Not accurate on smaller artefacts



Laser Scanner Triangulation



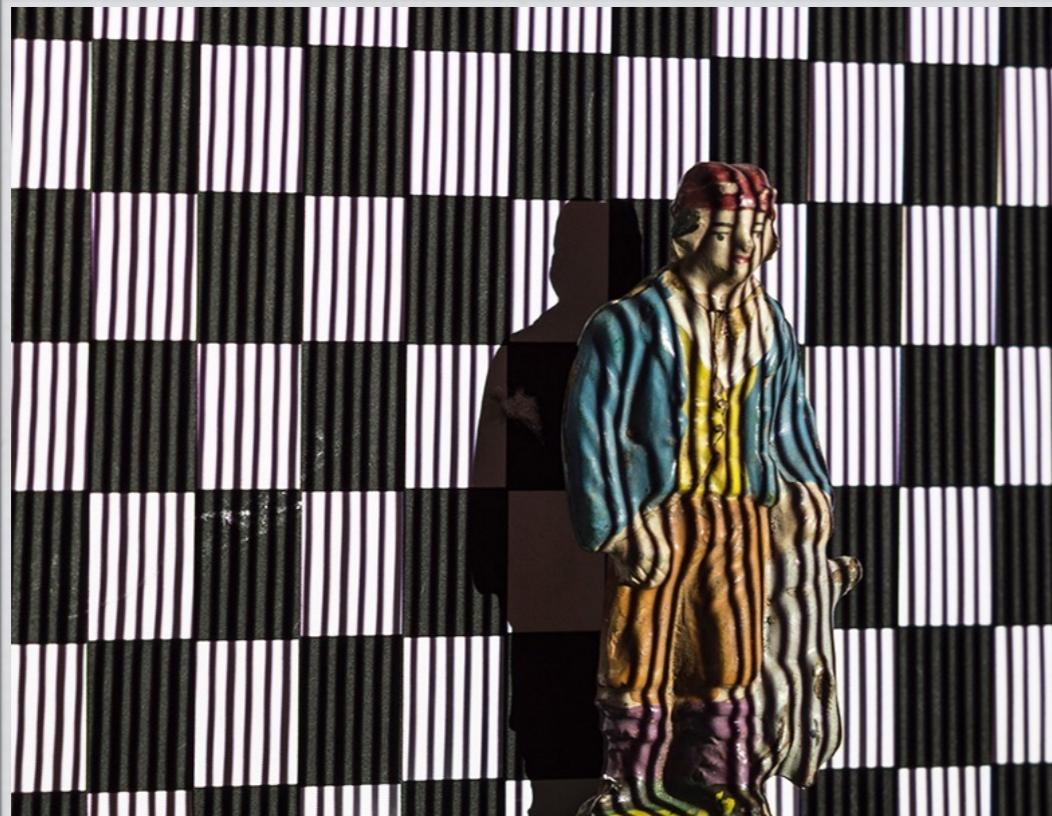
- * Cheaper than a ToF (but still between 12000 and 3000\$)
- * Better on smaller surfaces (not adequate for larger ones)
- * Portable
- * Ready to use



<http://surveyequipment.com/faro-scanner-freestyle-3d/>

<http://www.nextengine.com/>

Structured Light

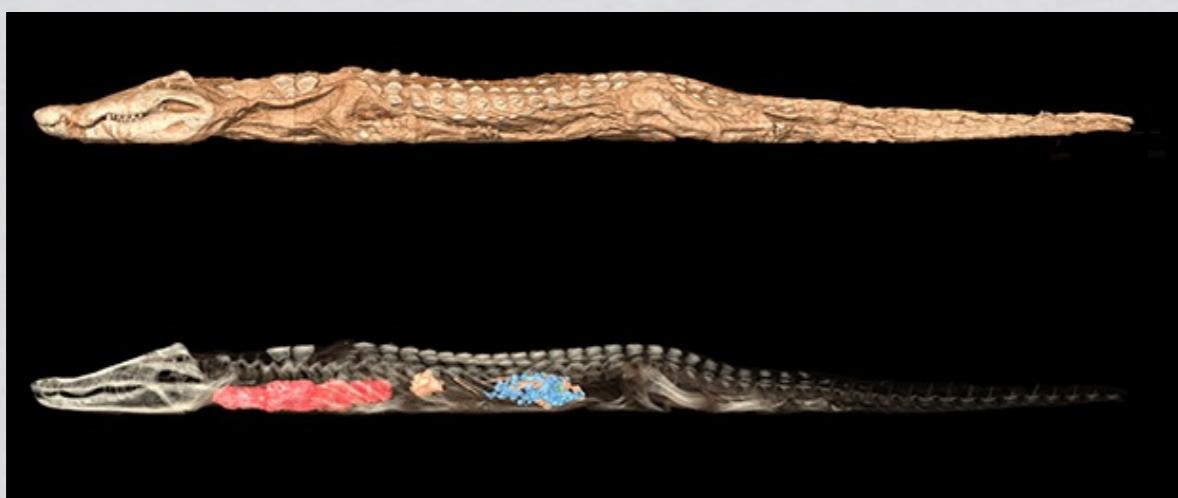
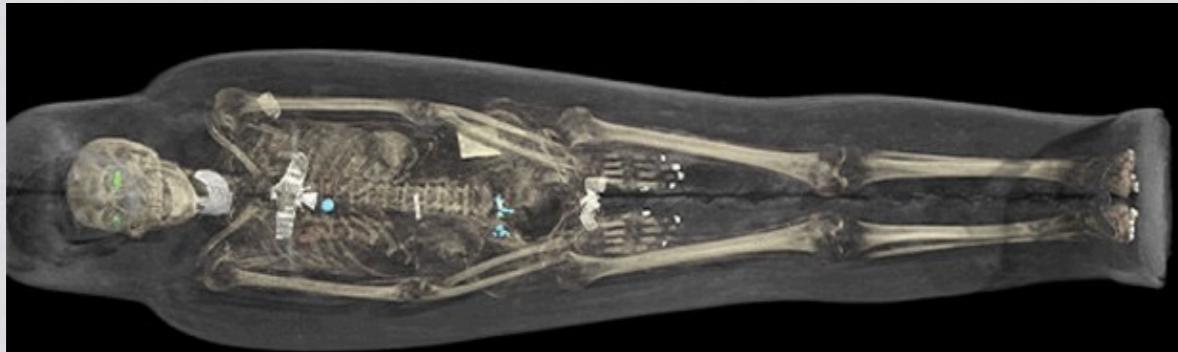


3D scanning by Structured Light using a mini (pico) projector coupled with the “3D scanning software” developed by D. Moreno and G.Taubin at Brown University School of Engineering.

<http://chsopensource.org/2015/02/02/structured-light-3d-pico-projectors/>

- * Fast
- * Accurate
- * Has to be performed in a studio
- * Requires calibration
- * Is slightly out of date, but still used and researched

CT Scan (Computed Tomography)



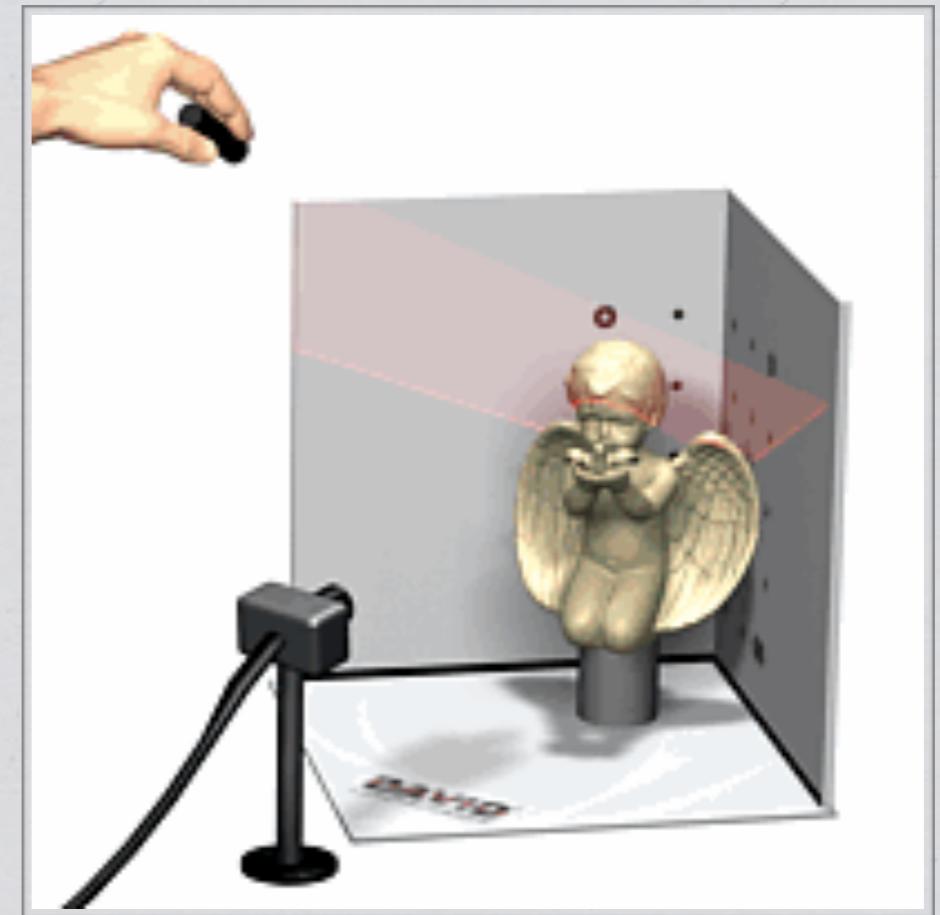
- * Expensive
- * Non portable
- * Requires training
- * Non invasive
- * Virtual autopsy

Images of CT scans used by the British Museum for the exhibitions
“Ancient Lives, New Discoveries” and “Scanning Sobekh”.

Low cost options

DIY Laser Scanner

- * Cheap starter kit (even cheaper if you DIY)
- * Good on small artefacts (1 to 40 cm)
- * Portable
- * Needs calibration
- * Needs studio setup



David 3D Scanner

<http://www.david-laserscanner.com/>

Depth Map Sensor

Hardware

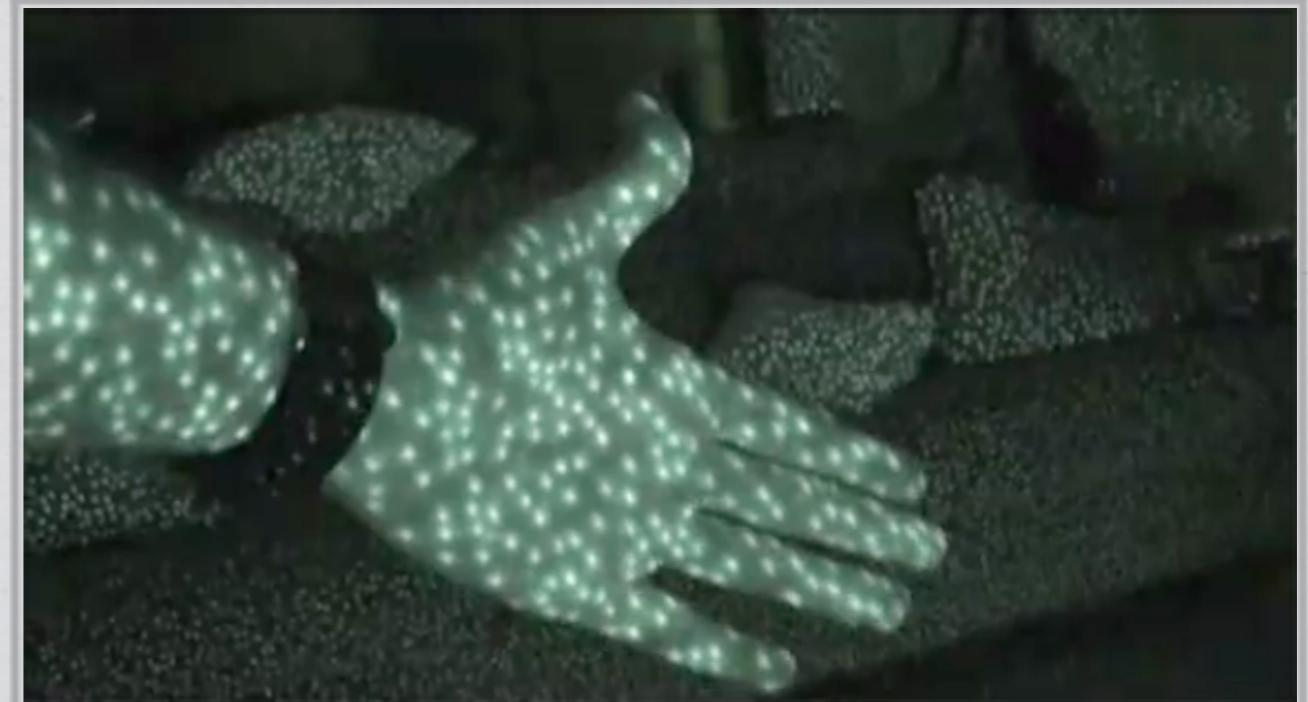
- * Kinect for PC
 - * Asus Xtion
- (both have pros and cons)



CREDITS: ANDREW MC WILLIAMS [HTTP://JAHYA.NET/](http://JAHYA.NET/)

Software

- * Reconstruct me
- * Skanect
- * Volumental



CREDITS: MATTHEW FISHER <HTTP://GRAPHICS.STANFORD.EDU/~MDFISHER/KINECT.HTML>
HTTP://WWW.YOUTUBE.COM/WATCH?V=NVVQJXGYKCU&FEATURE=PLAYER_EMBEDDED

Photogrammetry

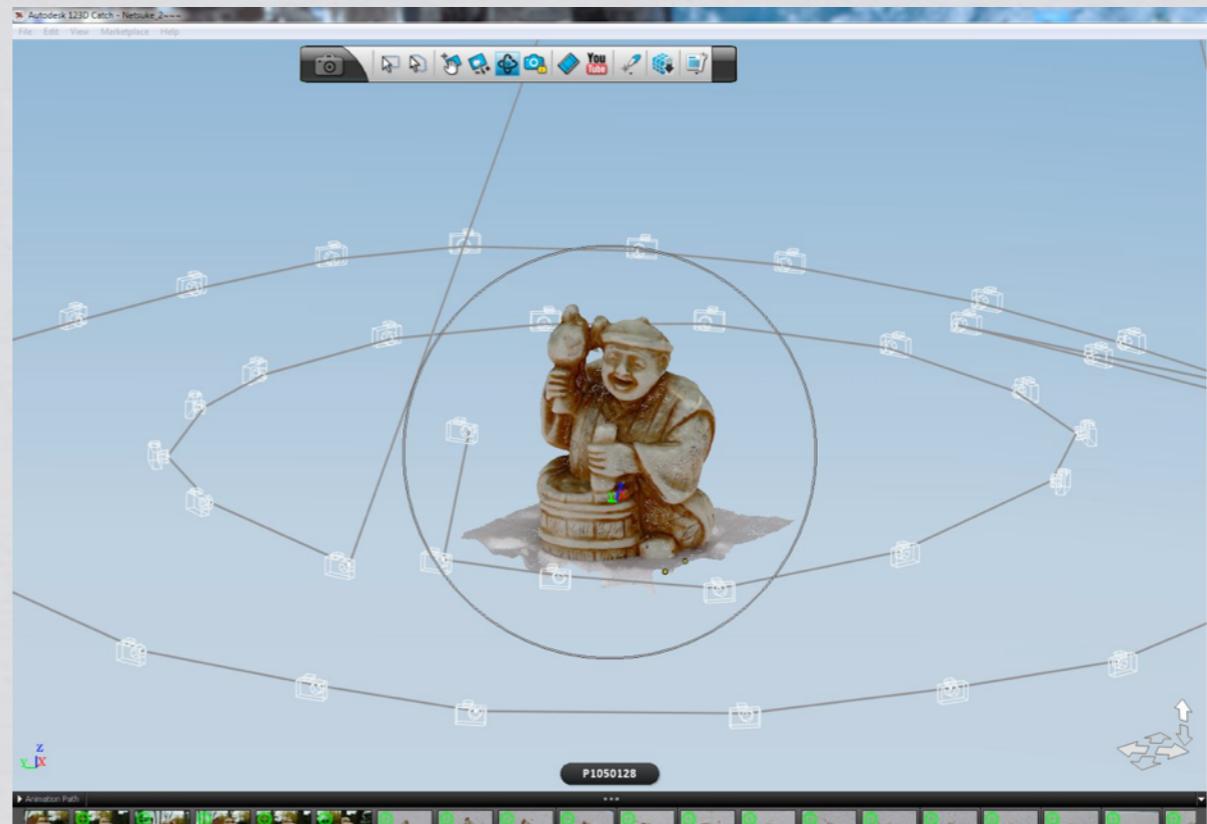
- * Based on triangulation
- * Cheap
- * Easy to learn
- * Portable equipment
- * 3D mesh as an output

Agisoft Photoscan

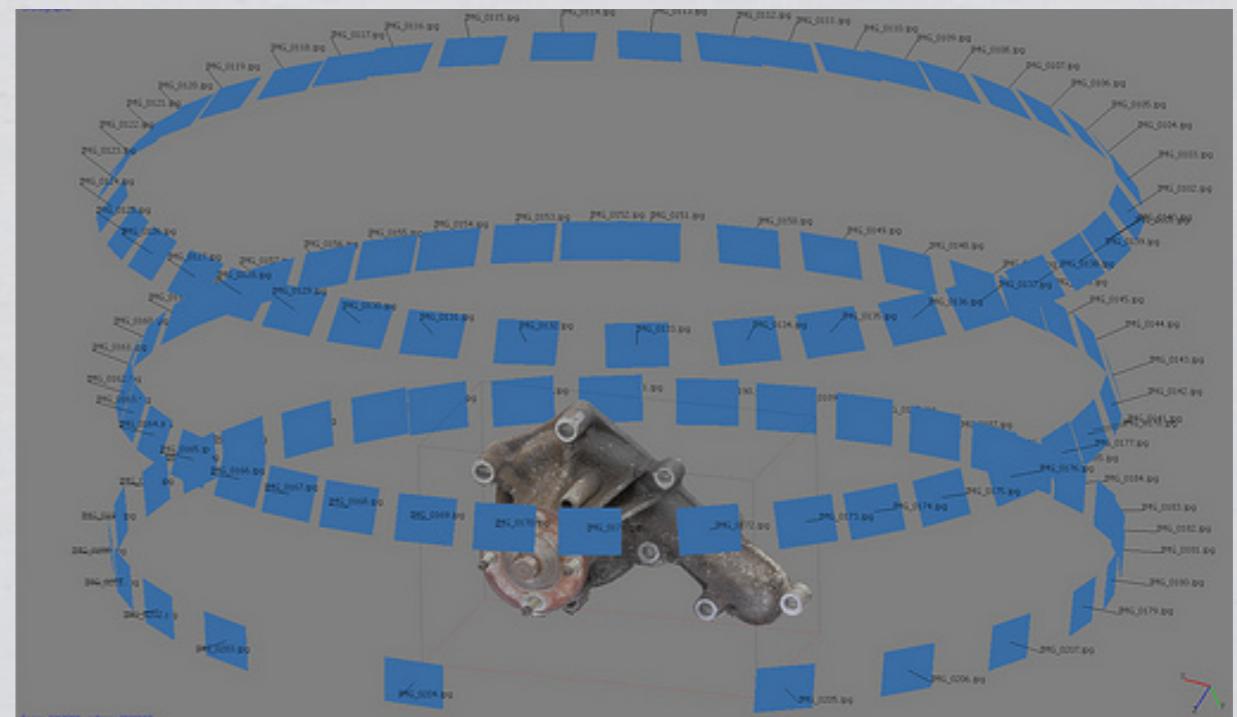
<http://www.agisoft.com/>

Autodesk123D catch

<http://www.123dapp.com/catch>



Capture with 123D catch <http://www.tcproject.net>



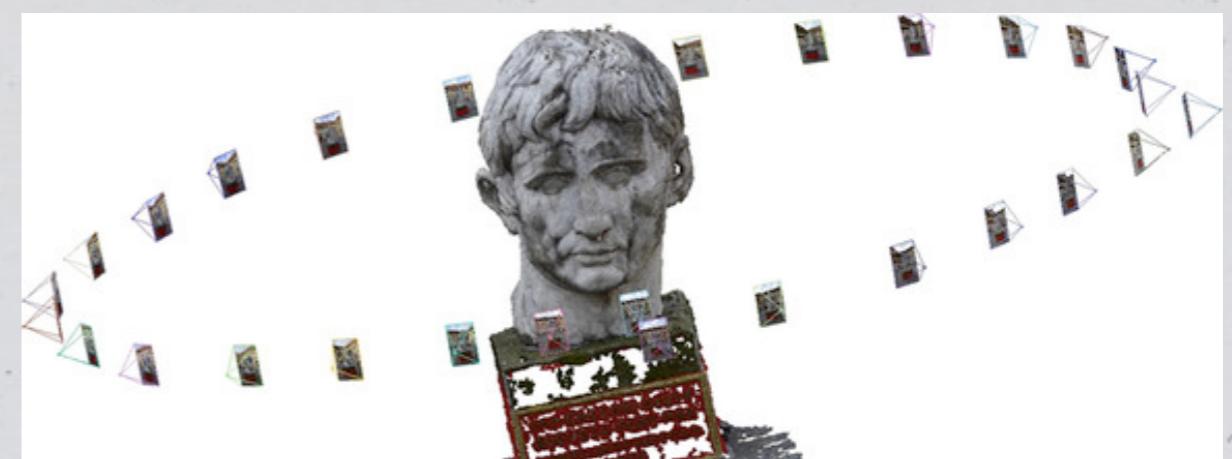
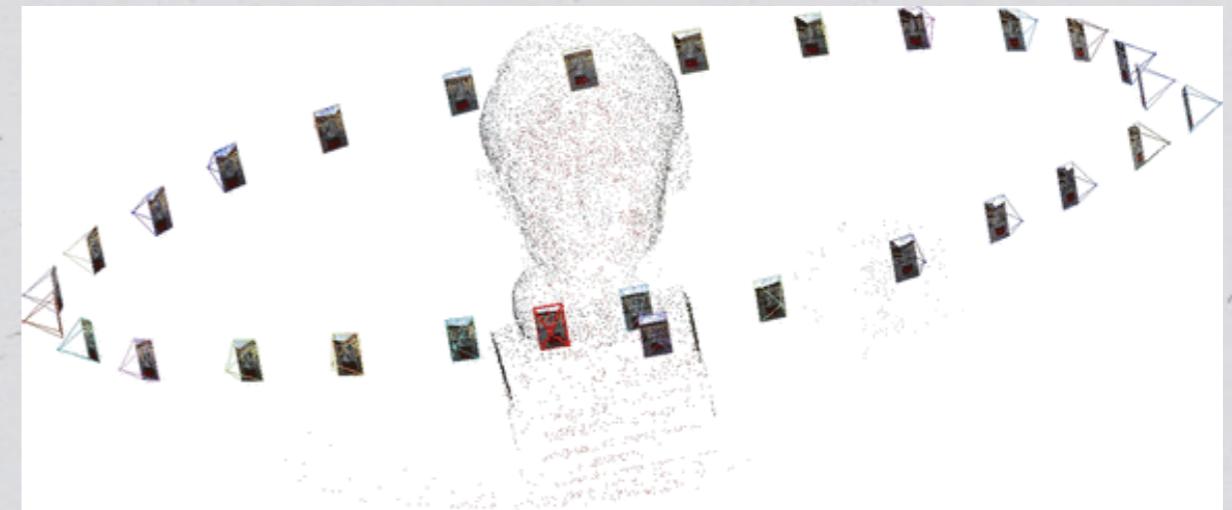
Capture with Photoscan <https://www.flickr.com/photos/erik-nl/sets/72157628813159493/>

Structure from Motion

- * Similar to Photogrammetry
- * Cheap
- * Relatively simple to use (but requires more IT skills)
- * Accurate colour information
- * Long processing time
- * Output in point cloud

Visual SFM

<http://ccwu.me/vsfm/>



<http://www.praehistorische-archaeologie.de>

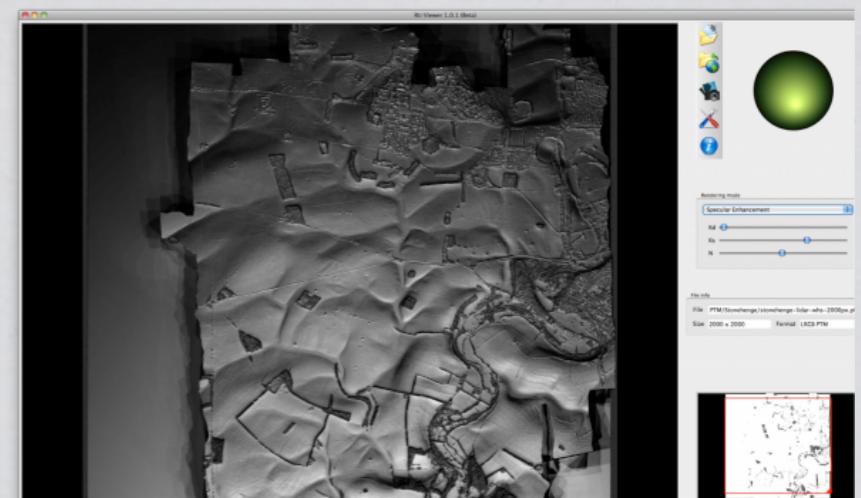
Reflectance Transformation Imaging (RTI)



- * Virtual relighting
- * Cheap (when not performed with the dome)
- * Free software
- * Can only be seen (easily) in the viewer

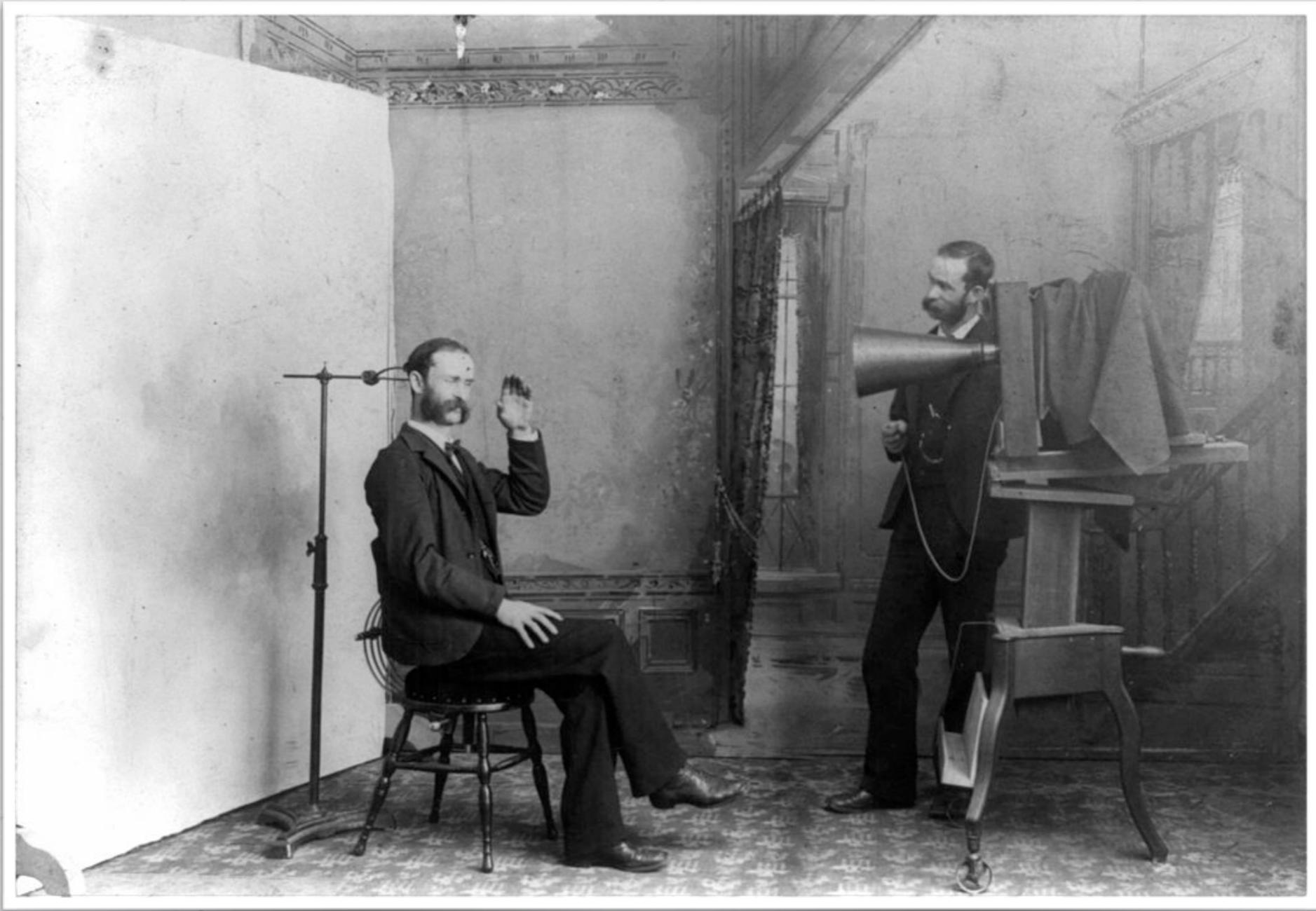


www.topoi.org

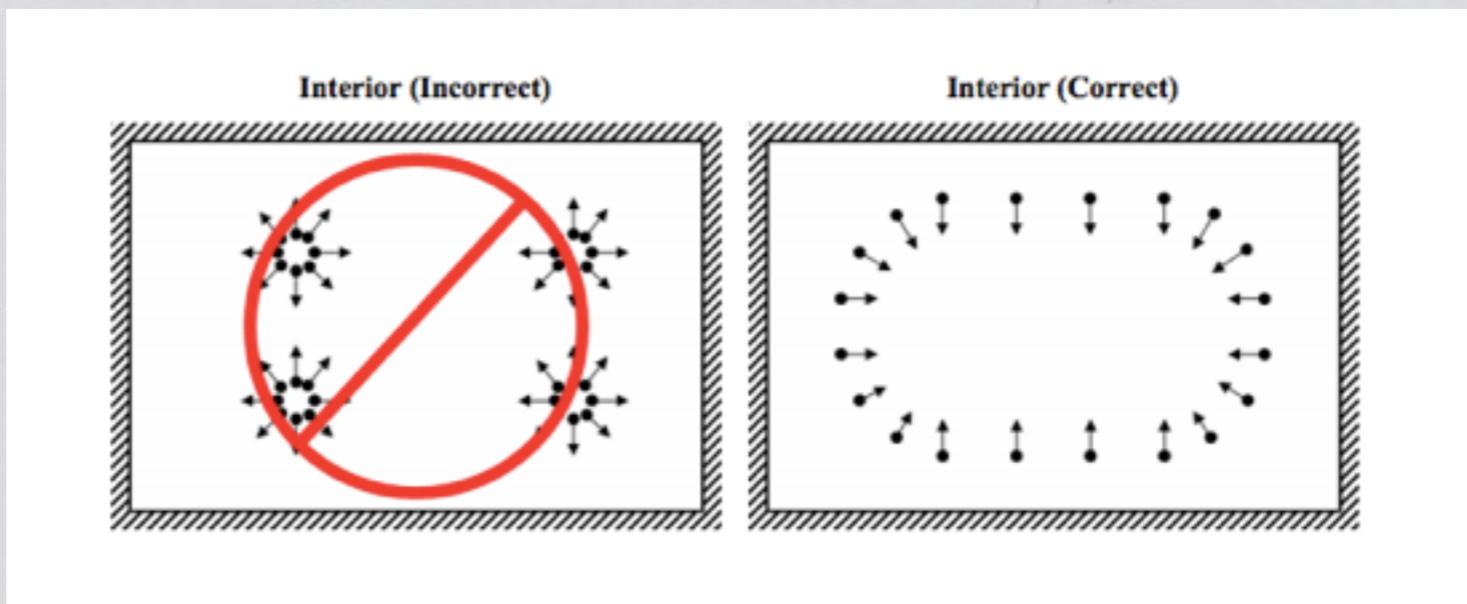
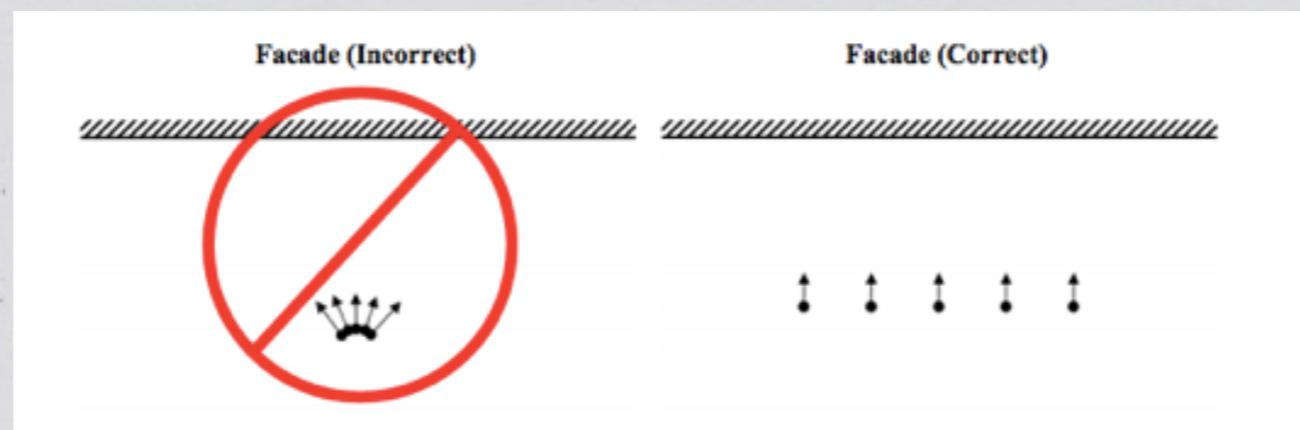
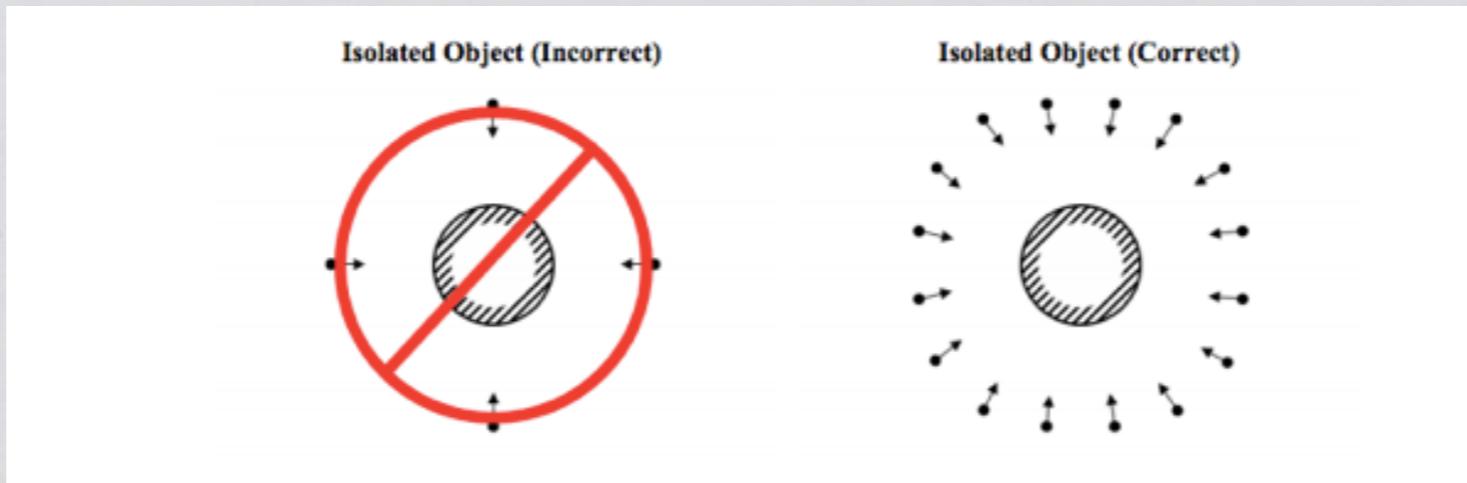


<http://www.wessexsearch.co.uk>

Exercise: digital imaging of an artefact



Photogrammetry Shooting Tips



Photogrammetry Shooting Tips

- * **POSITION**: The target **must** remain in the same position.
- * **LIGHT**: The target should be evenly lit. Avoid long shadows. Including your own!
- * **FOCUS**: The target must be on focus. Delete any blurred images before processing.
- * **SURFACE**: Each part of the target should be in at least two photographs. Ensure 40, 50% overlap (horizontally and vertically) when taking subsequent pictures. Check for occluded areas. Try different angles. Add close-ups after you have imaged the main mass.

Limits

- * Transparent surfaces
- * Glossy, shiny surfaces
- * Repetitive, featureless surfaces
- * Very thin, criss-crossing surfaces (hair, leaves)
- * (Cloud-based processing: performance and copyright issues)

It sometimes helps to:

- * Make the surface opaque
- * Add extra marks to help the software identifying features

Follow the step-by-step instructions in the handout to complete the exercise. The list of software and all the information you need are available online on the SunoikisisDC 2016 github

Documentation

- * Date and time of the photoshoot
- * Camera and lights
- * Positions of the camera during the photoshoot
- * Software and hardware
- * Compression and Post-editing

THANK YOU FOR YOUR ATTENTION

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@nottinauta

