

Numerical Analysis – Eigenvalue and Eigenvector

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Eigenvalue problem

$$Ax = \lambda x$$

λ : eigenvalue

x : eigenvector

※ spectrum: a set of all eigenvalue



Eigenvalue

Eigenvalue λ

$$(A - \lambda I)x = 0$$

if $\det(A - \lambda I) \neq 0 \rightarrow x=0$ (trivial solution)

\therefore To obtain a non-trivial solution,

$$\det(A - \lambda I) = 0$$

$$\rightarrow \begin{vmatrix} a_{11} - \lambda & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} - \lambda & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & a_{11} \\ a_{n1} & a_{n2} & \cdots & a_{nn} - \lambda \end{vmatrix} = 0$$

;Characteristic equation



Properties of Eigenvalue

1) Trace $A = \sum_{i=1}^n a_{ii} = \sum_{i=1}^n \lambda_i$

2) $\det A = \prod_{i=1}^n \lambda_i$

3) If A is symmetric, then the eigenvectors are

orthogonal: $x_i^T x_j = \begin{cases} 0, & i \neq j \\ G_{ii}, & i = j \end{cases}$

4) Let the eigenvalues of $A = \lambda_1, \lambda_2, \dots, \lambda_n$

then, the eigenvalues of $(A - aI)$

$$= \lambda_1 - a, \lambda_2 - a, \dots, \lambda_n - a,$$



Geometric Interpretation of Eigenvectors

- Transformation Ax

$Ax = \lambda x$: The transformation of an eigenvector
is mapped onto the same line of x .

- Symmetric matrix \rightarrow orthogonal eigenvectors

- Relation to Singular Value

if A is singular $\rightarrow 0 \in \{\text{eigenvalues}\}$



Eg. Calculating Eigenvectors(I)

Exercise

1) $\begin{bmatrix} -5 & 2 \\ 2 & -2 \end{bmatrix}$; symmetric, non-singular matrix
($\lambda = -1, -6$)

2) $\begin{bmatrix} -5 & 1 \\ -2 & -2 \end{bmatrix}$; non-symmetric, non-singular matrix
($\lambda = -3, -4$)



Eg. Calculating Eigenvectors(II)

3) $\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$; symmetric, singular matrix
($\lambda = 5, 0$)

4) $\begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix}$; non-symmetric, singular matrix
($\lambda = 7, 0$)



Discussion

- symmetric matrix
 - => orthogonal eigenvectors
- singular matrix
 - => $0 \in \{\text{eigenvalue}\}$
- Investigation into SVD



Similar Matrices

Two $n \times n$ matrices A and B are **similar** if a matrix S exists with $A = S^{-1}BS$. The important feature of similar matrices is that they have the same eigenvalues. The next result follows from observing that if $\lambda\mathbf{x} = A\mathbf{x} = S^{-1}BS\mathbf{x}$, then $BS\mathbf{x} = \lambda S\mathbf{x}$. Also, if $\mathbf{x} \neq \mathbf{0}$ and S is nonsingular, then $S\mathbf{x} \neq \mathbf{0}$, so $S\mathbf{x}$ is an eigenvector of B corresponding to its eigenvalue λ .

Eigenvalues and eigenvectors of similar matrices

Suppose A and B are similar $n \times n$ matrices and λ is an eigenvalue of A with associated eigenvector \mathbf{x} . Then λ is also an eigenvalue of B . And, if $A = S^{-1}BS$, then $S\mathbf{x}$ is an eigenvector associated with λ and the matrix B .

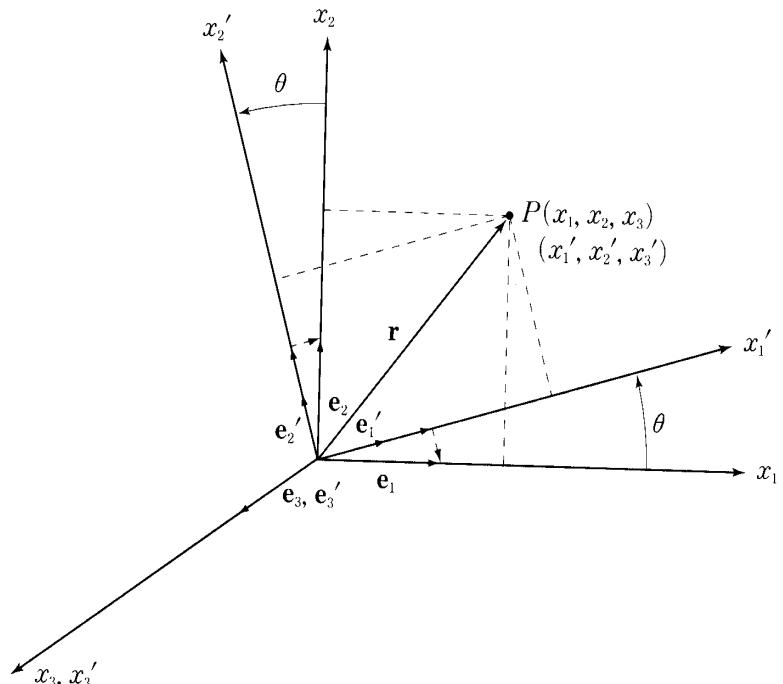
Eg. Rotation matrix



Similarity Transformation

Coordinate transformation

- ❖ $x' = Rx, y' = Ry$



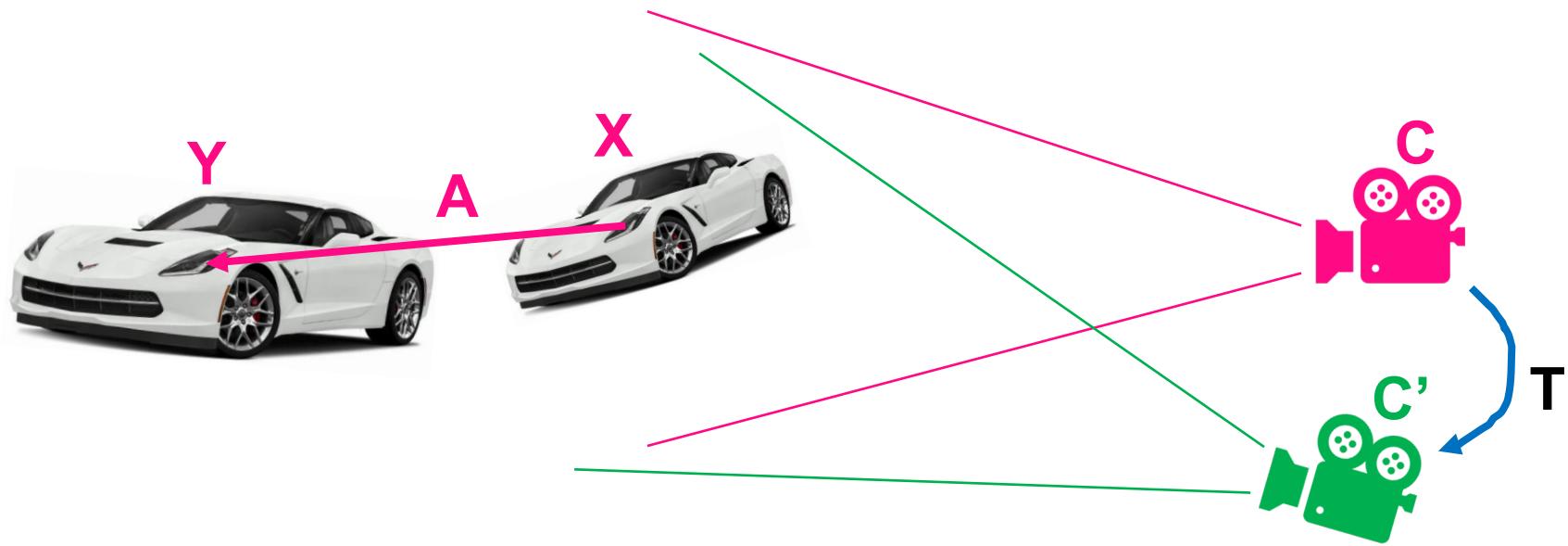
Similarity transformation

- ❖ $y = Ax$
- ❖ $y' = Ry = RAx = RA(R^{-1} x') = RAR^{-1} x' = Bx'$

$$B = RAR^{-1}$$



Similarity Transformation in CG



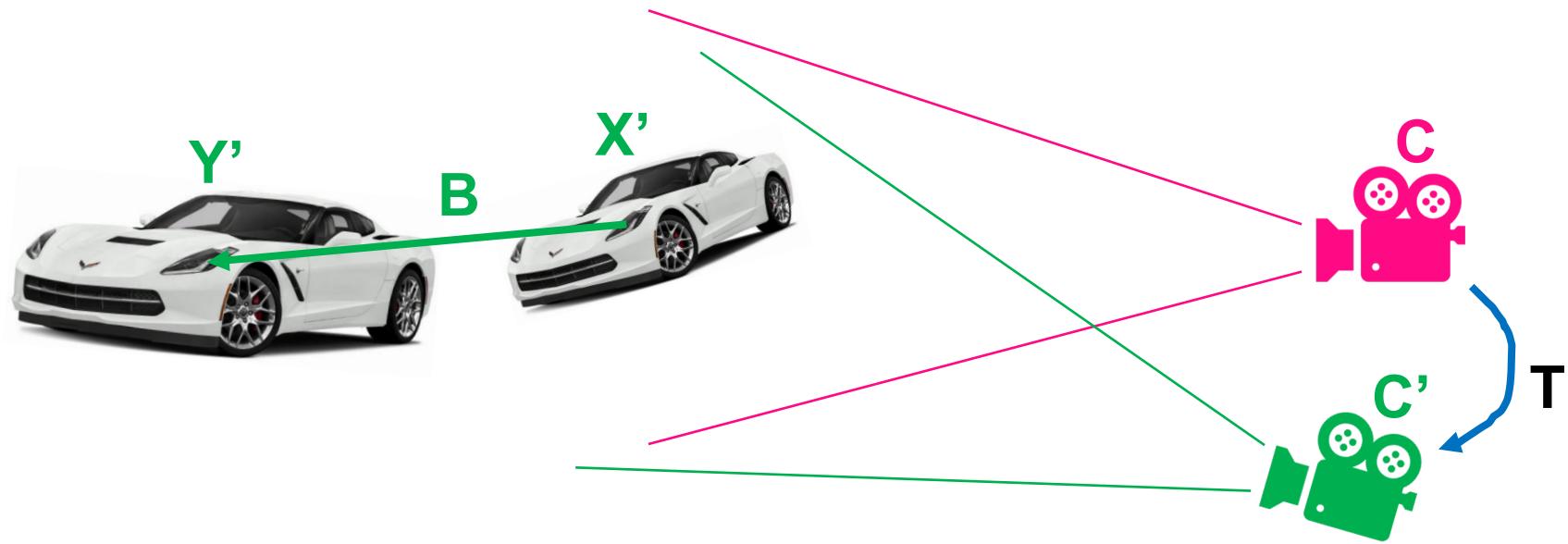
$X' = TX$ (camera coordinate transformation)

$Y = AX$ (object transformation seen from C)

What would be the object transformation B seen from C' ?

$$Y' = BX'$$





$X' = TX$ (camera coordinate transformation)

$Y = AX$ (object transformation seen from C)

What would be the object transformation B seen from C' ?

$$Y' = TY = TAX = TAT^{-1}X' = BX'$$

$$B = TAT^{-1}$$



Numerical Methods(I)

■ Power method

- ❖ Iteration formula

$$Ax^{(k)} = y^{(k+1)} = \lambda^{(k+1)}x^{(k+1)}$$

- ❖ for obtaining large λ



Eg. Power method

예제 3·17 다음 행렬에서 가장 큰 고유값과 해당 고유벡터를 역승법으로 구하라.

$$\mathbf{A} = \begin{bmatrix} -5 & 2 \\ 2 & -2 \end{bmatrix}$$

풀이 초기값 $\mathbf{x}^{(0)}$ 을

$$\mathbf{x}^{(0)} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

로 놓고, 식(3·57a)를 이용하여 계산하면,

$$\mathbf{Ax}^{(0)} = \begin{bmatrix} -5 & 2 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -3 \\ 0 \end{bmatrix} = \mathbf{y}^{(1)}$$

이것을 단위성분이 되도록 식(3·57b)와 같이 변형하자.

$$\begin{bmatrix} -3 \\ 0 \end{bmatrix} = -3 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \lambda^{(1)} \mathbf{x}^{(1)}$$

$\mathbf{x} = \mathbf{x}^{(1)}$ 을 식(3·57a)에 대입하여 계산하면 다음과 같다.

$$\mathbf{Ax}^{(1)} = \begin{bmatrix} -5 & 2 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -5 \\ 2 \end{bmatrix}$$

이 식을 식(3·57b)의 우변과 같이 변형하면,

$$\begin{bmatrix} -5 \\ 2 \end{bmatrix} = -5 \begin{bmatrix} \frac{1}{2} \\ 0 \end{bmatrix} = \lambda^{(2)} \mathbf{x}^{(2)}$$

이므로

$$\lambda^{(2)} = -5, \quad \mathbf{x}^{(2)} = \begin{bmatrix} \frac{1}{2} \\ 0 \end{bmatrix}$$

이다. 이러한 과정을 반복하면 그 결과는 다음과 같다.

반복횟수	λ	x_1	x_2
0	•	1.000000	1.000000
1	-3.000000	1.000000	0.000000
2	-5.000000	1.000000	-0.400000
3	-5.800000	1.000000	-0.482759
4	-5.965517	1.000000	-0.497110
5	-5.994220	1.000000	-0.499518
6	-5.999036	1.000000	-0.499920
7	-5.999839	1.000000	-0.499987
8	-5.999973	1.000000	-0.499998

따라서 수렴한 후 가장 큰 고유값과 고유벡터는 다음과 같다.

$$\lambda_1 = -6, \quad \mathbf{x}_1 = \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}$$



Numerical Methods (II)

■ Inverse power method

- ❖ Iteration formula

$$\begin{aligned} A^{-1}x^{(k)} = y^{(k+1)} &\Leftrightarrow Ay^{(k+1)} = x^{(k)} \\ &\Leftrightarrow Lc = x^{(k)}, Uy^{(k+1)} = c \end{aligned}$$

- ❖ for obtaining small λ



Exploiting shifting property

Let the eigenvalues of $A = \lambda_1, \lambda_2, \dots, \lambda_n$

then, the eigenvalues of $(A - al)$

$$= \lambda_1 - a, \lambda_2 - a, \dots, \lambda_n - a,$$

- Finding the maximum eigenvalue with opposite sign after obtaining λ
- Accelerating the convergence when an approximate eigenvalue is available



Deflated matrices

Suppose $\lambda_1, \lambda_2, \dots, \lambda_n$ are eigenvalues of A with associated eigenvectors $\mathbf{v}^{(1)}, \mathbf{v}^{(2)}, \dots, \mathbf{v}^{(n)}$ and that λ_1 has multiplicity 1. If \mathbf{x} is a vector with $\mathbf{x}^t \mathbf{v}^{(1)} = 1$, then

$$B = A - \lambda_1 \mathbf{v}^{(1)} \mathbf{x}^t$$

has eigenvalues $0, \lambda_2, \lambda_3, \dots, \lambda_n$ with associated eigenvectors $\mathbf{v}^{(1)}, \mathbf{w}^{(2)}, \mathbf{w}^{(3)}, \dots, \mathbf{w}^{(n)}$, where $\mathbf{v}^{(i)}$ and $\mathbf{w}^{(i)}$ are related by the equation

$$\mathbf{v}^{(i)} = (\lambda_i - \lambda_1) \mathbf{w}^{(i)} + \lambda_1 (\mathbf{x}^t \mathbf{w}^{(i)}) \mathbf{v}^{(1)},$$

for each $i = 2, 3, \dots, n$.

- It is possible to obtain eigenvectors one after another
- Properly assigning the vector \mathbf{x} is important
- Eg. Wielandt's deflation

$$\mathbf{x} = \frac{1}{\lambda_1 v_i^{(1)}} (a_{i1}, a_{i2}, \dots, a_{in})^t,$$



Eg. Using Deflation(I)

Example 4 The symmetric matrix

$$A = \begin{bmatrix} 4 & -1 & 1 \\ -1 & 3 & -2 \\ 1 & -2 & 3 \end{bmatrix}$$

has eigenvalues $\lambda_1 = 6$, $\lambda_2 = 3$, and $\lambda_3 = 1$. Assuming that the dominant eigenvalue $\lambda_1 = 6$ and associated unit eigenvector $\mathbf{v}^{(1)} = (1, -1, 1)^t$ have been calculated, the procedure just outlined for obtaining λ_2 proceeds as follows:

$$\mathbf{x} = \frac{1}{6} \begin{bmatrix} 4 \\ -1 \\ 1 \end{bmatrix} = \left(\frac{2}{3}, -\frac{1}{6}, \frac{1}{6} \right)^t,$$

$$\mathbf{v}^{(1)} \mathbf{x}^t = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \left[\frac{2}{3}, -\frac{1}{6}, \frac{1}{6} \right] = \begin{bmatrix} \frac{2}{3} & -\frac{1}{6} & \frac{1}{6} \\ -\frac{2}{3} & \frac{1}{6} & -\frac{1}{6} \\ \frac{2}{3} & -\frac{1}{6} & \frac{1}{6} \end{bmatrix},$$

and

$$\begin{aligned} B = A - \lambda_1 \mathbf{v}^{(1)} \mathbf{x}^t &= \begin{bmatrix} 4 & -1 & 1 \\ -1 & 3 & -2 \\ 1 & -2 & 3 \end{bmatrix} - 6 \begin{bmatrix} \frac{2}{3} & -\frac{1}{6} & \frac{1}{6} \\ -\frac{2}{3} & \frac{1}{6} & -\frac{1}{6} \\ \frac{2}{3} & -\frac{1}{6} & \frac{1}{6} \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 & 0 \\ 3 & 2 & -1 \\ -3 & -1 & 2 \end{bmatrix}. \end{aligned}$$



Eg. Using Deflation(II)

Deleting the first row and column gives

$$B' = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix},$$

which has eigenvalues $\lambda_2 = 3$ and $\lambda_3 = 1$. For $\lambda_2 = 3$, the eigenvector $\mathbf{w}^{(2)'}'$ can be obtained by solving the second-order linear system

$$(B' - 3I)\mathbf{w}^{(2)'} = \mathbf{0}, \quad \text{resulting in} \quad \mathbf{w}^{(2)'} = (1, -1)^t.$$

Adding a zero for the first component gives $\mathbf{w}^{(2)} = (0, 1, -1)^t$ and

$$\begin{aligned} \mathbf{v}^{(2)} &= (3 - 6)(0, 1, -1)^t + 6 \left[\left(\frac{2}{3}, -\frac{1}{6}, \frac{1}{6} \right) (0, 1, -1)^t \right] (1, -1, 1)^t \\ &= (-2, -1, 1)^t. \end{aligned}$$



Numerical Methods (III)

■ Hotelling's deflation method

- ❖ Iteration formula:

$$A_{i+1} = A_i - \lambda_i x_i x_i^T \text{ given } \lambda_i, x_i$$

- ❖ for symmetric matrices
- ❖ deflation from large to small λ



Numerical Methods (IV)

■ Jacobi transformation

- ❖ Successive diagonalization without changing λ .
- ❖ for symmetric matrices

- Atomic transformation:

$$P_{pq} = \begin{bmatrix} 1 & & & & \\ & \cdots & & & \\ & c & \cdots & s & \\ \vdots & & 1 & & \vdots \\ & -s & \cdots & c & \\ & & & & \cdots \\ & & & & 1 \end{bmatrix}$$



Homework

- Generate a 11×11 ***symmetric*** matrix ***A*** by using random number generator(Gaussian distribution with mean=0 and standard deviation=1.0]). Then, compute all eigenvalues and eigenvectors of ***A*** using the routines in the book, NR in C. Print the eigenvalues and their corresponding eigenvectors in the descending order.
 - ❖ You may use
 - `jacobi()`: Obtaining eigenvalues using the Jacobi transformation
 - `eigsrt()`: Sorting the results of `jacobi()`

