### **Brownian Motion**

Reflection Principle

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## Reflection Principle

Suppose that  $\{B_t\}_{t\geqslant 0}$  is a standard Brownian motion. Define the running maximum and minimum as

$$M_t = \max_{0 \leqslant s \leqslant t} B_s \text{ and } m_t = \min_{0 \leqslant s \leqslant t} B_s. \tag{1}$$

Obviously, we have  $M_t \geqslant 0 \geqslant m_t$  since  $B_0 = 0$ . Define a stopping time  $T_a$  for any  $a \in \mathbb{R}$ :

$$T_a = \min\left\{t : B_t = a\right\},\tag{2}$$

which is the first time when  $\{B_t\}_{t\geqslant 0}$  hits level a. By convention,  $T_a=\infty$  when  $\{B_t\}_{t\geqslant 0}$  never hits level a. We give two claims without proof.

#### Theorem

 $T_a < \infty$  almost surely.

### Theorem

(Strong independent increments) Process  $\{X_t\}_{t\geqslant 0}$  given by  $X_t=B_{T_a+t}-a$  is a standard Brownian motion and is independent of  $\{B_t\}_{0\leqslant t\leqslant T_a}$ .

## Reflection Principle

#### Theorem

(Reflection principle) For each  $a \geqslant 0$  we have

$$\mathbb{P}(M_t \geqslant a) = 2\mathbb{P}(B_t \geqslant a) = \frac{2}{\sqrt{2\pi t}} \int_a^\infty \exp\left(-\frac{x^2}{2t}\right) dx. \tag{3}$$

For each  $a \leq 0$  we have

$$\mathbb{P}\left(m_{t} \leqslant a\right) = 2\mathbb{P}\left(B_{t} \leqslant a\right) = \frac{2}{\sqrt{2\pi t}} \int_{-\infty}^{a} \exp\left(-\frac{x^{2}}{2t}\right) dx. \tag{4}$$

### Proof:



# Reflection Principle

### Theorem

For each  $a \ge 0, y \ge 0$  we have

$$\mathbb{P}(M_t \geqslant a, B_t \leqslant a - y) = \mathbb{P}(B_t \geqslant a + y). \tag{5}$$

For each  $a \leq 0, y \geq 0$  we have

$$\mathbb{P}\left(m_{t} \leqslant a, B_{t} \geqslant a + y\right) = \mathbb{P}\left(B_{t} \leqslant a - y\right). \tag{6}$$

**Proof**:

