

Spline

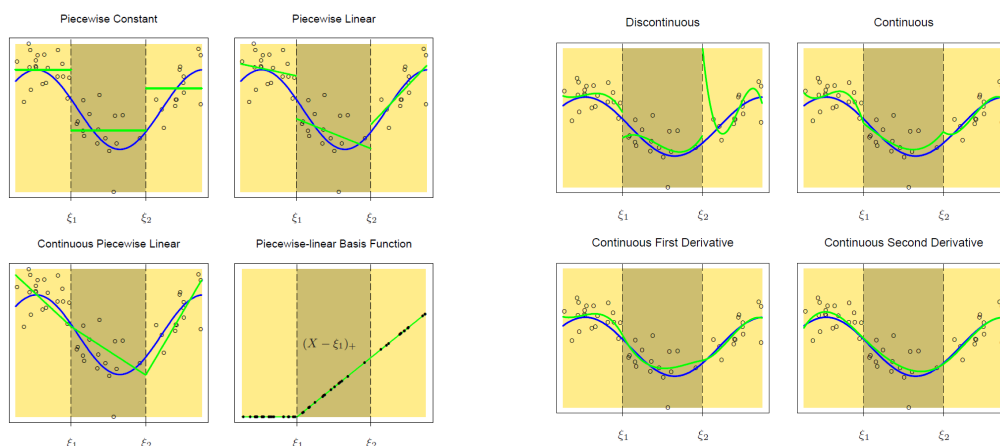
- $\forall t_0 < t_1 < \dots < t_{k+1}$
- **spline function**: a spline function of degree d on $[t_0, t_{k+1}]$ is a piecewise polynomial of degree d on $[t_j, t_{j+1})$
- **Knots**: points where the spline may not have continuous d^{th} derivative.
- $\forall \xi_1 < \xi_2$ (special case with 2 knots)

• **Piecewise Constant**:

$$B_1(x) = I(x < \xi_1) \quad B_2(x) = I(\xi_1 \leq x < \xi_2) \quad B_3(x) = I(\xi_2 \leq x)$$

• **Piecewise Linear**:

$$B_1(x) = 1 \quad B_2(x) = x \quad B_3(x) = (x - \xi_1)_+ \quad B_4(x) = (x - \xi_2)_+$$



• **Piecewise Cubic**:

$$B_1(x) = 1 \quad B_2(x) = x \quad B_3(x) = x^2 \quad B_4(x) = x^3$$

$$B_5(x) = (x - \xi_1)_+^3 \quad B_6(x) = (x - \xi_2)_+^3$$

• **Generalized Spline** (if knots $\{\xi_l\}_{l=1}^k$)

$$B_j(x) = x^{j-1}, \quad j=1, \dots, M \quad B_{M+l}(x) = (x - \xi_l)_+^{M-1}, \quad l=1, 2, \dots, k$$

Why they are spline???

1. We know that $B_j(x)$ $j=1, \dots, M+k$ are continuous

2. We know that $B_j^{(1)}(x)$ $j=1, \dots, M+k$ are continuous

\vdots

$M-1$. We know that $B_j^{(M-1)}(x)$ $j=1, \dots, M+k$ are continuous

\Rightarrow By **Algebraic Continuity Property**, $\sum_{j=1}^{M+k} \alpha_j B_j(x)$ has continuous $(M-1)^{\text{th}}$ derivative and continuous M -th derivative on points other than knots

Q: In 数值II we learnt Cubic Spline. Is spline for regression the same?

A: Yes, but in 数值II spline is used for interpolation, in statistics spline is used for fitting.

Cubic spline: $S_i(x) = ax^3 + bx^2 + cx + d \quad x \in [x_i, x_{i+1}]$

$$\text{s.t. } S_i(x_i) = f(x_i) \quad S_i(x_{i+1}) = f(x_{i+1}) \quad S_i'(x_{i+1}) = S_{i+1}'(x_{i+1}) \quad S_i''(x_{i+1}) = S_{i+1}''(x_{i+1})$$

Extra constraint: Complete: $S_0'(x_0) = k_0, S_{n-1}'(x_n) = k_n$

Natural: $S_0''(x_0) = S_{n-1}''(x_n) = 0$

Periodic: $S_0'(x_0) = S_{n-1}'(x_n) \quad S_0''(x_0) = S_{n-1}''(x_n)$

Not a knot: $S_0'''(x_0) = S_1'''(x_1) \quad S_{n-2}'''(x_{n-1}) = S_{n-1}'''(x_{n-1})$

Construct 4 basis polynomials.

$$\phi(x) = 3x^2 - 2x^3 \leadsto \phi(0) = 0 \quad \phi(1) = 1 \quad \phi'(0) = 0 \quad \phi'(1) = 0$$

$$\psi(x) = x^3 - x^2 \leadsto \psi(0) = \psi(1) = 0 \quad \psi'(0) = 0, \psi'(1) = 1$$

$$\text{Find } S_i(x) = \alpha_i \phi\left(\frac{x_{i+1}-x}{h}\right) + \beta_i \phi\left(\frac{x-x_i}{h}\right) + C_i \psi\left(\frac{x_{i+1}-x}{h}\right) + d_i \psi\left(\frac{x-x_i}{h}\right)$$

$$- S_i(x_i) = y_i \Rightarrow \alpha_i = y_i \quad - S_i'(x_i) = k_i \Rightarrow C_i = -h k_i$$

$$- S_i(x_{i+1}) = y_{i+1} \Rightarrow \beta_i = y_{i+1} \quad - S_i'(x_{i+1}) = k_{i+1} \Rightarrow d_i = h k_{i+1}$$

$$\text{And } S_i''(x_{i+1}) = S_{i+1}''(x_{i+1})$$

$$\Rightarrow 6 \frac{y_i}{h_i^2} - 6 \frac{y_{i+1}}{h_i^2} + 2 \frac{k_i}{h_i} + 4 \frac{k_{i+1}}{h_i} = -6 \frac{y_{i+1}}{h_{i+1}^2} + 6 \frac{y_{i+2}}{h_{i+1}^2} - 4 \frac{k_{i+1}}{h_{i+1}} - 2 \frac{k_{i+2}}{h_{i+1}}$$

$$\text{Let } \beta_i = \frac{1}{h_i}, \alpha_i = 2(\beta_i + \beta_{i+1}), \eta_i = 3 \frac{y_{i+1} - y_i}{h_i^2}$$

Then, in matrix form

$$\text{Complete: } \begin{pmatrix} \alpha_0 & \beta_0 & & & \\ \beta_0 & \alpha_0 & \beta_1 & & \\ & \beta_1 & \alpha_1 & \beta_2 & \\ & & \ddots & \ddots & \ddots \\ & & & \beta_{n-3} & \alpha_{n-2} & \beta_{n-2} \\ & & & & \beta_{n-2} & \alpha_{n-1} \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \\ \vdots \\ k_{n-1} \end{pmatrix} = \begin{pmatrix} \eta_0 + \eta_1 - \beta_0 k_0 \\ \eta_1 + \eta_2 \\ \vdots \\ \eta_{n-2} + \eta_{n-1} - \beta_n k_n \end{pmatrix}$$

$$\text{Natural } \begin{pmatrix} 2\beta_0 & \beta_0 & & & \\ \beta_0 & \alpha_0 & \beta_1 & & \\ & \beta_1 & \alpha_1 & \beta_2 & \\ & & \ddots & \ddots & \ddots \\ & & & \beta_{n-3} & \alpha_{n-2} & \beta_{n-2} \\ & & & & \beta_{n-2} & \alpha_{n-1} \end{pmatrix} \begin{pmatrix} k_0 \\ k_1 \\ \vdots \\ k_n \end{pmatrix} = \begin{pmatrix} \eta_0 \\ \eta_0 + \eta_1 \\ \vdots \\ \eta_n \end{pmatrix}$$

B-spline: A B-spline curve of degree k is defined by $S(t) = \sum_{i=0}^n N_{i,k}(t) \alpha_i$, where $N_{i,k}(t)$

are the basis functions defined using **de Boor-Cox recursion formula**.

$$N_{i,0}(t) = I(t_i \leq t < t_{i+1}), \quad N_{i,j}(t) = \frac{t - t_i}{t_{i+j} - t_i} N_{i,j-1}(t) + \frac{t_{i+j+1} - t}{t_{i+j+1} - t_{i+1}} \cdot N_{i+1,j-1}(t)$$

$$\begin{array}{ccccccc} N_{0,0}(t) & \rightarrow & N_{0,1}(t) & \cdots & N_{0,k-1}(t) & \rightarrow & N_{0,k}(t) \\ & \nearrow & & & & \nearrow & \\ N_{1,0}(t) & \rightarrow & N_{1,1}(t) & \cdots & N_{1,k-1}(t) & & \\ \vdots & & \vdots & & & & \\ N_{n-1,0}(t) & \rightarrow & N_{n-1,1}(t) & & & & \\ & \nearrow & & & & & \\ N_{n,0}(t) & & & & & & \end{array}$$

• **Matrix form**: $N_{i,j}(t) = \begin{vmatrix} w_{i,k}(t) & N_{i,j-1}(t) \\ (1-w_{i+k,k}(t)) & N_{i+j,j-1}(t) \end{vmatrix}$,

where $w_{i,k}(t) = \frac{t - t_i}{t_{i+k} - t_i}$

• **Properties**:

1. B-spline is a piecewise polynomial which only breaks at knots $\{t_i\}_{i=1}^n$,

2. $N_{i,j}(t) = 0$ for $t \notin (t_i, t_{i+j})$

3. $N_{i,j}(t) > 0$ for $t \in (t_i, t_{i+j})$

4. $\sum_{j=1}^{n+j} N_{i,j}(t) = 1 \quad \forall t \in [t_0, t_n]$

