### § 5.4.3 差分

定义5.2 设f(x)在等距节点

$$x_k = x_0 + kh$$
  $(k = 0,1,...,n)$ 

上的函数值为fk,则称

$$\Delta f_{k} = f_{k+1} - f_{k}, \nabla f_{k} = f_{k} - f_{k-1}$$

分别为一阶向前差分和一阶向后差分。

$$\Delta^{m} f_{k} = \Delta^{m-1} f_{k+1} - \Delta^{m-1} f_{k}, \nabla^{m} f_{k} = \nabla^{m-1} f_{k} - \nabla^{m-1} f_{k-1}$$

为m阶向前差分和m阶向后差分。

数学归纳可知:  $\Delta^m f_k = \nabla^m f_{k+m}$ 

在等距节点时,均差与差分的关系:

$$f[x_0, x_1] = \frac{f_1 - f_0}{x_1 - x_0} = \frac{\Delta f_0}{h}$$

$$f[x_0, x_1, x_2] = \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0} = \frac{\Delta f_1 - \Delta f_0}{2h^2} = \frac{\Delta^2 f_0}{2h^2}$$

$$f[x_0, x_1, ..., x_k] = \frac{\Delta^k f_0}{k! h^k}$$
  $(k = 1, 2, ...)$ 

$$f[x_0,...,x_k] = \frac{f^{(k)}(\xi)}{k!} \qquad \Delta^k f_0 = h^k f^{(k)}(\xi)$$

### § 5.4.4 等节距节点的插值公式

设节点 
$$x_k = x_0 + kh$$
  $(k = 0,1,...,n)$  记  $x = x_0 + th$   $(t > 0)$  则  $x - x_k = (t - k)h$ 

$$f[x_0, x_1, ..., x_k] \prod_{j=0}^{k-1} (x - x_j) = \frac{\Delta^k f_0}{k! h^k} t(t-1) ... (t-k+1) h^k$$

$$= \frac{\Delta^{k} f_{0}}{k!} \prod_{j=0}^{k-1} (t - j)$$

### 牛顿向前插值公式:

$$N_n(x_0 + th) = f_0 + \sum_{k=1}^n \frac{\Delta^k f_0}{k!} \prod_{j=0}^{k-1} (t - j)$$



#### 牛顿向前插值余项:

$$R_n(x_0 + th) = \frac{f^{(n+1)}(\xi)}{(n+1)!}t(t-1)...(t-n)h^{n+1}$$

差分代替导数的余项:  $\Delta^k f_0 = h^k f^{(k)}(\xi)$ 

$$\Delta^k f_0 = h^k f^{(k)}(\xi)$$

$$R_n(x_0 + th) = \frac{\Delta^{n+1} f_0}{(n+1)!} t(t-1)...(t-n)$$

设 
$$x_{n-k} = x_n - kh$$
  $(k = 0,1,...,n)$   $x = x_n + th$   $(t < 0)$  则  $x - x_{n-k} = (t + k)h$ 

#### 牛顿向后插值公式:

$$N_n(x_0 + th) = f_n + \sum_{k=1}^n \frac{\nabla^k f_n}{k!} \prod_{j=0}^{k-1} (t+j)$$

#### 牛顿向后插值余项:

$$R_n(x_n + th) = \frac{f^{(n+1)}(\xi)}{(n+1)!}t(t+1)...(t+n)h^{n+1}$$

$$R_n(x_n + th) = \frac{\nabla^{n+1} f_n}{(n+1)!} t(t+1)...(t+n)$$

【例 5.6】 给定  $f(x) = \cos x$  的函数表如下:

k	0	1	2	3	4	5	6
$x_k$	0.0	0.1	0.2	0.3	0.4	0.5	0.6
$f(x_k)$	1,0000	0.99500	0. 98007	0.95534	0.92106	0.87758	0.82534

用 Newton 插值法计算 cos 0.048 及 cos 0.566 的近似值,并估计误差。

$f(x_k)$	$\Delta f_k$	$\Delta^2 f_k$	$\Delta^3 f_k$	$\Delta^4 f_k$	$\Delta^5 f_k$	$\Delta^6 f_k$
1.000						
0.99500	-0.00500					
0.98007	-0.01493	-0,00993				
0.95534	-0.02473	-0.00980	0.00013			
0.92106	-0.03428	-0.00955	0.00025	0.00012		
0.87758	-0.04348	-0.00920	0.00035	0.00010	-0.00002	0.00001
0.82534	-0.05224	-0.00876	0.00044	0.00009	-0.00001	44

$$h=0.1 \stackrel{\omega}{=} x=0.048 \text{ ft}, t = \frac{x-x_0}{h} = 0.48$$

$$N_4(x_0+th) = f_0 + \Delta f_0 t + \frac{\Delta^2 f_0}{2!} t(t-1) + \frac{\Delta^3 f_0}{3!} t(t-1)(t-2) + \frac{\Delta^4 f_0}{4!} t(t-1)(t-2)(t-3) =$$

$$f_0 + t \left( \Delta f_0 + (t-1) \left( \frac{\Delta^2 f_0}{2!} + (t-2) \left( \frac{\Delta^3 f_0}{3!} + (t-3) \left( \frac{\Delta^4 f_0}{4!} \right) \right) \right)$$

$$= 1.0000 + 0.48 \left( -0.00500 - 0.52 \left( \frac{-0.00993}{2} - 1.52 \left( \frac{0.00013}{6} - 2.53 \frac{(0.00012)}{24} \right) \right) \right) = 0.99884 \approx \cos 0.048$$

$$|R_4(0.048)| \leqslant \left| \left| \frac{M_5}{5!} t(t-1)(t-2)(t-3)(t-4) \right| \right| h^5 = 1.5845 \times 10^{-7}$$

$$M_5 = |\sin 0.6| = 0.565$$

## § 5.5 埃尔米特(Hermite)插值

构造插值多项式H(x),不仅要求在某些节点上 函数值相等,还要求一阶导数甚至高阶导数值相等。

寻找一个次数<=N-1的多项式H(x),满足:

$$f(x_i) = H(x_i) \quad (i = 0,1,...,2)$$
$$f'(x_i) = H'(x_i)$$
$$f^{(m_i)}(x_i) = H^{(m_i)}(x_i)$$

当只有一个节点时,为m<sub>1</sub>次泰勒多项式:

$$H(x) = f(x_1) + f'(x_1)(x - x_1) + \frac{f''(x_1)}{2!}(x - x_1)^2 + \dots + \frac{f^{(m_1)}(x_1)}{m_1!}(x - x_1)^{m_1}$$

余项:

$$R(x) = f(x) - H(x) = \frac{f^{(m_1+1)}(\xi)}{(m_1+1)!} (x - x_1)^{m_1+1}$$

# 求埃尔米特多项式的待定常数步骤:

- (1) 确定多项式次数为(条件数减1);
- (2)利用k个函数值作k-1次拉格朗日插值多项式, 后面添加一个或几个的(x-x<sub>i</sub>)乘积项,项前设一些特定 常数,使该假设不影响k-1次拉格朗日插值多项式在节 点上的取值,又恰能符合埃尔米特多项式的总次数, 并使**待定常数**个数恰为给定**导数个数**。
  - (3) 用导数条件确定步骤2中设定的待定常数。

【例 5.8】 设  $f(x) = x^3$ ,已知 x=0,1,2 的某些函数值和导数值,在以下不同已知条件下,求埃尔米特插值多项式。

(1) 已知 
$$f(0), f(1), f(2), f'(1)$$
;

(2) 已知 
$$f(0), f(1), f'(0), f'(1)$$
;

(3) 已知 
$$f(\mathbf{1}), f'(1), f''(1)$$
;

(4) 已知 
$$f(0), f(1), f'(1), f''(1)$$
。

0	1	2
0	1	8
0	3	12
0	6	12
	0	0 1 0 3

(1) 已知 f(0), f(1), f(2), f'(1),则埃尔米特插值多项式必 3 次的

$$H_3(x) = L_2(x) + Ax(x-1)(x-2) =$$
  
 $3x^2 - 2x + Ax(x-1)(x-2)$ 

$$H_3'(1) = 4 - A = 3 \Rightarrow A = 1$$

$$H_3(x) = 3x^2 - 2x + x(x-1)(x-2) = x^3$$

(2) 已知 f(0), f(1), f'(0), f'(1), 埃尔米特插值多项式也是 3 次的。

$$H_3(x) = L_1(x) + (Ax + B)x(x - 1) =$$
  
 $x + (Ax + B)x(x - 1)$ 

$$H_3'(x) = 1 + Ax(x-1) + (Ax+B)(x-1) + (Ax+B)x$$

$$\begin{cases} H'(0) = -B+1 = 0 \\ H'(1) = A+B+1 = 3 \end{cases} \Rightarrow \begin{cases} A = 1 \\ B = 1 \end{cases}$$

$$H_3(x) = x + (x+1)x(x-1) = x^3$$

(3) 已知 f(♠),f'(1),f"(1),只有 3 个条件,应该是二次插值。

$$H_2(x) = f(1) + (Ax + B)(x - 1) = 1 + (Ax + B)(x - 1)$$

$$H'_{2}(x) = A(x-1) + Ax + B = 2Ax - A + B$$
  
 $H''_{2}(x) = 2A$ 

$$\begin{cases} H_2'(1) = A + B = 3 \\ H_2''(1) = 2A = 6 \end{cases} \Rightarrow \begin{cases} A = 3 \\ B = 0 \end{cases}$$

$$H_2(x) = 1 + (3x+0)(x-1) = 3x^2 - 3x + 1$$

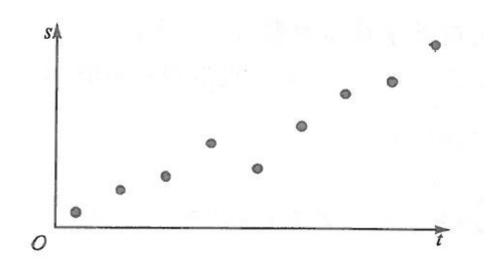
(4) 已知 f(0), f(1), f'(1), f''(1), 应该是三次插值。

$$H_3(x) = L_1(x) + (Ax + B)x(x - 1) = x + (Ax + B)(x - 1)$$

$$\begin{cases} H_3'(1) = 1 + A + B = 3 \\ H_3''(1) = 4A + 2B = 6 \end{cases} \Rightarrow \begin{cases} A = 1 \\ B = 1 \end{cases}$$

$$H_3(x) = x + (x+1)x(x-1) = x^3$$

# § 5.7 数据拟合的最小二乘法



$$S(t) = at + b$$

图 5-11 某物体的直线运动数据在坐标平面

记: 
$$\delta_i = S(t_i) - s_i$$

#### 最小化:

$$\|\delta\|_{2}^{2} = \sum_{i=0}^{m} \omega_{i} \delta_{i}^{2} = \sum_{i=0}^{m} \omega_{i} (S(t_{i}) - s_{i})^{2}$$

### 推广至一般情形:

$$\Phi = span\{\varphi_0(x), \varphi_1(x), ..., \varphi_n(x)\}$$

$$S*(x) = \sum_{j=0}^{n} a_j^* \varphi_j(x) \quad (n \le m)$$

#### 满足:

$$\|\delta\|_{2}^{2} = \sum_{i=0}^{m} \omega_{i}(S * (x_{i}) - y_{i}) = \min_{S \in \Phi} \sum_{i=0}^{m} \omega_{i}(S(x_{i}) - y_{i})^{2}$$

数据拟合的最小二乘法。

### § 5.7.1 法方程组

记:

$$\Psi(a_0, a_1, ..., a_n) = \sum_{i=0}^{m} \omega_i (S(x_i) - y_i)^2 = \sum_{i=0}^{m} \omega_i (\sum_{j=0}^{n} a_j \varphi_j(x_i) - y_i)^2$$

$$\frac{\partial \Psi}{\partial a_k} = 0 (k = 0, 1, ..., n)$$

得: 
$$\sum_{i=0}^{m} \omega_i (\sum_{j=0}^{n} a_j \varphi_j(x_i) - y_i) \varphi_k(x_i) = 0$$

$$\exists \mathbf{p}: \qquad \sum_{j=0}^n \left( \sum_{i=0}^m \omega_i \varphi_j(x_i) \varphi_k(x_i) \right) a_j = \sum_{i=0}^m \omega_i y_i \varphi_k(x_i)$$

#### 定义内积:

$$(\varphi_j, \varphi_k) = \sum_{i=0}^m \omega_i \varphi_j(x_i) \varphi_k(x_i) \quad (f, \varphi_k) = \sum_{i=0}^m \omega_i y_i \varphi_k(x_i)$$

$$\sum_{j=0}^{m} (\varphi_j, \varphi_k) a_j = (f, \varphi_k) \quad (k = 0, 1, ..., n)$$

#### 称为函数系在离散点上的法方程

$$\begin{pmatrix}
(\varphi_0, \varphi_0) & (\varphi_0, \varphi_1) & \dots & (\varphi_0, \varphi_n) \\
(\varphi_1, \varphi_0) & (\varphi_1, \varphi_1) & \dots & (\varphi_1, \varphi_n) \\
\vdots & \vdots & & \ddots & \vdots \\
(\varphi_n, \varphi_0) & (\varphi_n, \varphi_1) & \dots & (\varphi_n, \varphi_n)
\end{pmatrix} \begin{pmatrix}
a_0 \\
a_1 \\
\vdots \\
a_n
\end{pmatrix} = \begin{pmatrix}
(f, \varphi_0) \\
(f, \varphi_1) \\
\vdots \\
(f, \varphi_n)
\end{pmatrix}$$

由基函数组成的Gram行列式,存在唯一解a\*。

记: 
$$S*(x) = \sum_{j=0}^{n} a_j^* \varphi_j(x)$$

可证明:

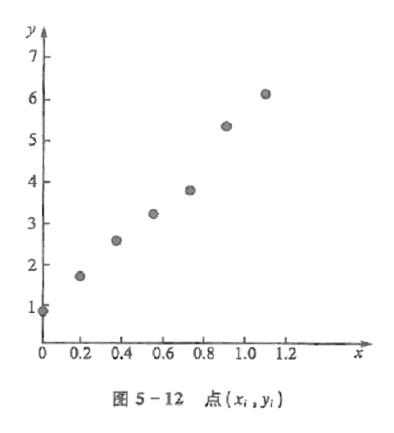
$$\sum_{j=0}^{m} \omega_{i} (S * (x_{i}) - y_{i})^{2} \leq \sum_{j=0}^{m} \omega_{i} (S(x_{i}) - y_{i})^{2}$$

平方误差可表示为:

$$\|\delta\|_{2}^{2} = |(f, f) - (S^{*}, f)| = \left| \sum_{i=0}^{m} \omega_{i} y_{i}^{2} - \sum_{i=0}^{m} a_{k}^{*}(\varphi_{k}, f) \right|$$

# 【例 5.8】 求拟合下列数据的最小二乘解。

i	0	1	2	3	4	5	6
$x_{\rm i}$	0.0	0, 2	0.4	0.6	0.8	1.0	1.2
Уi	0.9	1. 9	2. 8	3. 3	4.0	5. 7	6.5



### 选用线性函数:

$$p_1(x) = a_0 + a_1 x$$

$$n = 1, m = 6, \omega_{i} \equiv 1 \qquad (\varphi_{0}, \varphi_{1}) = (\varphi_{1}, \varphi_{0}) = \sum_{i=0}^{6} \omega_{i} x_{i} = 4.2$$

$$(\varphi_{0}, \varphi_{0}) = \sum_{i=0}^{6} \omega_{i} = 7 \qquad (\varphi_{1}, \varphi_{1}) = \sum_{i=0}^{6} \omega_{i} x_{i}^{2} = 3.64$$

$$(f, \varphi_{0}) = \sum_{i=0}^{6} \omega_{i} y_{i} = 25.1$$

$$(f, \varphi_{1}) = \sum_{i=0}^{6} \omega_{i} x_{i} y_{i} = 20.18$$

$$\begin{pmatrix} 7 & 4.2 \\ 4.2 & 3.64 \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \end{pmatrix} = \begin{pmatrix} 25.1 \\ 20.18 \end{pmatrix}$$

$$a_0 = 0.843, \quad a_1 = 4.57$$

$$p_1(x) = 0.843 + 4.57x$$

#### 【例 5.9】 求拟合下列数据的最小二乘解。

$x_i$	0.24	0.65	0.95	1. 24	1.73	2.01	2. 23	2.52	2.77	2. 99
yi	0.23	-0.26	-1.10	-0.45	0. 27	0.10	-0.29	0.24	0.56	1.00
$\omega_i$	1	1	0.8	0.9	1	1	1	1	0.9	0.9

所求函数可用  $y = \cos x$ ,  $y = \ln x$  和  $y = e^x$  的线性组合表示  $\varphi_0(x) = \ln x$ ,  $\varphi_1(x) = \cos x$ ,  $\varphi_2(x) = e^x$ 

$$\begin{bmatrix} 6.5651 & -5.1453 & 59.407 \\ -5.1453 & 4.8457 & -45.969 \\ 59.407 & -45.969 & 934.96 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 1.4481 \\ -2.0891 \\ 24.619 \end{bmatrix}$$

$$a = -0.99480$$
  $b = -1.1957$   $c = 0.030752$ 

 $S(x) = -0.99480 \ln x - 1.1957 \cos x + 0.030752 e^{x}$ 

多项式拟合:  $P_n(x) = \sum_{i=0}^n a_i x^i$ 

基底 
$$\varphi_j(x) = x^j (j = 0, 1, \dots, n)$$
,从而 
$$(\varphi_j, \varphi_k) = \sum_{i=0}^m \omega_i x_i^{j+k} \qquad (j, k = 0, 1, \dots, n)$$
 
$$(f, \varphi_k) = \sum_{i=0}^m \omega_i x_i^k y_i \qquad (k = 0, 1, \dots, n)$$

$$\begin{bmatrix} \sum_{i=0}^{m} \omega_{i} & \sum_{i=0}^{m} \omega_{i} x_{i} & \cdots & \sum_{i=0}^{m} \omega_{i} x_{i}^{n} \\ \sum_{i=0}^{m} \omega_{i} x_{i} & \sum_{i=0}^{m} \omega_{i} x_{i}^{2} & \cdots & \sum_{i=0}^{m} \omega_{i} x_{i}^{n+1} \\ \vdots & \vdots & & \vdots \\ \sum_{i=0}^{m} \omega_{i} x_{i}^{n} & \sum_{i=0}^{m} \omega_{i} x_{i}^{n+1} & \cdots & \sum_{i=0}^{m} \omega_{i} x_{i}^{2n} \end{bmatrix} \begin{bmatrix} a_{0} \\ a_{1} \\ \vdots \\ a_{n} \end{bmatrix} = \begin{bmatrix} \sum_{i=0}^{m} \omega_{i} y_{i} \\ \sum_{i=0}^{m} \omega_{i} x_{i} y_{i} \\ \vdots \\ \sum_{i=0}^{m} \omega_{i} x_{i}^{n} y_{i} \end{bmatrix}$$

**例5.10** 给定数据(x<sub>i</sub>,f<sub>i</sub>), i=0,1,2,4 选择适当模型求最小二乘拟合函数。

i	$\mathbf{x_i}$	$f_i$	lnf <sub>i</sub>	X <sup>2</sup> i	$x_i Y_i$	$\Phi^*(\mathbf{x})$
0	1.00	5. 10	1.529	1.000	1.629	5.09
1	1.25	5. 79	1.756	1.5625	2. 195	5. 78
2	1.50	6. 53	1.876	2. 2500	2.814	6. 56
3	1.75	7.45	2.008	3.0625	3. 514	7.44
4	2.00	8.46	2. 135	4.000	4. 270	8.44

选模型:  $y = ae^{bx}$ ,取对数: $\ln y = \ln a + bx$ 

$$(Y, \varphi_0) = \sum_{i=0}^4 Y_i = 9.404, (Y, \varphi_1) = \sum_{i=0}^4 Y_i x_i = 14.422$$

#### 法方程:

$$\begin{cases}
5A + 7.50b = 9.404 \\
7.50A + 11.875b = 14.422
\end{cases}$$

#### 解得:

$$A = 1.122, b = 0.5056, a = e^{A} = 3.071$$

$$y = 3.071e^{0.5056x} = \varphi^*(x)$$

#### 【例5.11】给定数据:

X	1.0	1.4	1.8	2. 2	2.6
У	0.931	0.473	0. 297	0. 224	0. 168

求形如 
$$y = \frac{1}{a + bx}$$
 的拟合函数。  
令  $Y = \frac{1}{a + bx}$  则拟合函数为:  $Y = a + bx$ 

i	1	2	3	4	5
${\tt x_i}$	1.0	1.4	1.8	2. 2	2.6
Yi	1.074	2. 114	3. 367	4. 464	5. 592

$$\begin{bmatrix} s_0 & s_1 \\ s_1 & s_2 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} T_0 \\ T_1 \end{bmatrix}$$

$$s_0 = 5$$
,  $s_1 = \sum_{i=0}^{4} x_i = 9$ ,  $s_2 = \sum_{i=0}^{4} x_i^2 = 17.8$   
 $T_0 = \sum_{i=0}^{4} Y_i = 16.971$ ,  $T_1 = \sum_{i=0}^{4} x_i Y_i = 35.3902$ 

$$\begin{bmatrix} 5 & 9 \\ 9 & 17.8 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 16.971 \\ 35.3902 \end{bmatrix}$$

$$a = -2.0535$$
,  $b = 3.0265$ 

$$y = \frac{1}{-2.0535 + 3.0265x}$$

# 本章小结

- 插值法概述
  - 插值多项式存在的唯一性
- 拉格朗日插值法

$$y(x) = \sum_{j=0}^{n} f(x_j) l_j(x)$$

$$l_{j}(x) = \frac{(x - x_{0})(x - x_{1})...(x - x_{j-1})(x - x_{j+1})...(x - x_{n})}{(x_{j} - x_{0})(x_{j} - x_{1})...(x_{j} - x_{j-1})(x_{j} - x_{j+1})...(x_{j} - x_{n})}$$

### 牛顿插值法

$$f[x_i, x_k] = \frac{f_k - f_i}{x_k - x_i} (k \neq i)$$

$$f[x_0, x_1, ..., x_{k-1}, x_k] = \frac{f[x_0, x_1, ..., x_{k-2}, x_k] - f[x_0, x_1, ..., x_{k-1}]}{x_k - x_{k-1}}$$

$$f(x) = f(x_0) + \sum_{k=1}^{n} f[x_0, x_1, ..., x_k] \prod_{j=0}^{k-1} (x - x_j)$$

$$N_n(x_0 + th) = f_0 + \sum_{k=1}^n \frac{\Delta^k f_0}{k!} \prod_{j=0}^{k-1} (t - j)$$

$$N_n(x_0 + th) = f_n + \sum_{k=1}^n \frac{\nabla^k f_n}{k!} \prod_{j=0}^{k-1} (t+j)$$

### • 数据拟合的最小二乘法

$$(\varphi_j, \varphi_k) = \sum_{i=0}^m \omega_i \varphi_j(x_i) \varphi_k(x_i) \quad (f, \varphi_k) = \sum_{i=0}^m \omega_i y_i \varphi_k(x_i)$$

$$\begin{pmatrix}
(\varphi_0, \varphi_0) & (\varphi_0, \varphi_1) & \dots & (\varphi_0, \varphi_n) \\
(\varphi_1, \varphi_0) & (\varphi_1, \varphi_1) & \dots & (\varphi_1, \varphi_n) \\
\vdots & \vdots & \ddots & \vdots \\
(\varphi_n, \varphi_0) & (\varphi_n, \varphi_1) & \dots & (\varphi_n, \varphi_n)
\end{pmatrix}
\begin{pmatrix}
a_0 \\
a_1 \\
\vdots \\
a_n
\end{pmatrix} = \begin{pmatrix}
(f, \varphi_0) \\
(f, \varphi_1) \\
\vdots \\
(f, \varphi_n)
\end{pmatrix}$$

# 课后作业

第五章习题的1、2、3、4、8、9、14(1)。