# Chapter 4-2. 连续时间傅立叶变换的性质



学文定 
$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) e^{j\omega t} d\omega = F^{-1} \{X(j\omega)\}$$

$$X(j\omega) = \int_{-\infty}^{+\infty} x(t)e^{-j\omega t}dt = F\left\{x(t)\right\} \quad x(t) \stackrel{F}{\longleftrightarrow} X(j\omega)$$

→ 奇偶性 偶信号的频谱为偶信号,奇信号的频谱为奇信号。

偶函数 
$$x(t) \stackrel{FT}{\longleftrightarrow} X(j\omega), x(-t) \stackrel{FT}{\longleftrightarrow} X(-j\omega)$$

奇函数 
$$x(t) \stackrel{FT}{\longleftrightarrow} X(j\omega), x(-t) \stackrel{FT}{\longleftrightarrow} -X(-j\omega)$$

类性 
$$x(t) \stackrel{\mathfrak{F}}{\leftrightarrow} X(j\omega) y(t) \stackrel{\mathfrak{F}}{\leftrightarrow} Y(j\omega) \Longrightarrow ax(t) + by(t) \stackrel{\mathfrak{F}}{\leftrightarrow} aX(j\omega) + bY(j\omega)$$

一 时移性质 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(j\omega)$$
  $x(t-t_0) \stackrel{\mathfrak{F}}{\longleftrightarrow} e^{-j\omega t_0} X(j\omega)$ 

**一**斯瓦尔定理 
$$\int_{-\infty}^{\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |X(j\omega)|^2 d\omega$$
  $\frac{|X(j\omega)|^2}{5\pi}$  频谱密度

#### 基本题4.6(1)





><mark>例题</mark> 计算x(t)的傅里叶变换

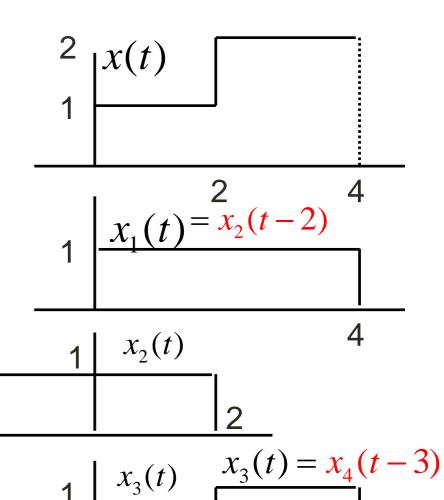
$$x(t) = \begin{cases} 1, |t| < T_1 \\ 0, otherwise \end{cases}$$
  $X(j\omega) = \frac{2\sin(\omega T_1)}{\omega}$ 

$$X_2(t)$$
:  $T_2 = 2$   $X_2(j\omega) = \frac{2\sin(2\omega)}{\omega}$ 

$$X_1(t): X_1(j\omega) = e^{-j2\omega} X_2(j\omega) = 2e^{-j2\omega} \frac{\sin(2\omega)}{\omega}$$

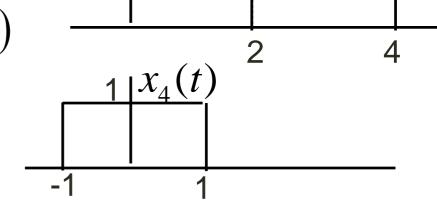
$$x_4(t)$$
:  $T_4 = 1$   $X_2(j\omega) = \frac{2\sin(\omega)}{\omega}$ 

$$x_3(t)$$
:  $X_3(j\omega) = e^{-j3\omega} X_4(j\omega) = 2e^{-j3\omega} \frac{\sin(\omega)}{\omega}$ 



$$x(t) = x_1(t) + x_3(t)$$
  $(j\omega) = X_1(j\omega) + X_3(j\omega)$ 

$$=\frac{2e^{-j2\omega}}{\omega}(\sin 2\omega + e^{-j\omega}\sin \omega)$$





微分 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(j\omega)$$
  $\longrightarrow$   $\frac{dx(t)}{dt} \stackrel{\mathfrak{F}}{\longleftrightarrow} j\omega X(j\omega)$ 

 积分 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(j\omega)$$
  $\longrightarrow \int_{-\infty}^{t} x(\tau) d\tau \stackrel{\mathfrak{F}}{\longleftrightarrow} \frac{1}{j\omega} X(j\omega) + \pi X(0) \delta(\omega)$ 

例4.11 已知  $g(t) = \delta(t)$   $G(j\omega) = 1$  求 $\mathbf{x}(t) = \mathbf{u}(t)$ 的傅里叶变换

$$x(t) = u(t) = \int_{-\infty}^{t} \delta(\tau) d\tau \xrightarrow{G(j\omega) = 1} X(j\omega) = \frac{G(j\omega)}{j\omega} + \pi G(0)\delta(\omega)$$
$$X(j\omega) = \frac{1}{j\omega} + \pi \delta(\omega)$$

已知**x(t)=u(t)**的傅里叶变换为  $X(j\omega) = \frac{1}{j\omega} + \pi \delta(\omega)$  计算 $g(t) = \delta(t)$ 的傅里叶变换

$$\delta(t) = \frac{du(t)}{dt} \longrightarrow G(j\omega) = j\omega X(j\omega) \longrightarrow G(j\omega) = 1 + j\omega\pi\delta(\omega)$$
$$G(j\omega) = 1 + 0 \bullet 1 = 1$$



微分 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(j\omega) \longrightarrow \frac{dx(t)}{dt} \stackrel{\mathfrak{F}}{\longleftrightarrow} j\omega X(j\omega)$$

$$\longrightarrow \chi(t) \xrightarrow{\mathcal{F}} X(j\omega) \longrightarrow \int_{-\infty}^{t} X(\tau) d\tau \xrightarrow{\mathcal{F}} \frac{1}{j\omega} X(j\omega) + \pi X(0) \delta(\omega)$$

 $\sim$  例4.12 用积分性质求x(t)的傅里叶变换  $X(j\omega)$ 

$$G(j\omega) = \frac{2\sin(\omega T_1)}{\omega} = \frac{2\sin\omega}{\omega} - e^{j\omega} - e^{-j\omega} = \frac{2\sin\omega}{\omega} - 2\cos\omega \xrightarrow{-1} \xrightarrow{\uparrow} \xrightarrow{t} t$$

$$X(j\omega) = \frac{G(j\omega)}{j\omega} + \pi G(0)\delta(\omega) \xrightarrow{G(0) = 0} X(j\omega) = \frac{2\sin\omega}{j\omega^2} - \frac{2\cos\omega}{j\omega}$$



方波: 
$$\frac{2\sin(\omega T_1)}{}$$



微分 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(j\omega)$$
  $\longrightarrow$   $\frac{dx(t)}{dt} \stackrel{\mathfrak{F}}{\longleftrightarrow} j\omega X(j\omega)$ 

$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(j\omega)$$

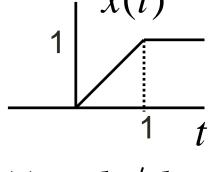
$$\longrightarrow \int_{-\infty}^{t} x(\tau) d\tau \stackrel{\mathfrak{F}}{\longleftrightarrow} \frac{1}{i\omega}$$



用积分性质求x(t)的傅里叶变换

$$x_1(t) = \frac{dx(t)}{dt} = \begin{cases} 1 & 0 \le t \le 1 \\ 0 & otherwise \end{cases} \qquad x_1(t) = x_2(t - 0.5)$$

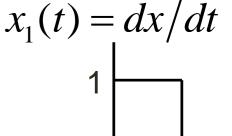
$$x_1(t) = x_2(t - 0.5)$$



$$X_2(j\omega) = \frac{2\sin 0.5\omega}{\omega}$$

$$x(t-t_0) \stackrel{\mathfrak{F}}{\longleftrightarrow} e^{-j\omega t_0} X(j\omega)$$

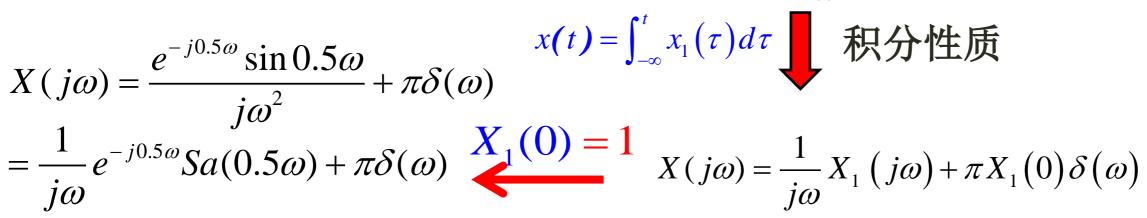
$$X_{2}(j\omega) = \frac{2\sin 0.5\omega}{\omega} \xrightarrow{x(t-t_{0}) \stackrel{\mathfrak{F}}{\leftrightarrow} e^{-j\omega t_{0}}} X(j\omega) = \frac{X_{1}(j\omega) = e^{-j\omega t_{0}} X_{2}(j\omega)}{= 2e^{-j0.5\omega} \frac{\sin 0.5\omega}{\omega}}$$

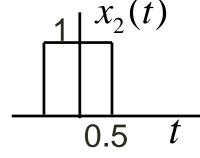


$$X(j\omega) = \frac{e^{-j0.5\omega} \sin 0.5\omega}{i\omega^2} + \pi \delta(\omega)$$

$$\frac{1}{i\omega}e^{-j0.5\omega}Sa(0.5\omega) + \pi\delta(\omega) \quad X_1(0) =$$

$$x(t) = \int_{-\infty}^{t} x_1(\tau) d\tau$$
 积分性质





# 时间与频率的尺度变换



表达式 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(jw)$$
  $\longrightarrow x(at) \stackrel{\operatorname{F}}{\longleftrightarrow} \frac{1}{|a|} X\left(\frac{jw}{a}\right)$  a是实常数

$$x(-t) \leftrightarrow X(-j\omega)$$
 时域扩展对应频域压缩,反之亦然



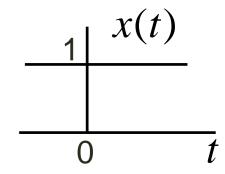
一 
$$\mathbf{y}$$
 水  $\mathbf{x}(t)$  的 傅里叶变换  $x(t)=1$ 

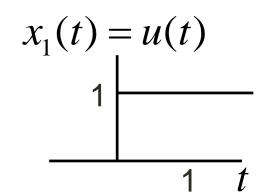
$$X_1(t) = u(t)$$
  $\longrightarrow X_1(j\omega) = \frac{1}{j\omega} + \pi\delta(\omega)$ 

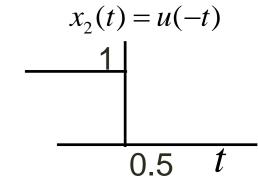
$$X_2(t) = u(-t) \longrightarrow X_2(j\omega) = X_1(-j\omega) = -\frac{1}{j\omega} + \pi\delta(\omega)$$

$$x(t) = 1 = x_1(t) + x_2(t) \longrightarrow X(j\omega) = X_2(j\omega) + X_1(j\omega)$$
$$= 2\pi\delta(\omega)$$

$$x(t) = a$$
 a为非**0**实数  $\Longrightarrow$  =  $2\pi a \delta(\omega)$ 







# 时间反转与频域微分



一时间反转 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(jw) \longrightarrow x(-t) \longleftrightarrow X(-j\omega)$$

$$x(t)$$
为偶函数  $x(t)=x(-t) \rightarrow X(j\omega) = X(-j\omega)$ 

$$x(t)$$
为奇函数  $x(t)=-x(-t) \rightarrow X(j\omega)=-X(-j\omega)$ 

→ 频域微分 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(jw)$$
 →  $tx(t) \longleftrightarrow j \frac{dX(j\omega)}{d\omega}$ 

$$-jtx(t) \longleftrightarrow \frac{dX(j\omega)}{d\omega}$$

基本题4-6(ac) 4.15

# 时间反转与频域微分



时间反转 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(j\omega) \longrightarrow X(-t) \longleftrightarrow X(-j\omega)$$

- 频域微分 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(jw)$$
  $\longrightarrow tx(t) \leftrightarrow j \frac{dX(j\omega)}{d\omega} - jtx(t) \leftrightarrow \frac{dX(j\omega)}{d\omega}$ 

微分 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(j\omega) \longrightarrow \frac{dx(t)}{dt} \stackrel{\mathfrak{F}}{\longleftrightarrow} j\omega X(j\omega)$$

$$x_1(t)=x(1-t)+x(-1-t)$$

$$x(t+1) \leftrightarrow e^{j\omega} X(j\omega)$$

$$x(-t+1) \longleftrightarrow e^{-j\omega} X(-j\omega)$$

$$x(t-1) \leftrightarrow e^{-j\omega} X(j\omega)$$

$$x(-t-1) \leftrightarrow e^{j\omega}X(-j\omega)$$

$$x_{2}(t) = \frac{d^{2}x(t-1)}{dt}$$

$$x(t-1) \leftrightarrow e^{-j\omega}X(j\omega)$$

$$\frac{dx(t-1)}{dt} \longleftrightarrow j\omega e^{-j\omega} X(j\omega)$$

$$\frac{d^2x(t-1)}{dt} \leftrightarrow (j\omega)^2 e^{-j\omega}X(j\omega)$$

# 共轭及共轭对称性



$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(j\omega) \longrightarrow x^*(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X^*(-j\omega)$$

<del>其</del>轭对称性

若x(t)为实数,则  $X(-j\omega) = X^*(j\omega)$  or  $X(j\omega) = X^*(-j\omega)$ 

$$\operatorname{Re}(X(j\omega)) = \operatorname{Re}(X(-j\omega))$$
 — 偶函数  $\operatorname{Im}(X(j\omega)) = -\operatorname{Im}(X(-j\omega))$  — 奇函数

 $|X(j\omega)|$ 是 $\omega$ 的偶函数, $X(j\omega)$ 是 $\omega$ 的奇函数 若x(t)为实、偶函数, $X(j\omega)$ 也为实偶函数 若x(t)为实、奇函数, $X(j\omega)$ 也为纯虚奇函数

说明: 计算实信号的傅里叶变换时,可以仅计算正频率,因为负频率可以利用正频率导出。



$$\begin{cases} x(t) = x_e(t) + x_o(t) \\ x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(j\omega) \end{cases} \qquad \qquad \qquad \qquad \begin{cases} x_e(t) \leftrightarrow \operatorname{Re}(X(j\omega)) \\ x_o(t) \leftrightarrow j \operatorname{Im}(X(j\omega)) \end{cases}$$

# 共轭及共轭对称性





共轭性 
$$x(t) \stackrel{\mathcal{F}}{\longleftrightarrow} X(j\omega)$$
  $\longrightarrow$   $x^*(t) \stackrel{\mathcal{F}}{\longleftrightarrow} X^*(-j\omega)$ 

- 字信号共轭性 若**x(t)**为实数,则 $X(-j\omega) = X^*(j\omega)$  or  $X(j\omega) = X^*(-j\omega)$

 $X(j\omega) = -X^*(-j\omega)$ 

$$\Re(X(j\omega)) = -\Re(X(-j\omega))$$
 一 奇函数  $\Im(X(j\omega)) = -\Im(X(-j\omega))$  一 偶函数  $|X(j\omega)| = \Im(X(-j\omega))$  一 偶函数  $|X(j\omega)| = \Im(X(j\omega))$  是  $\Im(X(j\omega))$  是  $\Im(X(j\omega))$ 

► 虚信号奇/偶 
$$\begin{cases} x(t) = x_e(t) + x_o(t) \\ x(t) \leftrightarrow X(jw) \end{cases} \qquad \qquad \qquad \begin{cases} x_e(t) \leftrightarrow j \text{Im}(X(j\omega)) \\ x_o(t) \leftrightarrow \text{Re}(X(j\omega)) \end{cases}$$

# 共轭及共轭对称性



共轭性 
$$x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X(jw)$$
  $\longrightarrow$   $x^*(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} X^*(-jw)$ 

若x(t)为纯虚函数,则  $X(-j\omega) = -X^*(j\omega)$   $X(j\omega) = -X^*(-j\omega)$ 

若**x(t)**为实数,则 
$$X(-j\omega) = X^*(j\omega)$$
 or  $X(j\omega) = X^*(-j\omega)$ 

$$X(j\omega) = (\frac{\sin 2\omega}{\omega})e^{j(2\omega + \frac{\pi}{2})}$$
 判断实虚性与奇偶性

$$= \frac{\sin(2\omega)}{\omega} e^{j2\omega} e^{j\frac{\pi}{2}} = j\frac{\sin(2\omega)}{\omega} e^{j2\omega} = -\frac{\sin 2\omega \sin 2\omega}{\omega} + j\frac{\sin 2\omega \cos 2\omega}{\omega}$$

$$X(-j\omega) = (\frac{\sin(-2\omega)}{-\omega})e^{j(-2\omega + \frac{\pi}{2})} = j\frac{\sin(2\omega)}{\omega}e^{-j2\omega} = \frac{\sin(2\omega)\sin(2\omega)}{\omega} + j\frac{\sin(2\omega)\cos(2\omega)}{\omega}$$

$$X(j\omega) \neq -X(-j\omega)$$
  $X(j\omega) \neq X(-j\omega)$  非奇非偶

$$X*(-j\omega) = \frac{\sin(2\omega)\sin(2\omega)}{\omega} - j\frac{\sin(2\omega)\cos(2\omega)}{\omega} \qquad X(j\omega) = -X*(-j\omega)$$
 虚信号



# 表达式

两个信号的卷积等于其傅里叶变换的乘积,即时域的卷积等于频域的乘积。

$$\begin{cases} x(t) \to X(j\omega) \\ h(t) \to H(j\omega) \end{cases} \longrightarrow y(t) = x(t) * h(t) \to Y(j\omega) = X(j\omega)H(j\omega)$$

注意:只有稳定的LTI系统才有频率响应 $H(j\omega)$ 。

# → 系统框图

#### LTI系统时域框图

$$(x(t) * h_1(t)) * h_2(t) = x(t) * (h_1(t) * h_2(t))$$

$$\xrightarrow{x(t)} h_1(t) \longrightarrow h_2(t) \xrightarrow{y(t)}$$

$$\xrightarrow{x(t)} h_2(t) \longrightarrow h_1(t) \xrightarrow{y(t)}$$

$$\xrightarrow{x(t)} h(t) = h_1(t) * h_2(t) \xrightarrow{y(t)}$$

$$\xrightarrow{x(t)} h(t) = h_2(t) * h_1(t) \xrightarrow{y(t)}$$

#### LTI系统频域框图



表达式 
$$y(t) = h(t) * x(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} Y(j\omega) = H(j\omega)X(j\omega)$$

例4.15 单位冲激信号

已知 
$$h(t) = \delta(t - t_0) \ x(t) \leftrightarrow X(j\omega)$$
 求  $Y(j\omega) = ?$  分析公式 
$$H(j\omega) = e^{-j\omega t_0} \xrightarrow{\text{卷积公式}} Y(j\omega) = H(j\omega)X(j\omega) = e^{-j\omega t_0}X(j\omega)$$

**──例4.16** differentiator微分器

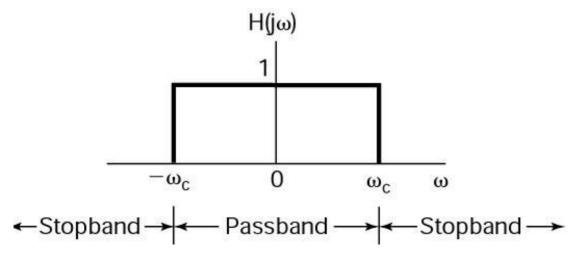
已知 
$$y(t) = \frac{dx(t)}{dt}$$
 求  $H(j\omega) = ?$ 

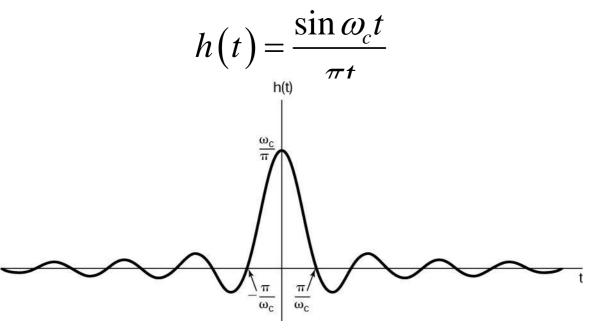
$$y(t) = \frac{dx(t)}{dt}$$
 微分性质  $Y(j\omega) = j\omega X(j\omega)$  卷积定理  $H(j\omega) = j\omega$ 



# 一例4.18 理想低通滤波器

$$H(j\omega) = \begin{cases} 1, |\omega| < \omega_c \\ 0, |\omega| > \omega_c \end{cases}$$



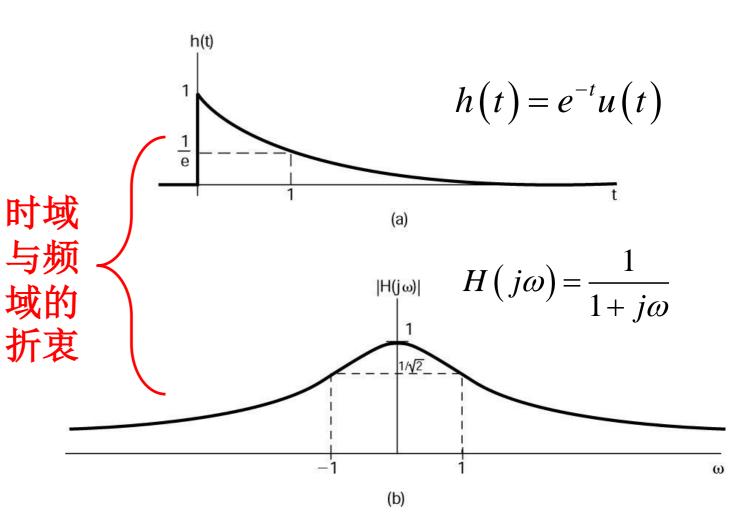


优点: 完美的频率选择性;

缺点:

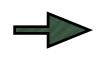
- (1)h(t<0)非0,是非因果的。
- (2)在时域中存在着振荡;
- (3)难以实现。

#### 简单RC电路实现的实用低通滤波器









### 例4. 20

求理想低通滤波器对sinc函数的响应。

$$x(t) = \frac{\sin \omega_i t}{\pi t}$$

$$h(t) = \frac{\sin \omega_c t}{\pi t}$$

$$y(t) = h(t) * x(t) = ?$$

两个sinc函数的卷积仍然是sinc函数

$$x(t) = \frac{\sin \omega_i t}{\pi t} \longrightarrow X(j\omega) = \begin{cases} 1, |\omega| \le \omega_i \\ 0, |\omega| > \omega_i \end{cases}$$

$$h(t) = \frac{\sin w_c t}{\pi t} \longrightarrow H(j\omega) = \begin{cases} 1, |\omega| \le \omega_c \\ 0, |\omega| > \omega_c \end{cases}$$

$$Y(j\omega) = \begin{cases} 1, |\omega| \le \omega_0 \\ 0, |\omega| > \omega_0 \end{cases}, \omega_0 = \min(\omega_i, \omega_c)$$



$$y(t) = \begin{cases} \frac{sin\omega_{c}t}{\pi t}, \omega_{c} \leq \omega_{i} \\ \frac{sin\omega_{i}t}{\pi t}, \omega_{c} \geq \omega_{i} \end{cases}$$

#### 基本题4-13





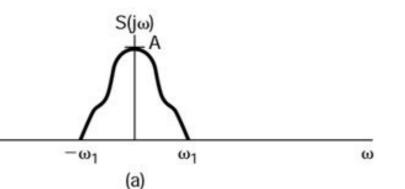
表达式 
$$r(t) = s(t)p(t) \stackrel{\mathfrak{F}}{\longleftrightarrow} R(j\omega) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} S(j\theta)P(j(\omega-\theta))d\theta$$

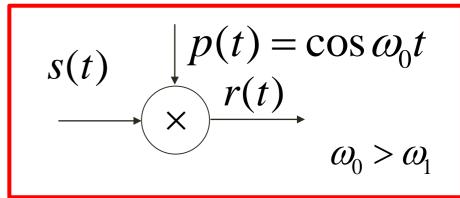
时域内的相乘对应于频域内的卷积。 两个信号相乘也称为幅度调制。

$$=\frac{1}{2\pi}\Big[S(j\omega)*P(j\omega)\Big]$$



#### 重要应用1----正弦幅度调制





#### Example 4.21

信号s(t)被一正 弦信号相乘后, 尽管信号被搬移 到较高频率,但 是信号所包含的 信息却完整的保 留了了下来。

$$p(t) = \cos \omega_0 t$$

$$P(j\omega) = \pi \delta(\omega - \omega_0) + \pi \delta(\omega - \omega_0)$$
(b)

$$R(j\omega) = \frac{1}{2\pi} \left[ S(j\omega) * P(j\omega) \right] \qquad R(j\omega)$$

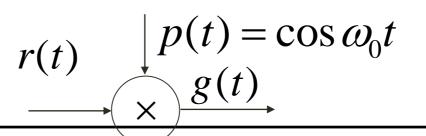
$$A/2 + \cdots$$

$$(-\omega_0 - \omega_1) \quad (-\omega_0 + \omega_1) \qquad (\omega_0 - \omega_1) \quad (\omega_0 + \omega_1)$$

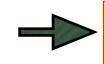
(c)

$$P(j\omega) = \pi\delta(\omega - \omega_0) + \pi\delta(\omega + \omega_0)$$

$$R(j\omega) = \frac{1}{2}S(\omega - \omega_0) + \frac{1}{2}S(\omega + \omega_0)$$







# 例4.22 重要应用2:正弦幅度解调基本思想

$$g(t) = r(t)p(t) \leftrightarrow G(j\omega) = \frac{1}{2\pi}[R(j\omega) \times P(j\omega)]$$

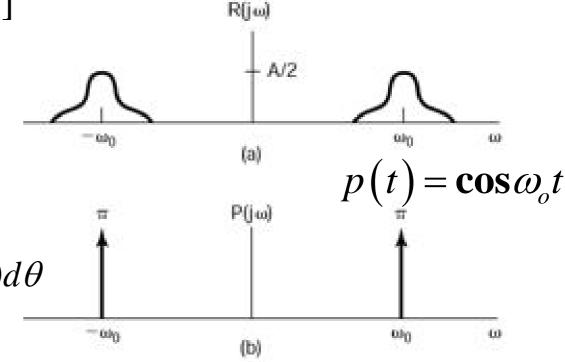
已知r(t)的频谱如右图所示, 计算G(jw)。

$$G(j\omega) = \frac{1}{2\pi} [R(j\omega) \times P(j\omega)]$$

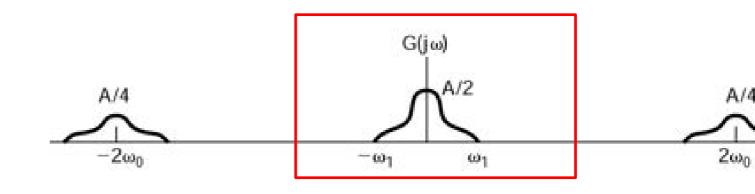
$$=\frac{1}{2\pi}\int_{-\infty}^{\infty}\pi\delta(\theta-\omega_0)R(\omega-\theta)+\pi\delta(\theta+\omega_0)R(\omega-\theta)d\theta$$

$$=\frac{1}{2}(R(\omega-\omega_0)+R(\omega+\omega_0))$$

若对G(jw)进行低通滤波, 再进行幅度加权,则可 以获取g(t)的频谱信息, 进而可以获取g(t)的信息。



$$P(j\omega) = \pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)$$







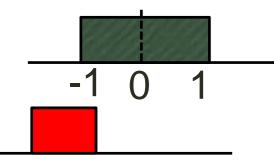
应用3

$$g(t) = r(t)p(t) \leftrightarrow G(j\omega) = \frac{1}{2\pi} [R(j\omega) \times P(j\omega)]$$

计算x(t)的傅里叶变换。

$$x(t) = \frac{\sin t \cdot \sin \frac{t}{2}}{\pi t^2}$$

傅立叶变换:时域复杂信号的乘 法转变成频域的卷积



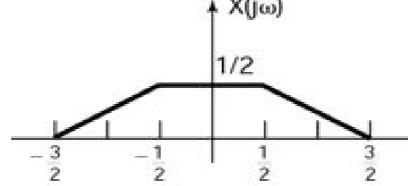
$$x(t) = \pi \left(\frac{\sin t}{\pi t}\right) \left(\frac{\sin\left(\frac{t}{2}\right)}{\pi t}\right)$$

$$X(j\omega) = \frac{1}{2\pi} \pi \mathcal{F}\left(\frac{\sin t}{\pi t}\right) * \mathcal{F}\left(\frac{\sin\left(\frac{t}{2}\right)}{\pi t}\right)$$

因为 
$$F(\frac{\sin(t)}{\pi t}) = \begin{cases} 1, |\omega| < W = 1 \\ 0, |\omega| > W = 1 \end{cases}$$

$$F(\frac{\sin(t/2)}{\pi t}) = \begin{cases} 1, |\omega| < W = \frac{1}{2} \\ 0, |\omega| > W = \frac{1}{2} \end{cases}$$

$$G(j\omega) = \begin{cases} t/2 + 3/4 & -3/2 \le t \le -1/2 \\ 1/2 & -1/2 \le t \le 1/2 \\ -t/2 + 3/4 & 1/2 \le t \le 3/2 \end{cases}$$





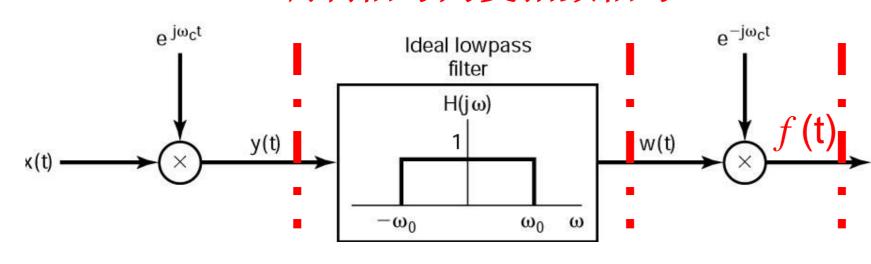


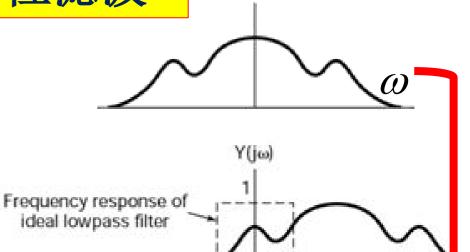


### 具有可变中心频率的频率选择性滤波

应用4

#### 调制信号为复指数信号





 $W(j\omega)$ 

**(1)** 

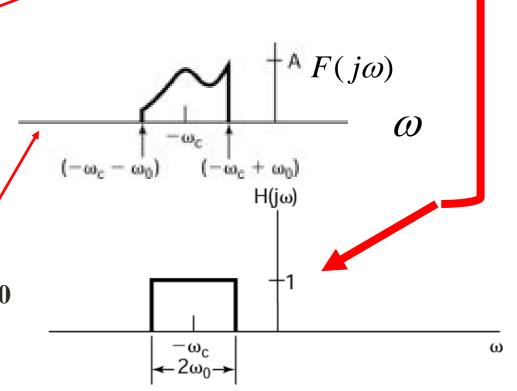
 $X(j\omega)$ 

$$y(t) = e^{j\omega_c t} x(t)$$
 频移性 
$$Y(j\omega) = X(j(\omega - \omega_c))$$

$$w(t) = h(t) * y(t) \longrightarrow W(j\omega) = H(j\omega)Y(j\omega)$$

$$f(t) = e^{-j\omega_c t} w(t) \longrightarrow F(j\omega) = W(j(\omega + \omega_c))$$

整个系统等效于一个中心频率为 $-\omega_c$ ,带宽为 $2\omega_0$ 的理想带通滤波器。



# 由线性系数微分方程表征的系统





## N阶线性常微分方程

**Differential Equation** 

$$\sum_{k=0}^{N} a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^{M} b_k \frac{d^k x(t)}{dt^k}$$



# **傅里叶微分性质求解法** $H(j\omega) = \frac{Y(j\omega)}{X(i\omega)} \longrightarrow h(t)$

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} \longrightarrow h(t)$$

$$\mathcal{F}\left\{\sum_{k=0}^{N} a_k \frac{d^k y(t)}{dt^k}\right\} = \mathcal{F}\left\{\sum_{k=0}^{M} b_k \frac{d^k x(t)}{dt^k}\right\}$$

$$Y(j\omega)\sum_{k=0}^{N}a_{k}(j\omega)^{k} = X(j\omega)\sum_{k=0}^{M}b_{k}(j\omega)^{k} \leftarrow \sum_{k=0}^{N}a_{k}(j\omega)^{k}Y(j\omega) = \sum_{k=0}^{M}b_{k}(j\omega)^{k}X(j\omega)$$

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{\sum_{k=0}^{M} b_{k}(j\omega)^{k}}{\sum_{k=0}^{N} a_{k}(j\omega)^{k}} \longrightarrow H(j\omega) \longrightarrow h(t)$$

# 由线性系数微分方程表征的系统





$$\sum_{k=0}^{N} a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^{M} b_k \frac{d^k x(t)}{dt^k} \qquad H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{\sum_{k=0}^{M} b_k (j\omega)^k}{\sum_{k=0}^{N} a_k (j\omega)^k}$$

已知:一稳定LTI系统有下列方程表征

$$\frac{dy(t)}{dt} + ay(t) = x(t) \quad a > 0$$

求其单位冲击响应。

$$H(j\omega) = \frac{1}{j\omega + a} \longrightarrow h(t) = e^{-at}u(t)$$

# 由线性系数微分方程表征的系统 $\frac{\sum_{b=0}^{M} b_k(j\omega)^k}{M^2}$ 例子 $\sum_{k=0}^{N} a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^{M} b_k \frac{d^k x(t)}{dt^k}$ $H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{\sum_{k=0}^{N} b_k(j\omega)^k}{\sum_{k=0}^{N} a_k(j\omega)^k}$





$$\sum_{k=0}^{N} a_{k} \frac{d^{k} y(t)}{dt^{k}} = \sum_{k=0}^{M} b_{k} \frac{d^{k} x(t)}{dt^{k}}$$

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{\sum_{k=0}^{\infty} a_k(j\omega)}{\sum_{k=0}^{\infty} a_k(j\omega)^k}$$

已知: 一稳定LTI系统有下列方程表征

$$\frac{d^2y(t)}{dt^2} + 4\frac{dy(t)}{dt} + 3y(t) = \frac{dx(t)}{dt} + 2x(t)$$

(1)求其单位冲击响应。 (2)若输入为e-tu(t),求其输出表达式

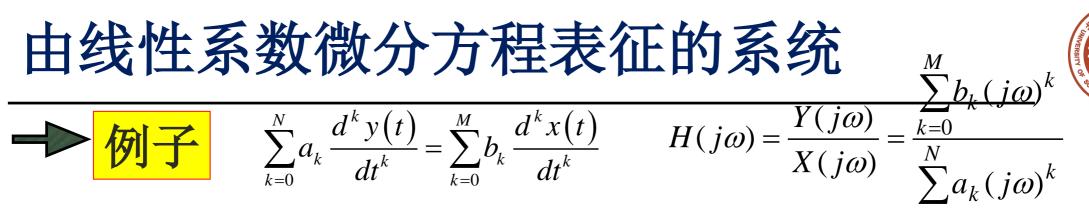
(1) 
$$H(j\omega) = \frac{j\omega + 2}{(j\omega)^2 + 4j\omega + 3} = \frac{1/2}{j\omega + 1} + \frac{1/2}{j\omega + 3} \longrightarrow h(t) = \frac{1}{2}e^{-t}u(t) + \frac{1}{2}e^{-3t}u(t)$$

(2) 
$$x(t) = e^{-t}u(t) \longrightarrow X(j\omega) = \frac{1}{1+i\omega} \longrightarrow$$

(2) 
$$x(t) = e^{-t}u(t)$$
  $\longrightarrow$   $X(j\omega) = \frac{1}{1+j\omega}$   $\longrightarrow$  
$$= \left[\frac{1/2}{j\omega+1} + \frac{1/2}{j\omega+3}\right] \frac{1}{j\omega+1}$$

$$Y(j\omega) = \frac{1/2}{(j\omega+1)^2} + \frac{1/4}{j\omega+1} + \frac{-1/4}{j\omega+3} + A_{11} = -A_{21} = \frac{1}{4} + \frac{1/2}{(j\omega+1)^2} + \frac{A_{11}}{j\omega+1} + \frac{A_{21}}{j\omega+3}$$

$$y(t) = \left[ \frac{1}{2} t e^{-t} + \frac{1}{4} e^{-t} - \frac{1}{4} e^{-3t} \right] u(t)$$





$$\sum_{k=0}^{N} a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^{M} b_k \frac{d^k x(t)}{dt^k}$$

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{\sum_{k=0}^{\infty} a_k(j\omega)}{\sum_{k=0}^{N} a_k(j\omega)^k}$$

考虑一个LTI系统,当输入  $x(t)=(e^{-t}+e^{-3t})u(t)$  响应为  $y(t)=(2e^{-t}-2e^{-4t})u(t)$ 

计算该系统的微分方程。

$$X(j\omega) = \frac{1}{j\omega + 1} + \frac{1}{j\omega + 3} = \frac{2j\omega + 4}{(j\omega + 1)(j\omega + 3)} = \frac{2(j\omega + 2)}{(j\omega + 1)(j\omega + 3)}$$

$$Y(j\omega) = \frac{2}{j\omega + 1} - \frac{2}{j\omega + 4} = \frac{6}{(j\omega + 1)(j\omega + 4)}$$

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{3(j\omega+3)}{(j\omega+2)(j\omega+4)} \qquad \longrightarrow \qquad h(t) = \frac{3}{2} \left(e^{-2t} + e^{-4t}\right) u(t)$$

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{3(j\omega+3)}{j\omega^2+6j\omega+8} \qquad \frac{d^2y(t)}{dt^2} + 6\frac{dy(t)}{dt} + 8y(t) = 3\frac{dx(t)}{dt} + 9x(t)$$

# 作业



- **4.6(b)**
- **4.7**(a)
- 4.9 (a)
- 4.19