

Message Passing Interface (MPI)

Part I

Compiling and Running

- . Several implementations of MPI exist, we use OpenMPI
- mpicc is used as the compiler for C
- mpiCC is used for C++
- mpirun -np "number of cores" executable
- For example if your executable is called "myEx" and you want to run with 256 processors
- . mpirun –np 256 myEx

Starting and Terminating MPI

- int MPI_Init(int* argc, char ** argv[])
 - Initializes the MPI library
 - . Must be called before any other MPI functions
 - . Call once and only once
 - . Must be called by all processes
 - do not use argc/argv before passing them to MPI_Init(). There could be arguments in there that are not meaningful to you; MPI_Init() will remove these MPI-specific options.
- int MPI_Finalize()
 - . Performs MPI library cleanup tasks
 - Any MPI calls after an MPI_Finalize() will fail
 - . Must be called by all processes

Starting and Terminating MPI

- int MPI_Init_thread(int* argc, char **
 argv[], int tenv_required,int*tenv_provided)
 - replacement for MPI_Init(); added in MPI-2
 - in addition, it initializes the threading environment
 - . MPI_THREAD_SINGLE: Only one thread will execute.
 - MPI_THREAD_FUNNELED: Process may be multithreaded, but only the main thread will make MPI calls.
 - MPI_THREAD_SERIALIZED: Processes may be multithreaded, and multiple threads may make MPI calls, but thread-concurrent MPI calls are disallowed.
 - . MPI_THREAD_MULTIPLE: Multiple threads may call MPI with no restrictions.
 - the actual level of threading provided is returned in tenv_provided; you may not get what you want.

Related MPI calls:

- MPI_Is_thread_main(): see if calling thread is a main thread
- MPI_Query_thread(): checks the threading level provided

Simple bookkeeping in MPI

- int MPI_Comm_size(MPI_Comm comm, int *size)
 - Returns the number of processes in the communicator in the variable size
- int MPI_Comm_rank(MPI_Comm comm, int *rank)
 - Returns a unique identifier (rank) of the calling process
 - Ranges from <u>zero to n-1</u>, where n is the number of processes in the communicator (both FORTRAN and C)

Communication domains

- communication domain: set of processes that are allowed to communicate with one another
- in MPI, the variable declared as MPI_Comm can represent a communicator
- use as argument to all message passing functions
- each process may belong to more than one communication domain
- MPI_COMM_WORLD is the default communicator, which includes all processes started via MPI via "mpirun" or similar
- the "rank" of a process is meaningful within a communication domain only

Passing a message: MPI_Send()

- int MPI_Send(void *buffer, int count, MPI_Datatype datatype, int destination, int tag, MPI_Comm comm)
 - Initiates a send of "buffer" and length "count" of type "datatype" to the process with rank "destination".
 - "tag" can be used to distinguish messages from one another if there are multiple messages sent to the same rank
- when does MPI_Send() return?
 - MPI_Send is a blocking call; it will not return until it is safe to free or change the memory pointed to by **buffer**.
 - MPI standard does not specify; up to the library implementor
 - if the implementor provides an intermediate buffer [i.e., allows an eager send], it can return as soon as message has been copied
 - if not, it does not return until the matching receive call (on another process) has completed
 - we have to assume the worst (that its return depends on the state of another process, i.e., it is synchronous)!

Message delivery expectations

- typical MPI implementations follow the recommendations of the MPI standard (although they are not required to)
- short messages: use an "eager send": message and envelope are sent immediately assuming destination can store it
 - a buffer typically exists on the receiving end for these "early arrival" messages
 - stored on the receiving end until the matching receive is posted
- long messages: use a synchronous send (or, "rendezvous")
 - message is not sent until destination gives an OK: handshaking operation.
- limit between small and large messages: 16KB, typical.
 Also, the user can usually set the limit through environment variables

Passing a message: MPI_Recv() [1 of 2]

- int MPI_Recv(void *buffer, int count, MPI_Datatype datatype, int source, int tag, MPI_Comm comm, MPI_Status *status)
 - Initiates a receive of buffer that has, at most, length count of type datatype from the process with rank source.
 - tag can be used to distinguish messages from one another if there are multiple messages sent to the same rank
 - . status is a structure used to obtain information about the receive
 - MPI_Recv does not return until the message has been safely copied into the buffer (blocks..semantics are assured)

Passing a message: MPI_Recv() [2 of 2]

- MPI_Status: small structure which gives information on the completed receive operation
 - this structure contains the following members:
 - · MPI_SOURCE
 - · MPI_TAG
 - · MPI_ERROR
- MPI_Get_count(MPI_Status *status,
 MPI_Datatype dtype, int *count)
 - can be used to determine the size of the received message, if needed

Wildcards for Receives

- To receive a message, we must specify its envelope exactly.
- To relax this requirement, we can use the following wildcards
 - MPI_ANY_SOURCE
 - MPI_ANY_TAG
- Or, if we want to post receive that does nothing,
 - · MPI_PROC_NULL
 - the receive returns successfully immediately, with no change to the receive buffer)
 - MPI_PROC_NULL can be used for sends as well. No message is sent.

Notes for FORTRAN users

- all MPI routines are subroutines; invoked with the CALL statement
- all MPI routines are capitalized
- all MPI routines have additional argument "ierr" at the end of the argument list; this is the return value of the routine
 - exceptions: MPI_WTIME and MPI_WTICK
- all MPI objects (MPI_Datatype, MPI_Comm, etc.) are of type INTEGER

Notes for FORTRAN users

- examples:
 - CALL MPI_SEND(a,10,MPI_DOUBLE_PRECISION,0,1, MPI_COMM_WORLD, ierr)
 - CALL MPI_RECV(a, 10, MPI_DOUBLE_PRECISION, 1, 1, MPI_COMM_WORLD, status, ierr)
 - source = status(MPI_SOURCE)
 - . tag = status(MPI_TAG)

Communication Modes (1 of 4)

- MPI_Send() and MPI_Recv() are termed "standard" sends and "standard" receives
 - underlying implementation may or may not buffer MPI_Send()
 - we must assume that it is synchronous (i.e., not buffered; buffering has the effect of decoupling the sender and receiver)
- send modes (blocking) (section 3.4, MPI Standard 1.1)

standard: MPI_Send()

. buffered: MPI_Bsend()

. synchronous: MPI_Ssend()

ready: MPI_Rsend()

Communication Modes (2 of 4)

- standard: MPI_Send()
 - nonlocal assumed [remember that we assume the worst]
 - typical MPI implementation:
 - mapped to either (modified) MPI_Rsend() or MPI_Ssend() directly
 - · "eager" send vs. "rendezvous" send, depending on message size
- buffered: MPI_Bsend()
 - local: its completion does not depend on another process.
 - user provides buffer
 - only one buffer for <u>all</u> buffered mode sends
 - MPI_Buffer_attach(void*buffer,int size)
 - MPI_Buffer_detach(void *buffer_ptr,int *size)
 - blocks until MPI has determined the buffer is not used for any operations
 - remember MPI_BSEND_OVERHEAD (per message overhead) and MPI_Pack_size()
 - typical MPI implementation: copy message data to a buffer, then initiate a nonblocking send

Communication Modes (3 of 4)

- synchronous: MPI_Ssend()
 - . nonlocal
 - can complete only when matching receive posted and data flow initiated
 - typical MPI implementation: sends a request-to-send message; receiver stores request. When matching receive posted, receiver sends a permission-to-send message, and the sender initiates data flow.
 - standard handshake protocol
- ready: MPI_Rsend()
 - local
 - should be started only if matching receive already posted; otherwise, the code is erroneous and the behavior is undefined.
 - removes the handshake synchronization overhead; improves performance; otherwise, same as standard mode send
 - typical MPI implementation: send message as soon as possible

Communication Modes (4 of 4)

- only one receive operation; can match any of the send modes:
 - . MPI_Recv()
- various modes exist for nonblocking operations as well:
 - MPI_Isend (standard mode, nonblocking)
 - MPI_lbsend (buffered mode, nonblocking)
 - MPI_Issend (synchronous mode, nonblocking)
 - MPI_Irsend(ready mode, nonblocking)

Nonblocking Communications

- all communication modes exist for nonblocking sends, but we will concentrate on MPI_Isend() in our examples
- MPI_Irecv(): nonblocking receive; can match any of the send calls, blocking or nonblocking

Nonblocking Communications

- int MPI_Isend(void *buffer, int count, MPI_Datatype datatype, int destination, int tag, MPI_Comm comm, MPI_Request * req)
 - arguments same as MPI_Send() with the addition of the MPI_Request parameter
 - request structure will allow us to test later for completion of the send operation
 - request structure is an "opaque object"

Nonblocking Communications

- int MPI_Irecv(void *buffer, int count,
 MPI_Datatype datatype, int source, int tag,
 MPI_Comm comm, MPI_Request *req)
 - arguments same as MPI_Recv() with the addition of the MPI_Request parameter and removal of MPI_Status parameter
 - request structure will allow us to test later for completion of the send operation
 - request structure is an "opaque object"

Completion of Nonblocking Communications

- MPI_Wait (MPI_Request *req, MPI_Status *status)
 - used to complete nonblocking communication
 - completion means that sender free to reuse or free buffer; or, receiver is OK to use the buffer data
 - does not indicate that message has been received, unless the synchronous nonblocking send (MPI_Issend) was used (and even then, it only means that the matching receive has been initiated).
 - blocks until request identified by reg is complete
 - one is allowed to call MPI_Wait with a null or inactive req, in which case it returns immediately with an empty status
- If we have an array of outstanding requests we want to wait on,
 - MPI_Waitany(), MPI_Waitall(), MPI_Waitsome()
 - waits for one, all, or at least one request to complete, respectively

Completion of Nonblocking Communications

- MPI_Test(MPI_Request *req, int *flag, MPI_Status *status)
 - nonblocking version of MPI_Wait()
 - returns flag = nonzero if operation is complete, and sets the status object just as MPI_Wait() would
- If we have an array of outstanding requests we want to test for,
 - MPI_Testany(), MPI_Testall(), MPI_Testsome()
 - tests for one, all, or at least one request to complete, respectively

Pending Message Operations

- MPI_Probe(int source, int tag, MPI_Comm comm, MPI_Status status)
 - allows incoming messages to be checked for, and information about that message to be obtained
 - can use wildcards
 - blocks until matching message found
 - possible use: if the message is pending, the status object will contain the length of the message. Allocate enough memory, then do a real receive.
- MPI_Iprobe(int source, int tag, MPI_Comm comm, int *flag, MPI_Status status)
 - . Nonblocking version
- Opinion: using these functions excessively probably indicates a serious logic problem. Use only when truly appropriate.

Pending Message Operations

- MPI_Cancel(MPI_Request *req)
 - local; does not depend on another process's state
 - still necessary to complete the communication with an MPI_Wait() or similar
 - if canceling a send to which a matching receive has already been posted, we must still satisfy the matching receive with another send!
 - if canceling a receive, we must still satisfy the matching send with another receive!
 - not guaranteed to cancel; only marks a communication for cancellation
 - can be an expensive operation; use with caution
 - opinion: this function opens a "can of worms". Just don't open a communication if you aren't sure that it should actually happen.
- MPI_Test_Cancelled(MPI_Status *status,int
 *flag)
 - determines whether cancel was successful or not.