第十一周周志

本周学习了MCS51单片机的基础编程知识,如基本的语言知识、控制I/O口、定时器的使用方法、中断的使用方法等,

练习代码如下图所示。

```
Computer Homework > 51 > G· 1.cpp > ② delay(void)

1  #include <reg51.h>
2  //·延时一段时间
3  void delay(void)
4  {
5     unsigned int i;
6     ··for (i = 0; i < 20000; i++)
7     ···;
8  }
9

10  void main(void)
11  {
12     ···while (1) · //无限循环
13     ···{
14     ···P1 = 0xfe; //·P1=1111·1110B, ·P1.0输出低电平
15     ···delay(); ··//延时一段时间
16     ···P1 = 0xff; //·P1=1111·1111B, ·P1.0输出高电平
17     ···delay(); ··//延时一段时间
18     ···}
19  }
```

```
#include <reg51.h> //包含单片机寄存器的头文件
   // 延时(约150ms)
   void delay150ms(void)
    unsigned char m, n;
     for (m = 0; m < 200; m++)
    for (n = 0; n < 250; n++)
12
   void main(void)
    ····unsigned char str[] = {"Now,Temperature is :"}; //将字符串赋给字符型全部元素赋值
     unsigned char i;
       while (1)
17
          ·i·=·0;······素开始显示
        ···while (str[i] ·!= ·'\0') ·//只要没有显示到结束标志'\0'
             P0 = str[i]; //将第i个字符送到P0口显示
           ····delay150ms(); //调用150ms延时函数
                        //指向下一个待显字符
23
             i++;
```

```
Computer Homework > 51 > € timer.cpp > ...
     #include <reg51.h>
     // 用定时器T0查询方式P2口8位控制LED闪烁
     void main(void)
      ····//·EA=1;·········//开总中断
      ····//·ET0=1;··········//定时器T0中断允许
      ··· TMOD = 0x01; ········//使用定时器T0的模式1
      ···THO = (65536 - 46083) / 256; //定时器T0的高8位赋初值
       TLO = (65536 - 46083) % 256; //定时器TO的高8位赋初值
      \mathsf{TR0} = \mathbf{1};
                            ····//启动定时器T0
 11
      TF0 = 0;
      P2 = 0xff;
 12
      · · · while · (1) · //无限循环等待查询
         while (TF0 == 0)
          TF0 = 0;
          P2 = ~P2;
           ··THO = (65536 - 46083) / 256; //定时器TO的高8位赋初值
       ······TL0 = (65536 - 46083) % 256; //定时器T0的高8位赋初值
```

```
Computer Homework > 51 > € interrupt.c > ...
    #include <reg51.h>

√ it D1 = P2 ^ 0; //将D1位定义为P2.0引脚

    void main(void)
    EA = 1;
                          · · / / 开总中断
     ···ET0 = 1; ········//定时器T0中断允许
       ·TMOD = 0x01; ······//使用定时器T0的模式2
       THO = (65536 - 46083) / 256; //定时器TO的高8位赋初值
       TL0 = (65536 - 46083) % 256; //定时器T0的高8位赋初值
     TR0 = 1;
                           ·//启动定时器T0
    while (1)
                           -//无限循环等待中断
    per . . . . ;
    void TimeO(void) interrupt 1 using 0 // "interrupt"声明函数为中断服务函数
       D1 = ~D1; ·······//按位取反操作,将P2.0引脚输出电平取反
       TH0 = (65536 - 46083) / 256; //定时器To的高8位重新赋初值
19
       TL0 = (65536 - 46083) % 256; //定时器T0的高8位重新赋初值
```