INTER-PROCESS COMMUNICATION

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Inter-Process Communication

IPC Methos

- Pipes and FIFO
- Message Passing
- Shared Memory
- Semaphore Sets
- Signals

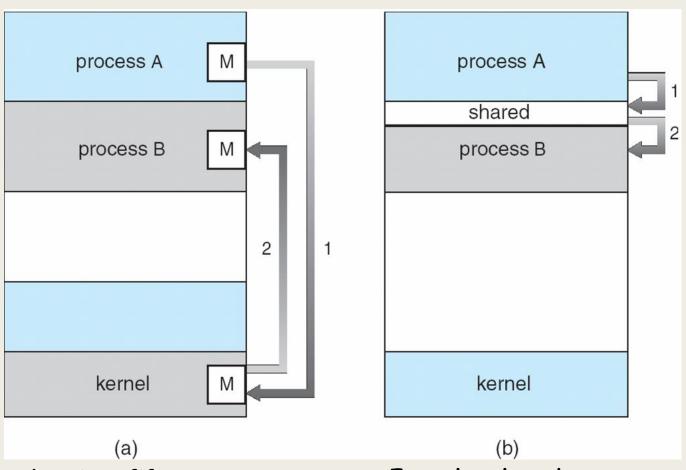
References:

- Beej's guide to Inter Process Communication for the code examples (https://beej.us/guide/bgipc/)
- Understanding Unix/Linux Programming, Bruce Molay, Chapters 10, 15
- Advanced Linux Programming Ch 5
- Some material also directly taken or adapted with changes from <u>Illinois</u> <u>course in System Programming</u> (Prof. Angrave), UCSD (Prof. Snoeren), and <u>USNA</u> (Prof. Brown)

Inter-Process Communication

- OS provides generic mechanisms to communicate
 - Un-named and Named Pipes
 - Explicit communication channel
 - Explicit Synchronization: read() operation is blocking
 - Message Passing: explicit communication channel provided through send()/receive() system calls
 - Explicit Synchronization through send() and recv()
 - Shared Memory: multiple processes can read/write same physical portion of memory; implicit channel
 - Implicit channel
 - No OS mediation required once memory is mapped
 - No synchronization between communicating threads
 - There is no read/send or write/recv available
 - How to know when data is available?

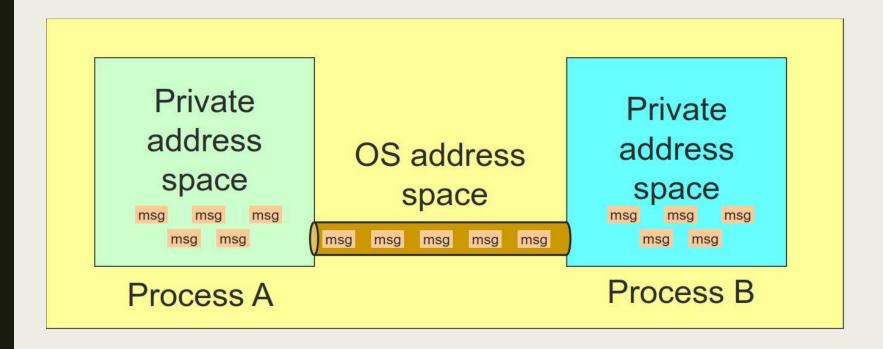
IPC Fundamental Communication Models



Example: pipe, fifo, message, signal

Example: shared memory, memory mapped file

Communication Over a Pipe

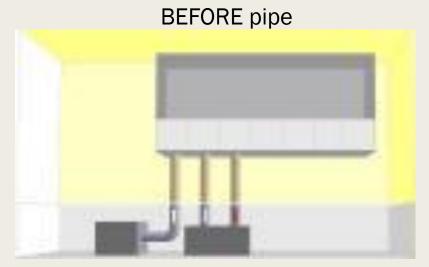


Unix Pipes (aka Unnamed Pipes)

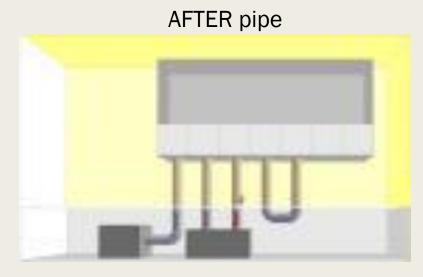
int pipe(int fildes[2])

- Returns a pair of file descriptors
 - fildes[0] is connected to the read end of the pipe
 - fildes[1] is connected to the write end of the pipe
- Create a message pipe
 - Data is received in the order it was sent
 - OS enforces mutual exclusion: only one process at a time
 - Processes sharing the pipe must have same parent in common

Pipe Creation



Process has some usual files open



Kernel creates a pipe and sets file descriptors

BEFORE

Shows standard set of file descriptors

AFTER

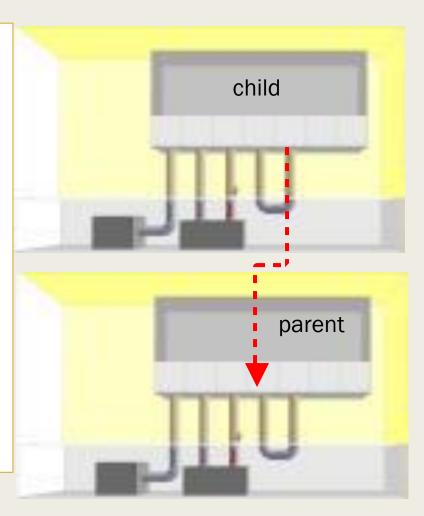
■ Shows newly created pipe in the kernel and the two connections to that pipe in the process

IPC Pipe - Method

```
#include <stdio.h>
#include <unistd.h>
void main ()
          char buf [10];
                                                         Connects the
          int fds [2];
          pipe (fds);
                                                         two fds as pipe
         printf ("sending msg: Hi\n");
write (fds[1], "Hi", 3);
read (fds[0], buf, 3);
          printf ("Received msg: %s\n", buf);
compute-linux1 tanzir/code> ./a.out
sending msg: Hi
Received msg: Hi
```

Unnamed Pipe Between Two Processes

```
int main ()
  int fds [2];
  pipe (fds); // connect the pipe
   if (!fork()){ // on the child side
       sleep (3);
       char * msq = "a test message";
       printf ("CHILD: Sent %s\n", msg);
       write (fds [1], msq,
strlen(msq)+1);
   }else{
       char buf [100];
       read (fds [0], buf, 100);
       printf ("PRNT: Recvd %s\n", buf);
   return 0;
```



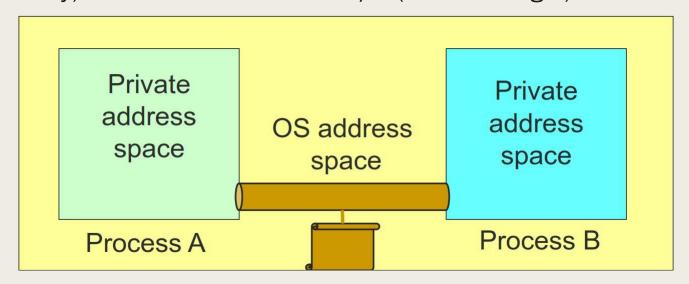
Shell Piping: "Is -I | wc -I"

```
void main ()
  int fds [2];
  pipe (fds); // connect the pipe
  if (!fork()){ // on the child side
      close (fds[0]); // closing unnecessary pipe end
      dup2 (fds[1], 1); // overwriting stdout with pipeout
      execlp ("ls", "ls", "-l", NULL);
   }else{
      close (fds[1]); // closing unnecessary pipe end
      dup2 (fds[0], 0); // overwrite stdin with pipe in
      execlp ("wc", "wc", "-l", NULL);
```

IPC- FIFO (named PIPE)

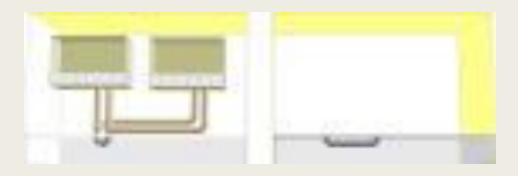
FIFO

- A pipe (also called unnamed pipe) disappears when no process has it open
- FIFOs (also called named pipes) are a mechanism that allow for IPC that's like using regular files, except that the kernel takes care of synchronizing reads and writes, and
- <u>Data is never actually written to disk</u> (instead it is stored in buffers in memory) so the overhead of disk I/O (which is huge!) is avoided.



FIFO vs PIPE

- A FIFO is like an unconnected garden hose lying on the lawn
 - Anyone can put one end of the hose to his ear and another person can walk up to the hose and speak into the other end
 - Unrelated people may communicate through a hose
 - Hose exists even if nobody is using it



FIFO

It's part of the file system

- It has a name and path just like a regular file.
- Programs can open it for reading and writing, just like a regular file.
- However, the file does not contain any data

Works like a Bounded Buffer

- Bytes travel in First-In-First-Out fashion: hence the name FIFO.
- Reading process must wait for the writer
- Writer must wait for the read operation once the buffer is full

FIFO - Problems

■ We still need to agree on a name ahead of time – how to communicate that??

```
FIFORequestChannel rc ("control", ..) {
    ...
    mkfifo ("control", PERMS); // create
}
```

- Not concurrency safe within a process
 - Like a file used by multiple processes/threads
 - Multiple threads writing can cause race condition

Using FIFO's

- How do I create a FIFO
 - mkfifo (name)
- How do I remove a FIFO
 - rm fifoname or unlink(fifoname)
- How do I listen at a FIFO for a connection
 - open (fifoname, O_RDONLY)
- How do I open a FIFO in write mode?
 - open(fifoname, O_WRONLY)
- How do two processes speak through a FIFO?
 - The sending process uses write and the listening process uses read. When the writing process closes, the reader sees end of file

FIFO DEMO

Writer

```
#define FIFO NAME "test.txt"
int main(void)
{
  char s[300];
  int num, fd;
  mkfifo(FIFO NAME, 0666); // create
  printf("Waiting for readers...\n");
  fd = open(FIFO NAME, O WRONLY); //open
  if (fd < 0)
    return 0;
  printf("Got a reader--type some
stuff\n");
  while (gets(s)) {
    if (!strcmp (s, "quit")) break;
    if ((num = write(fd, s, strlen(s)))
==-1
      perror("write");
    else
      printf("SENDER: wrote %d bytes\n",
num);
  //unlink (FIFO NAME);
  return 0;
```

Reader

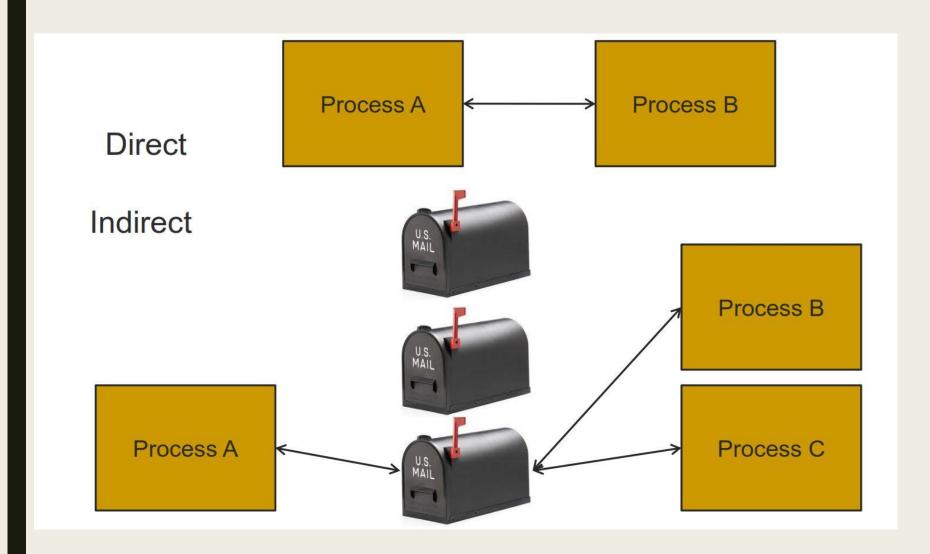
```
int main(void)
  char s[300];
  int num, fd;
 printf("waiting for writers...\n");
  fd = open(FIFO NAME, O RDONLY);
 printf("got a writer\n");
  do{
    if ((num = read(fd, s, 300)) == -1)
      perror("read");
    else {
      s[num] = ' \setminus 0';
      printf("RECV: read %d bytes:
\"%s\"\n", num, s);
  } while (num > 0);
  return 0;
```

IPC: Message Queue

Message Queue

- Mechanism for processes to communicate and to synchronize their actions
- IPC facility provides two operations:
 - send(message)
 - receive(message)
- If *P* and *Q* wish to communicate, they need to:
 - establish a communication link between them
 - exchange messages via send/receive

Message Passing



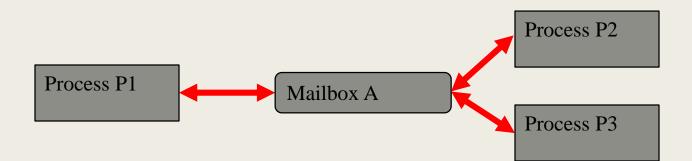
Direct Message Passing

- Processes must name each other explicitly:
 - send (P, message) send a message to process P
 - receive(Q, message) receive a message from process Q
- Properties of communication link
 - Links are established automatically (or implicitly) while sending/receiving
 - A link is associated with exactly one pair of communicating processes
 - Between each pair, there exists exactly one link
- Limitation: Must know the name or id of the other process



Indirect Message Passing

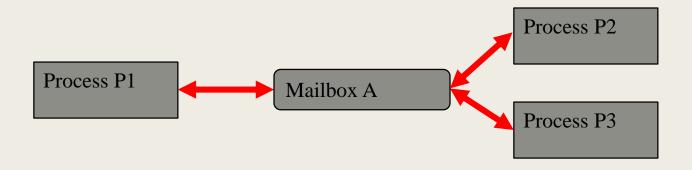
- Messages are directed to and received from mailboxes (also referred to as ports)
 - Mailbox can be owned by a process or by the OS
 - Each mailbox has a unique id
 - Processes can communicate only if they share a mailbox
- Properties of communication link
 - Link established only if processes share a common mailbox
 - A link may be associated with many processes
 - Each pair of processes may share several communication links



Indirect Message Passing

- Operations
 - create a new mailbox
 - send and receive messages through mailbox
 - destroy a mailbox
- Primitives are defined as:

send(A, message) - send a message to mailbox A
receive(A, message) - receive a message from mailbox A



Synchronization

- Message passing may be either blocking or non-blocking
- Blocking is considered synchronous
 - Blocking send has the sender block until the message is received
 - Blocking receive has the receiver block until a message is available
- Non-blocking is considered asynchronous
 - Non-blocking send has the sender send the message and continue
 - Non-blocking receive has the receiver receive a valid message or null
 - Does not wait for it
 - A receive may "fail" several times before it succeeds at the end

Operations on Message Queues

```
int mq_close(mqd_t mqdes)
```

Message Queue – Example

```
send(){
  mqd t mq = mq open("/testqueue", O RDWR O CREAT, 0664, 0);
  if (mq send(mq, av[1], strlen (av[1]) + 1, 0)<0) {
      perror ("MQ Send failure");
      exit (0);
  printf ("MQ Put: %s\n", av [1]);
  return 0;
recieve(){
 mqd t mq = mq open("/testqueue", O RDWR | O CREAT, 0664, 0);
  struct mq attr attr;
  mq getattr (mq, &attr); // get attribute
  char *buf = (char*)malloc (attr.mq msgsize);
 mq receive (mq, buf, attr.mq msgsize, NULL);
  printf ("MQ Receive Got: %s\n", buf);
  //clean-up
 mq close(mq);
  //mq unlink("/testqueue"); // remove from Kernel
  return 0;
```

IPC: Shared Memory

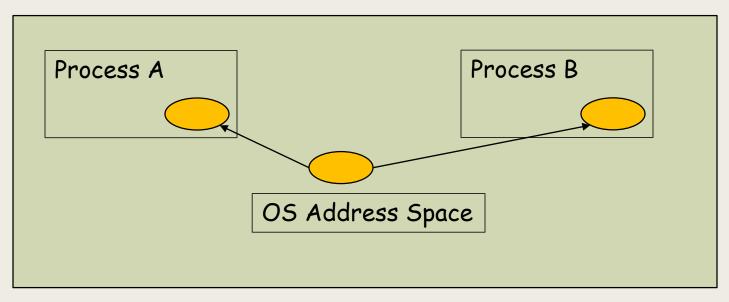
Shared Memory

- How does data travel through a FIFO?
 - 'write' copies data from process memory to kernel buffer and then 'read' copies data from a kernel buffer to process memory
- If both processes are on the same machine, then they may not need to copy data in and out of the kernel
 - They may exchange or share data by using a shared memory segment
 - Shared memory is to processes what global variables are to threads

Shared Memory

- Processes share the same segment of memory directly
 - Memory is mapped into the address space of each sharing process
 - Memory is persistent beyond the lifetime of the creating or modifying processes (until deleted)
- But, now the processes are on their own for synchronization
 - Mutual exclusion must be provided by processes using the shared memory
 - Semaphores to ensure Producer-Consumer relation also has to be now done by the respective processes

Shared Memory



- Processes request the segment
- OS maintains the segment
- Processes can attach/detach the segment

Facts about Shared Memory Segments

- A shared memory segment has a name, the name must start with "/"
- A shared memory segment has an owner and permission bits
- Processes may "map" or "unmap" a segment, obtaining/removing a pointer to the segment
- reads and writes to the memory segment are done via regular pointer operations

Shared Memory – POSIX functions

- **shm_open**: creates a shared memory segment
- **ftruncate**: sets the size of a shared memory segment
- mmap: maps the shared memory object to the process's address space
- **munmap**: unmaps from process's address space
- shm_unlink: removes the shared memory segment from the kernel
- close: closes the file descriptor associated with the shared memory segrment

Shared Memory Example

```
char* my shm connect(char* name, int len) {
   int fd = shm open(name, O RDWR|O CREAT, 0644 );
   ftruncate(fd, len); //set the length to 1024, the default
is 0, so this is a necessary step
   char *ptr = (char *) mmap(NULL, len, PROT READ|PROT WRITE,
MAP SHARED, fd, 0);// map
   if (fd < 0) {
       perror ("Cannot create shared memory\n");
       exit (0);
   return ptr;
void send(char* message) {
   char *name = "/testing";
   int len = 1024;
   char* ptr = my shm connect (name, len);
   strcpy(ptr, message); // putting data by just copying
   printf ("Put message: %s\n", message);
   close(fd); // close desc, does not remove the segment
   munmap (ptr, len); // this is a bit redundant,
```

Shared Memory Example- contd

```
void receive() {
    char *name = "/testing";
    int len = 1024;
    char* ptr = my_shm_connect (name, len)

    printf ("Got message: %s\n", ptr);
    shm_unlink (name); //this removes the segment
from Kernel, this is a necessary clean up
    exit(0);
}
```

Shared Memory - Summary

- It's great because it does not allocate extra memory
 - 3-times less memory (In others you have 1 copy in kernel, 2 others in the individual processes)
- But a huge problem looms
 - Who does synchronization?
 - There is no guarantee of order between sending and receiving processes
 - The receiver process can run first finding nothing or stale data in the buffer

Kernel Semaphores

- We have learned how to synchronize multiple threads using Semaphores and Locks
- But how do we synchronize multiple processes?
 - We will again need semaphores, but this time Kernel Semaphores
 - They are visible to separate processes who do not share address space

Kernel Semaphore Operations

- sem_open (name, ...) to create or connect to a semaphore
 - The name argument must start with a "/"
- sem_close () closes a semaphore
 - It does not destroy it from Kernel
- sem_unlink() removes from Kernel
 - Must be put in the destructor for PA5
- sem_wait() is equivalent to Semaphore::P() operation
- semd_post() is equivalent to Semaphore::V() operation
- Find out more from **sem overview(7)** in man pages