#### Reading Reference:

Textbook 1: Chapter 4 (Section 4.1-4.4)

# CONCURRENCY AND THREADS

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## Today's Conversation

#### ■ Threads

- A bit complex topic but central to our understanding of modern computer systems (HW and SW)
- We will build concepts incrementally and tie the picture together at the end

Adapted from contemporary courses in OS/Systems taught at Berkeley, UW, TAMU, UIUC, and Rice. Special acknowledgment to Profs Gu/Bettati/Tyagi at TAMU, Culler and Joseph at Berkeley

# Why Processes & Threads?

#### Goals:

- Multiprogramming: Run multiple applications concurrently
- Protection: Don't want a bad application to crash system!

#### **Solution:**

- Virtual Machine abstraction: give process illusion it owns machine (i.e., CPU, Memory, and IO device multiplexing)
- Process: unit of execution and allocation

#### **Challenge:**

- Process creation & switching expensive
- Need concurrency within same app (e.g., web server)

#### **Solution:**

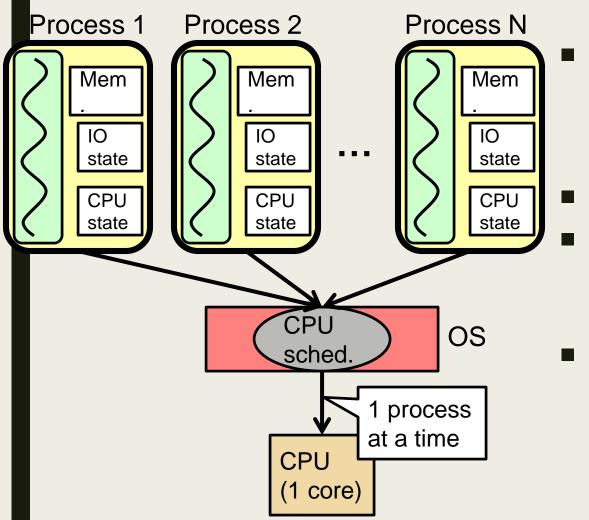
Thread: Decouple allocation and execution

Run multiple threads within same process

#### Motivation for Threads

- Process Context Switch has huge overhead. Requires switching:
  - CPU state (PC, PSW, all registers etc) fast
  - Memory Address Space SLOW
- Assumption: memory access without cache is slow
- A Memory Address Space comes with:
  - Virtual Memory System data
    - Page tables (mapping) and Translation Look-aside Buffer (TLB) (i.e., working as cache for mapping)
  - Actual Memory Content
    - Dirty (modified) pages that are updated only in cache, not in memory
    - Need to be updated in the memory before switch
- All of these become obsolete after a switch
  - All caches (L1, L2, ..), TLB become COLD
  - Require time to **WARM UP** as the new process runs

#### **Processes Context Switch**



- Process Switch overhead: high
  - CPU state: low
  - Memory/IO state: high
- Process creation: high
- Protection
  - CPU: yes
  - Memory/IO: yes
- Sharing overhead: high (involves at least a context switch)

#### **Thread Context Switch**

- Still requires:
  - The kernel scheduler to run, that overhead stays
  - Save the current CPU context, and load the next one
- But, the old address space stays. Thus, no WARM UP required for:

Saves time

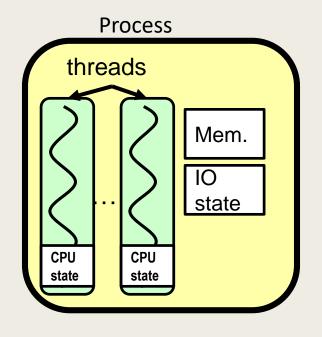
- Caches (L1, L2, L3, ...)
- TLB (cache for memory mapping)

 Result: Thread Context Switch is much Faster than Process Context Switch

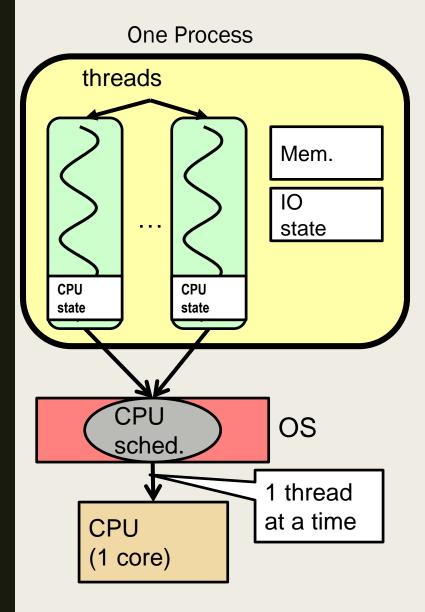
# Putting it together: Process

#### (Unix) Process

```
A(int tmp) {
 if (tmp<2)
                   Memory
  B();
 printf(tmp);
                   I/O State
B() {
                   (e.g., file,
 C();
                   socket
                   contexts)
C() {
 A(2);
                   CPU state
                   (PC, SP,
A(1);
                   registers..)
```



#### Threads Context Switch



- Thread Switch overhead: low
  - Only CPU state switched
- Thread creation: low
- Protection
  - CPU: yes
  - Memory/IO: No
- Sharing overhead: low
  - No context switches
  - Only low-overhead threadswitches

#### Threads in Use

- Operating systems need to be able to handle multiple things at once (MTAO)
  - processes, interrupts, background system maintenance
- Servers need to handle MTAO
  - Multiple connections handled simultaneously in a Web Server
- Parallel programs need to handle MTAO
  - To achieve better performance
- Programs with user interfaces often need to handle MTAO
  - To achieve user responsiveness while doing computation
- Network and disk bound programs need to handle MTAO
  - To hide network/disk latency

## There's a Problem!!!

Most of the time, threads are working on separate data, so scheduling doesn't matter:

Thread A 
$$x = 1;$$
 Thread B  $y = 2;$ 

■ However, What about (Initially, y = 12):

```
Thread A x = 1; y = 2; y = y+1; y = y*2;
```

- What are the possible values of x?

# Thread A Thread B x = 1; x = y+1; y = 2; y = y\*2

### Problem is at the lowest level

Most of the time, threads are working on separate data, so scheduling doesn't matter:

Thread A 
$$x = 1;$$
 Thread B  $y = 2;$ 

■ However, What about (Initially, y = 12):

# Thread A x = 1; y = 2; y = y\*2;

- What are the possible values of x?

# Thread A y = 2; $y = y^*2;$ x = 1; x = y+1;

### Problem is at the lowest level

Most of the time, threads are working on separate data, so scheduling doesn't matter:

```
Thread A x = 1; Thread B y = 2;
```

■ However, What about (Initially, y = 12):

```
Thread A x = 1; y = 2; y = y*2;
```

What are the possible values of x?

Thread A Thread B

```
y = 2;

x = 1;

x = y+1;

y = 2;

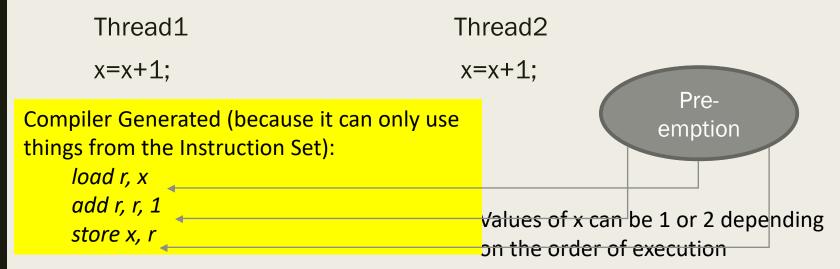
y = y*2;
```

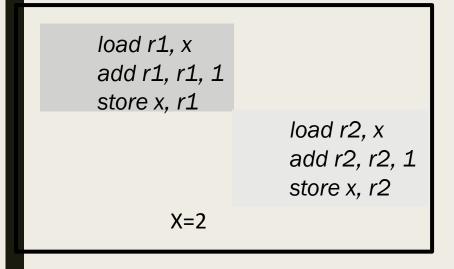
#### Race Condition is the name!!

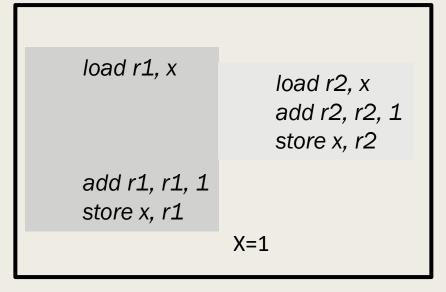
- Race condition: Output of a concurrent program depends on the order of operations between threads
- Cannot make any assumptions about relative speed of threads (i.e. interleaving is a given)
- Non-determinism is omnipresent:
  - Scheduler's decision depends on many factors
  - Processor architecture (e.g., variable clock rate, outof-order execution)

#### Race Condition for Instruction Set

■ Simple threaded code (assume x=0)







# Race Condition for Out-of-Order Execution

- Most architectures support (I should say "require") this feature
  - Pipelined processors cannot achieve peek performance without it

reorder

The idea is simple: compilers may reorder "unrelated" instructions like the following:

```
//global variables
bool done = false;
int data = -1;

Thread1 (){
    // takes a long time
    data = longfunction();
    done = true;
}
```

```
//global variables
bool done = false;
int data = -1;

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   // takes a long time
   data = longfunction();
}
```

# Out-of-Order Execution causing Race Condition

- The problem arises when there is an inter-thread dependency
- Because of thread 2's wait, the 2 lines in Thread1() are no longer independent
- However, the compiler has no way to tell that!!!

```
// thread 1's function,
// REORDERD
Thread1 (){
   done = true;
   data = longfunction();
}
```

```
// thread 2's function
Thread2 (){
  while (!done); // wait
  int newdata = compute (data);
}
```

#### Thread API

- We will discuss thread API from C++11 which is cross-platform
  - But for many other things, we will still use Linux for our PAs
- Here is an example:

```
#include <iostream>
#include <thread>
#include <unistd.h>
using namespace std;

void foo() {
    sleep(3);
    cout<<"foo done"<<endl;
}

void bar(int x){
    sleep(1);
    cout <<"bar done"<<endl;
}</pre>
```

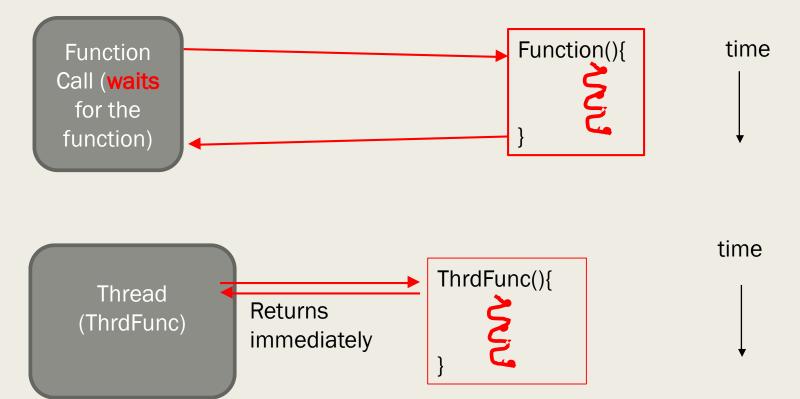
```
int main() {
  thread foothrd (foo); //calls foo() in a thread
  thread barthrd (bar,0);//calls bar(x) in a thread

cout << "main, foo and bar would now execute
  concurrently..." << endl;;

// synchronize threads:
  foothrd.join(); // pauses until foo finishes
  barthrd.join(); // pauses until bar finishes
  cout << "foo and bar completed.\n";
  return 0;
}</pre>
```

### Thread Execution

- Creating a thread is very similar to calling a function directly, with a slight difference shown below:
  - A regular function call is blocking, i.e., caller waits for callee
  - thread does NOT
- So, this is like fork(), creates the thread, calls the function inside, but does not wait



#### Race Condition Demonstration

- Start 2 (or more) threads that increment a shared variable times
  - Use pointer to data so that threads share
- Use a large number for x to ensure adequate overlap
- Notice that the output is different every time

```
void func (int * p, int x) {
    // increment *p x times
    for (int i=0; i<x; i++)
        *p = *p + 1;
int main(int ac, char** av) {
    int data = 0;
    int times = atoi (av [1]);
    // start 2 thread to increment the same variable
    thread t1 (func, &data, times);
    thread t2 (func, &data, times);
    t1.join(); // pauses until first finishes
    t2.join(); // pauses until second finishes
    cout << "data = " << data << endl;
    return 0;
```

```
osboxes@osboxes:~/$ ./a.out 10000000
data = 15003189
osboxes@osboxes:~/$ ./a.out 10000000
data = 13380972
osboxes@osboxes:~/$ ./a.out 10000000
data = 12565682
```