Database 2 course notes

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DBMS types

1.1 Relational DBMSs

- Formally introduced by **Codd** in 1970.
- ANSI standard: **SQL**.
- Composed of many relations in form of **2D tables**, containing **tuples**.
 - Logical view: data organized in tables.
 - Internal view: stored data.
 - Rows (tuples) are **records**.
 - Columns (fields) are attributes.
 - * They have specific data types.
- Constraints are used to restrict stored data.
- SQL is divided in DDL and DML.

1.1.1 Disadvantages

- Lack of flexibility: all processing is based on values in fields of records.
- Inability to handle complex types and complex interrelationships.

1.2 Object-oriented DBMSs

- Integrated with an OOP language.
- Supports:
 - Complex data types.
 - Type inheritance.

- Object behavior.
- Objects have an **OID** (object identifier).
- ADTs (abstract data types) are used for encapsulation.
- OODBMSs were standardized by **ODMG** (Object Data Management Group).
 - Object model, **ODL**, **OQL** and OOP language bindings.
- OQL resembles SQL, with additional features (object identity, complex types, inheritance, polymorphism, ...).

1.2.1 Disadvantages

- Poor performance. Queries are hard to optimize.
- Poor scalability.
- Problematic change of schema.
- Dependence from OOP language.

1.2.2 Advantages

- Composite objects and relations.
- Easily manageable class hierarchies.
- Dynamic data model
- No primary key management.

1.3 Object-relational DBMSs

- Hybrid solution, expected to perform well.
- Features:
 - Base datatype extension (inheritance).
 - Complex objects.
 - Rule systems.

Distributed systems

2.1 General information

- A distributed system is a **software** that makes **a collection of independent machines** appear as **a single coherent system**.
 - Achieved thanks to a **middleware**.
- Goals:
 - Making resource available.
 - Distribution **transparency**.
 - Openness and scalability.

2.1.1 Transparency

Type	Description
Access	Hides data access
Location	Hides data locality
Migration	Hides ability of a system to change object location
Relocation	Hides system ability to move object bound to client
Replication	Hides object replication
Concurrency	Hides coordination between objects
Failure	Hides failure and recovery

- Hard to fully achieve.
 - Users may live in different continents.
 - Networks are unreliable.
 - Full trasparency is costly.

2.1.2 Openness

- Conformance to well-defined interfaces.
- Portability and interoperability.
- Heterogeneity of underlying environments.
- Requires support for **policies**.
- Provides mechanisms to fulfill policies.

2.1.3 Scalability

- Size: number of users/processes.
- Geographical: maximum distance between nodes.
- Administrative: number of administrative domains.
- Techniques to achieve scalability:
 - Hide communication latencies.
 - * Use **asynchronous** communication.
 - * Use separate response handlers.
 - Distribution.
 - * Decentralized \mathbf{DNS} and information systems.
 - * Try to compute as much as possible on clients.
 - Replication/caching.
- Issue: inconsistency and global synchronization.

2.2 Types

2.2.1 Distributed Computing Systems

- HPC (high-performance computing).
- Cluster computing:
 - Homogeneous LAN-connected machines.
 - * Master node + compute nodes.
- Grid computing:
 - **Heterogeneous** WAN-connected machines.
 - Usually divided in **virtual organizations**.

2.2.2 Distributed Information Systems

- Transaction-based systems.
 - Atomicity.
 - Consistency.
 - **Isolation**: no interference between concurrent transaction.
 - **Durability**: changes are permanent.
- **TP Monitors** (transaction processing monitors) coordinate execution of a distributed transaction.
 - Communication middleware is required to separate applications from databases.
 - * RPC (remote procedure call).
 - * MOM (message-oriented middleware).

2.2.3 Distributed Pervasive Systems

- Small nodes, often mobile or embedded.
- Requirements:
 - Contextual change.
 - Ad-hoc composition.
 - Sharing by default.
- Examples:
 - Home systems.
 - Electronic health systems.
 - Sensor networks.

2.3 Architectures

2.3.1 Styles and models

- Architectural styles:
 - Layered: used for client-server systems.
 - Object-based: used for distributed systems.
- Decoupling models:
 - Publish/subscribe: uses event bus, decoupled in space.

 Shared dataspace: used shared persistent data space, decoupled both in space and time.

2.3.2 Centralized architectures

- Client-server.
- Three-layered view:
 - User-interface layer.
 - Processing layer.
 - Data layer.
- Multi-tiered architecture:
 - Single-tiered: dumb terminal/mainframe.
 - Two-tiered: client-server.
 - Three-tiered: each layer on separate machine.

2.3.3 Decentralized architectures

- **P2P** (peer-to-peer):
 - P2P architectures are **overlay networks**: application-level multicasting.
 - **Structured**: nodes follow a specific data structure.
 - * Example: ring, kd-tree.
 - **Unstructured**: nodes choose random neighbors.
 - * Example: random graph.
 - · Each node has a **partial view** of the network which is shared with random nodes selected periodically, along with data.
 - **Hybrid**: some nodes are special (and structured).
- Topology management:
 - 2 layers: structured and random.
 - * Promote some nodes depending on their services.
 - * Torus construction: create N*N grid, keep only **nearest neighbors** via distance formula.
 - * Superpeers: few specific nodes.
 - · Examples: indexing, coordination, connection setup.
- Hybrid architectures (P2P + client-server):
 - CDNs: edge-server architectures.

- **BitTorrent**: tracker and peers.

2.3.4 Architectures versus middleware

- Sometimes the middleware needs to **dyamically adapt its behavior** to distributed application/systems.
 - **Interceptors** can be used.
 - Adaptive middleware:
 - * Separation of concerns.
 - * Computational reflection (self runtime inspection).
 - * Component-based design.

2.3.5 Self-managing distributed systems

- Self-x operations:
 - Configuration.
 - Management.
 - Healing.
 - Optimization.
- Feedback control model.
 - Example: globule (collaborative CDN driven by cost model).

Distributed architectures

3.1 Distributed DBMSs

3.1.1 Basics and data fragmentation

- Based on **autonomy** and **cooperation**.
- Data **fragmentation** and **allocation**:
 - A relation R is split in R_i fragments.
 - **Horizontal** fragmentation:
 - * R_i : set of tuples with same schema as R.
 - * Like the where SQL clause.
 - **Vertical** fragmentation:
 - * R_i : set of tuples with subschema of R.
 - * Like the select SQL clause.

3.1.2 Transparency levels

- **Fragmentation** transparency: independence of a query from data fragmentation and allocation.
- Allocation transparency: fragment structure must be specified in a query, but not location.
- Language transparency: both fragment structure and location have to be specified in a query.

3.1.3 Transaction classification

• Remote request: readonly (select) transactions towards a single DBMS.

- Remote transaction: general transactions towards a single DBMS.
- **Distributed transaction**: towards multiple DBMSs, but every SQL operation targets a single DBMS.
- Distributed request: arbitrary transaction, language-level transparency.

3.2 Distributed DBMSs technology

3.2.1 Consistency and persistency

- Consistency: does not depend on data distribution. Constraints are only properties local to a specific DBMS. This is a limitation of DBMSs.
- **Persistency**: does not depend on data distribution. Every sistem guarantees persistency thanks to dumps and backups.

3.2.2 Optimization

- Global optimization is performed through a cost analysis.
 - A tree of possible alternatives is examined.
 - IO, CPU and bandwidth coss are taken into account.

3.2.3 Concurrency control

- Problem: two transactions t_1 and t_2 can be composed of subtransactions whose execution is in conflict.
 - The transactions are **locally serializable**.
 - The transactions are **not globally serializable**.
- Global serializability: two transactions are globally serializable if $\exists S \ (serial \ schedule)$ that is equivalent to every local schedule S_i .
 - For every node i, the projection S[i] of S needs to be equivalent to S_i
 - This property can fulfilled using **2-phase locking** or **timestamping**.

3.2.3.1 Lamport's method for timestamping

- Every transaction needs a timestamp of the time instant where it needs to be synchronized with other transactions.
- A timestamp is composed by two numbers: **node ID** and **event ID**.
- Nodes have a local counter that helps ordering transactions.

3.2.3.2 Distributed deadlock detection

- Two subtransactions may be waiting for one another in the same or in different DBMSs.
- A waiting sequence can be built for every transaction.
- Algorithm:
 - 1. DBMSs share their waiting sequences.
 - 2. Waiting sequences are composed in a **local waiting graph**.
 - 3. Deadlocks are detected locally and solved by aborting transactions.
 - 4. Updated waiting sequences are sent to other DBMSs.

3.3 Distributed transaction atomicity

3.3.1 2-phase commit protocol

- Conceptually similar to marriage.
- Servers are called **RMs** (resource managers).
- A coordinator is called **TM** (transaction manager).
- Both RMs and the TM have local logs.
- TM log records:
 - prepare: contains RMs identities.
 - global commit/abort: atomic and persistent decision regarding the entire transaction.
 - complete: conclusion of the protocol.
- RM log records:
 - ready: signals availability of the node.
- Algorithm (ideal situation):
 - Phase one (preparation):
 - 1. TM sends prepare, sets a timeout for RM responses.
 - RMs wait for prepare messages. On arrival, they send ready. If an RM is
 in a bad state, not-ready is sent instead, terminating the protocol (global
 abort).
 - 3. TM collects RM messages. On success, sends global commit.
 - Phase two:
 - 1. TM sends global decision, setting a **timeout**.
 - 2. Ready RMs wait for the decision. On arrival, they either log commit or abort, and send an ack to the TM.

- 3. TM collects all ack messages. If all of them arrived, complete is set. If an ack is missing, a new timeout is set and transmissions are repeated.
- The period between ready and commit/abort is called uncertainty interval the protocol tries to minimize its length.

3.3.1.1 Recovery protocols

- RM drops:
 - If last record was abort, actions will be undone.
 - If last record was commit, actions will be repeated.
 - If last record was ready, we are in a doubtful situation.
 - * Information needs to be requested from TM.
- TM drops:
 - If last record as prepare, some RMs may be locked.
 - * global abort will be sent, or the first phase will be repeated.
 - If last record was global commit/abort, the second phase needs to be repeated.
 - If last record was complete, everything is fine.
- Message loss: handled by timeouts, which cause a global abort in the first phase, or a retransmission in the second phase.

3.3.1.2 Optimizations

- **Presumed abort protocol**: if in doubt during a RM recovery, and TM has no information, abort is returned.
 - Some synchronous record writes can be avoided.
- **Read-only optimization**: if an RM only needs to read, it will not influence the transaction's result it can be ignored during second phase.
- TODO: other commits, replication, cooperation

3.3.2 Other commit protocols

- The biggest issue with the 2-phase protocol is that an RM can become stuck if the TM drops.
 - The following protocols don't have this issue but are less performant.

3.3.2.1 4-phase commit protocol

- The TM process can be replicated by a **backup process** on a different node.
 - On every phase, the TM first communicates with the backup, then with the RMs.

3.3.2.2 3-phase commit protocol

- After receiving ready from every RM, the TM has an additional pre-commit state.
 - If the TM drops during that state, any RM can become the TM, because every RM has to be ready.
- Unusable in practice due to widened uncertainty interval and atomicity issues in case of network partitioning.

3.3.2.3 Paxos commit

- More general goal: have nodes "agree" on a specific value in case of malfunction.
- Three node categories:
 - Proponent.
 - Acceptor.
 - Receiver.
- Three phases:
 - 1. Election of a coordinator.
 - 2. Acceptors agree on a value.
 - 3. The value is propagated to receivers.
- Algorithm:
 - 1. The coordinator sends n prepare messages to participants.
 - 2. Every participant sends ready to coordinator and to f acceptors.
 - 3. Every acceptor sends its state using f messages.
 - 4. Coordinator and acceptors are f + 1 nodes that know the state of the transaction. Any malfunction in f is not a problem.

3.3.2.4 X-Open DTP

- Guarantees interoperability of transactions on different DBMSs.
- Two main interfaces:
 - 1. **TM-interface**: between client and TM.
 - tm xxx functions.

- 2. **XA-interface**: between TM and RM.
 - Database vendors must guarantee XA-interface availability.
 - xa_xxx functions.
- Features:
 - RMs are passive. All control is in TM, which uses RPCs to enable RM functions.
 - Uses 2-phase commit with aforementioned optimizations.
 - Heuristical decisions are taken, which can harm atomiticy (notifying clients).

3.4 DBMS replication

- A data replicator handles replication and synchronization between copies.
 - Copies are updated asynchronously (no commit protocols).
- Replication data can be **batched** and reconciled with the copies all at once.
- Multidatabase systems: tree hierarchies of dispatchers and multiple DBs behind a single interface.

Parallel DBMSs and cloud architectures

4.1 Parallelism

- Ideally speeds up computation by a factor of 1/n.
- Two types:
 - 1. **Inter-query**: different queries ran in parallel.
 - 2. **Intra-query**: parts of the same query (subqueries) ran in parallel.

4.1.1 Relationship with data fragmentation

• Data fragments are in different locations, which can be associated to different processors.

4.1.2 Speed-up and scale-up

- **Speed-up**: only related to inter-query parallelism. Measures *tps* as the number of processors grows.
- Scale-up: related to both parallelism types. Measures $\frac{cost}{tps}$ aas the number of processors grows.

4.2 Cloud computing architectures

4.2.1 Classification

4.2.1.1 Features

- On-demand self-service: architecture elements can be defined depending on current needs through web interfaces.
- Remote access.
- Service measuring: architectural resources are rented using costs depending onuse.
- Elasticity.
- Resource sharing.

4.2.1.2 Types

- Private cloud: of an organization/institution.
- Community cloud: of a community of organizations/institutions.
- Public cloud: like AWS or Azure.
- Hybrid cloud: private cloud that use public services when needed.

4.2.1.3 Service models

- SaaS: clients rent finished applications.
- PaaS: clients rent hardware resources and base software.
- IaaS: clients rent only hardware resources.

4.2.2 Hadoop and MapReduce

- HDFS: distributed filesystem developed in Java.
 - Uses TCP/IP for communication.
 - Files are fragmented in separate nodes and are replicated.
 - The main node is called **NameNode**, others are called **workers**.
- MapReduce: parallel computation model.
 - Jobs are handled by a job tracker.
 - Jobs assign tasks, which are handled by a task tracker.

4.2.3 Apache Pig and Pig Latin

- Query system based on Hadoop.
- Data model is similar to OODBMSs, but does not support inheritance.
 - Data is organized in relationships.
 - Relations can contain duplicated elements (tuple bags).
 - There is no explicit primary key.
- Example query: FOREACH table GENERATE attribute0 attribute1;.

4.2.4 Apache Hive and Hive QL

• Similar to Pig, but closer to SQL.

Cloud computing

TODO: merge previous chapter into this one or viceversa?

TODO: add cloud federations to cloud models

5.1 Definitions

- Cloud computing describes a class of network-based computing:
 - A collection/group of networked hardware, software and infrastructure (platform).
 - Uses the Internet for communication/transport, providing hardware and software services to client.
- The complexity of the platforms is hidden behind simple **APIs**.
- Characteristics:
 - Remotely hosted.
 - **Ubiquitous**: services/data available from anywhere.
 - Commodified: pay for what you want/need.
 - Common characteristics:
 - * Massive scale.
 - * Resilient computing.
 - * Homogeneity.
 - * Geographic distribution.
 - * Virtualization.
 - * Service-orientation.
 - * Low-cost.
 - * Security.

- Essential characteristics:
 - * On-demand self-service.
 - * Broad network access.
 - * Elasticity.
 - * Resource pooling.
 - * Measured service.

5.2 Service models

5.2.1 Layers

- From application-focused to infrastructure-focused:
 - 1. Services.
 - 2. Application.
 - 3. Development.
 - 4. Platform.
 - 5. Storage.
 - 6. Hosting.

5.2.2 IaaS

• Provides hardware.

5.2.2.1 Virtualization

- The basis of IaaS.
- Virtual workspaces: abstraction over the execution environment.
 - Has specific resource quota and software configuration.
- Implemented on VMs (virtual machines).
 - Abstraction of the physical host.
 - Advantages:
 - * OS flexibility. Easier deployment.
 - * Versioning/backups/migrations.
- A VMM (virtual machine monitor, or hypervisor) is used to manage multiple VMs on a single machine.

5.2.3 PaaS

- Deploys user-created applications.
- Highly-scalable architecture.

5.2.4 SaaS

- Provides applications.
- Examples: Facebook apps, Google apps.

5.2.4.1 Maturity model

- Level 1: ad-hoc/custom. One instance per customer.
- Level 2: configurable per customer.
- Level 3: configurable and multi-tenant-efficient.
- Level 4: scalable (uses load balancer) level 3.

SQL vs NoSQL

6.1 SQL characteristics

- Data is stored in columns and tables.
- Relationships represented by data.
- DML and DDL.
- Transactions.
 - ACID properties.
- Abstraction from physical layer.
 - Declarative language.
 - Query optimization engine.

6.2 Big data

- Extremely large datasets.
- Challenges:
 - Analysis, capture, searching, storage, transfer, visualization, querying, security.
- Characteristics: volume, velocity and variety.
- Big data **analytics**: capture and analysis processes aiming to find patterns and correlations in huge heterogeneous datasets.

6.2.1 3-layer processing architecture

- 1. Online processing:
 - Real-time data capture/processing.

- Deals with **velocity**:
 - Algorithms need to be simple and fast.
- 2. Nearline processing:
 - Database-oriented.
 - Handles data storage and some processing (slightly more complex than online processing).
- 3. Offline processing:
 - Batch heavy-procesing of data.

6.2.2 Lambda architecture

- Principles:
 - 1. **Human fault-tolerance**: data needs to survive human errors and hardware faults.
 - 2. Data immutability: no updates/deletes.
 - 3. **Recomputation**: recomputing previous results must always be possible.
- Levels:
 - 1. **Batch layer**: stores the master dataset and computes **views** (pre-computing) using MapReduce algorithms.
 - 2. **Speed layer**: computes **real-time** views only with new data, not total data. Uses an **incremental model**.
 - 3. **Serving layer**: output of the batch layer. Handles view indexing and provides views to the query system.
 - The query system uses both batch and speed views.

6.3 NoSQL

- Class of non-relational data storage systems.
 - Types:
 - * Document store. Example: MongoDB.
 - * Column based. Example: Cassandra.
 - * Graph. Example: Neo4i.
 - * Kev-value.
- Usually do not require fixed schema and do not use joins.
 - Can be distributed.

- One or more ACID properties are relaxed.
 - **BASE** transactions:
 - * Basically available.
 - * Soft state.
 - * Eventually consistent.
 - Brewer's CAP theorem: a distributed system can support only two of the following:
 - * Consistency.
 - * Availability.
 - * Partition tolerance.
- Compared to SQL: higher scalability and flexibility.