# Implementation of a multithreaded compile-time ECS in C++14







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http://github.com/SuperV1234/meetingcpp2016

#### Overview of the talk

- "Entity-component-system" pattern in general.
- Overview of ECST.
  - Design and core values.
  - Features/limitations.
- Complete usage example.
- Architecture of ECST.
- Implementation of **ECST**.
- Future ideas.



# Entity-component-system

Concepts, benefits and drawbacks of the ECS architectural pattern.





#### What is an **entity**?

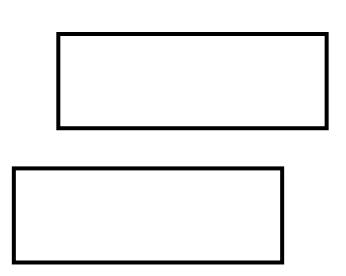
- Something tied to a concept.
- Has related data and/or logic.
- We deal with many entities.
  - We may want to track specific instances.
- Can be created and destroyed.
- Examples:
  - Game objects: player, bullet, car.
  - GUI widgets: window, textbox, button.



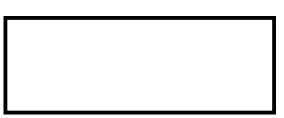
- An entity type is a polymorphic class.
- Data is stored inside the class.
- Logic is handled using runtime polymorphism.
- Very easy to implement.
- Cache-unfriendly.
- Runtime overhead.
- Lack of flexibility.

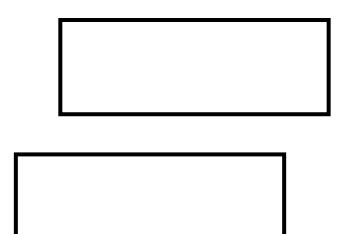


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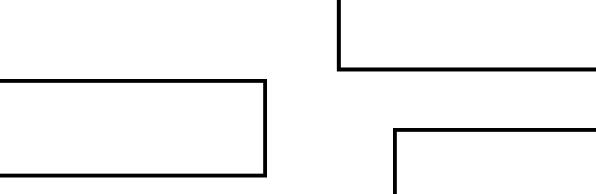
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```
struct Entity
{
    virtual ~Entity() { }
    virtual void update() { }
    virtual void draw() { }
};
```

```
struct Skeleton : Entity
{
    std::vector<Bone> bones;
    void update() override
    {
        // do things skeletons do
    }
};
```

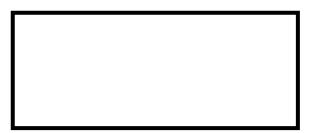
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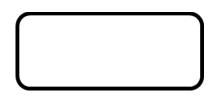
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- Components store data and have logic.
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- More **flexible**.
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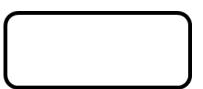


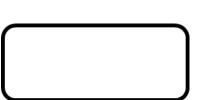
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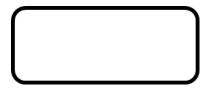


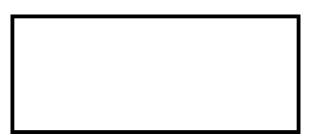




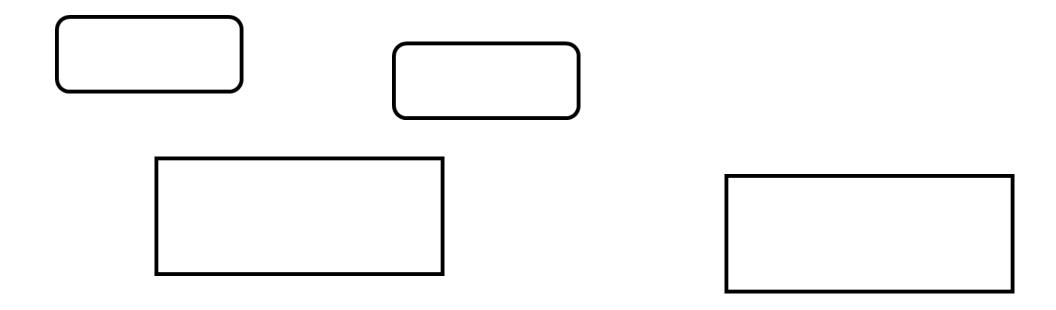


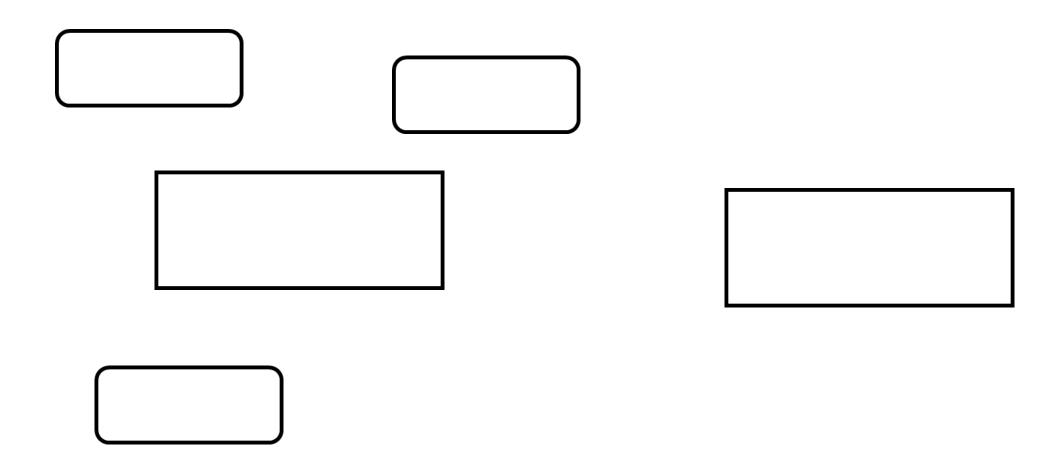


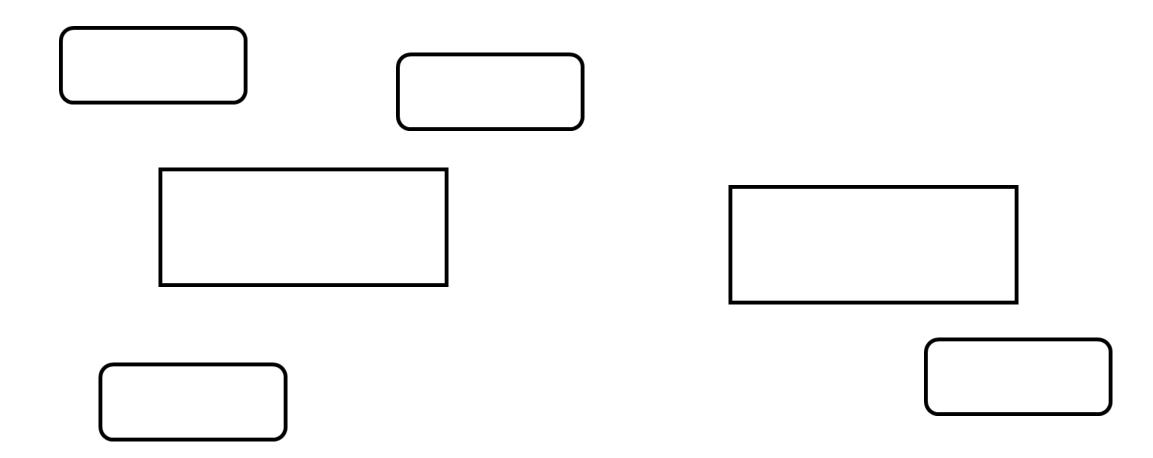


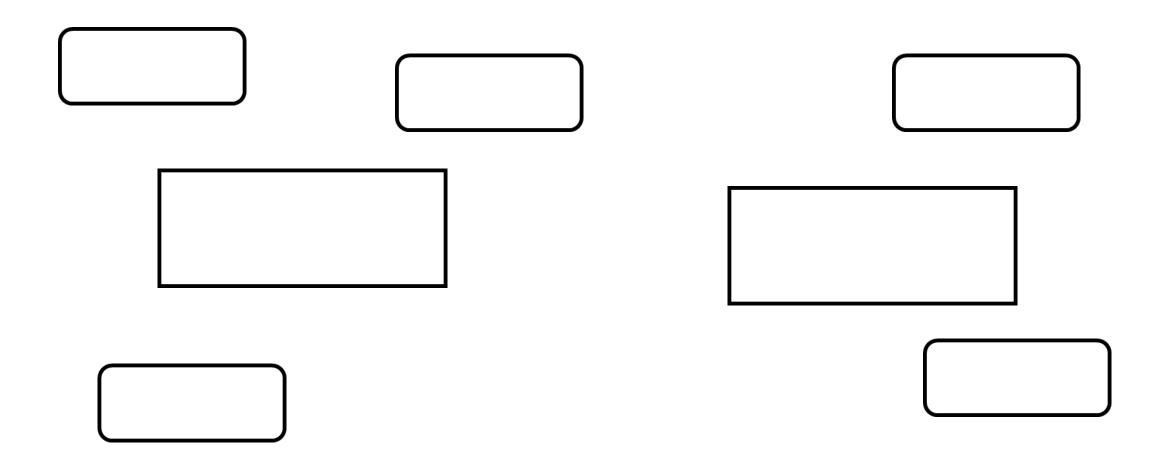


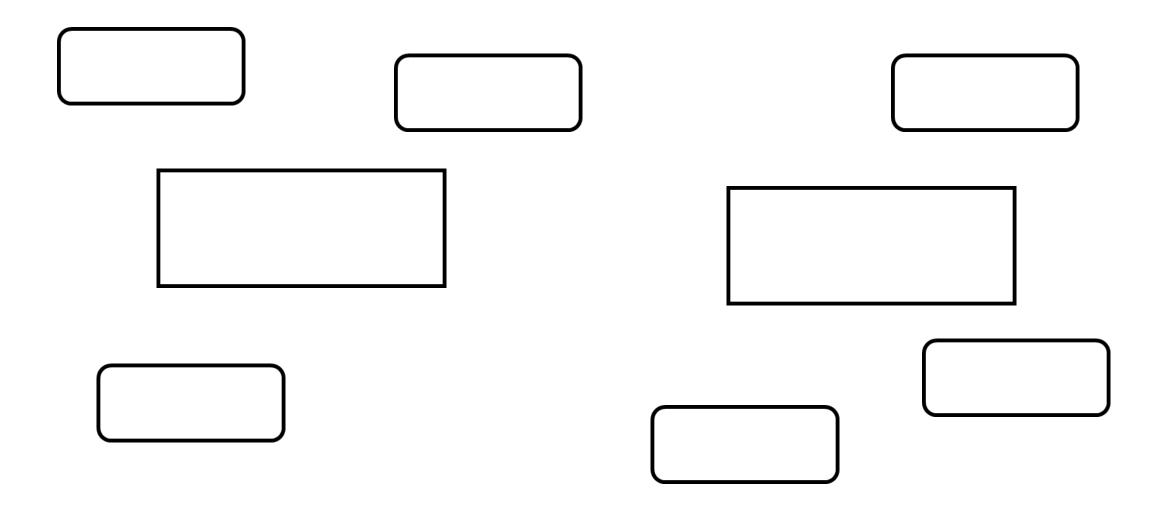












```
struct Component
   virtual ~Component() { }
    virtual void update() { }
    virtual void draw() { }
struct Entity
    std::vector<std::unique ptr<Component>> components;
    void update() { for(auto& c : components) c->update(); }
    void draw() { for(auto& c : components) c->draw(); }
```



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```



```
struct BonesComponent : Component
    std::vector<Bone> bones;
   void update() override
       // do things skeletons do
auto makeSkeleton()
    Entity e;
    e.components.emplace_back(std::make_unique<BonesComponent>());
    return e;
```

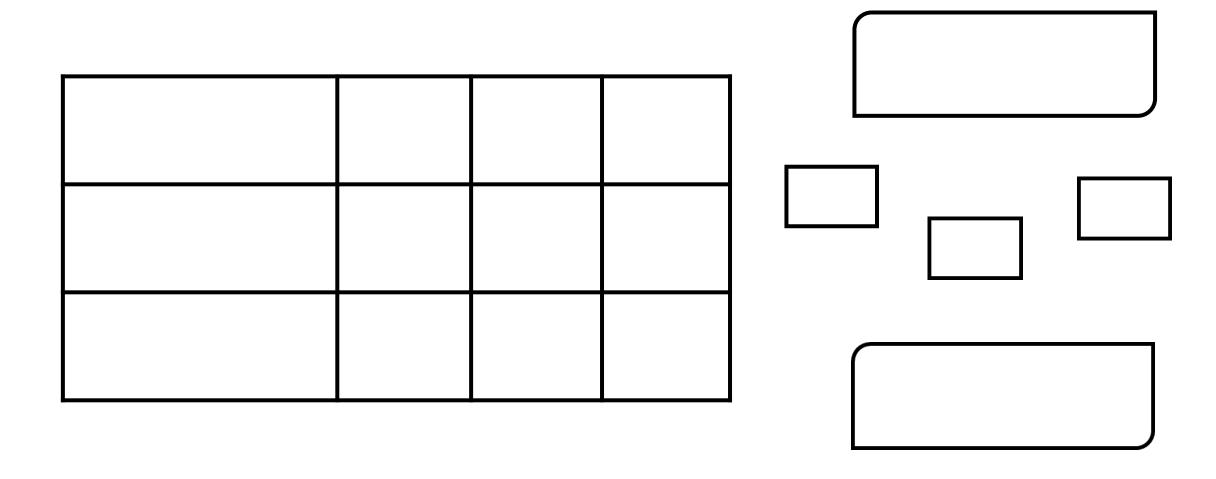


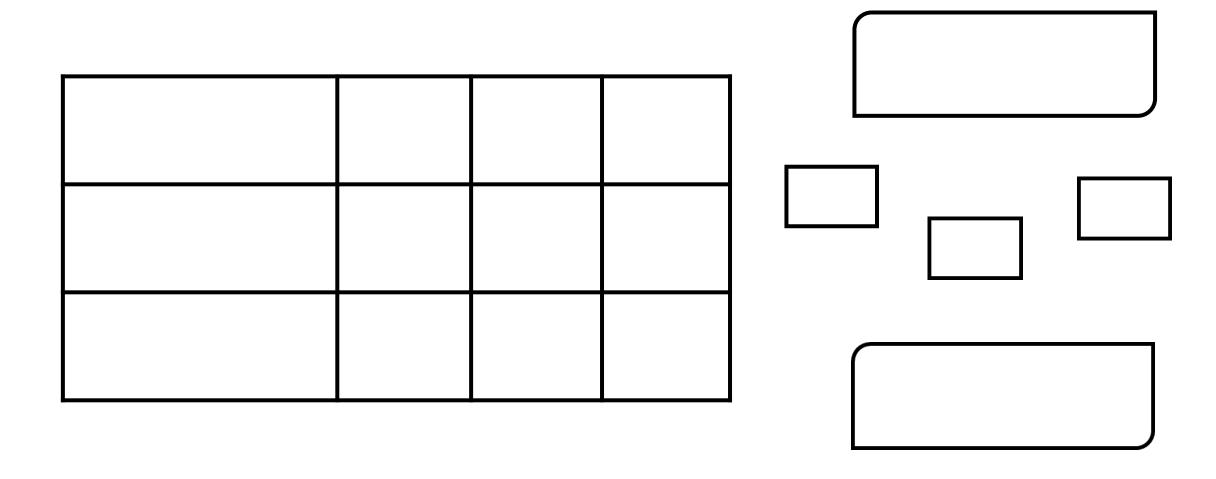
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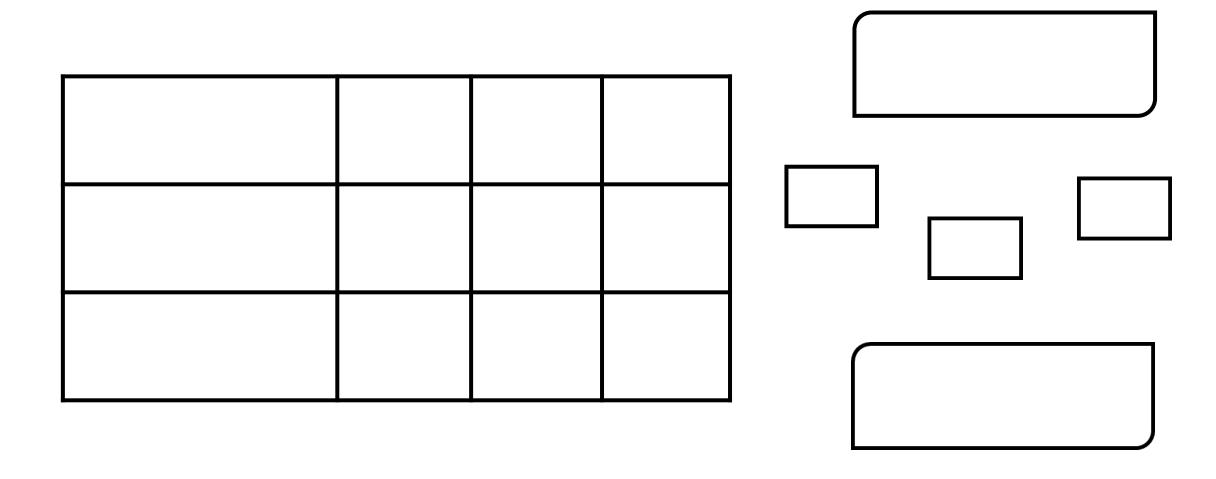


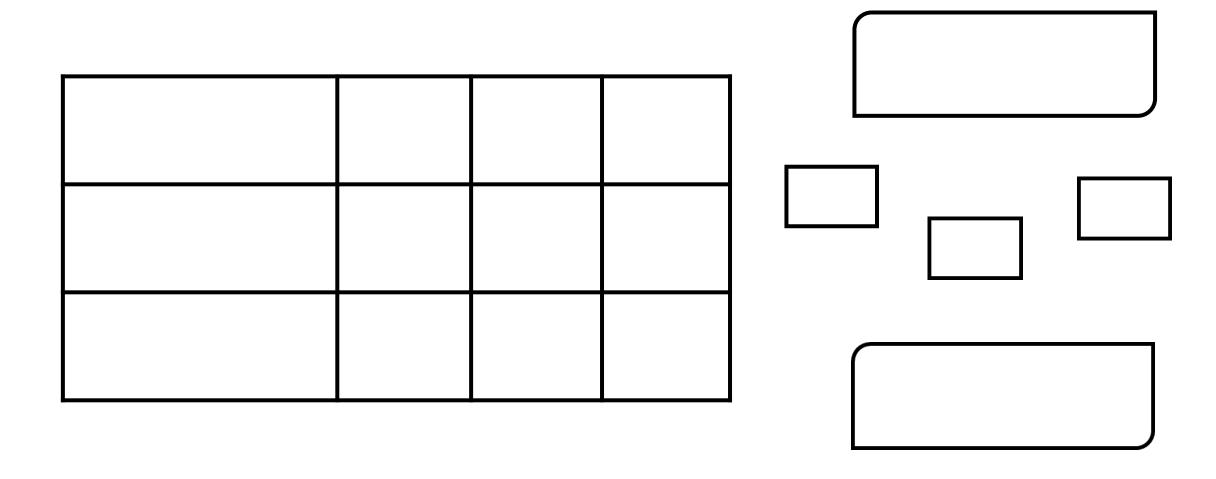
- An entity is a numerical ID.
- Components only store data (logicless).
- Logic is handled using systems.
- Potentially cache-friendly.
- Minimal runtime overhead.
- Great flexibility.
- Hard to implement.

10	NAME	Keyboard	STYLE	Focus	Mouse
0	TEXT BOX	<b>/</b>	/		
7	Button		/		/
2	Browser	<u></u>		<b>/</b>	<b>/</b>

































```
using Entity = std::size t;
constexpr std::size_t maxEntities{1000};
struct BonesComponent { /* ... */ };
struct AIComponent { /* ... */ };
struct SpriteComponent { /* ... */ };
struct Manager
    std::array<BonesComponent, maxEntities> bonesComponents;
    std::array<AIComponent, maxEntities> aiComponents;
    std::array<SpriteComponent, maxEntities> spritesComponents;
// ...
};
```



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// ...
};
```



```
struct SkeletonSystem
   Manager& manager;
   void process()
        manager.forEntitiesWith<AIComponent, BonesComponent>(
            [](auto& data, auto id)
                auto& ai = data.get<AIComponent>(id);
                auto& bones = data.get<BonesComponent>(id);
              // ...
```



# Storing components - one array per type

- Very easy to implement.
- Suitable for most projects.
- Easy to add/remove components at runtime.
- Can be «cache-friendlier».
- Wasteful of memory.

### Storing components – mega-array

- Potentially cache-friendlier.
- Minimizes memory waste.
- Very hard to implement.
  - Requires indexing tables.
  - Hard to deal with component addition/removal.
  - Very hard to keep track of free «slots» in the mega-array.





# ECST in a nutshell

What is it?





#### ECST in a nutshell – basics

- Given some component and system types...
- ECST allows users to **declaratively** define at **compile-time**:
  - Component storage layouts.
    - Used to leverage cache and easily play around with SOA/AOS layouts.
  - Relationships/dependencies between systems.
    - Used to automatically parallelize system execution.
  - Parallelism strategies.
    - System-specific parallelization choices. (e.g. split system **\$0** in 4 sub-tasks)
  - Application-wide settings.
    - (e.g. fixed entity limit VS dynamic entity limit)
- Application logic is completely independent from the choices above.



# **ECST** in a nutshell – declarative settings

- Compile-time data structure: option maps.
  - Made easy thanks to boost::hana!
- User syntax: fluent method chaining.

```
constexpr auto s =
    ecst::settings::make()
        .allow_inner_parallelism()
        .fixed_entity_limit(sz_v<50000>)
        .component_signatures(csl)
        .system_signatures(ssl)
        .scheduler(st::atomic_counter);
constexpr auto ssig_acceleration =
    ss::make(st::acceleration)
        .stateless()
        .parallelism(split_evenly_per_core)
        .read(ct::acceleration)
        .write(ct::velocity);
```

- 1. Define component types and tags.
- 2. Define system types and tags.
- 3. Define component signatures.
- 4. Define **system signatures**.
- 5. Define context settings.
- Instantiate and use ecst::context.
- 7. Access **system interfaces** and **component data** through **proxy objects** provided by the context.

1. Define component types and tags.

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5. Define **context settings**.

Instantiate and use ecst::context.

7. Access **system interfaces** and **component data** through **proxy objects** provided by the context.

Simple C++ classes.

No concepts to satisfy.

No ECST-specific classes to derive from.

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Wrappers around types that

can be used as values.

Equivalent to:

boost::hana::type\_c

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- 6. Instantiate and use ecst::

```
constexpr auto cs_physics =
    cs::make(ct::acceleration, ct::velocity)
        .contiguous_buffer();
```

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```
constexpr auto ssig_render =
    ss::make(st::render)
        .parallelism(none)
        .dependencies(st::velocity)
        .read(ct::position, ct::sprite)
        .output(ss::output<std::vector<Vertex>>);
```

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# ECST in a nutshell - how constexpr auto s =

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# Overview of ECST

Design, features, limitations and examples.





### Core values and concepts

- «Compile-time» ECS.
- Customizable settings/policy-based design.
- User-friendly syntax, independent from settings.
- Multithreading support.
  - Avoid explicit locking.
  - «Dataflow» programming.
- Modern boost::hana metaprogramming.
- Clean, modern and safe C++14.



- Component and system types are known at compile-time.
- Component instances can be created and destroyed at run-time.
- Entities can be created, destroyed and tracked at run-time.
- Combining it with run-time solutions is possible.
- Minimal run-time overhead.
- Better optimization opportunities.
- Longer compilation times.
- Unwieldy error messages.



```
struct position
   float x;
   float y;
};
struct velocity
   float x;
   float y;
};
struct acceleration
   float x;
   float y;
};
```

```
constexpr auto ssig_acceleration =
                             ss::make(st::acceleration)
                                  .stateless()
                                  .parallelism(split_evenly_per_core)
                                  .read(ct::acceleration)
                                  .write(ct::velocity);
struct acceleration
   template <typename TData>
   void process(ft dt, TData& data)
       data.for_entities([&](auto eid)
               auto& v = data.get(ct::velocity, eid). v;
               const auto& a = data.get(ct::acceleration, eid). v;
               v += a * dt;
           });
};
```

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# «Compile-time» ECS – g++ errors

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TSystemSignature = ecst::signature::system::impl:: isk::strategy::split\_evenlu\_fn::impl::parameterscecst::inner\_parallelisk::strategy::split\_evenlu\_fn::v\_cores\_getter>, std::tuplececst::signature::sustek::impl::tag\_implcek ecst::signature::system::impl::read\_imple:example::c::position>, ecst::signature::system::impl::read\_imple:example::c::color> >, ecst::signature::system::output::impl::o\_da instance(TSettings, TSystemSignature)::make\_other\_entity\_range\_provider(vrn::core::sz\_t, vrn::core::sz\_t) [with TSettings = ecst::settings::impl::datacecst::impl::datacecst::settings::impl::datacecst::settings::impl::datacecst::settings::impl::datacecst::settings: plkstd::integral\_constantklong unsigned int, 20000ul> >, std::tuplekecst::signature::component::impl::datakecst::signature::component::impl::tag\_implkexample::c::position locity> >, ecst::signature::component::impl::datakecst::signature::component::impl::tag\_implkexample::c::acceleration> >, ecst::signature::component::impl::datakecst::sign gnature::component::impl::tag\_implexample::c::circle> >, ecst::signature::component::impl::datakecst::signature::component::impl::tag\_implexample::c::mass> > >, std::tu ion», ecst::inner\_parallelisn::strategy::split\_evenly\_fn::inpl::paraneterskecst::inner\_parallelisn::strategy::split\_evenly\_fn::v\_cores\_getter», std::tuplek», std::tuplekec plkexample::c::acceleration> >, ecst::signature::system::output::impl::o\_none>, ecst::signature::system::impl::datakecst::signature::system::impl::tag\_implkexample::s::ve :strategy::split\_evenly\_fn::v\_cores\_getter>, std::tuplexecst::signature::system::impl::tag\_implxexample::s::acceleration> >, std::tuplexecst::signature::system::impl::mut ::signature::system::output::impl::o\_none>, ecst::signature::system::impl::datakecst::signature::system::impl::tag\_implkexample::s::keep\_in\_bounds>, ecst::inner\_paralleli; 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TSystemSignature = ecst::signature::system::impl::datakecst::signature::system::imp pl::parameters.ecst::inner\_parallelism::stratequ::split\_evenlu\_fn::v\_cores\_getter>, std::tuple.ecst::signature::sustem::impl::tag\_implkexample::s::solve\_contacts> >, std: ad\_implexample::c::position>, ecst::signature::system::impl::read\_implexample::c::color> >, ecst::signature::system::output::impl::o\_datakstd::vectorksf::Vertex> > >; v settings::impl::datakecst::settings::impl::threading::multikecst::settings::impl::system\_parallelism::enabled>, ecst::settings::impl::fixed\_implestd::integral\_constantklo ent::impl::taq\_implkexample::c::position> >, ecst::signature::component::impl::datakecst::signature::component::impl::taq\_implkexample::c::velocity> >, ecst::signature::c nature::component::impl::datacecst::signature::component::impl::tag\_implcexample::c::color> >, ecst::signature::component::impl::datacecst::signature::component::impl::ta :tag\_implexxmple::c::mass> > >, std::tuplexecst::signature::system::impl::dataxecst::signature::system::impl::tag\_implexxmple::s::acceleration>, ecst::inner\_parallelism res\_getter>, std::tuple<>, std::tuple<ecst::signature::sustem::impl::mutate\_imple::c::velocity>, ecst::signature::sustem::impl::read\_imple::c::acceleration>





# «Compile-time» ECS – clang++ errors

```
pres_code.cpp:116:70: error: no member named '_x' in 'example::c::position'
                         const auto& p0 = data.qet(ct::position, eid)._x;
/home/vittorioromeo/OMNorkspace/ecs_thesis/project/include/ecst/context/./system/./instance/instance.inl:112:32: note: in ins
      'example::s::render_colored_circle::process(ecst::context::system::impl::execute_datakecst::signature::system::impl::da
      ecst::inner_parallelism::strateqy::split_evenly_fn::impl::parameterskecst::inner_parallelism::strateqy::split_evenly_fn
      std::tuplekecst::signature::system::iмpl::read_iмplkexample::c::circle>, ecst::signature::system::iмpl::read_iмplkexamp
      ecst::signature::system::output::impl::o_datakstd::vectorksf::Vertex, std::allocatorksf::Vertex>>>>, ecst::context::
      ecst::settings::iмpl::fixed_iмpl<std::integral_constant<unsigned long, 20000> >, std::tuple<ecst::signature::сомропепt:
      ecst::signature::cомponent::iмpl::datakecst::signature::cомponent::iмpl::tag_iмplkexample::c::velocity> >, ecst::signat
      ecst::signature::cомponent::iмpl::datakecst::signature::cомponent::iмpl::tag_iмplkexample::c::color> >, ecst::signature
      ecst::signature::component::impl::datakecst::signature::component::impl::taq_implkexample::c::mass> > >, std::tuplekecs
      ecst::inner_parallelism::strateqy::split_evenly_fn::impl::parameterskecst::inner_parallelism::strateqy::split_evenly_fn
      ecst::signature::system::impl::read_implkexample::c::acceleration> >, ecst::signature::system::output::impl::o_none>,
      ecst::inner_parallelism::strategy::split_evenly_fn::impl::parameterskecst::inner_parallelism::strategy::split_evenly_fn
      std::tuplekecst::signature::system::impl::mutate_implkexample::c::position>, ecst::signature::system::impl::read_implke
      ecst::signature::system::impl::datakecst::signature::system::impl::tag_implkexample::s::keep_in_bounds>, ecst::inner_pa
      std::tuplekecst::signature::systeм::iмpl::tag_iмplkexaмple::s::velocity> >, std::tuplekecst::signature::systeм::iмpl::м
      ecst::signature::system::impl::read_implkexample::c::circle> >, ecst::signature::system::output::impl::o_none>, ecst::s
      ecst::inner_parallelism::strategy::split_evenly_fn::impl::parameterskecst::inner_parallelism::strategy::split_evenly_fn
      std::tuplekecst::signature::system::impl::read_implkexample::c::position>, ecst::signature::system::impl::read_implkexa
      ecst::signature::system::impl::datakecst::signature::system::impl::tag_implkexample::s::filler>, ecst::inner_parallelis
      ecst::signature::system::output::impl::o_noné>, ecst::signature::systém::impl::datakecst::signature::system::impl::tag_
ecst::inner_parallelism::strategy::split_evenly_fn::impl::parameterskecst::inner_parallelism::strategy::split_evenly_fn
      std::tuplekecst::signature::system::impl::mutate_implkexample::c::velocity>, ecst::signature::system::impl::mutate_impl
      ecst::signature::sustem::outnut::impl::o datakstd::vectorkexample::contact. std::allocatorkexample::contact> > > . ecs
```





#### «Compile-time» ECS – camomilla-processed errors

```
required from 'woid example::s
/pres_code.cpp:241:17:
./pres_code.cpp:871:29: required from 'example::update
 ecst::context::impl::datax?>;    TRenderTarget = sf::Rend
/hone/vittorioroneo/OHNorkspace/ecst/include/./ecst/./sy
ecst::context::system::data_proxy::multic?>; auto:75 =
ntext = ecst::context::impl::datac?>;    TRenderTarget
nplc?>, ecst::tag::system::inpl::tag_inplc?>)]::<?>]'
```





#### «Compile-time» ECS – camomilla-processed errors

```
<u>code.cpp:871:29:</u>
     :::context::impl::data<?>;
     /vittorioroneo/OHNorkspace/e
    ::context::system::data_proxx,:multic?>; and
    = ecst::context::impl::datac?>; TRenderTarg_t
mplc?>, ecst::tag::system::impl::tag_implc?>)]::<?>]'
```





#### «Compile-time» ECS – camomilla-processed errors



http://github.com/SuperV1234/camomilla





#### Customizable settings/policy-based design

- Behavior and storage layouts can be chosen at compile-time.
- Library users can create their own settings easily, including:
  - Scheduling algorithms.
  - Parallelization strategies.
  - Entity and component data structures.
- Focus on composability.

```
template <typename TComponent>
class hash map
public:
    using entity id = ecst::impl::entity id;
    using component type = TComponent;
    struct metadata
private:
    std::unordered map<sz t, TComponent> data;
    auto valid_index(sz t i) const noexcept
        return _data.count(i) > 0;
    auto entity_id_to_index(entity id eid) const noexcept
        return vrmc::to_sz_t(eid);
    template <typename TSelf>
    decltype(auto) get impl(
        TSelf&& self, entity_id eid, const metadata&) noexcept
        auto i = self.entitv id to index(eid):
```

# Syntax: independent from settings

 Chosen settings and strategies do not affect the syntax of the application logic.

```
proxy.execute_systems_overload( // .
    [](s::acceleration& s, auto& data)
    {
        s.process(data);
    },
    [](s::velocity& s, auto& data)
    {
        s.process(data);
    },
    [&window](s::rendering& s, auto& data)
    {
        s.process(window, data);
    });
}
```

- Enabled by default, customizable and can be optionally disabled.
- Two levels of parallelism:
  - Outer: independent system chains can run in separate parallel tasks.
  - Inner: system logic can be independently performed on entity subsets in separate tasks.



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- Types can be wrapped into values and vice versa.
- Greatly simplifies metaprogramming and compile-time computations.
- Core principle of **boost::hana**.

```
constexpr auto parallelism_policy =
   ipc::none_below_threshold::v(sz_v<10000>,
        ips::split_evenly_fn::v_cores()
   );
```



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```
constexpr auto parallelism_policy =
   ipc::none_below_threshold::v(sz_v<10000>,
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    );
```

Number wrapped in a compile-time type. Can be passed around as a value at compile-time.



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    );
```

Type wrapped into a constexpr value. Can be passed around as a value at compile-time.



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   );
```



```
/// @brief Given a list of system tags, returns a list of system IDs.
template <typename TSystemSignatureList, typename TSystemTagList>
constexpr auto tag_list_to_id_list(
    TSystemSignatureList ssl, TSystemTagList stl)
{
    return boost::hana::transform(stl, [ssl](auto x)
    {
        return signature_list::system::id_by_tag(ssl, x);
    });
}
```



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    });
}
```



# Code example.

Simple particle simulation implemented using ECST.





# Architecture of ECST.

"Components" of the entity component system.





# CONTEXT MAIN STORAGE SYSTEM MANAGER REFRESH STATE

```
constexpr auto component_signatures = setup_components();
constexpr auto system_signatures = setup_systems();
constexpr auto context_settings =
    setup_settings(component_signatures, system_signatures);
auto ctx = ecst::context::make(context_settings);
```

 Movable class that aggregates the main components of ECST.

# CONTEXT MAIN STORAGE SYSTEM MANAGER REFRESH STATE

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```

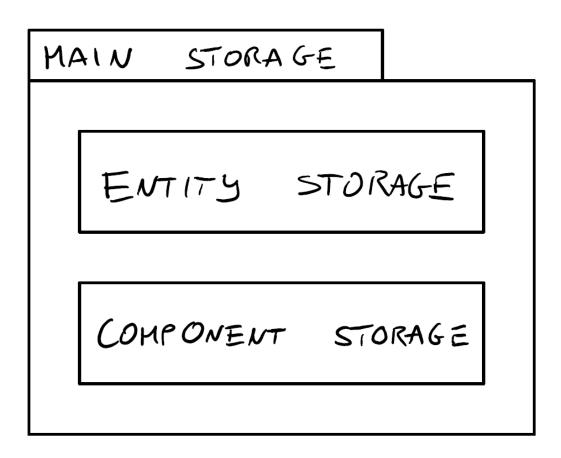
 Movable class that aggregates the main components of ECST.

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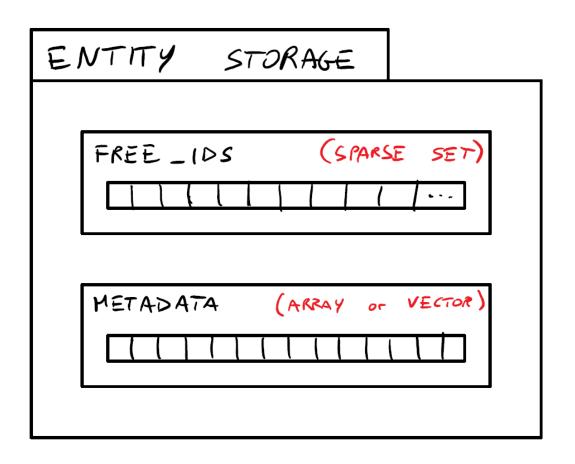
 Movable class that aggregates the main components of ECST.

#### Context -> Main Storage



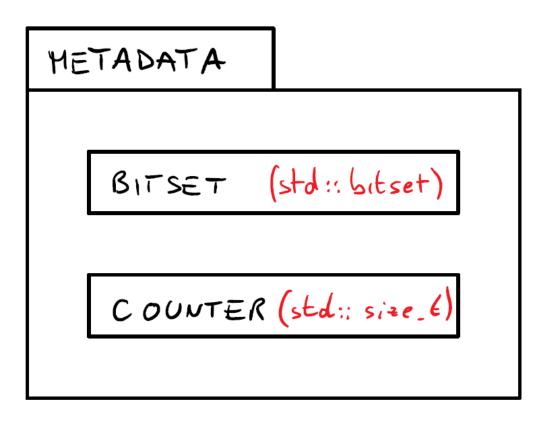
- Encapsulates entity storage, which deals with entity IDs and metadata.
- Encapsulates **component storage**, which deals with component data and component storage strategies.

#### Context -> Main Storage -> Entity Storage



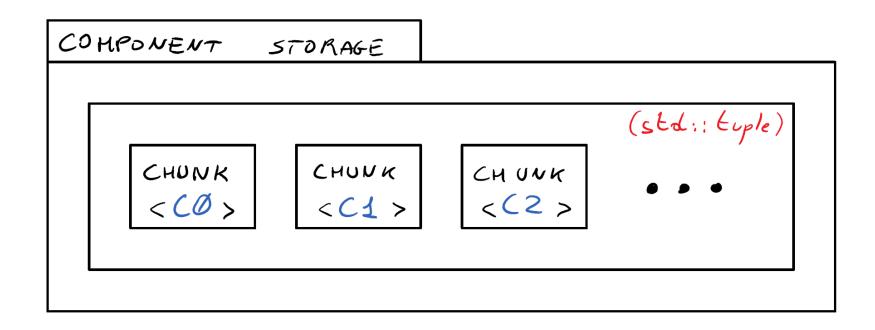
- Keeps track of used and unused entity IDs.
- Manages entity metadata.
  - Entity metadata may be enriched by component-container-specific metadata at compile-time.

### Context -> Main Storage -> Entity Storage -> Metadata



- Component bitset: keeps track of current components.
- Validity counter: differentiates entity instances which re-use a previous ID. Handles check the counter to prevent access to re-used entities.
- Eventual component storage metadata.

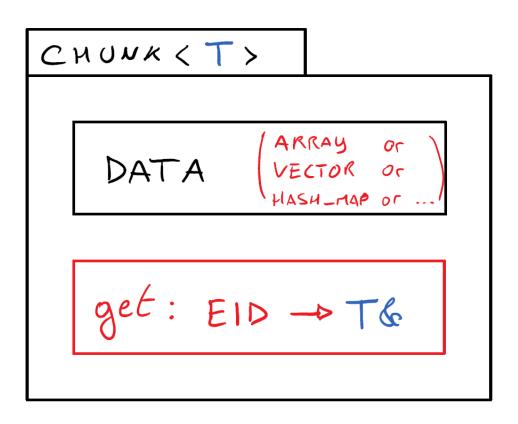
# Context -> Main Storage -> Component Storage



- Stores a tuple of component storage chunks.
  - Every chunk stores a specific component type in a specific data structure.

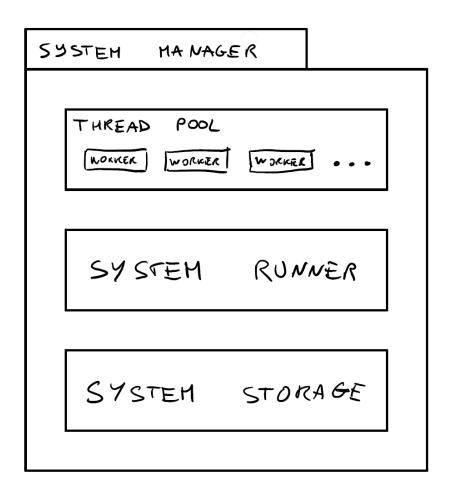


#### Context -> Main Storage -> Component Storage -> Chunk



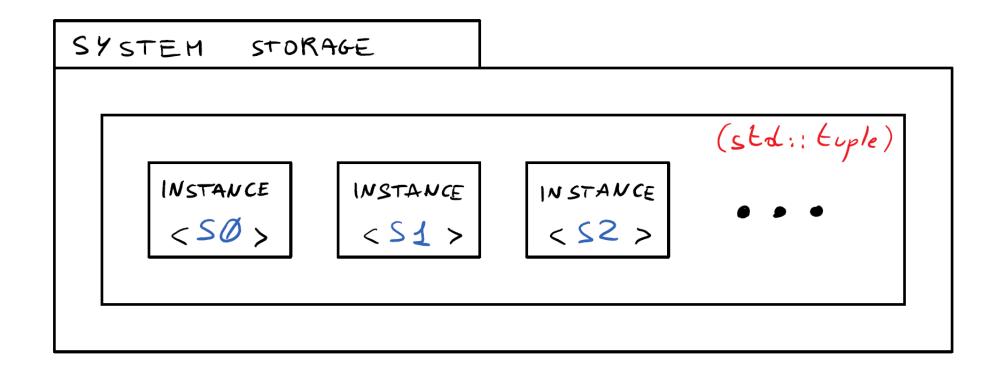
- Manages component data for a particular component type.
- Provides a way to retrieve component data by entity ID.

# Context -> System Manager



- Contains a **thread pool**, used to execute system logic.
- Contains a system runner which provides a nice interface for a system scheduler.
- Stores system instances and relative metadata in the system storage.

# Context -> System Manager -> System Storage



• Stores a **tuple** of **system instances**, one per system type.

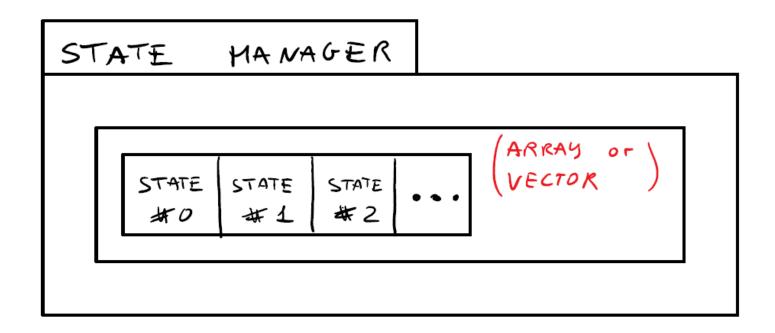


#### Context -> System Manager -> System Storage -> Instance



- Contains an instance of the "real" system type.
- Manages N subtasks states through the state manager.
- Keeps track of subscribed entities.
- Contains a inner parallelism executor instance.
- Contains a **bitset** representing the required components.

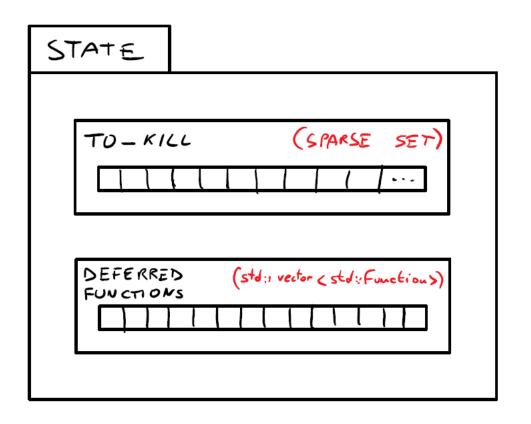
#### Context -> System Manager -> ... -> Instance -> State Manager



- Manages a number of states, that can change at run-time.
  - Every state is connected to a **subtask**.
    - Subtasks are executed in separate threads.



#### Context -> System Manager -> ... -> State Manager -> State



- Contains a set of entity IDs that will be killed during the next refresh step.
- Contains a vector of deferred functions that will be executed sequentially during the next refresh step.
- Optionally contains user-defined system output data.

# Implementation of ECST.

Challenges, execution flow, multithreading, and metaprogramming.



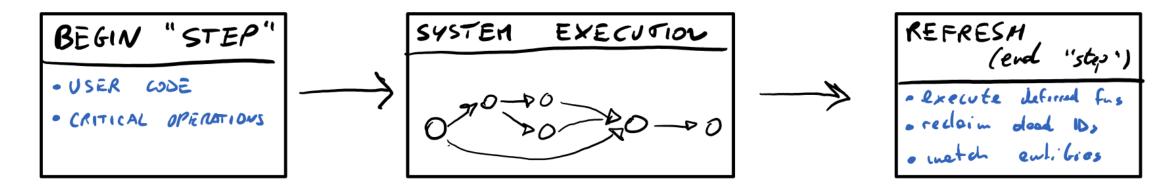


# Implementation details overview

- Execution flow and critical operations.
- Implementation challenges.
- System processing.
  - Multithreading details.
  - System scheduling (outer parallelism).
  - System inner parallelism.
- Proxies.
- Metaprogramming module examples.



#### Flow - overview



- System execution is preceded by a step, where critical operations can occur.
- After system execution, a **refresh** takes place, during which:
  - Deferred critical operations are executed.
  - Dead entity IDs are reclaimed.
  - New and modified entities are matched to systems.



# Flow - critical operations

- Operations that need to be executed sequentially in a separate final step are referred to as "critical".
  - Critical operations can be queued and deferred to a later step during system logic execution.
- Critical operations:
  - Creating or destroying an entity.
  - Adding or removing a component to/from an entity.
  - Running the system scheduler.
- Non-critical operations:
  - Analyzing/using a dependency's output system data.
  - Marking an entity as dead.
  - Accessing and mutating existing component data.



```
struct collision effects
   template <typename TData>
   void process(TData& data)
        data.for_entities([&](auto eid)
            const auto& contacts =
                data.get_previous_output(st::collision_detection);
            if(contacts.was_hit(eid))
                auto& h = data.get(ct::health, eid);
                h.damage();
                if(h.dead()) data.kill_entity(eid);
                data.defer([&](auto& proxy)
                    auto e = proxy.create_entity();
                    e.add_component(ct::effect_particle)
                        .set_effect(effects::explosion);
                });
        });
};
```

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                auto& h = data.get(ct::health, eid);
                h.damage();
                if(h.dead()) data.kill_entity(eid);
                data.defer([&](auto& proxy)
                    auto e = proxy.create_entity();
                    e.add_component(ct::effect_particle)
                        .set_effect(effects::explosion);
                });
        });
};
```

```
struct collision effects
   template <typename TData>
   void process(TData& data)
        data.for_entities([&](auto eid)
            const auto& contacts =
                data.get_previous_output(st::collision_detection);
            if(contacts.was_hit(eid))
                auto& h = data.get(ct::health, eid);
                h.damage();
                if(h.dead()) data.kill_entity(eid);
                data.defer([&](auto& proxy)
                    auto e = proxy.create_entity();
                    e.add_component(ct::effect_particle)
                        .set_effect(effects::explosion);
                });
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                        .set_effect(effects::explosion);
                });
        });
};
```

```
context.step([&](auto& proxy)
    proxy.system(st::render).prepare();
    proxy.execute_systems_overload(
        [dt](s::physics& s, auto& data){ s.process(dt, data); },
        [](s::render& s, auto& data){ s.process(data); });
    proxy.for_system_outputs(st::render,
        [&window](auto& s, auto& va)
            window.draw(va.data(), va.size(),
                PrimitiveType::Triangles, RenderStates::Default);
        });
});
```

```
context.step([&](auto& proxy)
    proxy.system(st::render).prepare();
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        [dt](s::physics& s, auto& data){ s.process(dt, data); },
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            window.draw(va.data(), va.size(),
                PrimitiveType::Triangles, RenderStates::Default);
        });
});
```

# Challenges

- Efficient management of entity IDs.
- Exploiting compile-time knowledge to increase performance and safety.
- Executing systems respecting dependencies between them and using parallelism when possible.
- Processing entities subsets of the same system in different threads.
- Dealing with entity/component addition/removal during system execution.
- Providing a clean and safe interface to the user.



### Sparse Integer Sets

- Extremely useful data structure to deal with entity ID management.
- Conceptually represents a set of unsigned integers.
- Allows:
  - **0(1)** test, insertion and removal.
  - **O(k)** iteration, where **k** is the number of integers in the set.

Used in system instances
 (subscribed entities) and in
 entity storage (available IDs).

```
/// @brief Sparse integer set, with fixed array storage.
template <typename T, sz_t TCapacity>
using fixed_array_sparse_set = impl::base_sparse_set<
   impl::sparse_set_settings<
     T,
     impl::sparse_set_storage::fixed_array<T, TCapacity>
     >;
```

### Sparse Integer Sets



# Data structure static dispatching – user syntax

- Users can choose settings at compile-time that can restrict the functionality of ECST in order to achieve superior performance.
- Example: max entity limit.

```
constexpr auto s =
    ecst::settings::make()
    .allow_inner_parallelism()
    .fixed_entity_limit(sz_v<50000>)
    .component_signatures(csl)
    .system_signatures(ssl)
    .scheduler(st::atomic_counter);
constexpr auto s =
    ecst::settings::make()
    .allow_inner_parallelism()
    .dynamic_entity_limit()
    .component_signatures(csl)
    .system_signatures(ssl)
    .system_signatures(ssl)
    .scheduler(st::atomic_counter);
```



# Data structure static dispatching – user syntax

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- Example: max entity limit.

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    .system_signatures(ssl)
    .system_signatures(ssl)
    .scheduler(st::atomic_counter);
```



- The "fluent" syntax is implemented using option maps.
- They are implemented on top of boost::hana::map.
- They map a compile-time key to a compile-time value and a compile-time boolean.
- The boolean prevents setting the multiple option twice.



```
namespace keys
{
    constexpr auto threading = sz_v<0>;
    constexpr auto entity_storage = sz_v<1>;
    constexpr auto component_signature_list = sz_v<2>;
    constexpr auto system_signature_list = sz_v<3>;
    constexpr auto scheduler = sz_v<4>;
    constexpr auto refresh_parallelism = sz_v<5>;
}
```



```
namespace keys
{
    constexpr auto threading \( \section \);
    constexpr auto entity_storage \( \section \) sz_v<1>;
    constexpr auto component_signature_list \( \section \) sz_v<2>;
    constexpr auto system_signature_list \( \section \) sz_v<3>;
    constexpr auto scheduler \( \section \) sz_v<4>;
    constexpr auto refresh_parallelism \( \section \) sz_v<5>;
}
```

Every key has a unique type.



```
template <typename TOptions>
class context_settings
    TOptions _map;
    template <typename TKey, typename T>
    constexpr auto change_self(const TKey& key, T x) const noexcept
        auto new_options = _map.set(key, x);
        return data<decltype(new options)>{};
public:
    template <typename T>
    constexpr auto set_threading(T x) const noexcept
        return change self(keys::threading, x);
```



```
template <typename TOptions>
class context_settings
   TOptions _map;
   template <typename TKey, typename T>
   constexp( auto )thange_self(const TKey& key, T x) const noexcept
       auto new options = map.set(key, x);
       return data<decltype(new options)>{}
                           Changing an option creates a new type.
public:
   template <typename T>
   constexp( auto set_threading(T x) const noexcept
       return change self(keys::threading, x);
```



### Data structure static dispatching – option maps

```
template <typename TKey, typename T>
constexpr auto option_map::set(const TKey& key, T x) const noexcept
   // Prevent setting same setting twice.
    static assert(
       bh::second(bh::at_key( map, key)) == bh::false c);
    auto new map = impl::replace( map,
        bh::make_pair(key, bh::make_pair(x, bh::true c)));
   return option map<decltype(new map)>{};
```



## Data structure static dispatching - dispatching

```
template <typename TSettings, typename TFFixed, typename TFDynamic>
auto dispatch_on_storage_type(
    TSettings && s, TFFixed && f_fixed, TFDynamic && f_dynamic)
    return static_if(s.has_fixed_capacity())
        .then([f fixed = FWD(f fixed)](auto xs)
                auto capacity = xs.get_fixed_capacity();
                return f_fixed(capacity);
        .else_([f dynamic = FWD(f dynamic)](auto xs)
                auto initial capacity = xs.get dynamic capacity();
                return f_dynamic(initial capacity);
            })(s);
```



### Data structure static dispatching - dispatching



```
constexpr auto ssig acceleration =
    ss::make(st::acceleration)
        .stateless()
        .parallelism(split evenly per core)
        .read(ct::acceleration)
        .write(ct::velocity);
                                  constexpr auto ssig velocity =
                                      ss::make(st::velocity)
                                          .parallelism(split_evenly_per_core)
                                          .dependencies(st::acceleration)
                                          .read(ct::velocity)
                                          .write(ct::position);
                                                         constexpr auto ssig render =
                                                             ss::make(st::render)
                                                                 .parallelism(none)
                                                                 .dependencies(st::velocity)
                                                                 .read(ct::position, ct::sprite)
                                                                 .output(ss::output<std::vector<Vertex>>);
```



```
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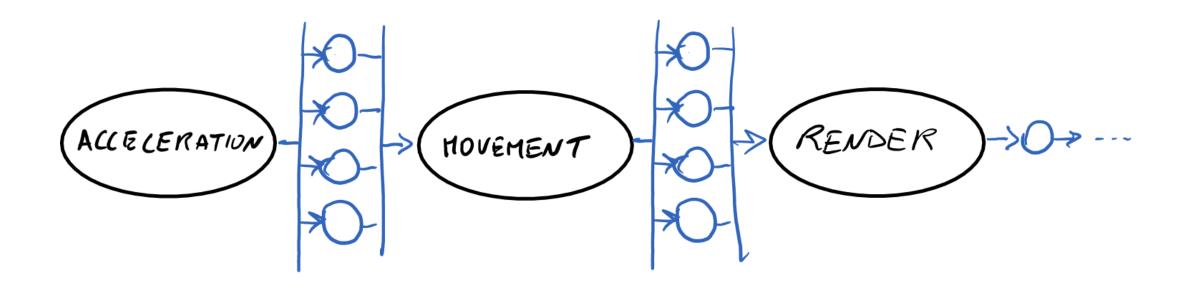
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```



 An implicit directed acyclic graph is built thanks to the compile-time system signatures.





```
struct acceleration
    template <typename TData>
    void process(ft dt, TData& data)
        data.for_entities([&](auto eid)
                auto& v = data.get(ct::velocity, eid)._v;
                const auto& a = data.get(ct::acceleration, eid). v;
               v += a * dt;
            });
```



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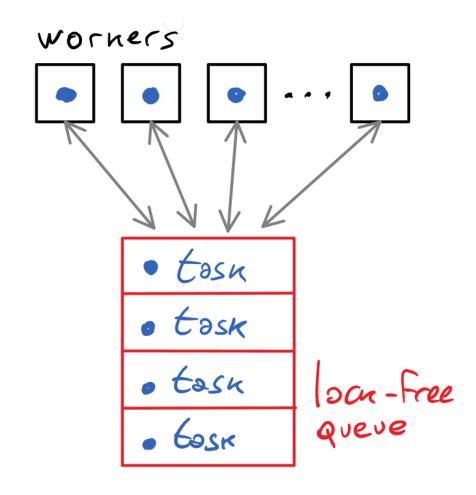


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                auto& v = data.get(ct::velocity, eid)._v;
                const auto& a = data.get(ct::acceleration, eid). v;
               v += a * dt;
            });
```



## Multithreading details

- Avoid busy waiting, use condition variables.
- Use thread pooling with a fast lock-free concurrent queue.
- Avoid futures, use atomic counters with condition variables to wait for tasks to complete.





## Multithreading details – lock-free queue

- moodycamel::BlockingConcurrentQueue
  - By Cameron Desrochers (cameron314 on GitHub).
    - <a href="https://github.com/cameron314/concurrentqueue">https://github.com/cameron314/concurrentqueue</a> (Simplified BSD License)

```
template <typename TF>
void pool::post(TF&& f)
{
    _queue->enqueue(std::move(f));
}
```

```
void worker::run()
{
    task t;

while(_running)
    {
        // Dequeue (blocking) and execute.
        _queue->wait_dequeue(_queue.ctok(), t);
        t();
    }

_finished = true;
}
```

- Condition variables and counters are used to wait for multiple tasks to complete.
  - Used both in system scheduling and in inner parallelism.
- The latch struct aggregates a mutex, a condition variable and a counter.

```
{
    latch l{n};

    l.execute_and_wait_until_zero(cb, []
        {
            run_tasks(n);
        });
}
```

- Condition variables and counters are used to wait for multiple tasks to complete.
  - Used both in system scheduling and in inner parallelism.
- The latch struct aggregates a mutex, a condition variable and a counter.

std::experimental::latch



```
class latch
private:
    std::condition_variable _cv;
    std::mutex _mutex;
    std::size_t counter;
public:
    latch(std::size_t initial count) noexcept;
    void decrement_and_notify_one() noexcept;
    void decrement_and_notify_all() noexcept;
    template <typename TF>
    void execute_and_wait_until_zero(TF&& f);
```

- latch is essentially a simple abstraction to prevent busy waiting.
- Clean «interface»
   functions that take it as
   a parameter are defined
   for convenience and
   safety.

```
/// @brief Accesses `cv` and `c` through a `lock_guard` on `mutex`, and
/// calls `f(cv, c)`.
template <typename TF>
void access_cv_counter(
    mutex_type& mutex, cv_type& cv, counter_type& c, TF&& f) noexcept
{
    std::lock_guard<std::mutex> l(mutex);
    f(cv, c);

    // Prevent warnings.
    (void)l;
}
```

- Access to the counter is synchronized thanks to a lock\_guard that locks the mutex contained in the counter blocker.
- The passed function will be executed after locking, to prevent mistakes and explicit locking.



 This is how the counter is decremented and the waiting threads are notified.

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```
/// @brief Locks `mutex`, executes `f` and waits until `predicate`
/// through `cv`.
template <typename TPredicate, typename TF>
void execute_and_wait_until(mutex_type& mutex, cv_type& cv,
    TPredicate&& predicate, TF&& f) noexcept
{
    std::unique_lock<std::mutex> l(mutex);
    f();
    cv.wait(l, FWD(predicate));
}
```

- The above function is used to wait for a predicate to become true.
- As previously seen, a function is passed to avoid mistakes, explicit locking and explicit waiting.



## System scheduling

- Current scheduling policy: "atomic counter".
  - Explored alternative: when\_all(...).then(...) chain generation.
- The scheduler uses a **remaining systems** latch which keeps track of how many systems have been executed.
  - The caller thread blocks until all systems' executions have been completed.
- Every system instance uses a **remaining dependencies** atomic counter.
  - In the beginning, all instances with **zero** dependencies are executed.
  - As soon as an instance is done, all dependents' counters are decremented.
    - If a dependency counter reaches zero, that instance is executed.



## System scheduling - scheduler

```
template <typename TContext, typename TStartSystemTagList, typename TF>
void atomic_counter::execute(TContext& ctx, TStartSystemTagList sstl, TF& f)
   // Number of unique nodes traversed starting from every node in `sstl`.
    constexpr auto chain size(
        signature_list::system::chain_size(ssl(), sstl));
   // Aggregates the required synchronization objects.
    latch b(chain size);
   // Starts every independent task and waits until the remaining tasks
   // counter reaches zero.
    b.execute and wait until zero([&]
           this->start_execution(ctx, sstl, b, f);
        });
```

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   // Starts every independent task and waits until the remaining tasks
   // counter reaches zero.
    b.execute and wait until zero([&]
           this->start_execution(ctx, sstl, b, f);
        });
```

```
void task<TDependencyData>::run(TTaskGroup& tg, TLatch& b, TID my id,
                                TContext& ctx, TF& f)
    auto& s_instance(ctx.instance_by_id(my id));
    s instance.execute(ctx, f);
    b.decrement_and_notify_one();
   // For every dependent task ID...
    dependency_data().for_dependent_ids([this, &tg, &b, &ctx, &f](auto id) {
        // ...retrieve the corresponding task.
        auto& dt = tg.task_by_id(id);
       // Then, inform the task that one of its dependencies (the
       // current task) has been executed.
        if(dt.dependency_data().decrement_and_check())
            // Recursively run the dependent instance if all dependencies have
           // been processed.
            ctx.post_in_thread_pool([&] { dt.run(tg, b, id, ctx, f); });
    });
```

```
void task<TDependencyData>::run(TTaskGroup& tg, TLatch& b, TID my id,
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                                  TContext& ctx, TF& f)
    auto& s_instance(ctx.instance_by_id(my_id));
    s instance.execute(ctx, f);
    b.decrement and notify one();
    // For every dependent task ID...
    dependency_data().for_dependent_ids([this, &tg, &b, &ctx, &f](auto id) {
                                                   context.step([&](auto& proxy)
        // ...retrieve the corresponding task.
        auto& dt = tg.task_by_id(id);
                                                      proxy.system(st::render).prepare();
                                                      proxy.execute_systems_overload(
        // Then, inform the task that one of it.
                                                          [dt](s::physics& s, auto& data){ s.process(dt, data); },
        // current task) has been executed.
                                                          [](s::render& s, auto& data){ s.process(data); });
        if(dt.dependency_data().decrement_and_c
            // Recursively run the dependent instance if all dependencies have
            // been processed.
            ctx.post_in_thread_pool([&] { dt.run(tg, b, id, ctx, f); });
    });
```

### System inner parallelism

- Every running system instance can be split in subtasks.
  - The instance has a counter of running subtasks.
  - As soon as a subtask is finished, the counter is decremented.
  - A latch is used to wait for the counter to become zero.
- Splitting strategies can be composed at compile-time and extended by the users.
  - Strategy executors can be stateful.
    - Motivating example: self-profiling executor that chooses between single-threaded and multi-threaded system execution during application run-time.



## System inner parallelism – parallel execution

```
template <typename TSettings, typename TSystemSignature>
template <typename TContext, typename TF>
void instance<TSettings, TSystemSignature>::execute_in_parallel(
    TContext & ctx, TF && f
    )
{
    // Aggregates synchronization primitives.
    _parallel_executor.execute(*this, ctx, f);
}
```

- System inner parallel execution is done through a **parallel executor**, which is stored inside the system instance and encapsulates an execution strategy (or a composition of strategies).
- Synchronization is handled inside the executor.



## System inner parallelism – parallel execution

```
template <typename TSettings, typename TSystemSignature>
template <typename TContext, typename TF>
void instance<TSettings, TSystemSignature>::execute_in_parallel(
    TContext & ctx, TF && f
    )
{
    // Aggregates synchronization primitives.
    _parallel_executor.execute(*this, ctx, f);
}
```

- System inner parallel execution is done through a **parallel executor**, which is stored inside the system instance and encapsulates an execution strategy (or a composition of strategies).
- Synchronization is handled inside the executor.



# System inner parallelism – executor example

```
template <typename TInstance, typename TContext, typename TF>
void split evenly::execute(TInstance& inst, TContext& ctx, TF&& f)
    constexpr auto split_count = sz v<parameters::subtask count()>;
    auto per split = inst.subscribed count() / split count;
    inst.prepare_and_wait_n_subtasks(split_count, [&](auto& b)
            auto run subtask = [&inst, &b, &ctx, &f](
                auto split idx, auto xi begin, auto xi end)
                // Create Looping execution function.
                auto bse = inst.make bound slice executor(
                    b, ctx, split idx, xi begin, xi end, f);
                inst.run subtask in thread pool(ctx, std::move(bse));
            };
            // Builds and runs the subtasks.
            utils::execute split compile time(inst.subscribed count(),
                per split, split count, run subtask);
        });
```

# System inner parallelism – executor example

```
template <typename TInstance, typename TContext, typename TF>
void split evenly::execute(TInstance& inst, TContext& ctx, TF&& f)
    constexpr auto split_count = sz v<parameters::subtask count()>;
    auto per split = inst.subscribed count() / split count;
    inst.prepare_and_wait_n_subtasks(split_count, [&](auto& b)
            auto run subtask = [&inst, &b, &ctx, &f](
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                auto bse = inst.make bound slice executor(
                    b, ctx, split idx, xi begin, xi end, f);
                inst.run subtask in thread pool(ctx, std::move(bse));
            };
            // Builds and runs the subtasks.
            utils::execute split compile time(inst.subscribed count(),
                per split, split count, run subtask);
        });
```

```
template <typename TInstance, typename TContext, typename TF>
void split evenly::execute(TInstance& inst, TContext& ctx, TF&& f)
    constexpr auto split_count = sz v<parameters::subtask count()>;
    auto per split = inst.subscribed count() / split count;
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            auto run subtask = [&inst, &b, &ctx, &f](
                auto split idx, auto xi begin, auto xi end)
                // Create Looping execution function.
                auto bse = inst.make bound slice executor(
                    b, ctx, split idx, xi begin, xi end, f);
                inst.run subtask in thread pool(ctx, std::move(bse));
            };
            // Builds and runs the subtasks.
            utils::execute split compile time(inst.subscribed count(),
                per split, split count, run subtask);
        });
```

```
template <typename TInstance, typename TContext, typename TF>
void split evenly::execute(TInstance& inst, TContext& ctx, TF&& f)
    constexpr auto split_count = sz_v<parameters::subtask_count()>;
    auto per split = inst.subscribed count() / split count;
    inst.prepare_and_wait_n_subtasks(split_count, [&](auto& b)
            auto run_sub template <typename TSettings, typename TSystemSignature>
                auto splitemplate <typename TF>
                         void instance<TSettings, TSystemSignature>::prepare and wait n subtasks(
                // Create
                             sz t n, TF && f)
                auto bse {
                             _sm.clear_and_prepare(n);
                    b, c
                             counter blocker b{n};
                inst.run
                             // Runs the parallel executor and waits until the remaining subtasks
            };
                             // counter is zero.
                             execute and wait until counter zero(b, [this, &b, &f]
            // Builds and
            utils::execu
                                     f(b);
                per split
                                  });
        });
```



```
template <typename TInstance, typename TContext, typename TF>
void split evenly::execute(TInstance& inst, TContext& ctx, TF&& f)
    constexpr auto split_count = sz v<parameters::subtask count()>;
    auto per split = inst.subscribed count() / split count;
    inst.prepare_and_wait_n_subtasks(split_count, [&](auto& b)
            auto run subtask = [&inst, &b, &ctx, &f](
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                auto bse = inst.make bound slice executor(
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                inst.run subtask in thread pool(ctx, std::move(bse));
            };
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        });
```



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template <typename TInstance, typename TContext, typename TF>
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                auto split idx, auto xi begin, auto xi end)
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                auto bse = inst.make bound slice executor(
                    b, ctx, split idx, xi begin, xi end, f);
                inst.run subtask in thread pool(ctx, std::move(bse));
            };
            // Builds and runs the subtasks.
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```



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            auto run subtask = [&inst, &b, &ctx, &f](
                auto split idx, auto xi begin, auto xi end)
                // Create Looping execution function.
                auto bse = inst.make bound slice executor(
                    b, ctx, split idx, xi begin, xi end, f);
                inst.run subtask in thread pool(ctx, std::move(bse));
            };
            // Builds and runs the subtasks.
            utils::execute split compile time(inst.subscribed count(),
                per split, split count, run subtask);
        });
```



```
template <typename TInstance, typename TContext, typename TF>
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    constexpr auto split_count = sz v<parameters::subtask count()>;
    auto per split = inst.subscribed count() / split count;
    inst.prepare_and_wait_n_subtasks(split_count, [&](auto& b)
            auto run subtask = [&inst, &b, &ctx, &f](
                auto split idx, auto xi begin, auto xi end)
                // Create Looping execution function.
                auto bse = inst.make bound slice executor(
                    b, ctx, split idx, xi begin, xi end, f);
                inst.run subtask in thread pool(ctx, std::move(bse));
            };
            // Builds and runs the subtasks.
            utils::execute split compile time(inst.subscribed count(),
                per split, split count, run subtask);
        });
```

```
template <typename TSettings, typename TSystemSignature>
template <typename TCounterBlocker, typename TContext, typename TF>
auto instance<TSettings, TSystemSignature>::make_bound_slice_executor(
    TCounterBlocker & cb, TContext & ctx, sz_t state_idx, sz_t i_begin,
    sz_t i_end, TF && f) noexcept
{
    return [this, &cb, &ctx, &f, state_idx, i_begin, i_end]
    {
        this->make_slice_executor(cb, ctx, state_idx, i_begin, i_end)(f);
    };
}
```

 The above function binds a range of entities (subset of subscribed entities) to an execution callable object.

```
template <typename TSettings, typename TSystemSignature>
template <typename TCounterBlocker, typename TContext, typename TF>
auto instance<TSettings, TSystemSignature>::make_bound_slice_executor(
    TCounterBlocker & cb, TContext & ctx, sz_t state_idx, sz_t i_begin,
    sz_t i_end, TF && f) noexcept
{
    return [this, &cb, &ctx, &f, state_idx, i_begin, i_end]
    {
        this->make_slice_executor(cb, ctx, state_idx, i_begin, i_end)(f);
    };
}
```

 The above function binds a range of entities (subset of subscribed entities) to an execution callable object.

```
template <typename TSettings, typename TSystemSignature>
template <typename TCounterBlocker, typename TContext>
auto ECST PURE FN instance<TSettings,</pre>
    TSystemSignature>::make slice executor(TCounterBlocker & cb,
   TContext & ctx, sz t state idx, sz t i begin, sz t i end) noexcept
   return [this, &cb, &ctx, state_idx, i_begin, i_end](auto&& f)
        auto data =
            this->make entity range data(ctx, state idx, i begin, i end);
       // Executes the processing function over the slice of entities.
       this->execute_subtask_and_decrement_counter(cb, data, f);
   };
```



```
template <typename TSettings, typename TSystemSignature>
template <typename TCounterBlocker, typename TContext>
auto ECST PURE FN instance<TSettings,</pre>
    TSystemSignature>::make slice executor(TCounterBlocker & cb,
   TContext & ctx, sz t state idx, sz t i begin, sz t i end) noexcept
   return [this, &cb, &ctx, state_idx, i_begin, i_end](auto&& f)
        auto data =
            this->make entity range data(ctx, state idx, i begin, i end);
       // Executes the processing function over the slice of entities.
       this->execute_subtask_and_decrement_counter(cb, data, f);
   };
```



```
template <typename TSettings typename TSvstemSignature>
                        template <typename TSettings, typename TSystemSignature>
template <typename 7
                        template <typename TCounterBlocker, typename TData, typename TF>
auto ECST PURE FN in
                        void instance<TSettings,</pre>
    TSystemSignature
                           TSystemSignature>::execute_subtask_and_decrement_counter( // .
    TContext & ctx,
                           TCounterBlocker & cb, TData & data, TF && f
    return [this, &cl
                           f( system, data);
                           decrement_cv_counter_and_notify_all(cb);
        auto data =
             this->ma
        // Executes the processing function over the slice of entities.
        this->execute subtask and decrement counter(cb, data, f);
    };
```



```
template <typename TSettings, typename TSystemSignature>
template <typename TCounterBlocker, typename TContext>
auto ECST PURE FN instance<TSettings,</pre>
    TSystemSignature>::make slice executor(TCounterBlocker & cb,
   TContext & ctx, sz t state idx, sz t i begin, sz t i end) noexcept
   return [this, &cb, &ctx, state_idx, i_begin, i_end](auto&& f)
        auto data =
            this->make entity range data(ctx, state idx, i begin, i end);
       // Executes the processing function over the slice of entities.
       this->execute_subtask_and_decrement_counter(cb, data, f);
   };
```



#### **Proxies**

- Proxies are used to limit the scope in which critical operations can be executed.
- **Data proxies** are used during system execution to provide component data access and system output access.
- **Defer proxies** are used in defer(...) calls to allow the user to queue up critical operations that will be executed in the **refresh step**. **Step proxies** derive from defer proxies, and allow the execution of system schedulers.
- Executor proxies allow fine-grained execution of system instances.
  - (e.g. calling a function per subtask, or calling a function pre/post system execution)



### Proxies – data proxy

```
struct acceleration
    template <typename TData>
    void process(ft dt, TData& data)
        data.for_entities([&](auto eid)
                auto& v = data.get(ct::velocity, eid)._v;
                const auto& a = data.get(ct::acceleration, eid)._v;
               v += a * dt;
            });
```

### Proxies – data proxy

```
struct acceleration
    template <typename TData>
    void process(ft dt, TData& data)
        data.for_entities([&](auto eid)
                auto& v = data.get(ct::velocity, eid)._v;
                const auto& a = data.get(ct::acceleration, eid)._v;
               v += a * dt;
            });
```

### Proxies – defer proxy

```
data.for_entities([&](auto eid)
        const auto& contacts =
            data.get previous output<s::collision detection>();
        if(contacts.was_hit(eid))
            auto& h = ecst::get<c::health>(data, eid);
            h.damage();
            if(h.dead()) data.kill_entity(eid);
            data.defer([&](auto& proxy)
                auto e = proxy.create_entity();
                auto& ep = e.add_component(ct::effect particle);
                ep.set_effect(effects::explosion);
            });
    });
```

### Proxies – defer proxy

```
data.for_entities([&](auto eid)
        const auto& contacts =
            data.get previous output<s::collision detection>();
        if(contacts.was_hit(eid))
            auto& h = ecst::get<c::health>(data, eid);
            h.damage();
            if(h.dead()) data.kill_entity(eid);
            data.defer([&](auto& proxy)
                auto e = proxy.create_entity();
                auto& ep = e.add_component(ct::effect particle);
                ep.set_effect(effects::explosion);
            });
    });
```

### Proxies – defer proxy

```
data.for_entities([&](auto eid)
        const auto& contacts =
            data.get previous output<s::collision detection>();
        if(contacts.was_hit(eid))
            auto& h = ecst::get<c::health>(data, eid);
            h.damage();
            if(h.dead()) data.kill_entity(eid);
            data.defer([&](auto& proxy)
                auto e = proxy.create_entity();
                auto& ep = e.add_component(ct::effect particle);
                ep.set_effect(effects::explosion);
            });
    });
```

### Proxies – step proxy

```
context.step([&](auto& proxy)
    proxy.system(st::render).prepare();
    proxy.execute_systems_overload(
        [dt](s::physics& s, auto& data){ s.process(dt, data); },
        [](s::render& s, auto& data){ s.process(data); });
    proxy.for_system_outputs(st::render,
        [&window](auto& s, auto& va)
            window.draw(va.data(), va.size(),
                PrimitiveType::Triangles, RenderStates::Default);
        });
});
```

### Proxies – step proxy

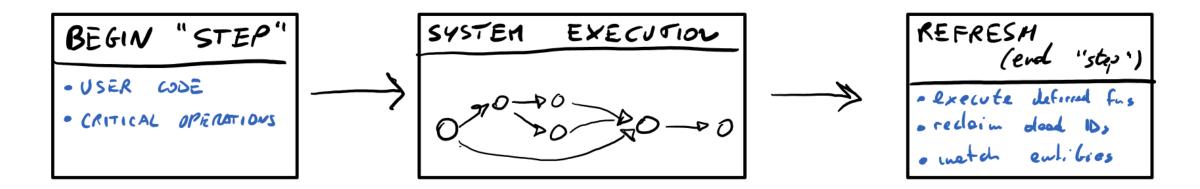
```
context.step([&](auto& proxy)
    proxy.system(st::render).prepare();
    proxy.execute_systems_overload(
        [dt](s::physics& s, auto& data){ s.process(dt, data); },
        [](s::render& s, auto& data){ s.process(data); });
    proxy.for_system_outputs(st::render,
        [&window](auto& s, auto& va)
            window.draw(va.data(), va.size(),
                PrimitiveType::Triangles, RenderStates::Default);
        });
});
```

#### Proxies – executor proxy

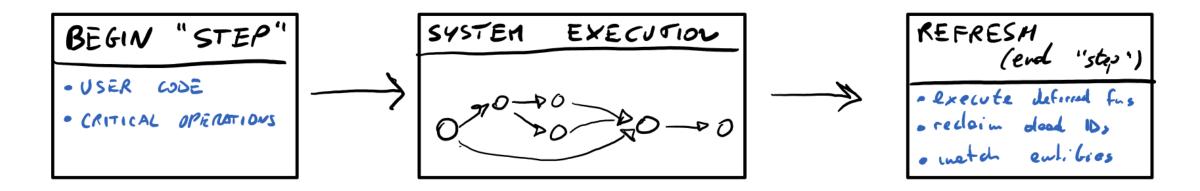
```
sea::t(st::spatial_partition)
    .detailed_instance([&](auto& i, auto& executor)
            auto& s(i.system());
            s.clear_cells();
            executor.for_subtasks([&s](auto& data){ s.process(data); });
            i.for_outputs([](auto& xs, auto& sp vector)
                    for(const auto& x : sp_vector) xs.add_sp(x);
                });
        }))
```

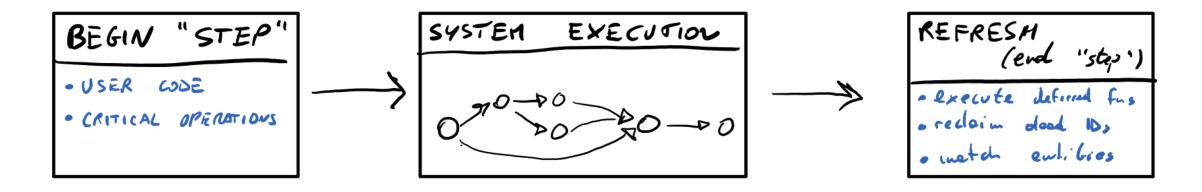
#### Proxies – executor proxy

```
sea::t(st::spatial_partition)
    .detailed_instance([&](auto& i, auto& executor)
            auto& s(i.system());
            s.clear_cells();
            executor.for_subtasks([&s](auto& data){ s.process(data); });
            i.for_outputs([](auto& xs, auto& sp vector)
                    for(const auto& x : sp_vector) xs.add_sp(x);
                });
        }))
```

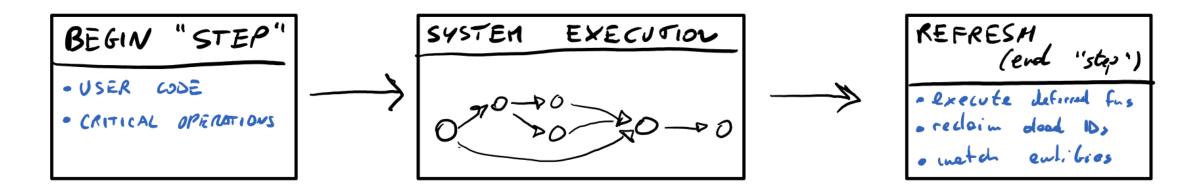












```
template <typename TSettings>
_ctx.step([this, dt](auto& proxy)
                                                              void data<TSettings>::refresh impl()
                               template <typename TSettings> {
                                                                  // Execute deferred functions, filling up the refresh state and
       proxy.execute_systems(/
                               template <typename TContext,
                                                                  // allocating memory if necessary.
       /* ... */
                               void system manager<TSettings</pre>
                                                                  refresh impl execute deferred( refresh state);
                                   TContext& context, TF&& f
                                                                  // Unsubscribe all killed entities from systems.
                                   _system_runner.execute(co
                                                                  refresh impl kill entities( refresh state);
                                                                  // Match all modified and new entities to systems.
                                                                  refresh impl match entities( refresh state);
```



```
template <typename TSettings>
template <typename TF>
auto context::data<TSettings>::step(TF&& f)
    // Clear refresh state.
    _refresh_state.clear();
    // Build context step proxy.
    step_proxy_type step_proxy{*this, _refresh_state};
    // Execute user-defined step.
    f(step proxy);
    // Refresh context.
    refresh();
```

```
template <typename TSettings>
template <typename TF>
auto context::data<TSettings>::step(TF&& f)
   // Clear refresh state.
    refresh state.clear();
                                  template <typename TSettings>
                                  class refresh state
    // Build context step proxy.
    step_proxy_type step_proxy{*t
                                  private:
                                      using set type = dispatch set<TSettings>;
    // Execute user-defined step.
                                      set type to match ids, to kill ids;
    f(step_proxy);
                                  public:
   // Refresh context.
    refresh();
```

```
template <typename TSettings>
template <typename TF>
auto context::data<TSettings>::step(TF&& f)
    // Clear refresh state.
    _refresh_state.clear();
    // Build context step proxy.
    step_proxy_type step_proxy{*this, _refresh_state};
    // Execute user-defined step.
    f(step proxy);
    // Refresh context.
    refresh();
```

```
template <typename TSettings>
template <typename TF>
auto context::data<TSettings>::step(TF&& f)
    // Clear refresh state.
    _refresh_state.clear();
    // Build context step proxy.
    step_proxy_type step_proxy{*this, _refresh_state};
    // Execute user-defined step.
    f(step proxy);
    // Refresh context.
    refresh();
```

### Flow – refresh step

```
template <typename TSettings>
void context::data<TSettings>::refresh()
   // Execute deferred functions, filling up the refresh state and
   // allocating memory if necessary.
    refresh_impl_execute_deferred( refresh state);
    // Unsubscribe all killed entities from systems.
    refresh_impl_kill_entities(_refresh_state);
   // Match all modified and new entities to systems.
    refresh_impl_match_entities( refresh state);
```



# Flow – refresh step – execute deferred functions

```
template <typename TSettings>
template <typename TRefreshState>
void context::data<TSettings>::refresh_impl_execute_deferred(TRefreshState& rs)
    defer_proxy_type defer_proxy{*this, rs};
    for_systems_sequential([&defer_proxy](auto& system)
            system.for_states([&defer_proxy](auto& state)
                    // The execution of deferred functions fills the
                    // refresh state and alters the context state.
                    state.execute_deferred_fns(defer_proxy);
                });
        });
```



# Flow – refresh step – execute deferred functions

```
template <typename TSettings>
template <typename TRefreshState>
void context::data<TSettings>::refresh_impl_execute_deferred(TRefreshState& rs)
    defer_proxy_type defer_proxy{*this, rs};
    for_systems_sequential([&defer_proxy](auto& system)
            system.for_states([&defer_proxy](auto& state)
                    // The execution of deferred functions fills the
                    // refresh state and alters the context state.
                    state.execute_deferred_fns(defer_proxy);
                });
        });
```



# Flow – refresh step – execute deferred functions

```
template <typename TSettings>
template <typename TRefreshState>
void context::data<TSettings>::refresh_impl_execute_deferred(TRefreshState& rs)
    defer_proxy_type defer_proxy{*this, rs};
    for_systems_sequential([&defer_proxy](auto& system)
            system.for_states([&defer_proxy](auto& state)
                    // The execution of deferred functions fills the
                    // refresh state and alters the context state.
                    state.execute_deferred_fns(defer_proxy);
                });
        });
```



# Flow – refresh step – reclaim dead entities

```
template <typename TSettings>
template <typename TRefreshState>
void context::data<TSettings>::refresh impl kill entities(TRefreshState& rs)
    for_systems_sequential([&rs](auto& system)
            system.for states([&rs](auto& state)
                    state.for_to_kill([&](auto eid){ rs.add_to_kill(eid); });
                });
        });
    for systems parallel ([this, &rs](auto& system)
            rs.for_to_kill([&system](auto eid){ system.unsubscribe(eid); });
        });
    rs.for to kill([this](auto eid){ this->reclaim(eid); });
```

#### Flow – refresh step – reclaim dead entities

```
template <typename TSettings>
template <typename TRefreshState>
void context::data<TSettings>::refresh impl kill entities(TRefreshState& rs)
    for_systems_sequential([&rs](auto& system)
            system.for states([&rs](auto& state)
                    state.for_to_kill([&](auto eid){ rs.add_to_kill(eid); });
                });
        });
    for systems parallel ([this, &rs](auto& system)
            rs.for_to_kill([&system](auto eid){ system.unsubscribe(eid); });
        });
    rs.for to kill([this](auto eid){ this->reclaim(eid); });
```

#### Flow – refresh step – reclaim dead entities

```
template <typename TSettings>
template <typename TRefreshState>
void context::data<TSettings>::refresh impl kill entities(TRefreshState& rs)
    for_systems_sequential([&rs](auto& system)
            system.for states([&rs](auto& state)
                    state.for_to_kill([&](auto eid){ rs.add_to_kill(eid); });
                });
        });
    for systems parallel ([this, &rs](auto& system)
            rs.for_to_kill([&system](auto eid){ system.unsubscribe(eid); });
        });
    rs.for to kill([this](auto eid){ this->reclaim(eid); });
```

#### Flow – refresh step – reclaim dead entities

```
template <typename TSettings>
template <typename TRefreshState>
void context::data<TSettings>::refresh impl kill entities(TRefreshState& rs)
    for_systems_sequential([&rs](auto& system)
            system.for states([&rs](auto& state)
                    state.for_to_kill([&](auto eid){ rs.add_to_kill(eid); });
                });
        });
    for systems parallel ([this, &rs](auto& system)
            rs.for_to_kill([&system](auto eid){ system.unsubscribe(eid); });
        });
    rs.for to kill([this](auto eid){ this->reclaim(eid); });
```

#### Flow – refresh step – match entities to systems

```
template <typename TSettings>
template <typename TRefreshState>
void context::data<TSettings>::refresh impl match entities(TRefreshState& rs)
    for_systems _parallel ([this, &rs](auto& system)
            rs.for_to_match([this, &system](auto eid)
                    // Get entity metadata.
                    auto& em(this->metadata(eid));
                    // Check if the bitset matches the system.
                    if(system.matches_bitset(em.bitset()))
                        system.subscribe(eid);
                    else
                        system.unsubscribe(eid);
                });
        });
```

#### Flow – refresh step – match entities to systems

```
template <typename TSettings>
template <typename TRefreshState>
void context::data<TSettings>::refresh impl match entities(TRefreshState& rs)
    for_systems _parallel ([this, &rs](auto& system)
            rs.for_to_match([this, &system](auto eid)
                    // Get entity metadata.
                    auto& em(this->metadata(eid));
                    // Check if the bitset matches the system.
                    if(system.matches_bitset(em.bitset()))
                        system.subscribe(eid);
                    else
                        system.unsubscribe(eid);
                });
        });
```

# Flow – refresh step – match entities to systems

```
template <typename TSettings>
template <typename TRefreshState>
void context::data<TSettings>::refresh impl match entities(TRefreshState& rs)
    for_systems _parallel ([this, &rs](auto& system)
            rs.for_to_match([this, &system](auto eid)
                    // Get entity metadata.
                    auto& em(this->metadata(eid));
                    // Check if the bitset matches the system.
                    if(system.matches_bitset(em.bitset()))
                        system.subscribe(eid);
                    else
                        system.unsubscribe(eid);
                });
        });
                                                                (s_bs & e_bs) == s_bs
```





```
namespace impl
    template <typename TList, typename TComparer>
    auto find_if_impl(TList 1, TComparer c)
        auto res = find_first_index_of_matching(l, c);
        return static_if(is_null(res))
            .then([](auto){ return null v; })
            .else_([=](auto y){ return at(1, y); })(res);
template <typename TList, typename TComparer>
constexpr auto find_if(TList 1, TComparer c)
    return decltype(impl::find_if_impl(1, c)){};
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# Conclusion

Resources and future ideas.





# Resources – (1)

- https://www.researchgate.net/publication/305730566
  - My thesis!
- http://t-machine.org
  - Articles on data structures, multithreading and networking.
  - Wiki with **ES approaches** and existing implementations.
- http://stackoverflow.com/questions/1901251
  - In-depth analysis of component-based engine design.
- http://bitsquid.blogpost.it
  - Articles on contiguous component data allocation strategies.
- http://gameprogrammingpatterns.com/component
  - Covers component-based design and entity communication techniques.
- http://randygaul.net
  - Articles on component-based design, covering communication and allocation.



# Resources -(2)

- Existing C++11/14 ECS libraries:
  - <a href="https://github.com/grandstack/Pronto">https://github.com/grandstack/Pronto</a> (uses compile-time entities).
  - https://github.com/discoloda/Diana (uses sparse sets heavily).
  - <a href="https://github.com/alecthomas/entityx">https://github.com/alecthomas/entityx</a> (uses compile-time components and events).
- https://maikklein.github.io/post/2016-01-14-Entity-Component-System/
  - «The general design of my flawed compile-time entity component system in C++14.»
- https://www.reddit.com/r/gamedev/comments/3nv8uz
  - Discussion on my previous CppCon 2015 ECS talk.



# Resources -(3)

- http://stackoverflow.com/questions/35778864/buildingasynchronous-future-callback-chain-from-compile-time-dependencygraph
  - Building asynchronous `future` callback chain from compile-time dependency graph (DAG)
  - StackOverflow question I asked regarding the generation of a callback chain for system execution.
- <a href="http://cs.stackexchange.com/questions/2524/getting-parallel-items-in-dependency-resolution">http://cs.stackexchange.com/questions/2524/getting-parallel-items-in-dependency-resolution</a>
  - Executing tasks with dependencies in parallel.



#### Future ideas – (1)

- Create system hierarchy. (WIP)
  - Some systems can act directly on component data (ignoring entities), allowing SIMD operations and in-order component data traversal.
- Match system subtasks to next system subtasks to use partial outputs without merging.

# Future ideas – (2)

- Find an alternative to deferred functions.
  - Avoid std::function overhead.
  - Proxy object + command queues?
  - Move-only SBO functions?
- Generic "fluent settings" definition library.
  - Define "settings" schemas at compile-time.
  - Focus on constraints and composability.
  - Statically verify settings with nice error messages.
- Avoid latches, use no-allocation asynchronous computation chains.
- Allow "streaming" system connections.



# Questions?

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# Thank you for attending!



