Interpolation

Interpolation is the process of finding a formula often a polynomial whose graph will pass through a given set of points to represent the value of a function. It has a various number of applications in engineering and science, that are used to construct new data points within the range of a discrete data set of known data points. This method is always needed to compute the value of a function for an intermediate value of the independent function. In short, interpolation is a process of determining the unknown values that lie in between the known data points.

It is mostly used to predict the unknown values for any geographical related data points such as noise level, rainfall, elevation, and so on.

Linear interpolation

It is a method for estimating the value of a function at a point between two known data points (x_0, y_0) and (x_1, y_1) by finding a polynomial that passes through the data points. In this method, the data points are represented as the coefficients of a polynomial equation, which is then used to estimate the value of the function at an unknown point. The formula can written as

$$P_1 = y_0 \left(\frac{x_1 - x}{x_1 - x_0} \right) + y_1 \left(\frac{x - x_0}{x_1 - x_0} \right)$$

In this chapter, we shall use Sagemath to compute interpolation with two data point. The code is given in the diagram below

Figure 1: Sagemath code for Linear Interpolation.

Example 1

For the data points (2, 3) and (5, 7), find $P_1(x)$. By substituting the values in the code above we obtained $\frac{15-3x}{3} + \frac{7x-14}{3}$

```
| def so linear interpolation (point_1, point_2, point=None):
| def so linear interpolation (point_1, point_2, point=None):
| def so linear interpolation (point_1):
| y_1 = point_2[-1]:
| x_0 = point_1[0]:
| x_1 = point_2[0]:
| denom_value = x_1 - x_0
| denom_value = x_1 - x_0
| left_equation = getEquation(x=x_0, y=y_0, denominator = denom_value, second_point=True):
| right_equation = getEquation(x=x_0, y=y_1), denominator = denom_value, second_point=True):
| right_equation = getEquation(x=x_0, y=y_1), denominator = denom_value, second_point=True):
| right_equation = getEquation(x=x_0, y=y_1), denominator = denom_value, second_point=True):
| right_equation = getEquation(s=x_0, y=y_1), denominator = denom_value, second_point=True):
| right_equation = getEquation(s=x_0, y=y_1, second_point=True):
| right_equation = getEquation(s=x_0, y=y_1, second_point=True):
| right_equation = getEquation(s=x_0, s=second_point=True):
| right_equation = getEquation(s=second_point=True):
|
```

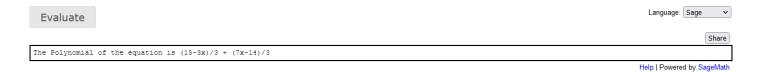


Figure 2: Solution to example 1.

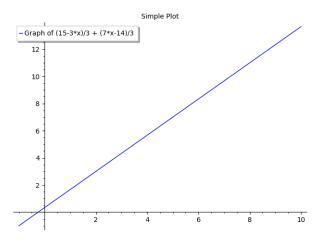


Figure 3: Graph of $\frac{15-3x}{3} + \frac{7x-14}{3}$ by Sagemath.

Example 2

For the data points (0.82, 2.270500) and $(0.83, 2.293319, \text{ find } P_1(x) \text{ and evaluate } P_1(0.826)$. By substituting the points in the Sagemath code above we obtained 2.2841914

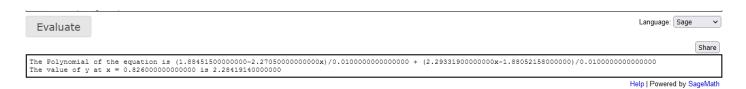


Figure 4: Solution to example 2.

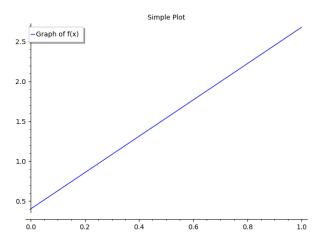


Figure 5: Graph of $P_1(x)$ by Sagemath.

Higher Order Interpolation

Higher-order interpolation, also known as polynomial interpolation, refers to the process of finding a polynomial of a higher degree that passes through a set of data points. While linear interpolation uses first-degree (linear) polynomials, higher-order interpolation uses polynomials of a higher degree (quadratic, cubic, etc.) to represent the data.

The general form of a polynomial for higher-order interpolation can be written as:

$$P_n(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

Where n is the degree of the polynomial and a_n, a_{n-1}, \dots, a_0 are coefficients to be determined based on the given data points.

To perform higher-order interpolation, we typically need to set up a system of equations using the data points and then solve for the coefficients of the polynomial.

Given a set of data points $(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)$, where x_i and y_i are the known data points, and a target x-coordinate x at which we want to estimate the value, the solution is given by Lagrange's formula

$$P_n(x) = y_0 L_0(x) + y_1 L_1(x) + y_2 L_2(x) + \dots + y_n L_n(x)$$

where the Lagrange's basis functions are given by

$$L_k(x) = \frac{(x - x_0)(x - x_1) \cdots (x - x_{k-1})(x - x_{k+1}) \cdots (x - x_n)}{(x_k - x_0)(x_k - x_1) \cdots (x_k - x_{k-1})(x_k - x_{k+1}) \cdots (x_k - x_n)}$$
for k = 0, 1, 2,..., n

The Sagemath code to determine higher order Interpolation is shown below:

```
from sympy import symbols, simplify

# We Define the Lagrange interpolation function

+ def lagrange interpolation(x_values):
    n = len(x_values)
    x_symbols(x')
    tesut = 0

9    for in range(n):
        if i = 1;
        result = 0

10        if i = 1;
        if i = 1
```

Figure 6: Sagemath code for Higher Order Interpolation.

Example 3

Determine the Polynomial $P_2(x) = a_0 + a_1x + a_2x2$ whose graph passes through the points (1, 4), (2, 0) and (3, 12). Solution

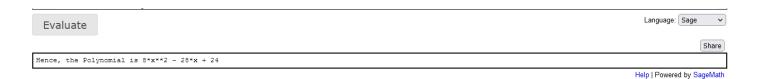


Figure 7: Solution to example 3.

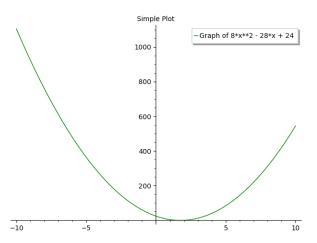


Figure 8: Graph of $8 * x^2 - 28 * x + 24$ by Sagemath.