Lab.1: Cross Toolchain for ARM Linux (Binutils, GCC)

Purpose

Learn how to build a cross compiler from its source code.

Steps

- 1. Download source codes from: 1. http://ftp.tsukuba.wide.ad.jp/software/gcc/snapshots/7.3.0-RC-20180122/ 2. http://ftp.gnu.org/gnu/binutils/ 3. ftp://ftp.gnu.org/gnu/glibc/glibc-2.27.tar.gz
 - 4. git clone git@github.com:raspberrypi/linux.git --depth 1
- 2. Build Cross Binutils:
 - 1. mkdir WORK
 - 2. cd WORK
 - 3. mv ../binutils-2.30.tar.gz ./
 - 4. tar -zxvf binutils-2.30.tar.gz
 - 5. mkdir build_binutils
 - 6. cd build_binutils
 - 7. ../binutils-2.30/configure --prefix=\$HOME/WORK/crossgcc1 --target=arm-linux-gnueabihf
 - 8. make
 - 9. make install
- 3. Build a Bare-metal Cross Compiler:
 - 1. sudo dnf install gmp-devel mpfr-devel libmpc-devel
 - 2. mv ../gcc-7.3.0-RC-20180122.tar.gz ./
 - 3. tar -zxvf gcc-7.3.0-RC-20180122.tar.gz
 - 4. mkdir build_gcc1
 - 5. cd build_gcc1
 - 6. export PATH=\$PATH:\$HOME/WORK/crossgcc1/bin

../gcc-7.3.0-RC-20180122/configure --prefix=\$HOME/WORK/crossgcc1 --target=arm-linuxgnueabihf --enable-languages=c --without-headers --disable-libmudflap --disablelibatomic --with-arch=armv6 --disable-shared --enable-static --disable-decimal-float -disable-libgomp --disable-libitm --disable-libquadmath --disable-libsanitizer --disable-

- 7. libssp --disable-threads --with-float=hard --with-fpu=vfp --with-newlib
- 8. make -j 7
- 9. make install
- 4. Install kernel headers
 - 1. cd linux
 - 2. make headers_install ARCH=arm INSTALL_HDR_PATH=\$HOME/WORK/sysroot/usr
- 5. Build EGLIBC
 - 1. tar -zxvf glibc-2.27.tar.gz
 - mkdir build_eglibc
 - cd build_eglibc

```
../glibc-2.27/configure --prefix=/usr --host=arm-linux-gnueabihf --target=arm-linux-
       qnueabihf --with-headers=$HOME/WORK/sysroot/usr/include --includedir=/usr/include --
   4. enable-add-ons --disable-multilib
   5. make -j 7
   6. make install install_root=$HOME/WORK/sysroot
Build Cross Binutils
   1. mkdir build_binutils2
   2. cd build_binutils2
       ../binutils-2.30/configure --prefix=$HOME/WORK/crossgcc2 --target=arm-linux-gnueabihf --
   3. with-sysroot=$HOME/WORK/sysroot
   4. make
   5. make install
7. export PATH=$PATH:$HOME/WORK/crossgcc2/bin
8. Build a Cross Compiler

    mkdir build_gcc2

   2. cd build_gcc2
       ../gcc-7.3.0-RC-20180122/configure --prefix=$HOME/WORK/crossgcc2 --target=arm-linux-
```

```
gnueabihf --enable-languages=c --with-sysroot=$HOME/WORK/sysroot --with-arch=armv6 --
with-fpu=vfp --with-float=hard --disable-libmudflap --enable-libgomp --disable-libssp --
enable-libquadmath --enable-libquadmath-support --disable-libsanitizer --enable-lto --
enable-threads=posix --enable-target-optspace --with-linker-hash-style=gnu --disable-nls
--disable-multilib --enable-long-long
```

- 4. make -j 7
- 5. make install -j 7
- 9. Test:
 - 1. \$HOME/WORK/crossgcc2/bin/arm-linux-gnueabihf-gcc test.c

Discussion

At first, I configured gcc with --enable-languages=c,c++. This made the make phase of gcc fail every time. So, I spent 2.5 days fixing this which is really frustrating. Eventually, I gave up c++ and the building process went smoothly.

After the tool chain was successfully built, I tested arm-linux-gnueabihf-gcc test.c and it gave the result: fatal error: stdio.h: No such file and directory. So, I consulted Professor Chen and found out that it was my \$PATH which is misconfigured.

As of now, the cross compiler finally works.