

Forensics and Malware Analysis

Malware Analysis I

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Ref: Coursera - Malicious Software and its Underground Economy: Two Sides to Every Story



Very brief history of Malware

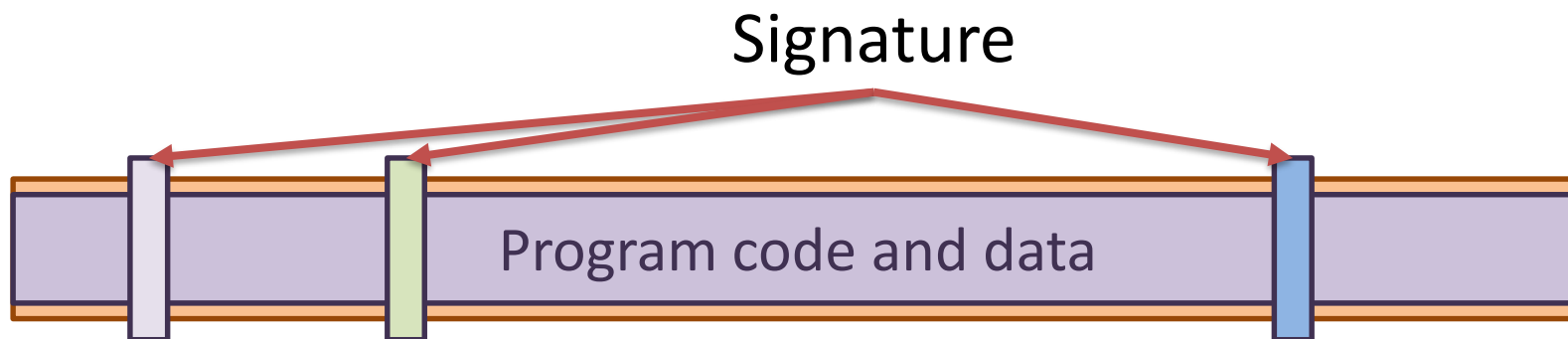
- Era of Discovery
 - Reason for malware: show skills, curiosity, no intentional harm, no financial gain
 - Anti-Malware: small scale reverse engineering
 - Ex: BrainBoot, Internet Worm

Very brief history of Malware

- Era of Transition
 - Reason for malware: show skills, no intentional harm, no financial gains.
 - Ex. Melissa, CIH, ILoveYou, etc.
 - Anti-Malware:
 - reverse engineering
 - signature based detection

Very brief history of Malware

- Era of Transition (cont.)
 - signature based detection
 - Instruction level signatures
 - Heuristics
 - Wildcards monitoring of specific files



Very brief history of Malware

■ Current Era

- Reason for malware: mostly financial gain
 - Malware more difficult to analyse
 - code obfuscation, polymorphism
 - tools to automatically mutate malware
- Anti-Malware:
 - reverse engineering
 - signature based detection
 - increased computing power and sensors
 - still not behavior based

Architecture Reminder

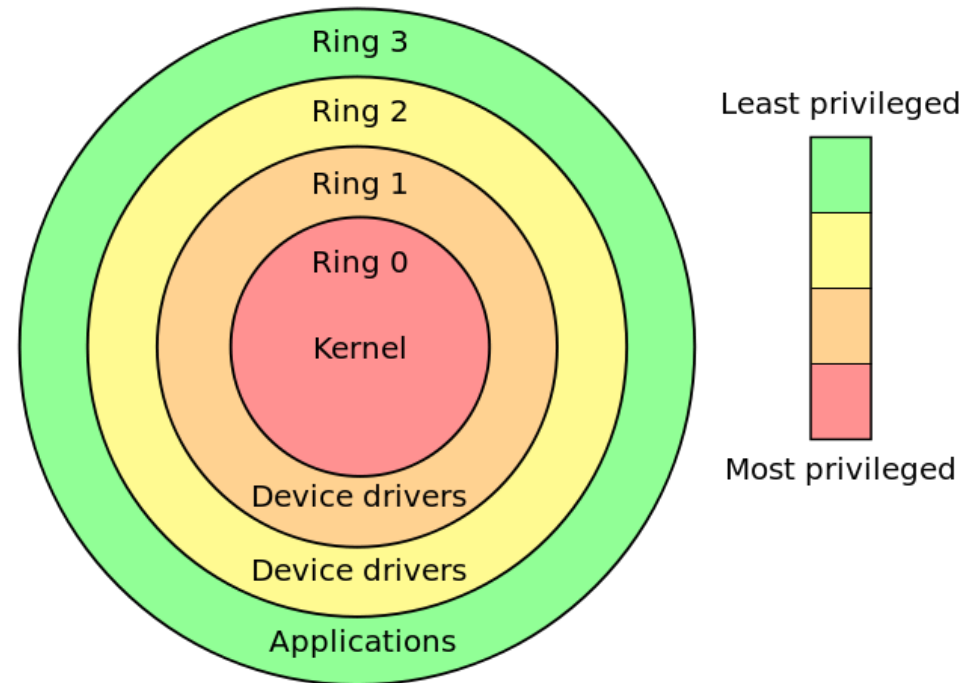
- Memory description (user space + kernel space, page files, page files permissions, etc.)
- Privilege levels/rings (0-3 in intel)
- User space at ring 3
- Kernel at ring 0
- System calls transfer control from user space to kernel space (in a OS controlled way)

Architecture Reminder

- Protection rings, are mechanisms to protect data and functionality from faults (by improving fault tolerance) and malicious behavior.

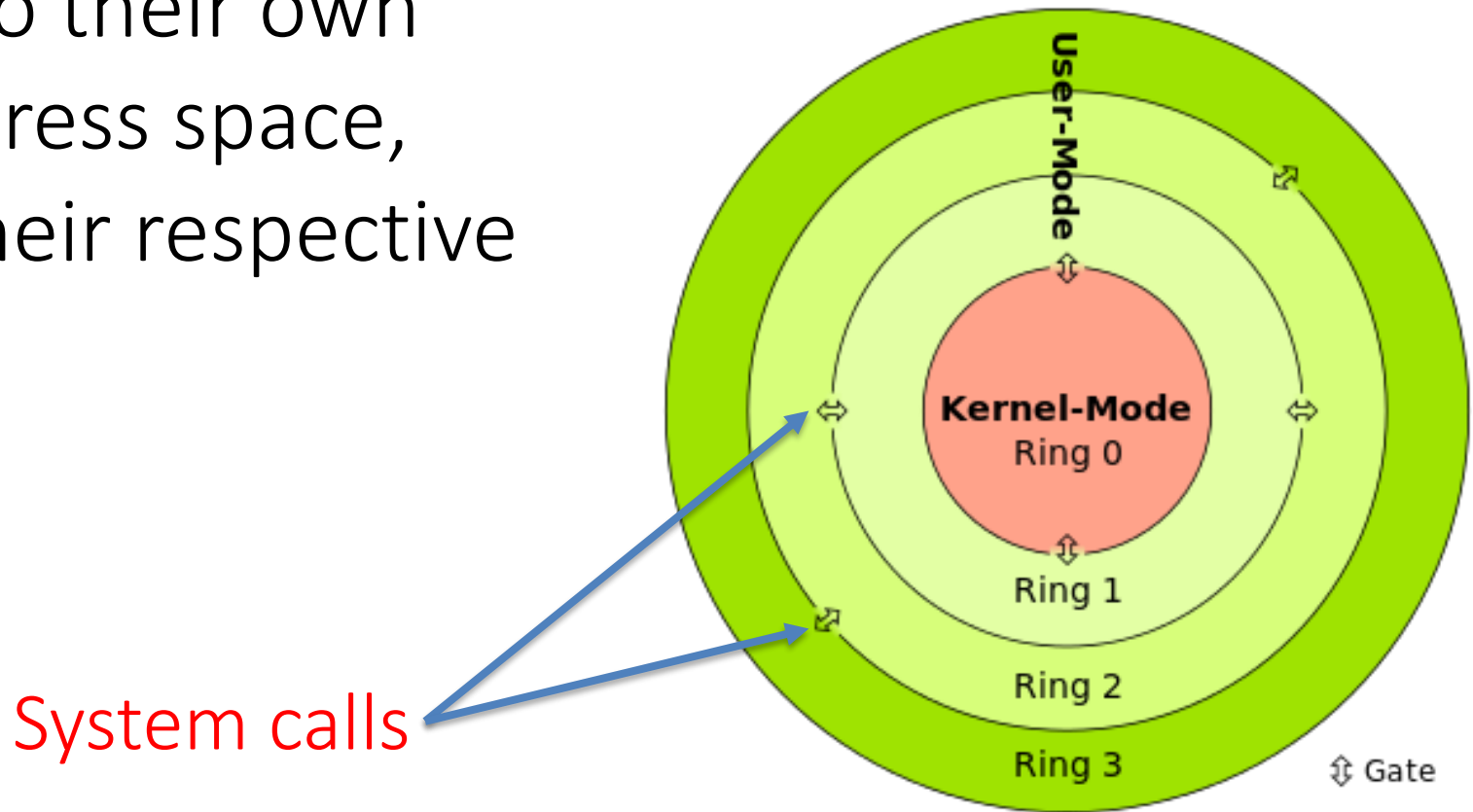
Architecture Reminder

- Ring0:
 - most privileges
 - interacts most directly with physical hardware
-
- Ring3:
 - least privileges
 - Uses system calls to interact with physical hardware



Architecture Reminder

- Programs are (usually) limited to their own address space, within their respective ring.



System calls

- System calls: controlled entry points into the kernel, which allow a process to request that the kernel perform some action on the process's behalf.
- The kernel makes a range of services accessible to programs via the system call application programming interface

System calls as APIs

- OS provide a API to access system calls
- API is implemented a library
 - Unix: glibc; Windows: ntdll.dll
- The library wrapper functions use ordinary function calling convention
 - i.e. ASM subroutine calls

Architecture Reminder

- Types of System calls:
 - process control (e.g. start /stop process)
 - file management (e.g. read/write to disk)
 - device management (e.g. interact with hardware)
 - information maintenance (e.g. set time, get proc. info)
 - communication (e.g. establish remote connections)

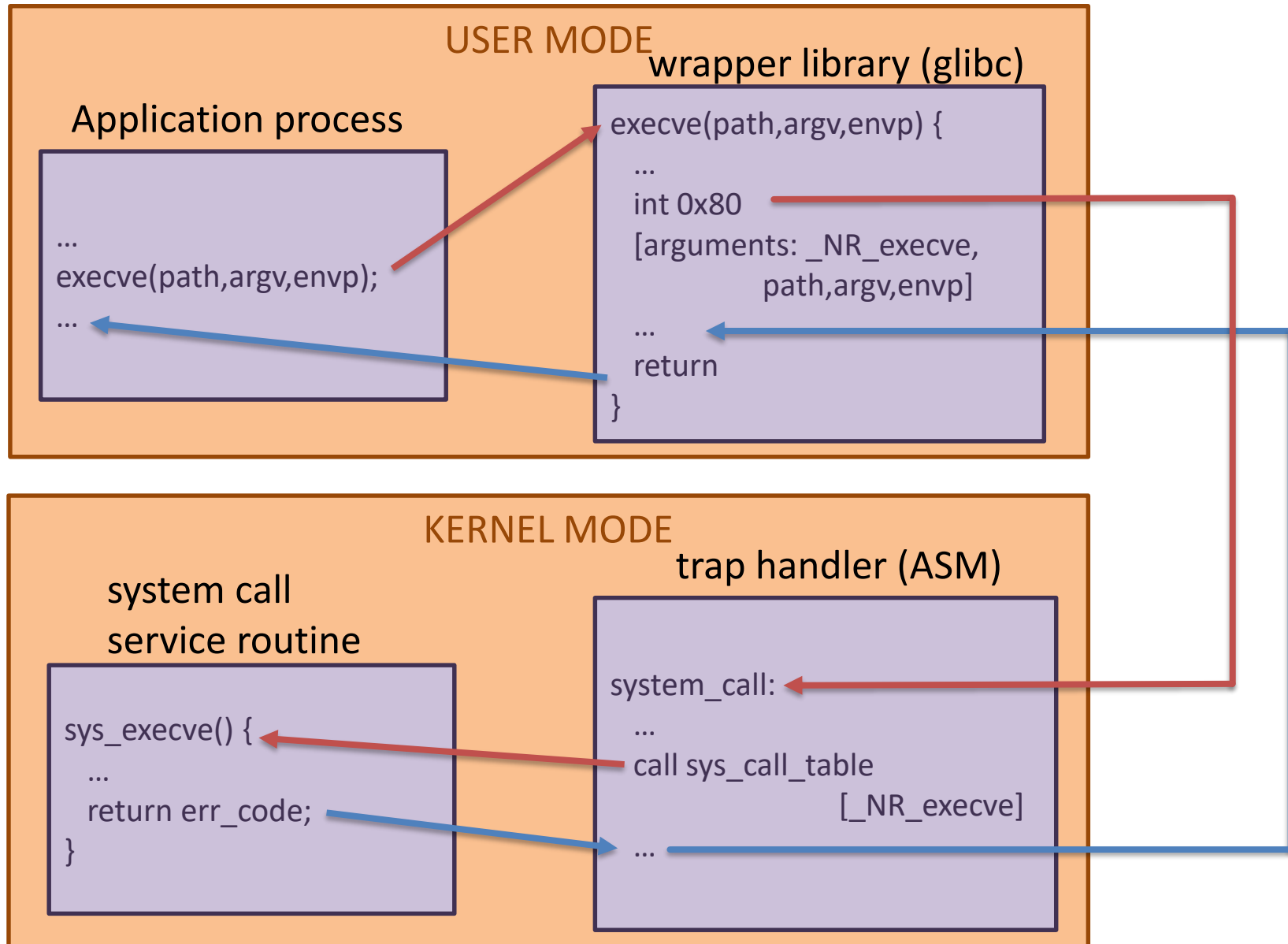
Function calls

- C library functions like **printf** and **scanf** are wrappers around **system calls**.
- ... but not all C library functions execute system calls e.g. **string.h** library functions, including **strcmp**, are **function calls**.

Executing a system call

- **The standard method:** the library function executes a trap machine instruction (int 0x80).
 - this causes the processor to switch from user mode to kernel mode and execute code pointed to by location 0x80 of the system's trap vector.
- **The sysenter instruction:** a faster method of entering kernel mode than the conventional int 0x80 trap instruction.
 - In Linux sysenter is supported in the 2.6 kernel and from glibc 2.3.2 onward.

Executing a system call



- C function **execve**: syscall that launches a new process

Quick intro to reverse engineering

How to analyse malware

- Malware is usually written in ASM, C, etc.
- ASM
 - Low level symbolic language
 - Processor specific
 - Directly translated into binary format (1 to 1 mapping to machine language)

ASM

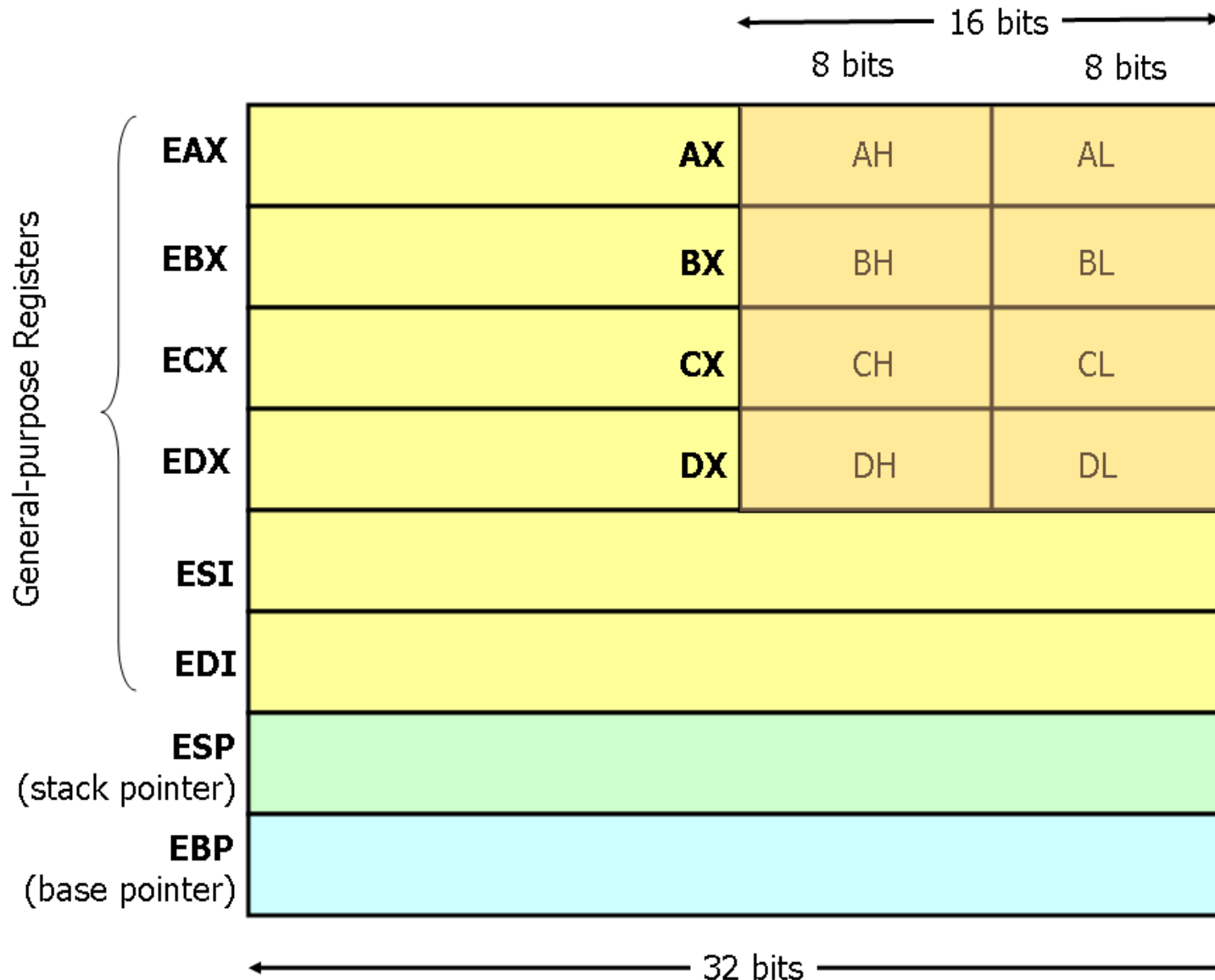
- Different types of instructions

- Data transfer: mov, xchg, push, pop...
- Binary arithmetic: add, sub, mul, div, inc, dec,...
- Logical: and, or, xor, not
- Control transfer: jmp, jne, call, ret, int,...
- Input/output: in, out

- CPU/HW Registers

- General purpose registers: (r)/(e)**ax**, (r)/(e)**bx**, (r)/(e)**cx**, (r)/(e)**dx**
and **r8** to **r15** in x64 CPUs
- Instruction pointer: (r)/(e)**ip**
- Base pointer: (r)/(e)**bp**
- Stack pointer: (r)/(e)**sp**

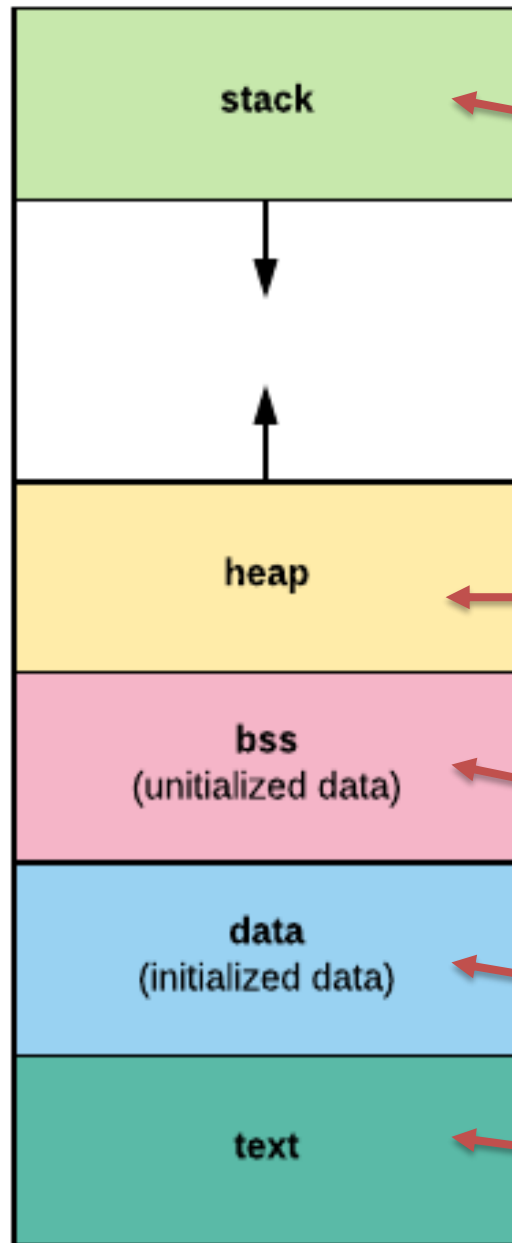
CPU registers



CPU registers & executable files

- CPU/HW Registers (cont.)
 - Flags: ZF, SF, CF...
- Object file Segment Registers:
 - CS – code segment
 - DS – data segment
 - SS – stack segment
 - ES (and FS, GS) – extra segment(s)

Executable files



STACK: Contains the program stack. Has a "stack pointer" register tracks the top of the stack. The stack area is adjoined to the heap area and they grew towards each other.

HEAP: heap area is shared by all threads, shared libraries, and dynamically loaded modules in a process.

BSS segment: global/static variables that are initialized to zero or do not have explicit initialization.

Data segment: contains global or static variables. Contains DS and ES.

Code segment: contains executable instructions, is RO.

ASM Syntax

- ASM – two ways of representing ASM instructions

1. Intel (usually Windows)

- syntax

`label: destination, source ; comment`

- pointers between []
- hex prefixed with 0x

2. AT&T (usually Linux)

ASM Syntax

- ASM – two ways of representing ASM instructions

1. Intel

2. AT&T

- syntax:

`label: source, destination # comment`

- pointers between ()
- numerical constants prefixed with \$
- hex prefixed with 0x
- binary prefixed with 0b
- registers prefixed with %

■ Conditionals

```
#include <stdio.h>
```

```
int main (int argc,  
          char **argv){  
    int a=1;  
    if (a != 0){  
        printf("A != 0\n");  
    } else {  
        printf("A = 0\n");  
    }  
}
```

```
.A:  
    mov dword ptr [ebp - 8], 1 ; input a  
.LC0:  
    .string "A = 0\n"  
.LC1:  
    .string "A != 0\n"  
main:  
    [function prologue]  
    mov al, byte ptr [ebp - 8]  
    test al,al  
    jnz .L2 ; jump if not 0  
    mov ESP, [LC1]  
    call printf  
    jmp .L3 ; jump to end of the if (i.e. "}" )  
.L2:  
    mov ESP, [LC0]  
    call printf  
.L3:  
    leave  
    ret
```


ASM

■ Loops

```
#include <stdio.h>
```

```
int main (int argc, char ** argv){  
    int i=1;  
    while (i<10){  
        i++;  
    }  
}
```

```
.main:  
    [function prologue]  
    mov dword ptr [ebp - 4], 1 ; input i  
.LOOP:  
    mov eax, dword ptr [ebp - 4]  
    cmp eax, 10  
    jge .L3  
    inc eax  
    mov dword ptr [ebp - 4], eax  
    jmp LOOP  
.L3:  
    leave  
    ret
```

ASM

■ Functions

```
#include <stdio.h>
```

```
int main (int argc, char ** argv){  
    return myfunc(1,2);  
}
```

```
.main:
```

```
    ; save current program location &  
    ; opt. EAX, ECX EDX (not here)  
    push ebp      ; prologue for main  
    mov ebp, esp ; equiv to: enter 0,0
```

```
...
```

```
    ; prepare to run function
```

```
    push 2
```

```
    push 1
```

```
    call myfunc
```

```
...
```

```
    ;restore program to saved location
```

```
    mov esp, ebp ;
```

```
    pop ebp      ; epilogue for main
```

ASM

■ Functions

```
#include <stdio.h>
```

```
int myfunc(a,b){ return a+b; }
```

```
int main (int argc, char ** argv){  
    myfunc(1,2);  
}
```

```
.myfunc:                ; stack situation  
    ;[prologue]         ; after [prologue]  
    mov eax,[ebp+4]  
    mov ebx,[ebp+6]      ; ebp+0 => old ebp  
    add eax, ebx         ; ebp+2 => ret addr  
    ;[epilogue]         ; ebp+4 => 1  
    ret 4                ; ebp+6 => 2
```

```
.main:
```

```
    ; save current program location &  
    ; opt. EAX, ECX EDX (not here)  
    push ebp            ; prologue for main  
    mov ebp, esp        ; equiv to: enter 0,0
```

```
    ...  
    ; prepare to run function  
    push 2  
    push 1  
    call myfunc
```

```
    ...  
  
    ;restore program to saved location  
    mov esp, ebp ;  
    pop ebp      ; epilogue for main
```

ASM

■ Functions

```
#include <stdio.h>
```

```
int myfunc(a,b){ return a+b; }
```

```
int main (int argc, char ** argv){  
    myfunc(1,2);  
}
```

```
.myfunc:
```

```
    ;[prologue]; changes stack point.
```

```
    mov eax,[ebp+4]
```

```
    mov ebx,[ebp+6]
```

```
    add eax, ebx
```

```
    ;[epilogue]; changes stack point.
```

```
    ret
```

Result is usually
placed in EAX



```
.main:
```

```
    ; save current program location &  
    ; optionally EAX, ECX EDX (not here)
```

```
    push ebp      ; prologue for main
```

```
    mov ebp, esp ; equiv to: enter 0,0
```

```
    ...
```

```
    ; prepare to run function
```

```
    push 2
```

```
    push 1
```

```
    call myfunc
```

```
    ...
```

```
    ;restore program to saved location
```

```
    mov esp, ebp ;
```

```
    pop ebp      ; epilogue for main
```

ASM

■ Functions

Function prologue:

```
push ebp ; save base pointer
mov ebp, esp ; create new stack
sub esp, N ; create N bytes on stack
```

or:

```
enter N, 0
```

Function epilogue:

```
mov esp, ebp ; restore space
pop ebp ; restore base pointer
ret M; return to calling func,
      popping the extra m
      arguments
```

or:

```
leave
ret M
```

Disassembly

- Disassembly involves taking a binary blob, separating code and data and extracting the instructions.
- In a disassembled program we can
 - Locate functions
 - Recognize jumps
 - Identify local variables
 - i.e. understand the program's behaviour

Disassembly

- Disassembling programs is not an easy task
 - Separating code from data is very difficult.
 - e.g bitstream: ... 0x8b 0x44 0x24 0x04 ...
mov eax, [esp+0x04]
 - 0x8b is data => 0x44 0x24 0x04
inc esp
and al, 0x04

Disassembly

- Two main algorithms for doing disassembly
 - Linear sweep (objdump,...)
 - Recursive traversal (IDApr)

Linear sweep

- Linear sweep:
 - Locates instructions: where one instruction, begins another one ends
 - Assumes that everything that is marked as code is actually machine instructions (of course not true for malware!)
 - Disassembly starts from the first bit and continues in a linear fashion, i.e. instructions are disassembled one after the other until the end of the section is reached.

Linear sweep

- Linear sweep:

- Pros:

- Provides complete coverage of a programs code sections:
e.g. calls are not followed because eventually the code for that call will be reached.

- Cons:

- Oblivious to the flow of the program.
 - Compilers often mix code and data which results in disassembled “junk” (e.g. a switch statement in C can translate to a jmp table in asm).

Linear sweep

08048350	B8 66 83 04 08	mov \$0x8048366,%eax
08048355	FF D0	call *%eax
08048357	C3	ret
08048358	48	dec %eax
08048359	65	gs
0804835A	6C	insb (%dx),%es:(%edi)
0804835B	6C	insb (%dx),%es:(%edi)
0804835C	6F	outsb %ds:(%esi),(%dx)
0804835D	20 57 6F	and %dl,0x6f(%edi)
08048360	72 6C	jb 0x80483ce
08048362	64 21 0A	and %ecx,%fs:(%edx)
08048365	0D BA 0E 00 00	or \$0xeba,%eax
0804836A	00 B9 58 83 04 08	add %bh,0x8(%ecx)
08048370	BB 00 00 00 00	mov \$0x0,%ebx
08048375	B8 04 00 00 00	mov \$0x4,%eax
0804837A	CD 80	int \$0x80
0804837C	B8 00 00 00 00	mov \$0x0,%eax
08048381	C3	ret

Linear sweep

08048350	B8 66 83 04 08	mov \$0x8048366,%eax
08048355	FF D0	call *%eax
08048357	C3	ret
08048358	48 65 6C 6C 6F 20 57	(data)
0804835F	6F 72 6C 64 21 0A 0D	(data)
08048366	BA 0E 00 00 00	mov \$0xe,%edx
0804836B	B9 58 83 04 08	mov \$0x8048358,%ecx
08048370	BB 00 00 00 00	mov \$0x0,%ebx
08048375	B8 04 00 00 00	mov \$0x4,%eax
0804837A	CD 80	int \$0x80
0804837C	B8 00 00 00 00	mov \$0x0,%eax
08048381	C3	ret

Recursive traversal

Recursive traversal

- Recursive transversal “follows” the control flows.
- Types of control flows
 - Sequential flow: pass execution to the next instruction that follows immediately (mov, push, add)
 - Conditional branching: set of instructions that follow after a jump instruction
 - Unconditional branching: set of instruction that would happen if jump is not executed.

Recursive traversal

- Types of control flows (cont.)
 - Function calls: set of instructions following a `call` instruction
 - Returns: recursive transversal disassembles programs based on calls and jumps. Every call is placed in a “stack” and once the flow is disassembled completely the disassembly resumes from the stack (i.e. the recursive part).

Recursive traversal

- Recursive traversal:
 - Pros:
 - distinguish code from data
 - enables creation of flow graphs
 - Cons:
 - Some parts of the program may not be disassembled.
 - Inability to follow indirect code paths.

Lets see it in action!

- objdump disassembly

```
objdump -d desktop/examples/reveng/r1 | less
```

1. AT&T syntax
2. Disassembled using linear sweep

Lets see it in action!

- IDAPro disassembly
 - Open IDAPro
 - Load exercise
desktop/examples/reveng/r1
- 1. Intel syntax
- 2. Disassembled using Recursive transversal: flow graph, code segment, data segment, strings,...
- 3. Compare IDAPro and objdump output

GHIDRA



- <https://ghidra-sre.org/>
- <https://github.com/NationalSecurityAgency/ghidra>