

BACHELOR

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Undervisere:

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~~f~~ → BRITE
→ explain
→ Show pointing
→ more background, especially
about spectroscopy. → show a spec.
→ spectrophotometry)

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1

Background

1.1 Observations In Space

Observations of objects in space can be conducted both from Earth and from orbits in space. Kjeldsen et al. talks about how performing astronomy from Earth is limited by the filtering and distortion of electromagnetic radiation by the Earth's atmosphere, a feature that protects life on Earth from ultraviolet and gamma rays. The altitude needed to detect the different bands of the electromagnetic spectrum is illustrated in figure 1.1. From Earth radio waves, near-infrared and visible light are observable. For observing other frequencies of the electromagnetic spectrum it is necessary to have observatories in space where the atmosphere is not present. There are several ways of observing and examining objects in space. To make observations from space most often the equipment needed is launched into space on board a satellite and the two most commonly used methods for examining astronomy objects in space are via Photometry and Spectrophotometry.

1.1.1 Nanosatellites - Cubesats

In the last decade launching a satellite into space has become more accessible with the introduction of smaller and cheaper nanosatellites, also called Cubesats. A Cubesat is small satellite made up of multiples of $10 \times 10 \times 10$ cm cubic units. Cubesats are often build with off the shelf components for their electronics and structure. Only in recent time the technology has evolved to allow for high performance miniature star trackers, that are used to determine the orientation of the satellite in space. With a star tracker and a pointing controller, consisting of three axis reaction wheels used to rotate the satellite, the satellite is able to keep its needed orientation for observations in space (?). Satellites in orbit are also subject to temperature variations due to the satellite being exposed to direct sunlight or being in the shadow of the Earth. If build the AU-SAT will consist of four unit and will be tested to verify it can hold up to the environment in space.

6

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1

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X rays

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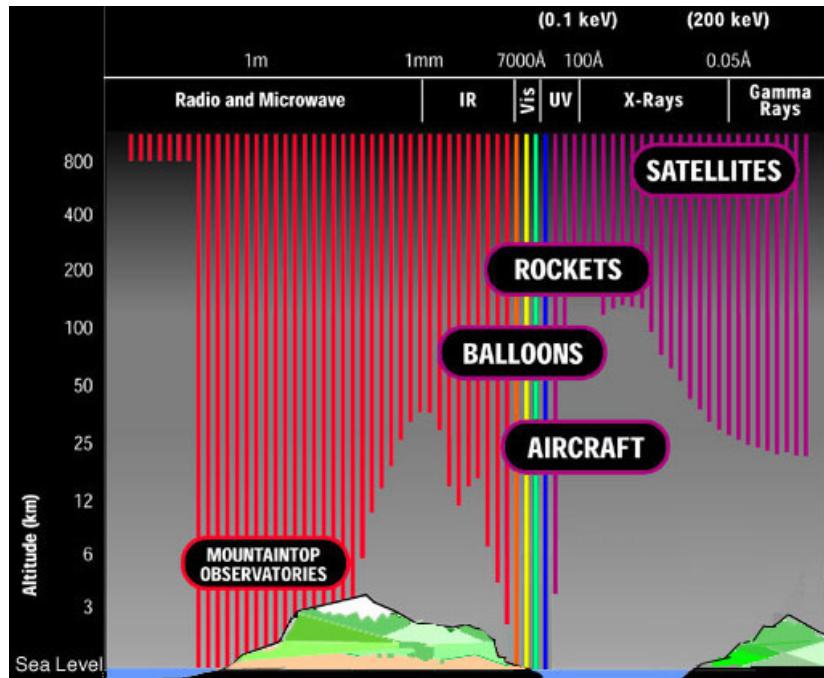


Figure 1.1: Illustration of the altitude needed to observe the different bands of the electromagnetic spectrum Fig. from (Online).¹

1.1.2 Photometry

broad & narrow

Photometry is concerned with measuring the change in the intensity of an astronomical object's electromagnetic radiation. In its most basic form, photometry is conducted by gathering light through a telescope on to a photosensitive instrument which records the light energy, coming from the object being examined. Photometry is often limited to a narrow wavelength range by adding filters to the telescope that allow the wanted wavelength to pass through. Photometry can be used to measure oscillations in stars by monitoring the brightness and colour fluctuations over time (Kjeldsen et al.).

E.g. BRITE, MOST !
Kepler as well

1.1.3 Spectrophotometry

NO
this is
spectroscopy

Spectrophotometry uses an instrument called a spectrograph, that separates light into a frequency or wavelength spectrum and records the signal using a camera. Most often the deflection of the light produced either by refraction or by diffraction. The deflection of light by refraction uses that light of different wavelength is deflected in different angles when traveling from one medium to another medium with a different refractive index. Deflection of light by diffraction makes use of the phenomena which occurs when a wave encounters an obstacle. Diffraction is defined as the bending of light around the corners of an obstacle. To split light into several beams traveling in different directions a diffraction grating can be used. A diffraction grating is an optical component with a periodic structure typically of ridges on their surface. The deflection of

details such as slit ...

¹http://migall.fastmail.fm.user.fm/astronomy/telescopes_detectors/emr/page6.htm

the light hitting the diffraction grating depend on the spacing of the grating and the wavelength of the light hitting it.

So what happens then?

Ocean Optics USB4000 Spectrograph

H fig.

HWL calib

The spectrograph used in the experiments of this thesis is the USB4000 spectrograph from *Ocean Optics*.²

Th Ar. laser comb.

1.2 The Space Mission Life Cycle and Architecture

e mission

When planning the work in space, a large amount of work must first be done back on earth. This is the case whether planning a manned mission or launching a satellite into orbit. *Wertz and Larson (1999)* gives a nice overview of the progress of designing a space mission:

- *Concept exploration*, The initial study phase, in which a broad definition of the space mission and its components.
- *Detailed development*, the formal design phase, which results in a detailed definition of the system components and test of hardware and development.
- *Production and deployment*, the construction of the ground and flight hardware and launch of the final system.
- *Operations and support*, the day-to-day operations of the space system, its maintenance and support, and its deorbit or recovery at the end of the mission life.

Further more all space missions consist of a set of elements and the arrangement of these elements form the space mission architecture (*Wertz and Larson, 1999*).

The subject of the mission is the object to be examined that either interacts with or is sensed by payload. For the AU-SAT the subject is to observe the light from stars.

H [platform] *rephrase* ?
 The payload consist of the hardware and software that sense or interact with the subject. The payload is contained within the spacecraft bus which also holds all the subsystems that handle, altitude, orbit, power, telemetry and data. The payload and spacecraft bus are together called the spacecraft. The payload for AU-SAT mission would be the AU-SAT, which include a telescope, an onboard computer, for communications and onboard data processing and likely a spectrograph to analyze the incoming light from the stars.

The launch system includes the launch facility and the launch vehicle that is needed to launch the payload into orbit.

²www.oceanoptics.com

Followed orbit
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S.*
The *orbit* is the path or trajectory of the spacecraft. There are several orbits the spacecraft enters before it reaches its mission orbit. Often a low earth orbit with an altitude between 200-2000 km is used for Cubesats. The orbit is often an end-of-life orbit, where over time the spacecraft will be slowed down by drag and end its life burning up in the atmosphere. The end-of-life orbit is usually used for Cubesats.

LEO

The *ground systems* consist of the ground stations that connect with the spacecraft, so the operators are able to control the spacecraft and receive the telemetry and the mission data.

For the AU-SAT the Department of Physics and Astronomy Aarhus University will decide the subject of the mission and determine the payload for the satellite. The scope of this bachelor's thesis is to examine a possible type of spectrograph that could be included in the payload if the satellite is launched. The spacecraft bus will be delivered by the Danish Cubesat company GomSpace. For the launch system, it will be required to buy a free spot on a commercial rocket, that would deliver the spacecraft on a desired orbit for observations.

why here? front!

the stability

2

Development and Setup of ~~Physical Tests~~

SPG → we talked!

2.1 Preface

In order to determine the possibilities and limitations of making observations with a spectrograph similar to the spectrograph, it was necessary to perform initial testing on the spectrograph. To examine the spectrograph it was decided to develop different setups to test the stability of the measurements. In an orbit in space the SPG will be pointed at different objects to analyze the light they radiate and thereby analyze the properties of the objects.

Why? | In the laboratory however the light source observed by the spectrograph needed to be a light source with a very well known spectrum in the range of the spectrograph. For a well known light source and its spectrum, the laboratory wavelength of a peak located in the spectrum is well documented, which enables the SPG to be calibrated. Upon the development of the setups it was necessary to consider what kind of environment the SPG could be subject to if it was launched to space.

What is the definition? | As mentioned in section 1.1.1, two common factors for a space craft in orbit, are movement due to pointing of the space craft and variations of the temperature inside the spacecraft. Furthermore the observations of astronomical objects are often performed over a long duration of time, which means measurements taken over a long period of time must be stable. With these factors taken into consideration, three experiment setups with different purposes were designed.

1. Stationary ~~Physical Test~~ - Analysis of measurements with the spectrograph being stationary.
2. Simulated Vibration ~~Physical Test~~ - Analysis of measurements with the spectrograph with simulation of pointing via vibrations.

3. Temperature Dependence ~~Physical Test~~ - Analysis of measurements with the spectrograph at variable temperatures.

The development, purpose and improvements of the three experiments and the calibration of the spectrograph will be discussed in the following sections.

2.1.1 Calibration of the USB4000 Spectrograph

Missing

2.1.2 Helium Spectrum

To examine the stability of the spectrograph, six spectral lines within the Helium spectrum will be used. Helium has well known spectral emission lines that are well defined and distributed across the wavelength range of the spectrograph being examined in this bachelor's thesis. The use of well defined spectral emission lines ensures that any broadening or shift of the spectral lines are happening within the spectrograph. In figure 2.1 the spectral emission lines in the Helium spectrum in the range 380-900 nm are shown.

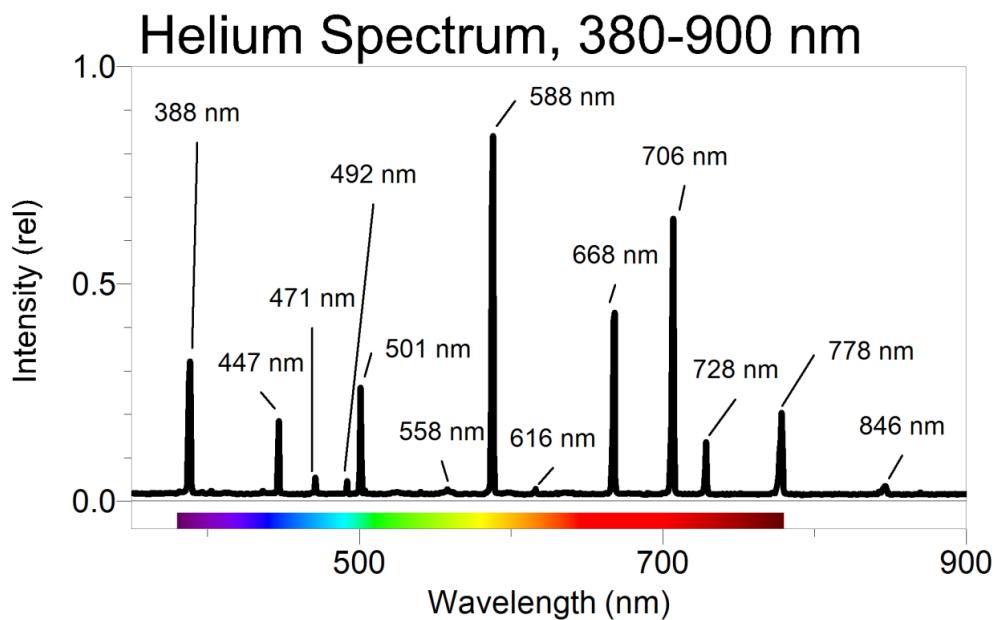


Figure 2.1: Spectral lines in the Helium spectrum in the range 380–900 nm. Fig. from ([Born, 2014](#)).

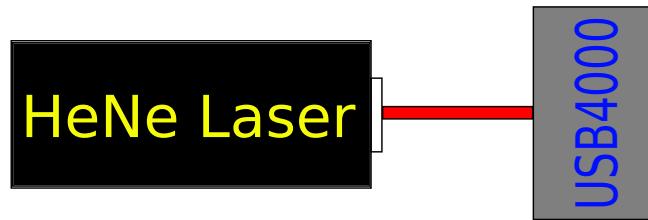
2.2 First Experiment- Stationary Measurements

The purpose of the first setup was to determine the stability of multiple readings over a long period of time from the spectrograph. The parts used for the first initial setup were:

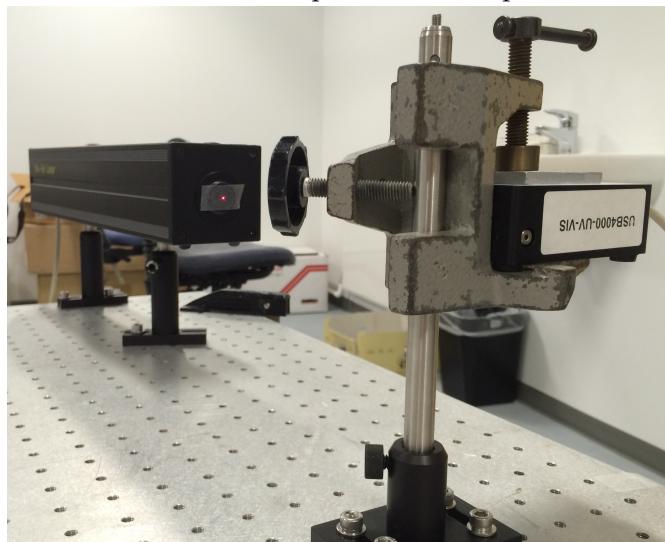
- HeNe laser

- USB4000 Spectrograph with the data acquisition software, *SpectraSuite*¹.
- Optical bench for mounting the setup

The HeNe laser was chosen as the first light source because it had a well documented single peak in its spectrum. The initial setup for the first experiment, is shown in fig. 2.2, where a sketch of the setup is illustrated as well as a picture of the actual setup.



(a) Sketch of the setup for the first experiment.



(b) Actual setup for the first experiment.

Figure 2.2: The setup for the initial run of the stationary measurement with a HeNe laser as the light source. In the top panel a sketch of the top view of the setup is illustrated and in figure 2.2b the actual setup is shown from an angle. The tape used as a scrambler is visible over the output lens of the laser.

The setup for the stationary measurement was very simple as there were no moving parts or control of temperature as was done in later tests. For the execution of the experiment the HeNe laser was aligned with the spectrograph which was connected to the data acquiring software, *SpectraSuite*. The laser was fitted with tape across the output lens, this was done because the tape performs like a scrambler which causes the light beam to become more uniform. This was done as an attempt to make the setup less sensitive to alignment of the laser beam on the spectrograph slit. The parameters for the initial test were,

¹<http://oceanoptics.com/wp-content/uploads/SpectraSuite.pdf>

- The HeNe Laser was set to an output of 1 mW and the tape was used as a scrambler by placing it over the exit slit of the laser which was pointed onto the entrance slit of the USB4000.
- In *SpectraSuite* the integration time was set to 10 ms, allowing for a high peak to be located at the expected wavelength. Measurements were done every 20 s for a total of 1000 measurements.
- *SpectraSuite* saved the intensity as a function of wavelength to a text file. No filtering of noise from the CCD or smoothing was applied.

After the run of the initial setup some problems were found,

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- The results were dependent on the alignment of the laser and the spectrograph. Small vibrations could cause observable changes in the alignment, which caused the laser to saturate the CCD detector, making the measurements useless.
 - The change in alignment was also able to change the form of the Gaussian peak in the measured spectrum to a very flat and wide peak, which was most likely because of internal reflections within the spectrograph.
 - Although the HeNe laser produces a well defined peak, it would be preferable if several peaks located over the range of the spectrograph could be observed, to obtain more data for analysis.
- ?*

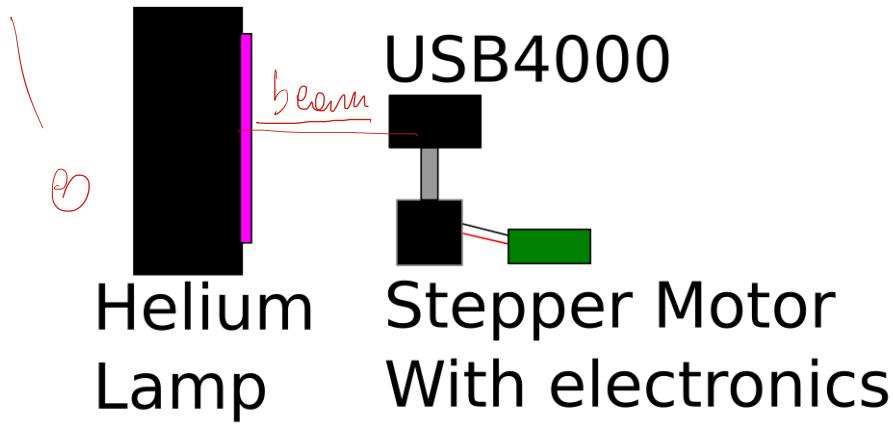
After running the initial setup where the problems mentioned earlier were present, improvements to the setups were introduced. Most of the issues were in someway related to the use of the HeNe laser as the light source. The size of the light spot from the laser was too small compared to the entrance slit of the spectrograph, this meant that the light over the whole entrance slit was not as uniform as desired.

of what

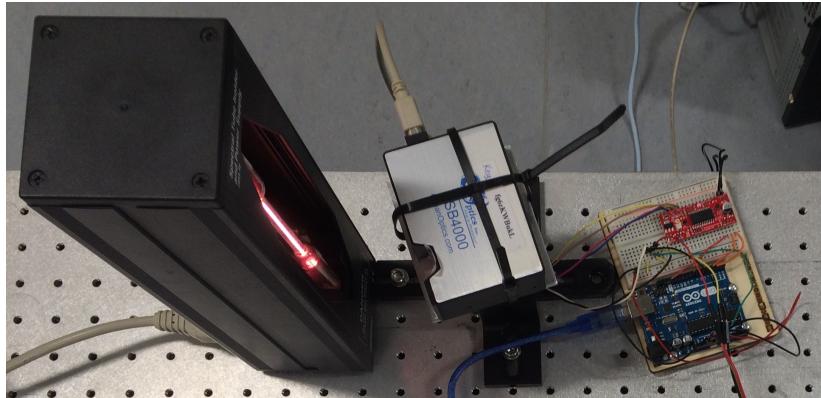
For the reasons explained above for the initial setup, the light source used for measurements was changed to a Helium calibration lamp which was used for calibration as well. In this case there are several peaks across the measurable range could be selected in the output spectrum to observe for the experiments and the light hitting the entrance slit would be more uniformly spread out due to the lamp no focusing the light on to a small area. Furthermore the mounting to the optical bench was changed in such way that it could be used for the second test as well, which examined simulated pointing via vibrations of the spectrograph. The spectrograph was therefore mounted on top of the shaft of a stepper motor. The stepper motor was mounted with four 90° angle pieces onto the optical bench next to the electronics controlling it. The stepper motor was turned off for the stationary test but could be made to move when needed in the second experiment. A sketch and the real setup can be seen in figure 2.3.

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shape*

The change of light source meant that the final parameters of the test were changed,



(a) Sketch of setup.



(b) Actual setup.

Figure 2.3: The final setup for both the stationary experiment and simulated pointing experiment. Figure 2.3a shows a sketch of the setup seen from the side and figure 2.3b shows the actual setup. The electronics were only used to control the stepper motor in the simulated pointing experiment.

- The light source was changed to the Helium calibration lamp.
- The tape used as a collimator was moved to the entrance slit of the spectrograph and the Helium calibration lamp was placed such that the CCD detector in the spectrograph was not saturated.
- Integration time in *Spectrasuite* was set to 100 ms. Measurements were still done every 20 s for a total of 1000 measurements, and saved to a text file with the intensity for every wavelength for data processing.

2.3 Second Physical Test - Simulated Pointing

The purpose of the second experiment was to test the stability of the measurements from the spectrograph, when it was exposed to vibrations. The setup for the second experiment included the parts used for the final setup in the stationary experiment additional to,

Explain what an unproper pointing does to the data (in the intro)

2.4. Third Experiment - Temperature Dependence

- The stepper motor was now used to simulate the pointing of the spacecraft by rotating the spectrograph back and forth over an angle spanning 45° . The rotation was done with a frequency of 1,04 Hz, which allowed for enough light exposure at the different angles for the spectrograph to obtain detectable peaks in the output spectrum.
- The electronics used to control the stepper motor were the two commercial development boards, *Raspberry Pi* and *Arduino Uno*. These were programmed to move the stepper motor at the desired frequency.
- Measurements were taken every 20 s for a total of 1000 measurements. Every measurement was saved to a text file, with the intensity as a function of wavelength.

The setup was the same as for the stationary measurement which can be seen in figure 2.3.

2.4 Third Experiment - Temperature Dependence

The purpose of the third experiment was to determine the temperature dependency of the measurements from the spectrograph. For this experiment it was necessary to build a housing environment where the temperature could be controlled as precisely as possible. The system would need to be well insulated so the temperature inside could be kept stable for long enough time to allow the temperature of the spectrograph to come into equilibrium with the set temperature. In orbit the temperature will vary on a 90 minute cycle. Because the housing of the spectrograph was not open the temperature inside can not be measured directly, this is why each temperature is held for long duration to ensure that the spectrograph is at the set temperature of the housing. Furthermore a window for the light to enter the housing was preferable as this would allow the light source to be placed outside the housing, allowing for a smaller volume in which the temperature needed to be controlled. For the actual heating of the housing and how to control the temperature precisely, different methods were considered,

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- A hot air blower manually set to different temperatures.
- Thermoelectric cooling by using a Peltier device, which can transfer heat from one side of the device to the other depending on the direction of the current going through it, thereby being able to heat up one of the device sides.
- A heater circuit design by ourselves and controlled by a PID controller.

For the use of a hot air blower the housing for the experiment would quickly become complicated to build to allow for a hot air entrance without a large heat loss, which could cause the temperature to be unstable. A Peltier device is mainly used for cooling purposes by ensuring that the hot side of the device

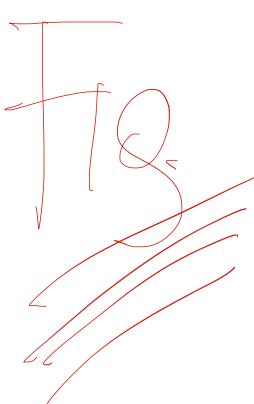
itself is cooled. Thereby allowing the cold side to be cooled even further by transferring its excess heat to the hot side. It would be time consuming to develop a setup that worked with precision control of the hot side of the Peltier device.

Therefore we used a setup using a heater circuit we designed ourselves, that could keep the volume of the housing small and would only need a few wires to be run inside the housing. The heater circuit was controlled by an *Arduino Uno* running PID controller software. After discussing with the electronics department of Aarhus University Institute for Physics and Astronomy, a simple circuit was designed which satisfied our needs. The circuit schematics can be seen in figure 2.4. The circuit is run off a 12 V power supply, with the positive terminal connected to a power resistor, functioning as the heating element of the circuit. The high power resistor is capable of having large amounts of power delivered to it, causing it to heat up as current flows through it and as the voltage drops across it. The resistor was connected to ground through a transistor controlled by the *Arduino Uno*. The transistor works as a switch, which connects the collector and emitter legs of the transistor when a voltage is applied to the base leg. The resistor was connected to the collector leg and the emitter leg was connected to ground, while the base leg was connected to the *Arduino Uno* with the PID software. The PID software controlled when and for how long the collector and emitter legs were connected based on the temperature readings from a temperature sensor connected to the *Arduino Uno* from inside the test housing. With the wanted temperature inside the housing being adjustable from the PID software, the test could be run without the need to physically interrupt the setup.

After deciding on the wanted setup, an initial test setup was built to ensure the heating circuit and PID controller were working as planned. The initial setup was constructed with the following parts:

- The housing was made from a small cardboard box, as high insulation was not needed for testing if the heater circuit and PID controller worked as expected. This setup is shown in fig. 2.5.
- A 12 V power supply, BD649 Transistor, SH650 Resistor and TMP35 Temperature sensor.²

The spectrograph was placed in the housing with a window for the light to enter. Tape was used to insulate the window and work as a scrambler like in the previous experiments. The power resistor was mounted on a heatsink in contact with the spectrograph, the temperature sensor was mounted on the spectrograph as well. The power resistor and temperature sensor were mounted directly onto the spectrograph because it was expected to provide the fastest heating and most stable temperature readings. A small fan was put in the housing to circulate the air to get a uniform temperature inside the housing. The cables were then run outside the housing to the remaining circuit. The setup inside and outside the housing can be seen in fig. 2.5.



²Component Datasheets : <http://www.alldatasheet.com>

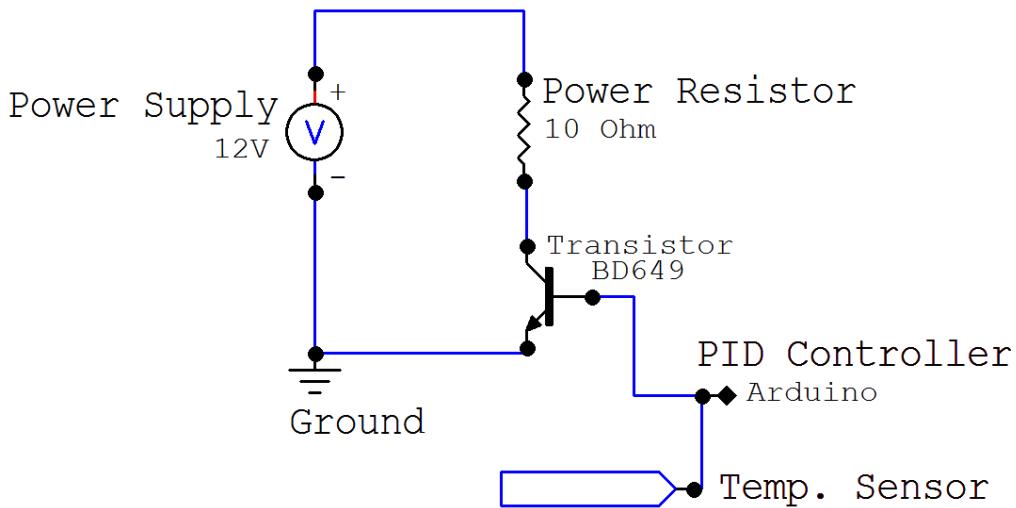


Figure 2.4: Schematic view of the heater circuit used to control the temperature in the housing for the temperature dependence experiment.

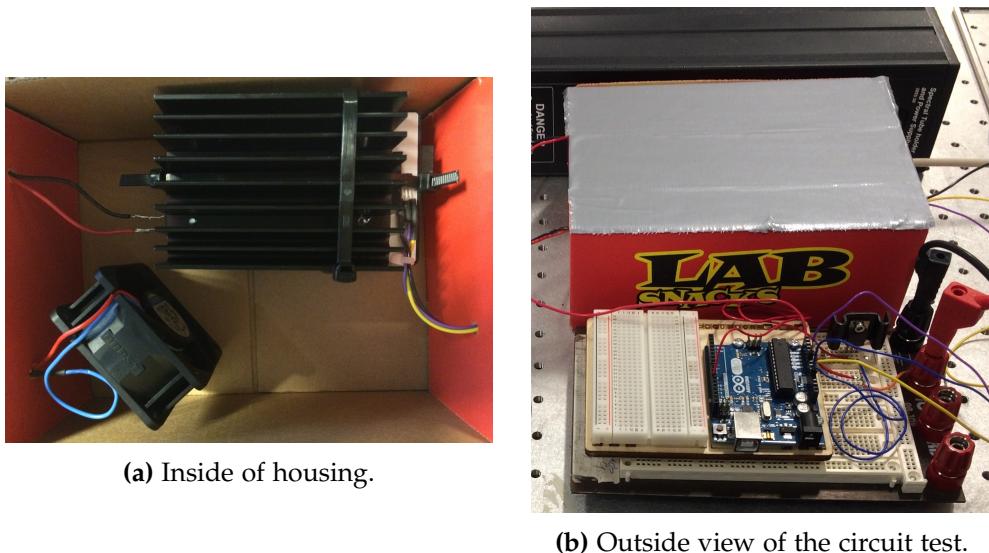


Figure 2.5: The inside and outside view of the setup to test the heater circuit and PID controller. The left panel shows the resistor with heatsink and the temperature sensor mounted on top of the spectrograph as well as the fan for circulating the air. In the right panel the outside of the setup is shown, including the Helium lamp in the background, the part of the heater circuit located outside the housing.

After conducting the initial test of the heater circuit and PID controller some adjustments were made for the final setup to improve stability of the temperature in the housing,

- The housing was changed to a Styrofoam box for better insulation allowing the set temperature to be reached faster.
- The resistor and temperature sensor were moved so they were not in

contact with the spectrograph, but instead the heating and temperature measurements were done on the circulating air. This was done because it allowed for a more stable temperature within the housing.

The final setup for the third experiment with the mentioned improvements can be seen in figure 2.6.

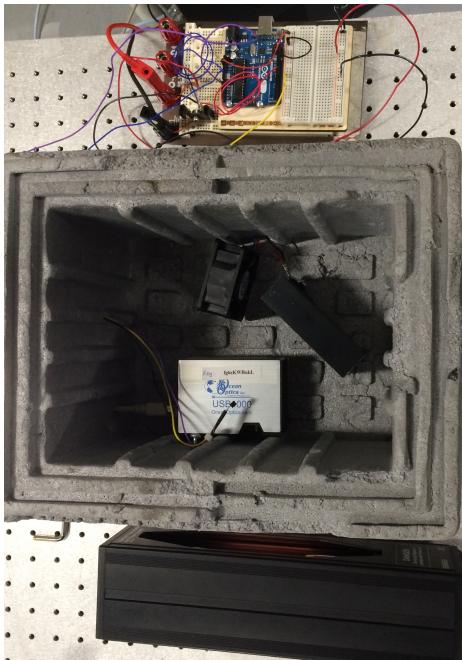


Figure 2.6: The final setup used for the third experiment. The spectrograph was placed with the entrance slit aligned with the light window made in the side of the housing. The resistor with heatsink was placed in front of the fan so the circulating air was heated and the temperature sensor was placed so it measured the air temperature. The housing was closed off with a lid when the experiment was run.

With the final setup decided upon the third experiment was run with the parameters,

- Measurements were made with the temperature varying from 19,5° to 49,3° in eleven equally spaced steps. Because the spectrograph was heated by the circulating air, the temperature was held steady for each step for two hours to allow for uniform temperature in the spectrograph.
- Integration time in *SpectraSuite* was set to 100 ms and measurements were taken every 1 s for a total of 60 measurements for every temperature step. The intensity of every wavelength was saved to a text file for data processing.

3

data → always plural!

Results

3.1 General method of data processing

The Helium spectrum from each measurement was saved to a text file, which included wavelengths with corresponding photon count. As an example of what the Helium spectrum from a measurement looks like, the unfiltered data with background noise, from a stationary measurement is shown in fig. 3.1.

The six peaks that will be used for determining the stability of the spectrograph for all three experiments, are marked and numbered from one to six in fig. 3.1 with the numbering starting from the peak with the lowest wavelength. The corresponding laboratory wavelength to peak number are shown in tbl. 3.1.

The data from all measurements within each experiment firstly had the background noise from the CCD sensor removed. The background noise needed to be removed before is was possible to fit any functions to the data. This is done by using the intensity for wavelengths below 350 nm, where no spectral line are present from Helium, here only the noise on the CCD sensor is present, the average of the measured intensity for all wavelengths below 350 nm was subtracted from the relative intensity for all data. Then for every measurement the six marked peaks in fig. 3.2 will be found within each spectrum, and a Gaussian function will be fitted to each peak to determine the centroid wavelength of all

Peak number	Wavelength [nm]
1	388.9
2	447.1
3	501.6
4	587.6
5	667.8
6	706.5

Table 3.1: Wavelengths for the six spectral lines that will be used in the experiments of this thesis (Abramzon and Siegel, 1999).

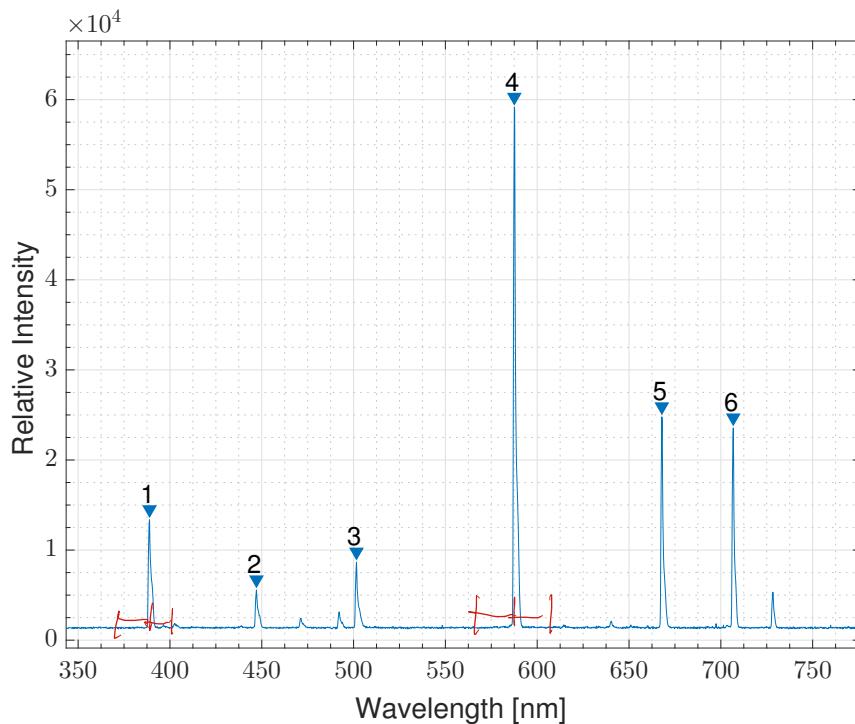


Figure 3.1: Example of the Helium spectrum from a measurement with the spectrograph, here illustrated by a spectrum from a stationary measurement. The six peaks that are used to determine the stability of the centroid wavelength value are marked and numbered one to six starting from the peak with the shortest wavelength.

the peaks. These wavelengths will be compared within all three experiments. Peak number 4, located around 587 nm, will be used for all three experiments to illustrate the data processing.

The general form of a Gaussian function is:

$$f(x) = A \exp\left(-\frac{(x - b)^2}{2\sigma^2}\right), \quad (3.1)$$

where, A is the amplitude, b is the centroid value of the peak and σ is the standard deviation, which determines the width of the Gaussian profile.

The typical form of a peak with a fitted Gaussian function is shown in fig. 3.2a. It can be seen that the peak has a "shoulder" on the right which can be easily fit by two Gaussian. This is illustrated in fig. 3.2b. From section 2.1.2 we know the spectral lines of Helium are well defined, which means that the "shoulder" of the spectral line is most likely caused by internal reflections within the spectrograph. To determine the specific cause of this broadening, it would be necessary to take the spectrograph apart and do further testing. This is beyond the scope of this bachelor's thesis but the broadening will be filtered out in the data processing.

I explain that $\Delta\lambda$ is always constant, which further suggests internal reflection.

3.1. General method of data processing

To accurately identify the centroid of the peak, to be measured, it is necessary to fit to a combination of two Gaussian functions of the form:

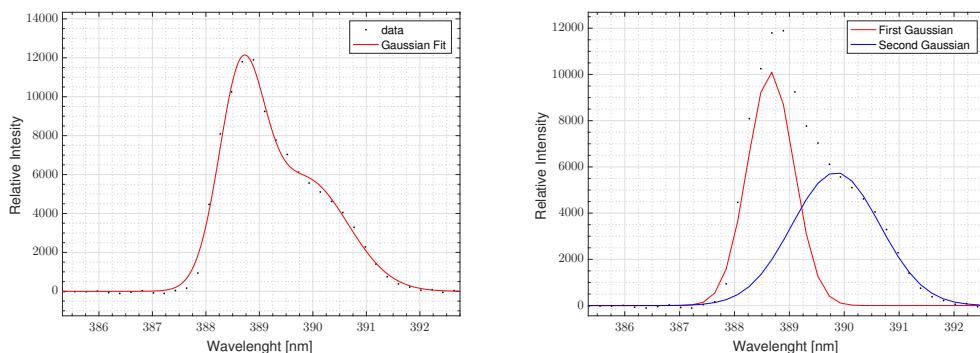
$$f(x) = A_1 \exp\left(-\frac{(x - b_1)^2}{2\sigma_1^2}\right) + A_2 \exp\left(-\frac{(x - b_2)^2}{2spg\sigma_2^2}\right), \quad (3.2)$$

and when a fit in the form of eq. 3.2 has been found, we are able to get the information about the two separate Gaussian function and thereby get the centroid information about the narrow and tall peak in which we are interested.

One way to determine the uncertainty for every found wavelength is to use the *Full Width at Half Maximum* (FWHM), which is the width of the peak at half the maximum amplitude. FWHM is determined by the standard deviation, σ . The relationship between the two is given by:

$$FWHM = 2\sqrt{2\ln 2}\sigma, \quad (3.3)$$

where σ is obtained from the Gaussian function fitted to every peak.



(a) Typical peak form, with double Gaussian fitted. (b) The two single Gaussian functions that make up the fit in fig. 3.2a.

Figure 3.2: Overview of the general observed Gaussian peak form. Fig. (a) shows the form of the two combined Gaussian functions that are fitted to the experimental data and fig. (b) shows how the combined Gaussian can be split up into two single Gaussian functions.

Another way of determining the uncertainty is possible if an average of multiple measurements is done. Averaging multiple measurements is a practice often used when making observations from space. In space, observations are more prone to noise from radiation hitting the CCD sensor than on Earth, due to higher radiation in space. By averaging over measurements a single measurement with an increased value due to radiation hitting the CCD sensor is less prominent and thereby reduces the uncertainty of the measurement. From n measurements, the average, \bar{x} , and the standard deviation can be calculated from,

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i, \quad (3.4)$$

$$\sigma = \sqrt{\frac{1}{n-1} \sum_{i=1}^n (x_i - X)^2}. \quad (3.5)$$

From the standard deviation the uncertainty, S_X , of the average can be calculated,

$$S_X = \frac{\sigma}{\sqrt{n}} \quad (3.6)$$

3.2 First Experiment - Stationary Measurements

For the first experiment, an algorithm was written in Matlab to analyze all the measurements. In the data from every measurement the six peaks mentioned in ~~tbl.~~ 3.1 were found. Each of the six peaks were then fitted to a function of the form seen in eq. 3.2. The parameters obtained from the fit were analyzed in order to identify which belonged to the narrow and taller peak. With these parameters it was possible to fit a function of the form seen in eq. 3.1, to the data, where the measured noise from the earlier discussed "shoulder" Gaussian, was filtered out. The fit to a single Gaussian allowed for a more narrow width of the peak, which led to a smaller FWHM value and thereby a smaller uncertainty on the found wavelengths.

Now?

After the six peaks had been found in all measurements, the data ~~was~~ was filtered from peaks that had not been fitted properly by the algorithm. Bad fittings were visible ~~by~~ the FWHM values. All the peaks that had been fitted correctly had FWHM values around 1 nm, while the bad fitted peaks had FWHM values above 2 nm. The data filtered out by high FWHM values was less than 10% of the total measurements.

were
outliers?
removed?

The found wavelengths for each peak was then plotted against the time from the start of the experiment. For peak number 4, all the ~~found~~ wavelengths is shown in fig. 3.3a and the uncertainties in form of the FWHM for the ~~found~~ wavelengths is shown in fig. 3.3b. The ~~uncertainties of the found wavelengths~~ have a magnitude around 1 nm, when eq. 3.3 was used.

The measurements were then collected in bins containing twenty measurements and were analyzed using ~~the~~ standard deviation described in eq. 3.4, 3.5 and 3.6. The average of each bin was calculated and the uncertainty was calculated from eq. 3.6. The ~~found~~ wavelengths over time are shown in fig. 3.4a along with the calculated uncertainties.

The last processing of the data from the first experiment was done by taking the average of all the ~~found~~ wavelengths for each peak. Then the uncertainty of the average for each peak was found. The average peak wavelengths are shown in ~~tbl.~~ 3.2 where they can be compared to the laboratory wavelengths of the peaks. The uncertainty for each peak is shown in fig. 3.4b.

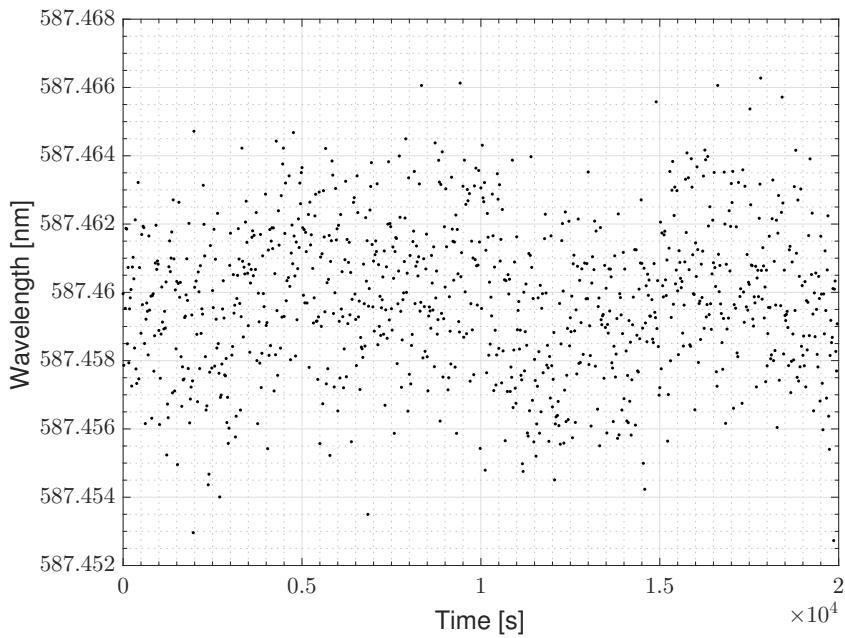
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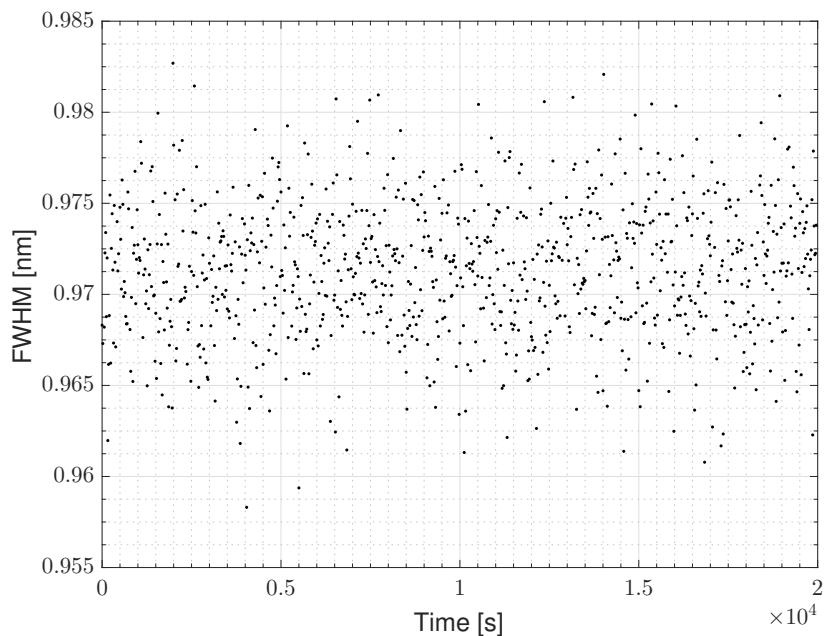
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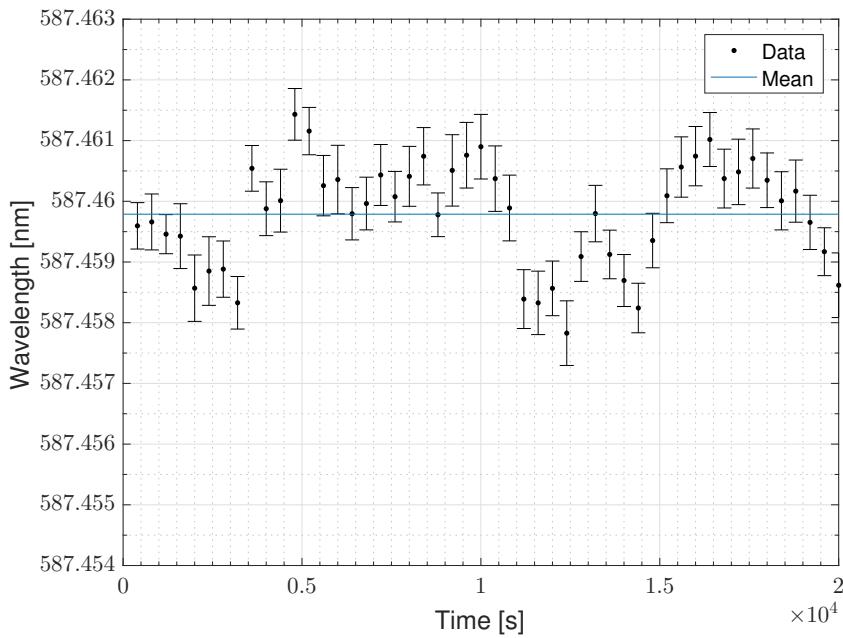


(a) Measured wavelengths over time.

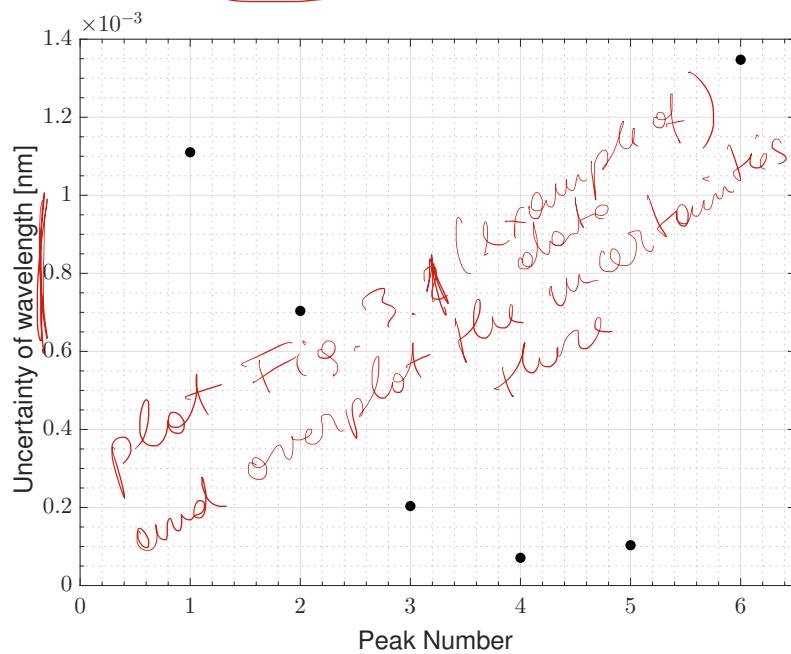


(b) FWHM for wavelengths over time.

Figure 3.3: First Experiment: In the top panel the found wavelengths, for peak 4, from the thousand measurements is shown over time. In the bottom panel the FWHM values for the found wavelengths, for peak 4, are shown.



(a) Wavelengths measured when the measurements were binned.



(b) The uncertainty of the average wavelength for every peak.

Figure 3.4: First Experiment: In the top panel the average wavelengths for bins containing twenty measurements are shown over time. The uncertainty of each wavelength is illustrated with errorbars. In the bottom panel the uncertainty of the total average wavelength found for each peak is shown.

uph.

3.3 Second Experiment - Simulated Pointing via Vibrations

For the second experiment the same methods were used to analyze the data from the measurements and to filter the measurements which were badly fitted. Based

3.3. Second Experiment - Simulated Pointing via Vibrations

Peak number	Average Wavelength [nm]	Laboratory Wavelength	$S_x [10^{-3} \text{ nm}]$
1	389,02	388,65	1,1
2	447,22	447,14	0,7
3	501,56	501,58	0,2
4	587,46	587,56	0,1
5	667,66	667,82	0,1
6	706,34	706,52	1,3

Table 3.2: First Experiment: Overview of the average wavelengths of the six peaks calculated from a thousand measurements. The uncertainty of each average wavelength and the laboratory wavelengths are also shown.

on the experience of determining the peak wavelengths from the measurements in the first experiment, both for every measurement and with measurements binned together, the wavelength was determined by binning measurements and calculating the uncertainty of the average wavelength. This is done because the uncertainty of the found wavelengths when using every measurement alone is large compared to the range the found wavelengths are within.

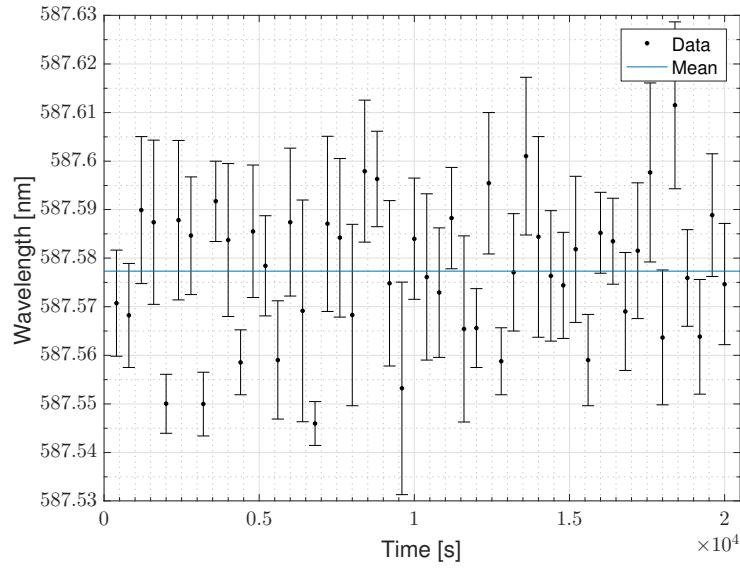
The measurements were divided into bins containing twenty measurements each. The average wavelength for the six peaks in every bin were calculated with eq. 3.4 and the uncertainties were calculated with eq. 3.6. For peak 4, the average wavelengths found over time are shown in fig. 3.5a.

For each peak of all the found wavelengths, were averaged and their uncertainties were calculated. The uncertainties are shown in fig. 3.4b. The average wavelengths found along with the calculated uncertainty for each peak are shown in tbl. 3.3.

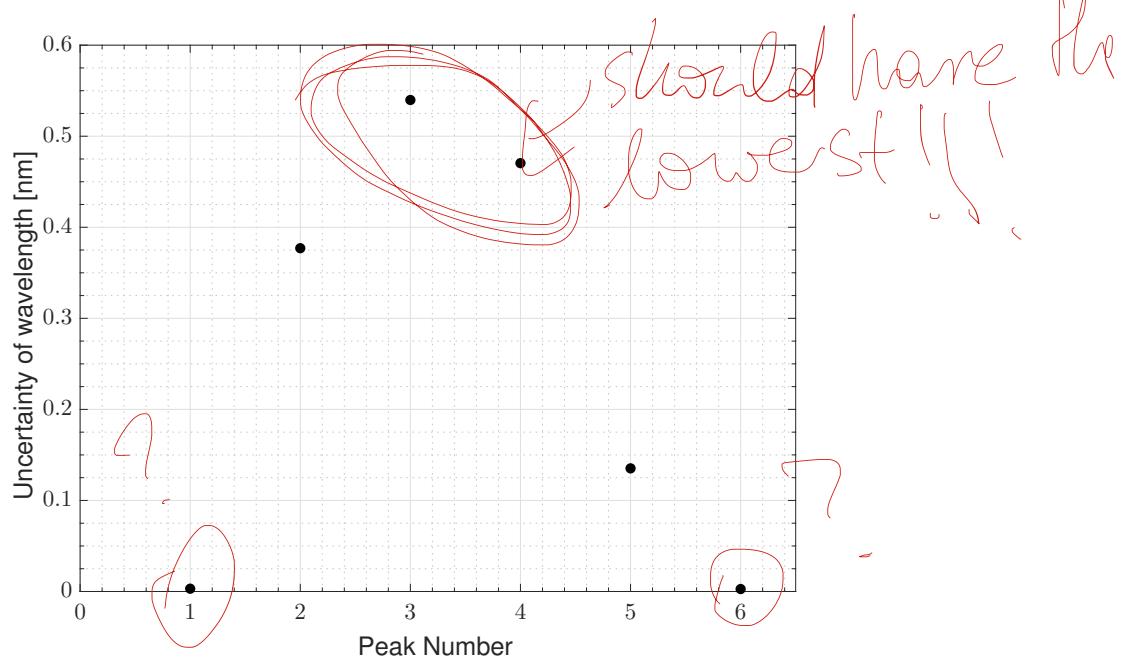
Peak number	Average Wavelength [nm]	Laboratory Wavelength	$S_x [\text{nm}]$
1	389,06	388,65	0,01
2	448,41	447,14	0,37
3	503,29	501,58	0,54
4	588,13	587,56	0,47
5	667,82	667,82	0,14
6	706,34	706,52	0,02

Table 3.3: Second Experiment: Overview of the average wavelengths of the six peaks calculated from a thousand measurements.

3.3. Second Experiment - Simulated Pointing via Vibrations



(a) Wavelengths measured with bins containing twenty measurements for peak 4.



(b) The uncertainty of the average wavelength for every peak.

Figure 3.5: Second Experiment: In the top panel the calculated average wavelengths for peak 4, with bins containing twenty measurements, are shown over time. The uncertainty of each wavelength is illustrated with errorbars and the mean over all the found wavelengths is shown. In the bottom panel the uncertainty of the total average wavelength found for each peak is shown.

3.4 Third Experiment - Temperature Variations

For the third experiment, 60 measurement were made for twelve different temperature steps. The temperatures are listen in tbl. 3.4.

Step	Temperature [°C]	Step	Temperature [°C]	Step	Temperature [°C]
1	19,5	5	32,4	9	42,2
2	25,0	6	35,9	10	44,8
3	28,1	7	36,9	11	47,8
4	29,9	8	39,8	12	49,3

Table 3.4: The twelve temperature steps where measurements were made for the third experiment.

In the 60 measurements the six peaks were fitted in the same way as in the first and second experiment. The wavelengths found for each peak in the 60 measurements were then used to calculate the average wavelength for every peak and their uncertainties were calculated. This was done for all temperatures. The shift of the wavelengths measured by the spectrograph against the change in temperature for all six peaks is shown in fig. 3.6.

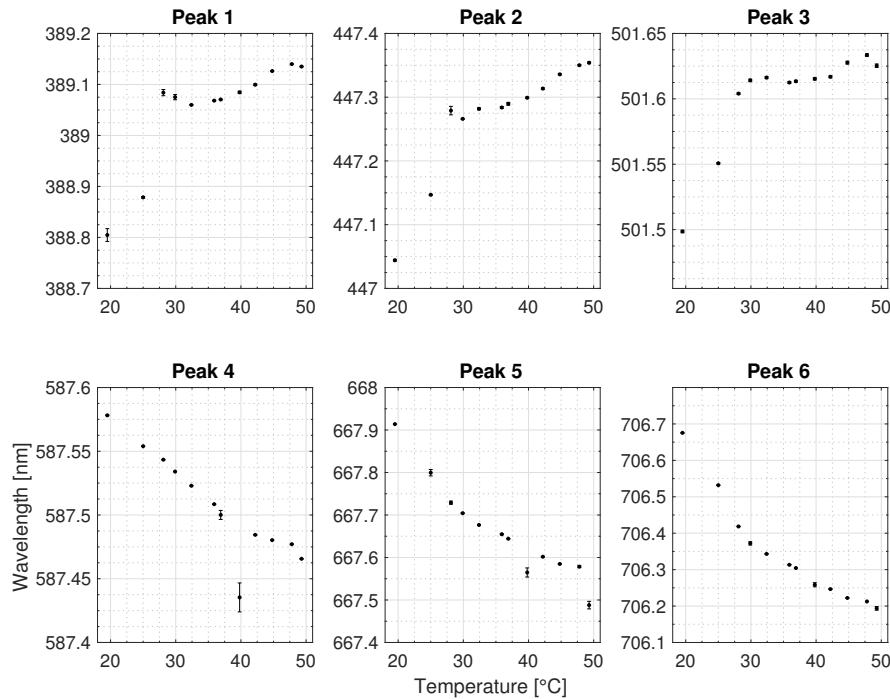


Figure 3.6: Third Experiment: The measured wavelengths by the spectrograph, for the six peaks as a function of temperature. Uncertainties are calculated with eq. 3.6.

For each peak the shift in wavelength as a function of temperature was fitted to a function,

$$\lambda_{shift}(T) = a_{shift}T + \lambda_{Laboratory}, \quad (3.7)$$

3.4. Third Experiment - Temperature Variations

where λ_{shift} is the shifted wavelength value, a_{shift} is the shift in wavelength per $^{\circ}\text{C}$ and $\lambda_{Laboratory}$ is the laboratory wavelength. The uncertainties, in form of the standard deviation, for the slope coefficients were found from their 95%-confidence interval.

Based on the results in fig. 3.6, the slope coefficients, a_{shift} , for the six peaks were plotted against the wavelengths of the peaks. The slope coefficients as a function of the wavelength were then fitted to the function,

$$a_{shift}(\lambda) = a_{slope}\lambda + b_{offset}, \quad (3.8)$$

where a_{slope} is the change of the a_{shift} coefficients per wavelength, λ , and b_{offset} is an offset of the scale for the spectrograph.

The a_{shift} coefficients against wavelength is shown together with the fitted eq. 3.8 in fig. 3.7.

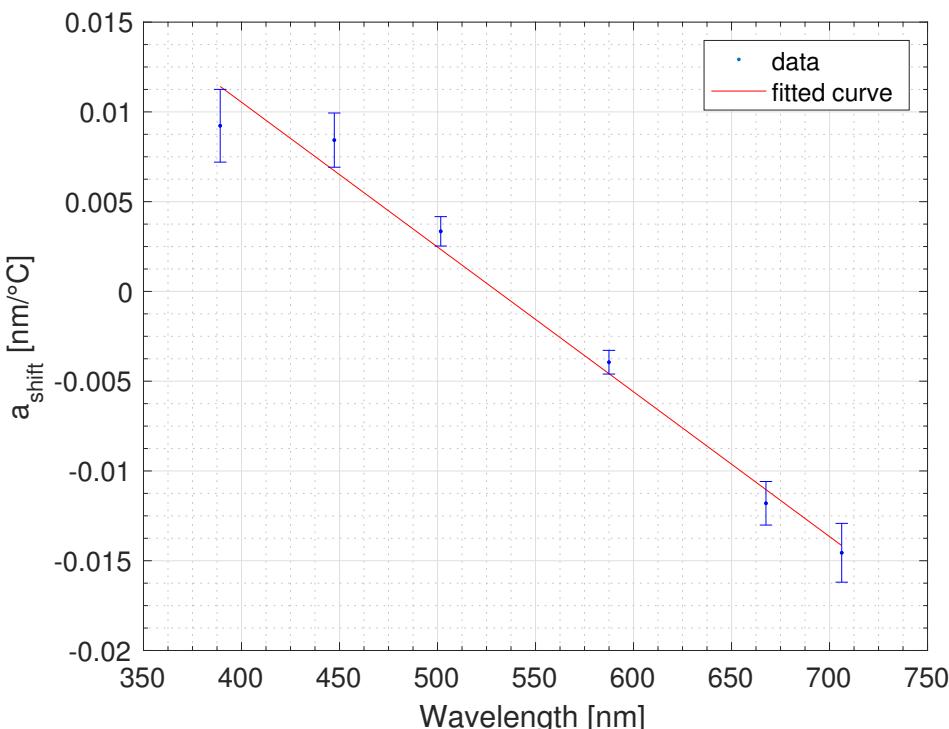


Figure 3.7: The a_{shift} coefficient are shown as function of wavelength. The a_{shift} coefficients are found by a fit to the found wavelengths under the assumption, that the found wavelengths of the peaks are shifted linearly as a function of temperature.

The results from the three experiments will be discussed in the following chapter.

4

Discussion

The three developed experiments set out to simulate conditions the spectrograph would be working in if it was placed in a satellite in orbit around Earth.

The first experiment took measurements over a long period of time with the spectrograph being stationary. The analysis of the data from the first experiment was the first time that multiple measurements were used to examine to which precision the spectrograph could identify the wavelengths of the selected peaks. The results from the first experiment, showed that using single measurements from the spectrograph meant that the uncertainties of the found wavelengths were in the order of 1 nm magnitude. Further analysis of the data showed that binning measurements together and averaging their values, meant that the wavelengths could be identified with uncertainties in the order of 10^{-3} nm magnitude. The use of multiple measurements is a method already used to correct for cosmic rays producing additional counts in pixels on the CCD (Kjeldsen et al.). The binning of measurements to determine the wavelengths was therefore used in the following two experiments.

It was clear from the first experiment that it would be ideal to do further tests of the spectrograph to investigate the cause of the "shoulder" peak in the measurements, shown in fig. 3.2a. To determine the cause of this, the spectrograph would have to be taken apart for further examination which was beyond the scope of this thesis. It would be ideal to run the experiments again once the cause of the "shoulder" peak has been identified and removed. The final results of the first experiment suggested that the wavelength midrange has the largest stability in determining the wavelengths of the peaks, corresponding to a smaller uncertainty of the found wavelength as shown in fig. 3.4b. Repeated runs of the first experiment would be needed to reproduce and verify the results.

For the second experiment the precision of the wavelengths identified for the six peaks was examined under simulation of pointing. The measurements were binned together and an average wavelength was found for each peak. The results of the second experiment found that the wavelengths for the peaks were

found with larger uncertainties than in the first experiment. Opposite the first experiment, the second experiment suggests that the precision of the wavelength identification for the peaks is smallest in the midrange of the spectrograph. This further suggests for the experiments to be run again before concluding on the final results.

The third experiment examined the change in identified wavelengths for the six peaks at different temperatures. For peak 1 to peak 3, which cover the range from 388 nm to 503 nm, the results shown in fig. 3.6 suggested that peaks were shifted to higher wavelengths. The results also showed that the wavelength shifts for peak 1 to 3 became smaller when going from peak 1 to peak 3. For peak 4 to peak 6, which cover the range from 587 nm to 706 nm, suggested that the peaks were shifted to lower wavelengths. The shift to lower wavelengths increased for the peaks going from peak 4 to peak 6.

Furthermore from the results it seemed that the shifts for the peaks 4 to 6, were linearly dependent of temperature. For peak 1 to 3 is was not clear that the shifts could be linearly dependent on temperature, as the measurements around 30 °C were outliers for this to be the case. However, based on the results for peak 4 to 6, the assumption that the shifts for all peaks were linear dependent of temperature was made. The identified wavelength for each peak was then fitted to a linear function of the temperature, so the slope for each fit could be compared. This was done in fig. 3.7 which suggested that the slopes for the different fits were themselves linear dependent of the wavelength. For these results to be verified, the third experiment would need to be run several times again and produce similar results before being able to conclude that they are in fact correct. This would be very interesting to examine ongoing if further testing was to be done.

This is a summary not a discussion.

✓ What do you expect?

✓ What do you get and why? Even if you don't know speculate!

✓ What needs to be done in order to find out?

5

Conclusion

~~Results~~ This is compound
How does with the possible answers?

In this thesis the USB4000 spectrograph was examined to illuminate the possibilities and limitations for using a compact spectrograph for observations in space onboard a Cubesat. Taking in to consideration the environment satellites are subject to, three experiments were developed and build to test the measurements from the spectrograph, on six of the emission lines from Helium.

If what's the share?
The first experiment was designed to test the stability of stationary measurements over a long period of time. From the first experiment it was found that noise in form of "shoulder" peaks was present at a constant distance from the true peaks in the measured spectrums. It was found that the noise from the "shoulder" peaks could be filtered out in the analysis so the uncertainties for the true peaks wavelengths could be found to be in the order of magnitude 10^{-3} nm. Furthermore it was suggested that the cause of the noise should be examined in further tests.

In the second experiment the stability of measurements when simulating pointing of the satellite, by vibrations was examined. It was found that with simulated pointing the wavelengths of the peaks had uncertainties in the order of magnitude 10^{-1} nm.

Why?
The third experiment tested the effect of the measurements taken with varying temperature. It was found that the identified wavelengths for the peaks were shifted when the temperature was varied for measurements. The results from the third experiment suggested that the shifts of the six peaks were not identical. A theory was suggested that the rate of change of wavelength for the different peaks was linear dependent of wavelength however it was concluded that further experiments must be conducted with similar results in order to verify this theory.

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