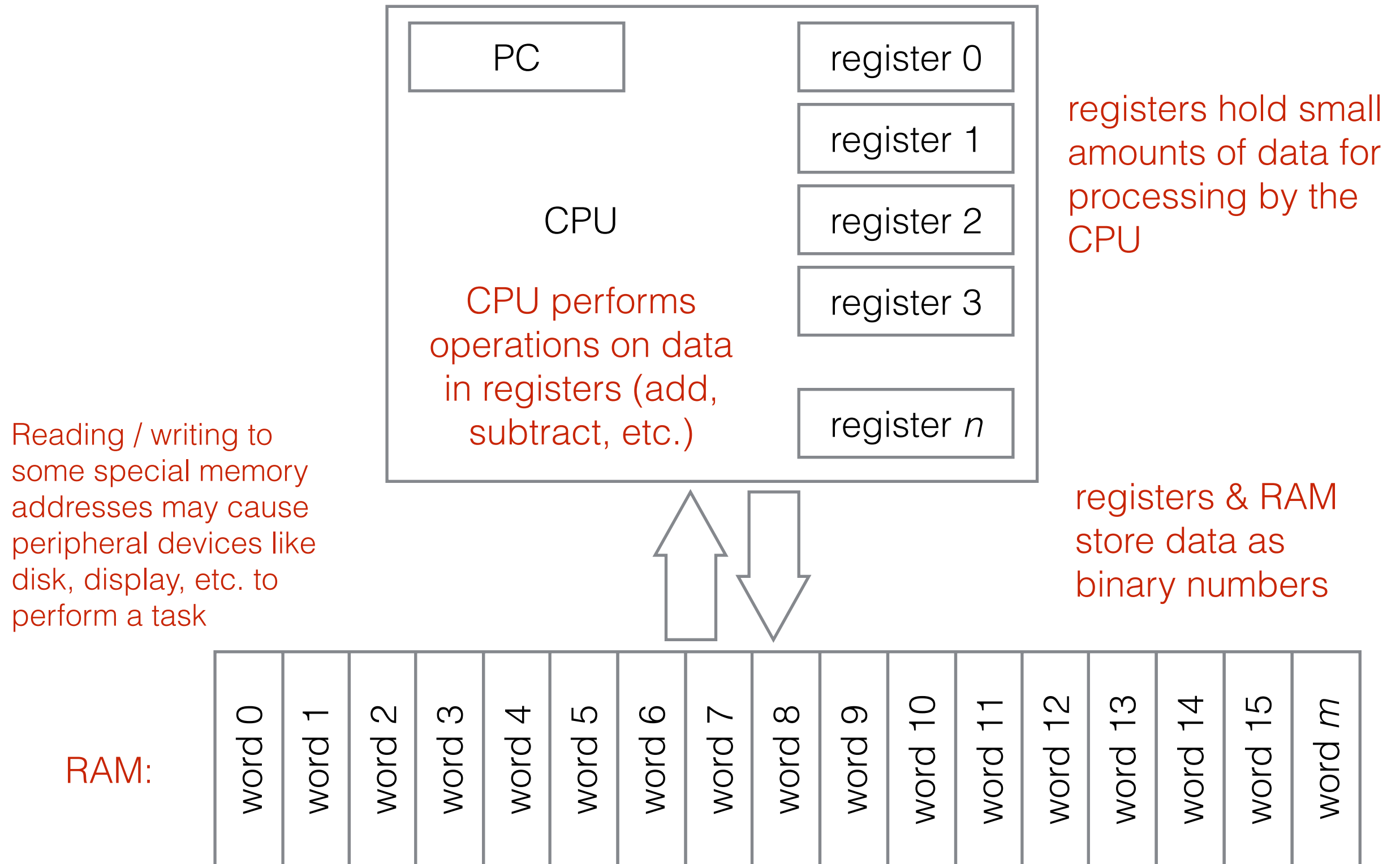


Computer Architecture

02-201 / 02-601

The Conceptual Architecture of a Computer



Binary Representation

Base 10 (decimal) notation:

$$\begin{array}{r} 4 \ 2 \ 5 \ 6 \\ + \ 4 \times 10^3 \\ \hline 4 \ 2 \ 5 \ 6 \end{array}$$

Diagram illustrating the expansion of the decimal number 4256 into its positional values:

- 4 $\times 10^3$
- 2 $\times 10^2$
- 5 $\times 10^1$
- 6 $\times 10^0$

Computers store the numbers in binary because it has transistors that can encode 0 and 1 efficiently.

Each 0 and 1 is a *bit*.

Built-in number types each have a maximum number of bits.

Base 2 (binary) notation:

$$\begin{array}{r} 1 \ 0 \ 0 \ 0 \ 0 \ 1 \ 0 \ 1 \ 0 \ 0 \ 0 \ 0 \ 0 \\ + \ 1 \times 2^{12} \\ \hline \end{array}$$

Diagram illustrating the expansion of the binary number 10000101000000 into its positional values:

- 1 $\times 2^{12}$
- 0 $\times 2^{11}$
- 0 $\times 2^{10}$
- 0 $\times 2^9$
- 0 $\times 2^8$
- 1 $\times 2^7$
- 0 $\times 2^6$
- 1 $\times 2^5$
- 0 $\times 2^4$
- 0 $\times 2^3$
- 0 $\times 2^2$
- 0 $\times 2^1$
- 0 $\times 2^0$

$$4256 = 10000101000000$$

Hexadecimal Representation

Decimal isn't good for computers because they work with bits.
But writing everything in binary would be tedious.
Hence, we often use base 16, aka "hexadecimal":

Base 10 (decimal) notation:

$$\begin{array}{r} 4 \ 2 \ 5 \ 6 \\ \vdots \quad \vdots \quad \vdots \quad \downarrow \\ \vdots \quad \vdots \quad 6 \times 10^0 \\ \vdots \quad 5 \times 10^1 \\ 2 \times 10^2 \\ + \ 4 \times 10^3 \\ \hline 4 \ 2 \ 5 \ 6 \end{array}$$

Base 16 (hexadecimal) notation:

$$\begin{array}{r} 1 \ 0 \ A \ 0 \\ \vdots \quad \vdots \quad \vdots \quad \downarrow \\ \vdots \quad \vdots \quad A \times 16^1 \\ 0 \times 16^2 \\ + \ 1 \times 16^3 \\ \hline 1 \times 4096 + 10 \times 16 = 4256 \end{array}$$

Need 16 different digits, so use 0,1,2,3,4,5,6,7,8,9,A,B,C,D,E,F

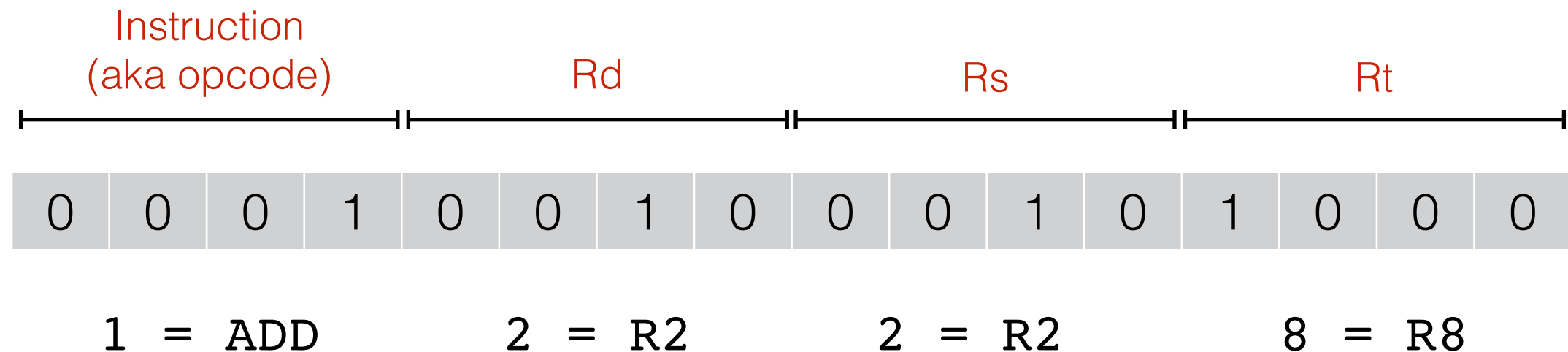
A=10, B=11, C=12, D=13, E=14, F=15

Add CPU instruction

ADD Rd, Rs, Rt

Set register Rd to $R_s + R_t$

An instruction is encoded as a sequence of bits:



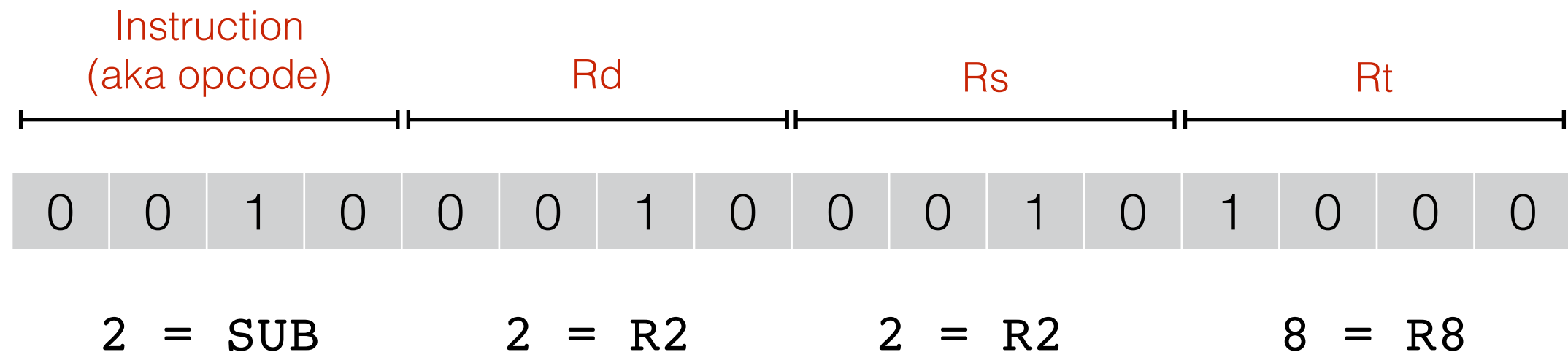
Written as a hexadecimal number: 1228_{16}

Subtract CPU instruction

SUB Rd, Rs, Rt

Set register Rd to Rs - Rt

The SUB instruction is the same format as ADD, but with a different opcode:



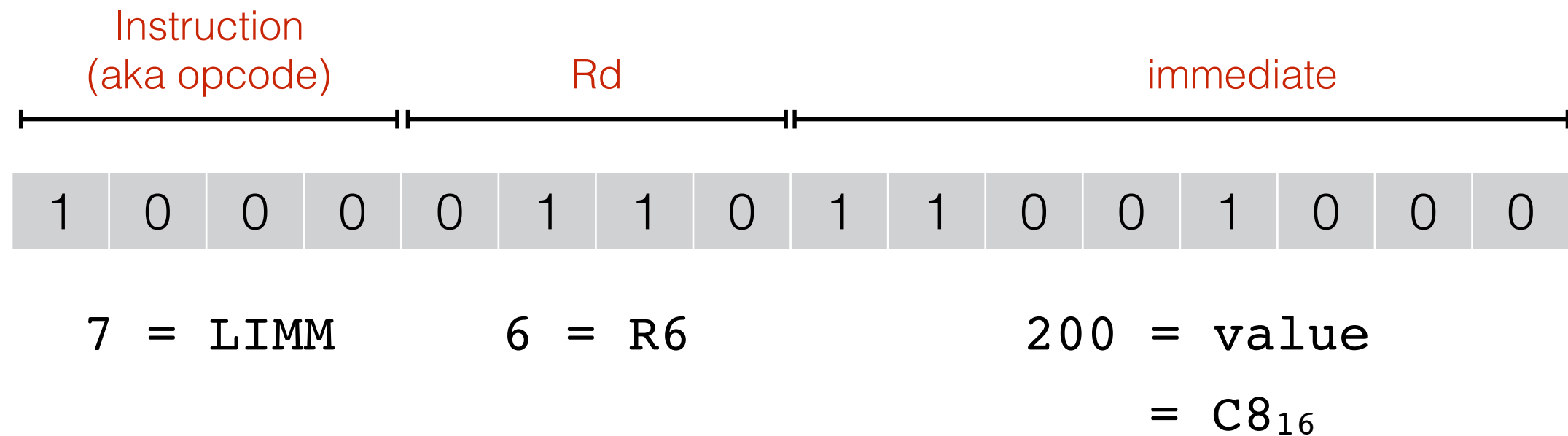
Written as a hexadecimal number: 2228_{16}

Load “Immediate” Instruction

LIMM Rd, value

Set register Rd to value

For LIMM, the last 8 bits give the value to copy into Rd:



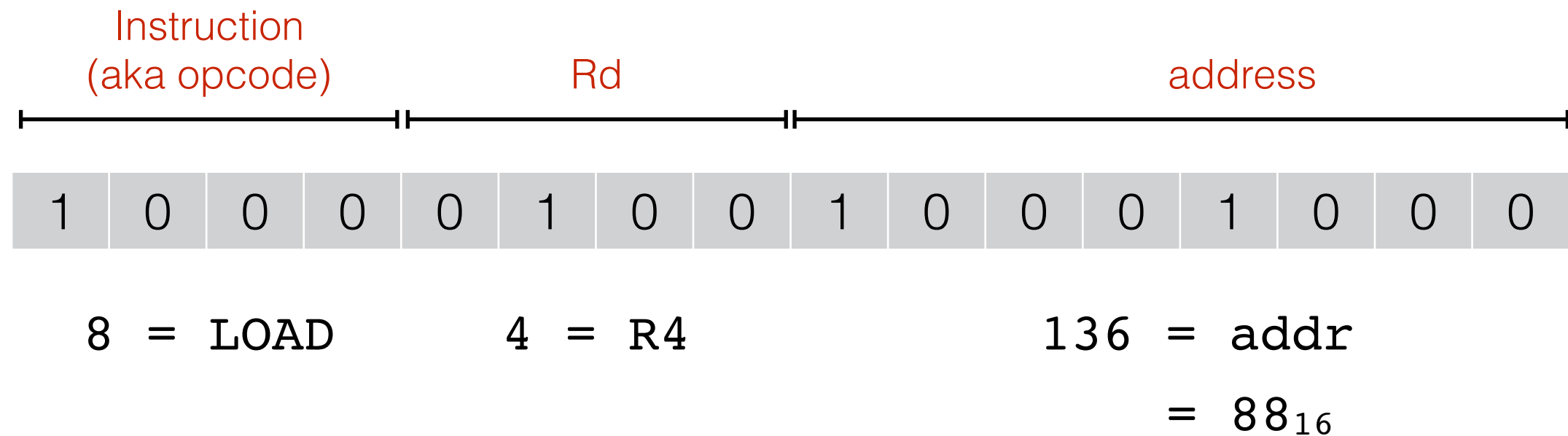
Written as a hexadecimal number: 76C8₁₆

Load Instruction

LOAD Rd, addr

Set register Rd to ram[addr]

For LOAD, the last 8 bits give the address of the memory cell to copy into Rd:



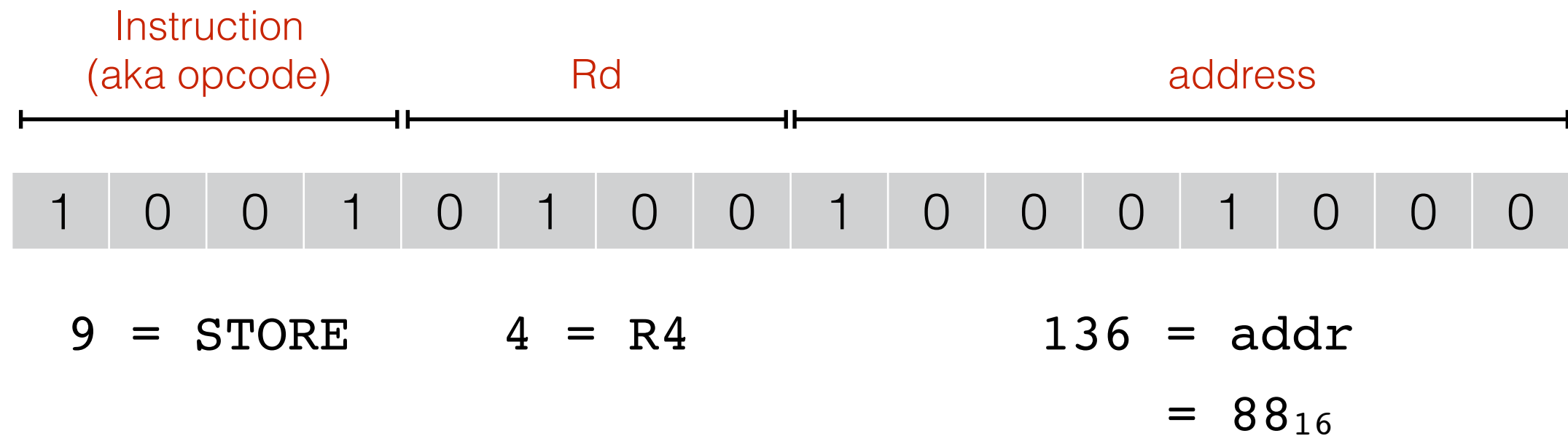
Written as a hexadecimal number: 8488₁₆

Store Instruction

STORE Rd, addr

Set register ram[addr] to Rd

For LOAD, the last 8 bits give the address of the memory cell to copy into Rd:



Written as a hexadecimal number: 9488₁₆

An Example Program

```
LIMM R1, 64      // R1 = 200
LIMM R2, 1E      // R2 = 30
ADD R2, R1, R2   // R2 = R1 + R2
STORE R2, 46     // ram[70] = R2
```

What does this program do?

An Example Program

LIMM R1, 64	// R1 = 200
LIMM R2, 1E	// R2 = 30
ADD R2, R1, R2	// R2 = R1 + R2
STORE R2, 46	// ram[70] = R2

What does this program do?

Stores 200 + 30 into memory location 70

Similar to the following Go program:

```
var r1 int = 200
var r2 int = 30
r2 = r1 + r2
var ram70 int = r2
```

Go manages the registers and memory locations for you.

It may keep a variable in a register, memory, or both.

Where is the program stored?

The program is just a sequence of **integers** that encode for instructions.

```
LIMM R1, 64      // R1 = 200      ; 7164
LIMM R2, 1E      // R2 = 30       ; 721E
ADD R2, R1, R2   // R2 = R1 + R2  ; 1212
STORE R2, 46     // ram[70] = R2   ; 9246
```

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```

These integers are stored in the same RAM used for variables:

address	RAM
↓	
10:	7164
11:	721E
12:	1212
13:	9242

Where is the program stored?

The program is just a sequence of **integers** that encode for instructions.

```
LIMM R1, 64          // R1 = 200          ; 7164
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STORE R2, 46          // ram[70] = R2     ; 9246
```

These integers are stored in the same RAM used for variables:

The CPU has a special register called PC (“program counter”) that contains the address of the current instruction.

After each instruction, the PC is incremented by 1.

address		RAM
PC =	10:	7164
	11:	721E
	12:	1212
	13:	9242

Where is the program stored?

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```
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	↓	
	10:	7164
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	12:	1212
	13:	9242

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	10:	7164
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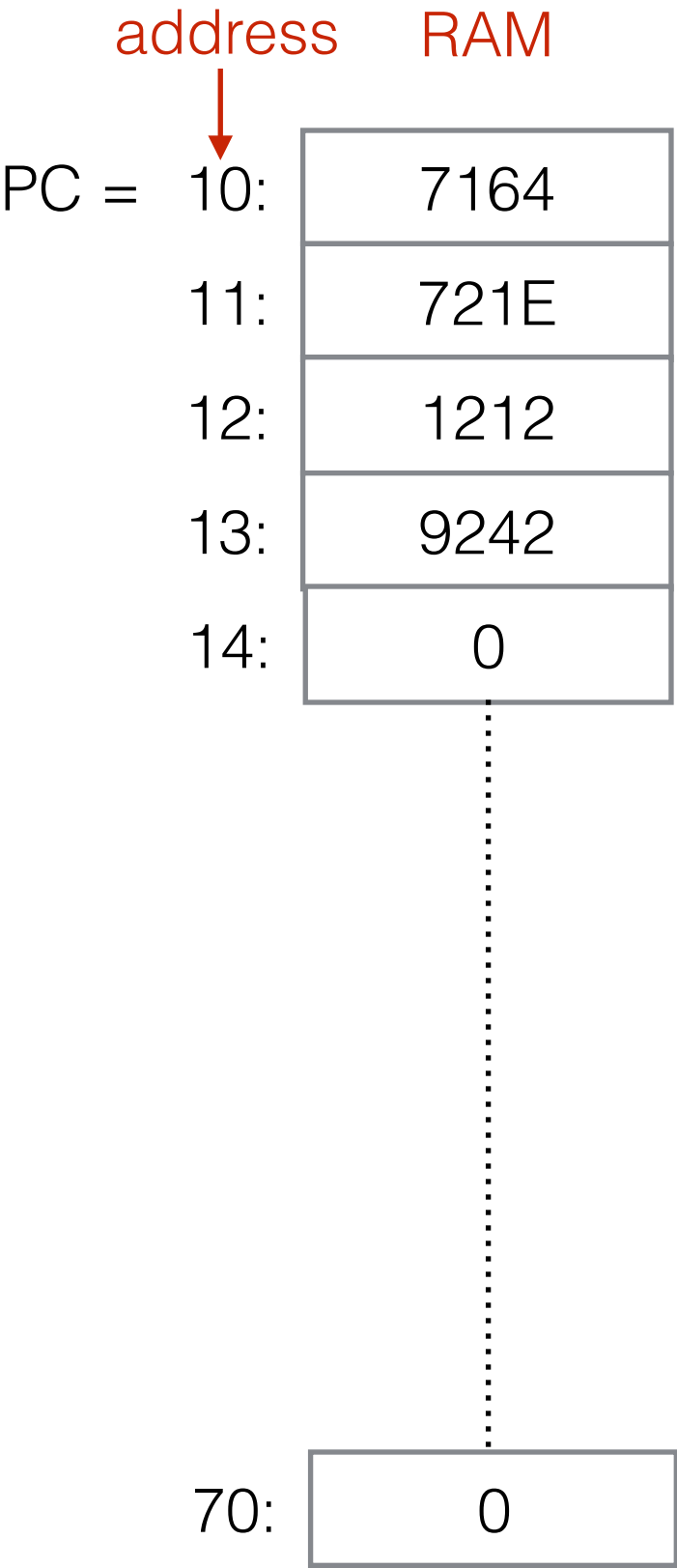
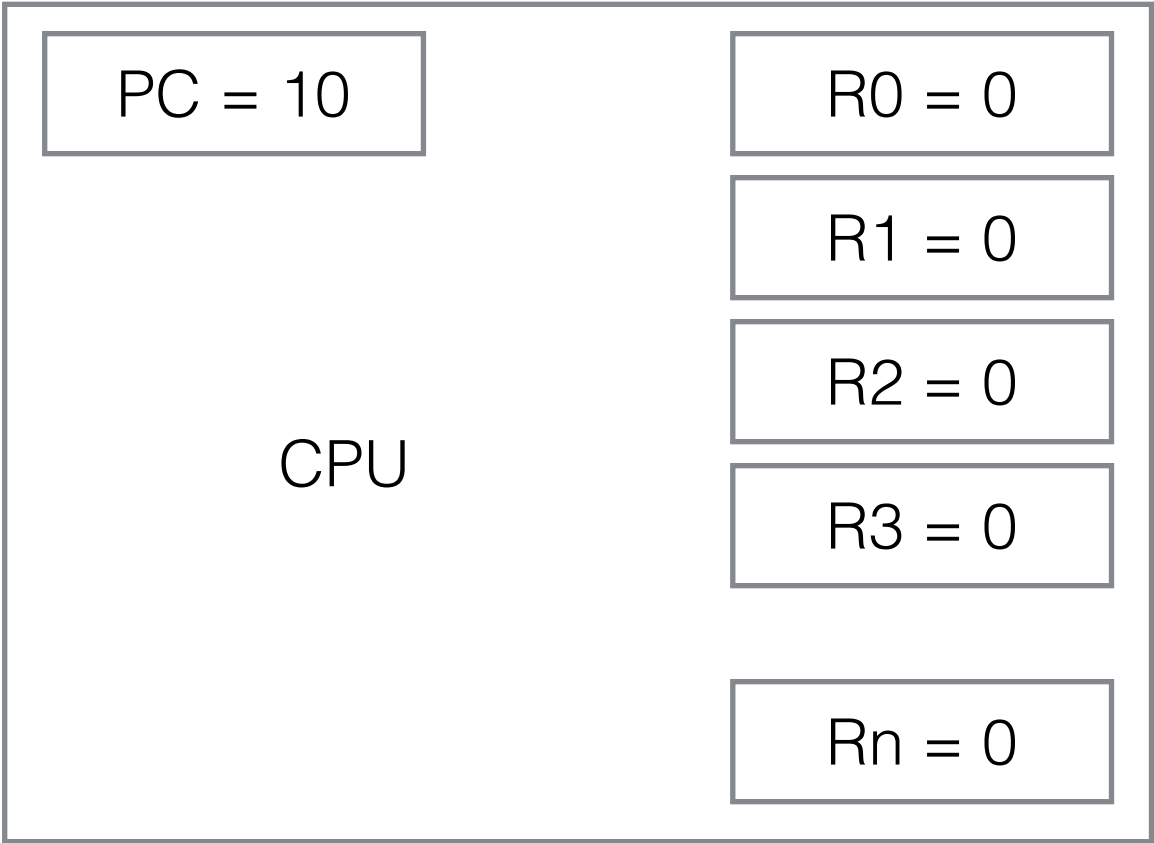
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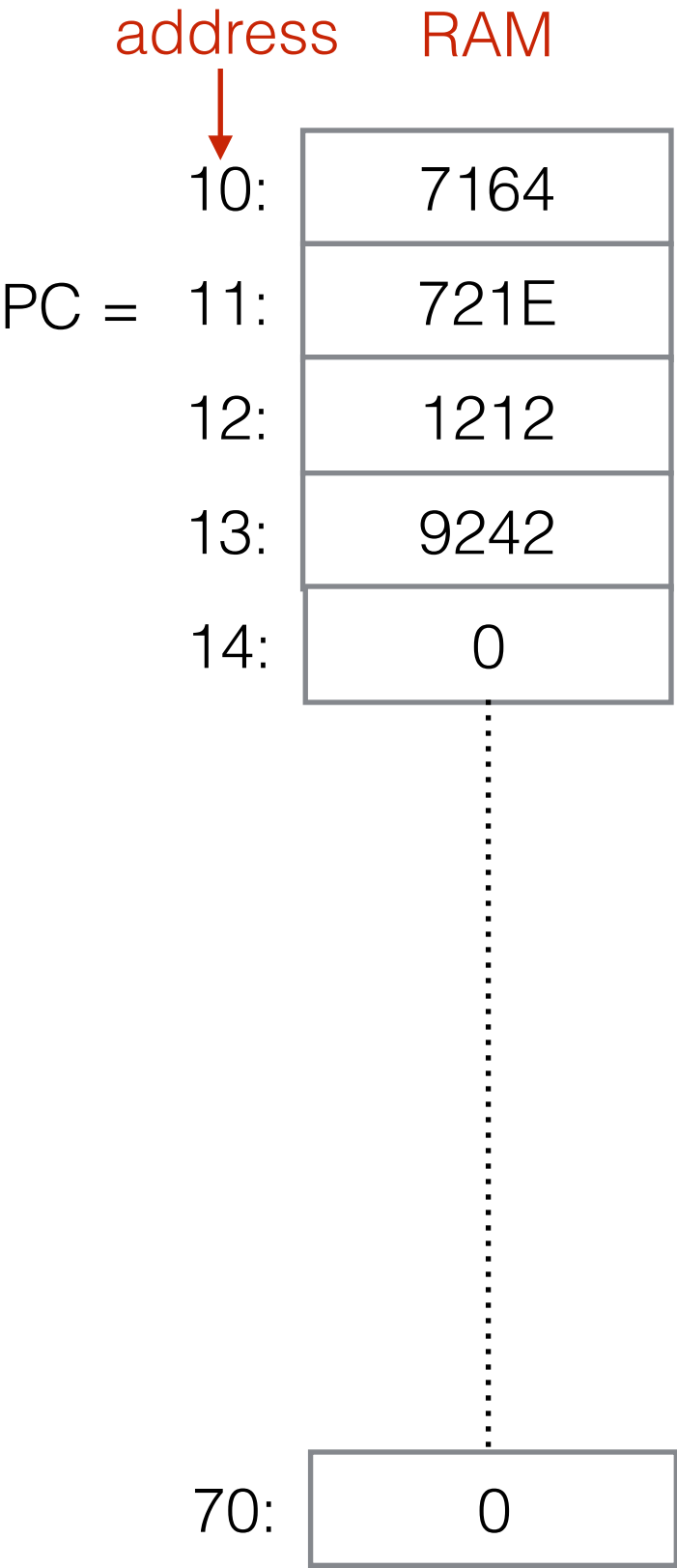
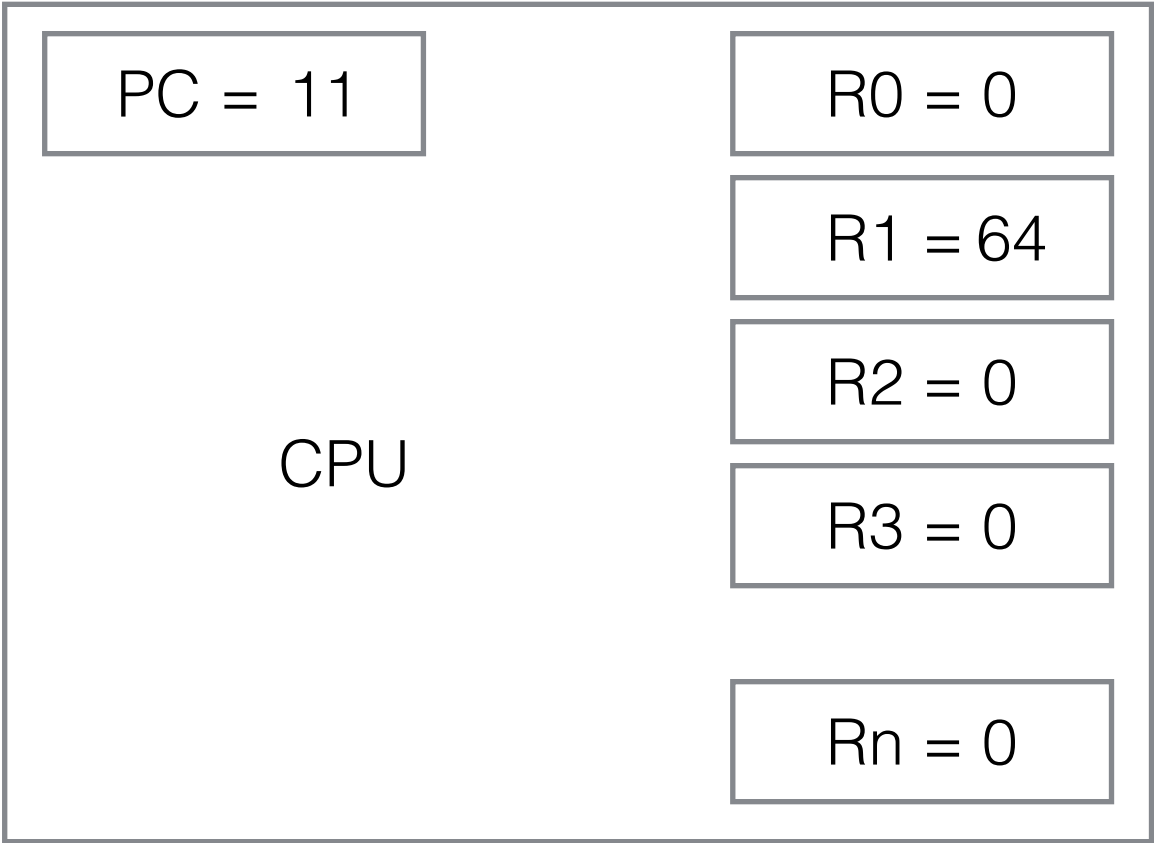
After each instruction, the PC is incremented by 1.

address	RAM
10:	7164
11:	721E
12:	1212
PC = 13:	9242

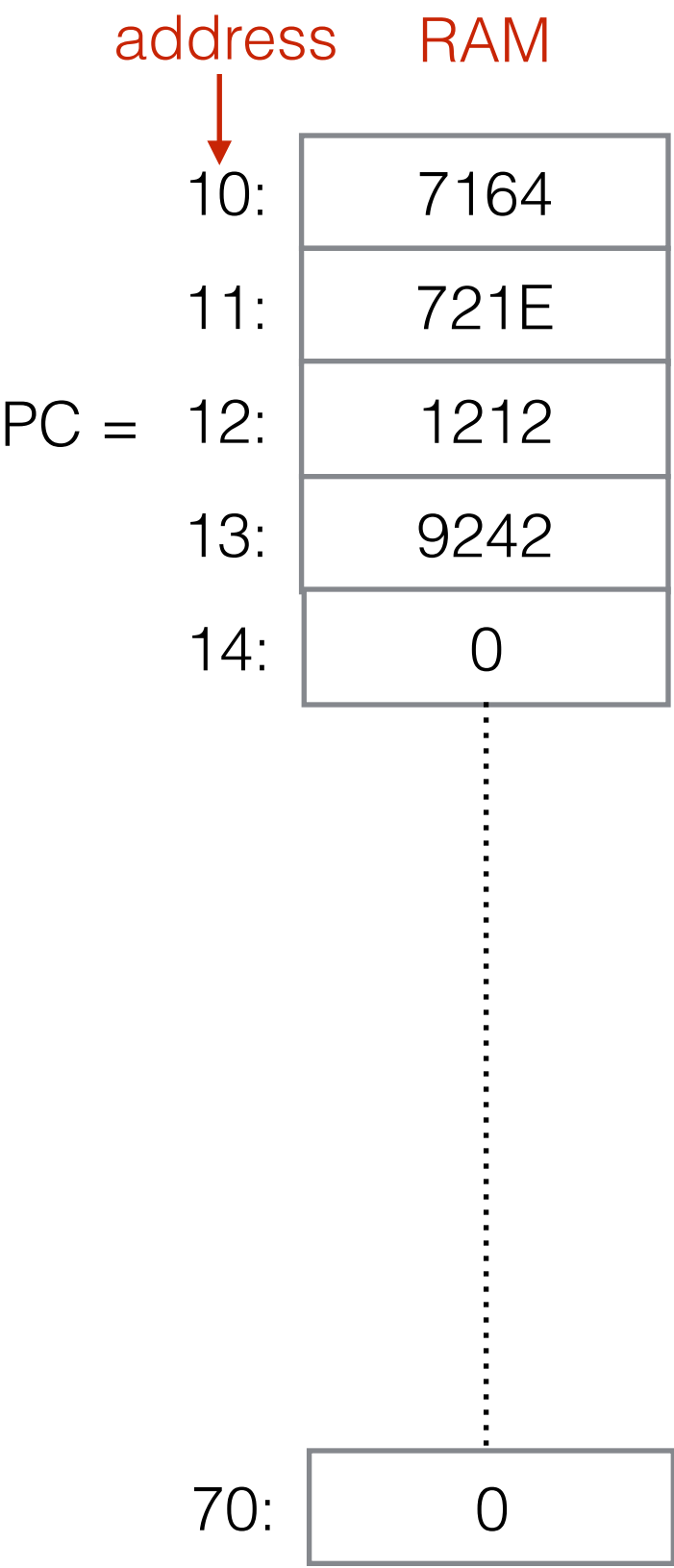
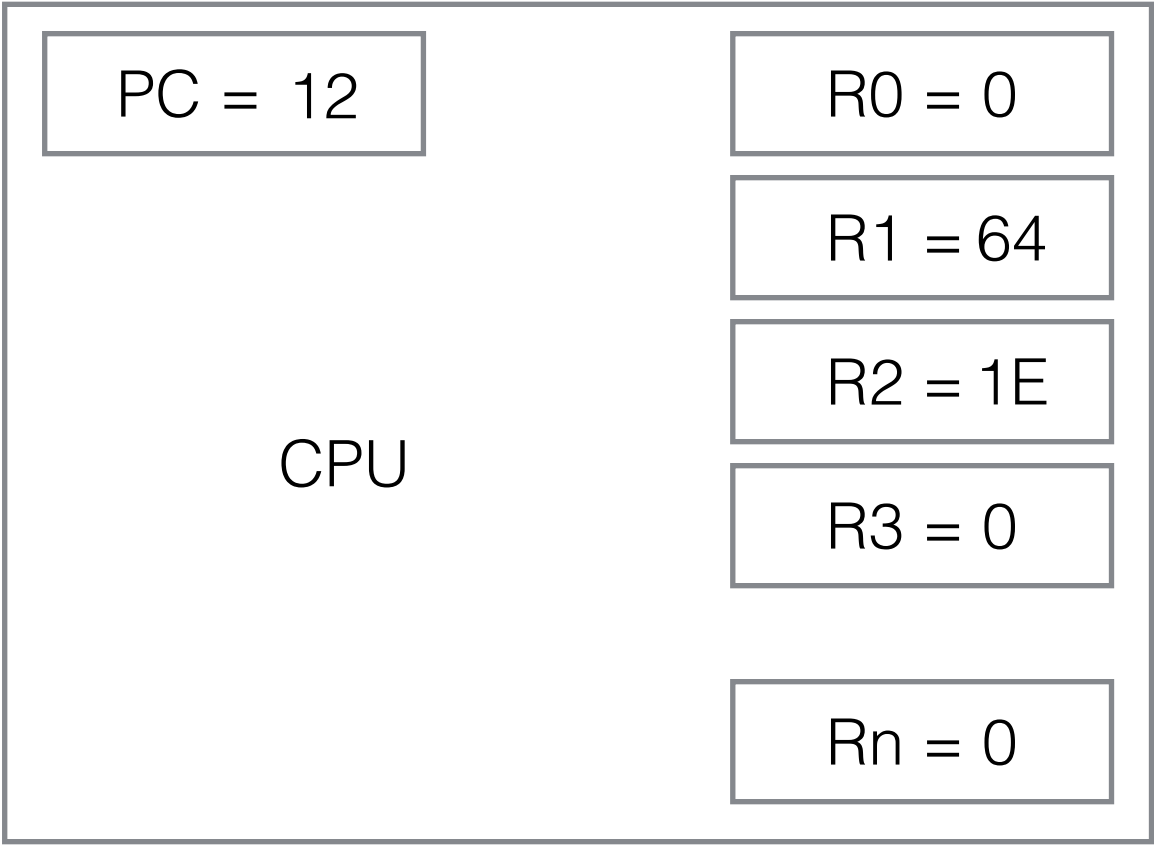
```
LIMM R1, 64      // R1 = 200      ; 7164
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ADD R2, R1, R2    // R2 = R1 + R2 ; 1212
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```



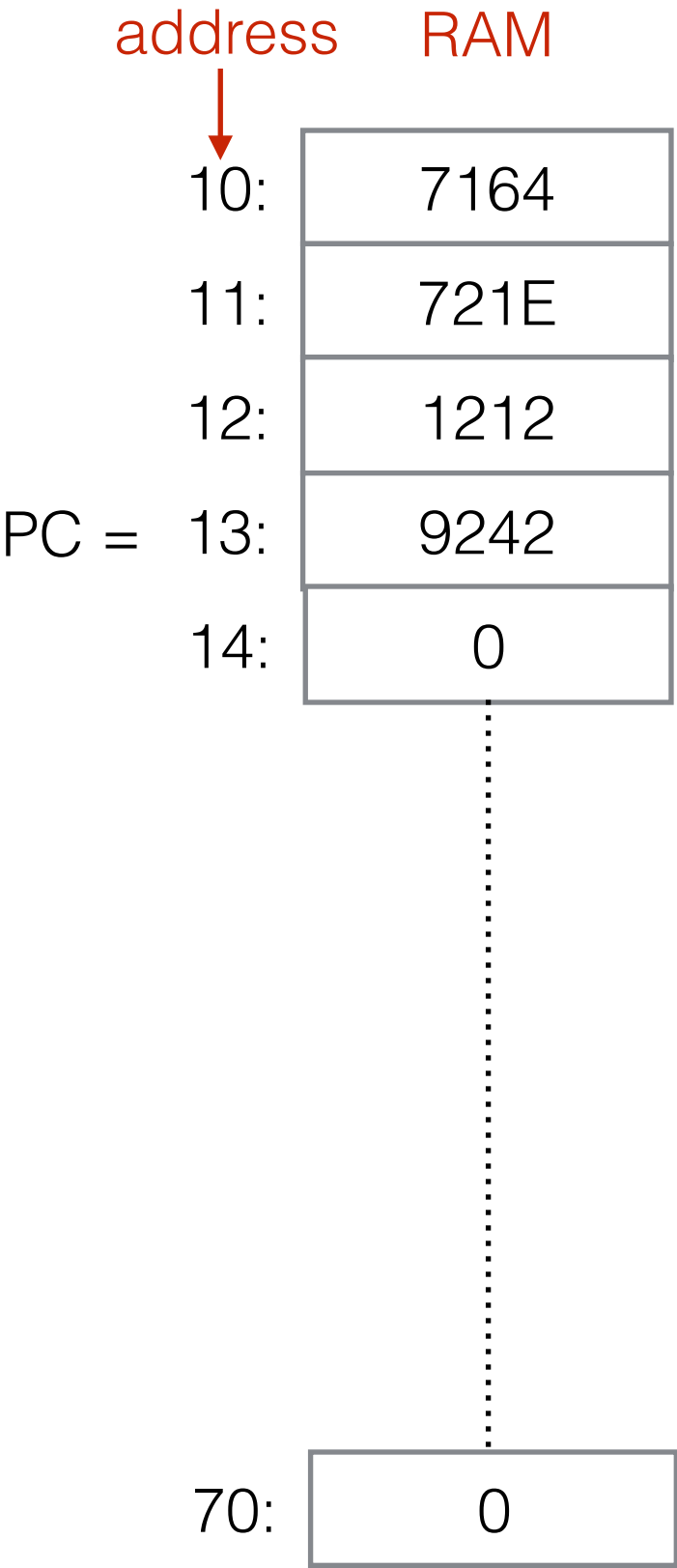
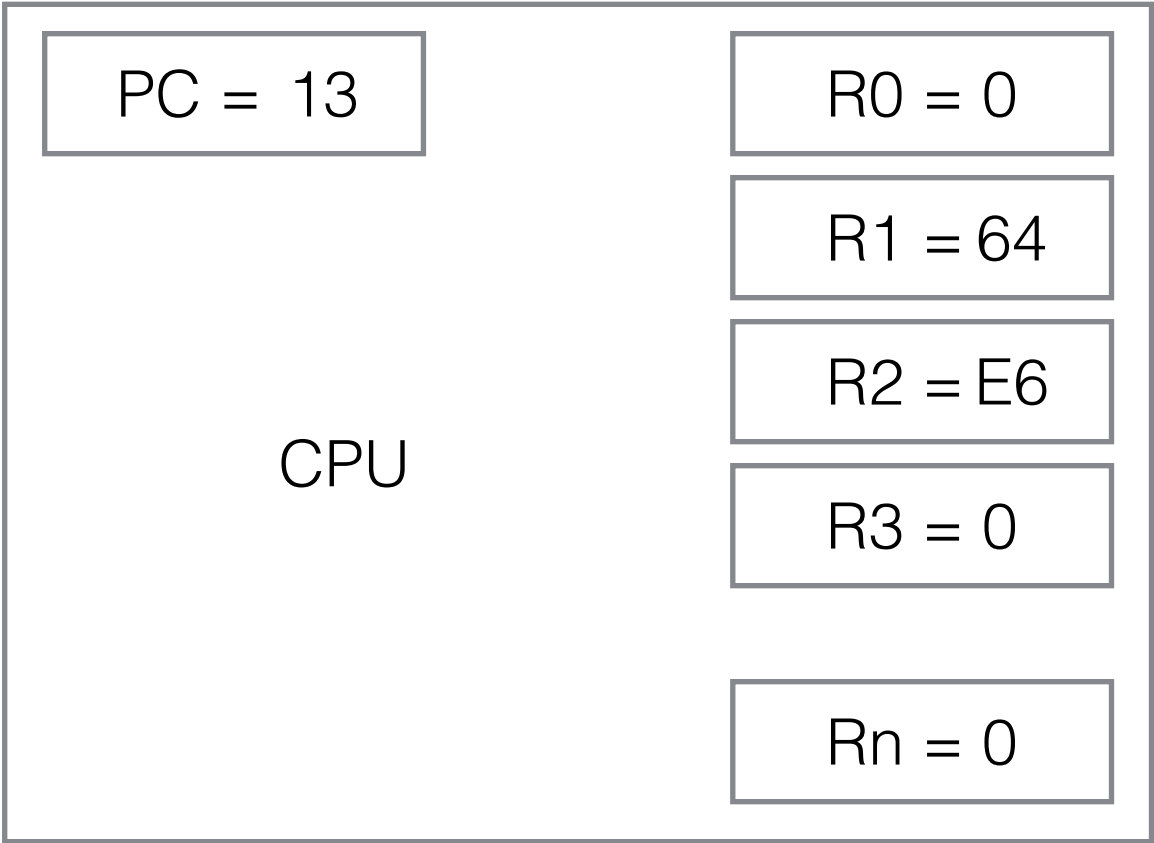
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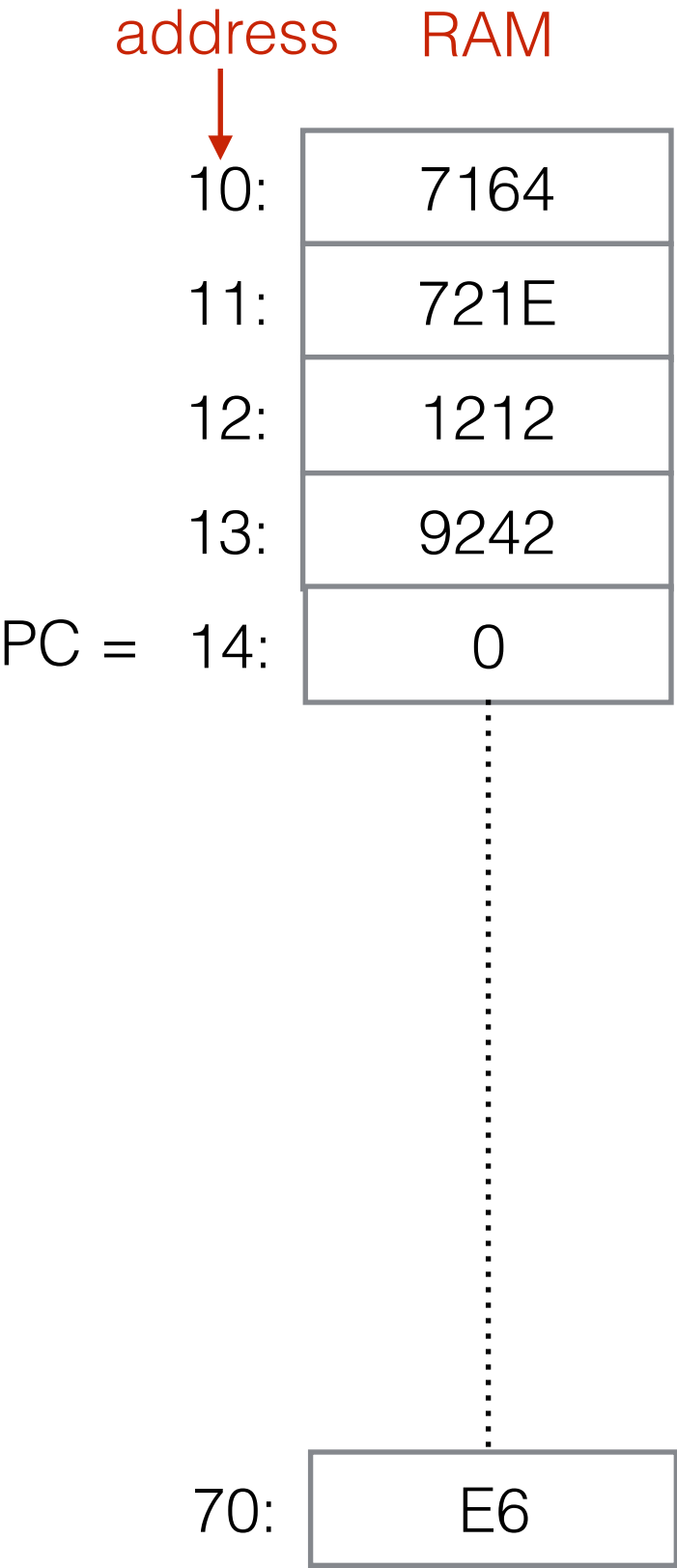
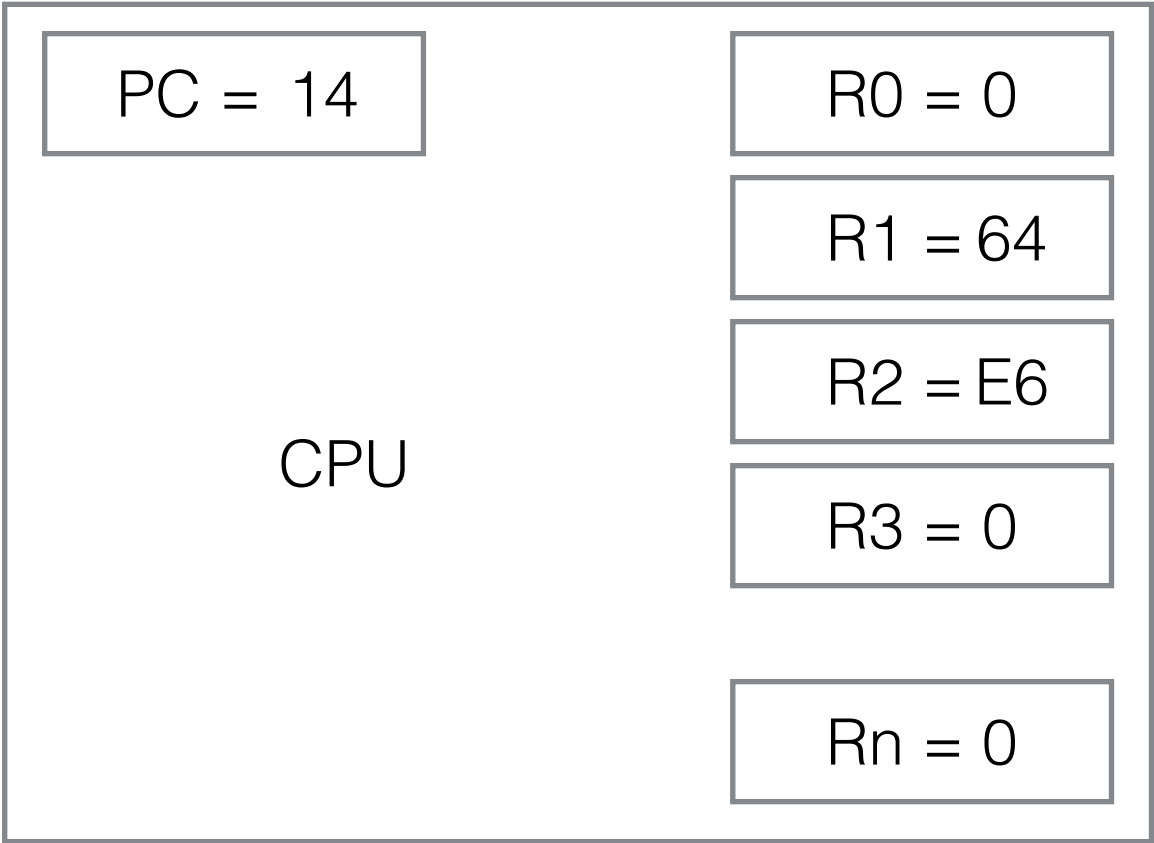
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```



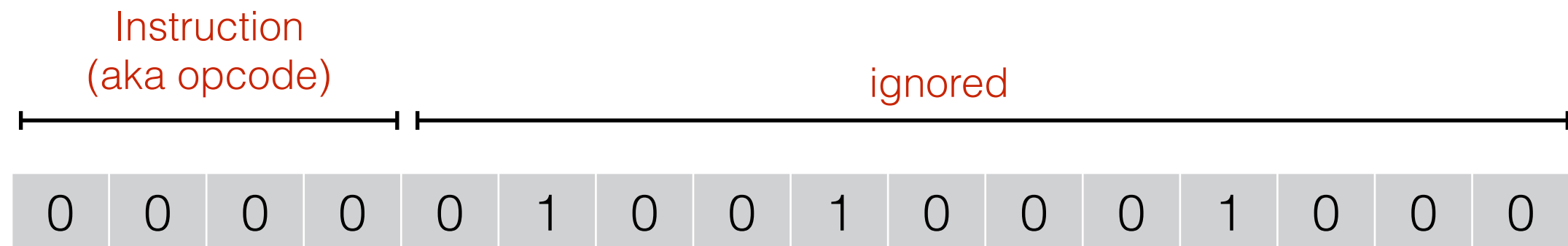
```
LIMM R1, 64      // R1 = 200      ; 7164
LIMM R2, 1E      // R2 = 30       ; 721E
ADD R2, R1, R2   // R2 = R1 + R2  ; 1212
STORE R2, 46     // ram[70] = R2   ; 9246
```



Ending the program

The computer will keep grabbing an integer, interpreting it as an instruction, and then incrementing PC indefinitely.

To stop this process, you have to add a HALT instruction:



0 = HALT

LIMM R1, 64	// R1 = 200	; 7164
LIMM R2, 1E	// R2 = 30	; 721E
ADD R2, R1, R2	// R2 = R1 + R2	; 1212
STORE R2, 46	// ram[70] = R2	; 9246
HALT	// stop program	; 0000

Input, Output, and 0

Register 0 always has value 0

Stores to memory location FF writes the value to the output

Reads from memory location FF read a value from the input

STORE R3, FF

Write the value R3 to the output

LOAD R4, FF

Read the next input value into R3

Example:

LIMM R1, 64	// R1 = 200	; 7164
LOAD R2, FF	// R2 = input	; 72FF
ADD R2, R1, R2	// R2 = R1 + R2	; 1212
STORE R2, FF	// write R2 to output	; 9246
HALT	// stop program	; 0000

Other Arithmetic Operations: AND

AND Rd, Rs, Rt

Set register Rd to Rs AND Rt

AND takes two binary numbers a and b and creates a binary c number where the ith bit of c is 1 if and only if the ith bits of both a and b are 1:

a:

0	0	1	0	0	0	1	0	0	0	1	0	1	1	0	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

b:

0	0	1	0	1	0	0	0	0	1	1	0	1	0	0	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

c:

0	0	1	0	0	0	0	0	0	0	1	0	1	0	0	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

↑
1 because both a and b
have 1 in this position.

↑
0 because both a has 0
in this position.

Exclusive Or: XOR

XOR Rd, Rs, Rt

Set register Rd to Rs XOR Rt

XOR takes two binary numbers a and b and creates a binary c number where the ith bit of c is 1 if either a or b but not both have 1 in their ith bit:

a:

0	0	1	0	0	0	1	0	0	0	1	0	1	1	0	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

b:

0	0	1	0	1	0	0	0	0	1	1	0	1	0	0	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

c:

0	0	0	0	1	0	1	0	0	1	0	0	0	1	0	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

↑
0 because both a and b
have 1 in this position.

↑
1 because exactly one
of a, b have 1 at this
position.

AND and XOR in Go

Go has bitwise operators:

& = AND

^ = XOR

```
var r1 int = 200
var r2 int = 30
r2 = r1 & r2
var r3 int
r3 = r2 ^ r1
```

r1 = 0000000011001000

r2 = 0000000000001110

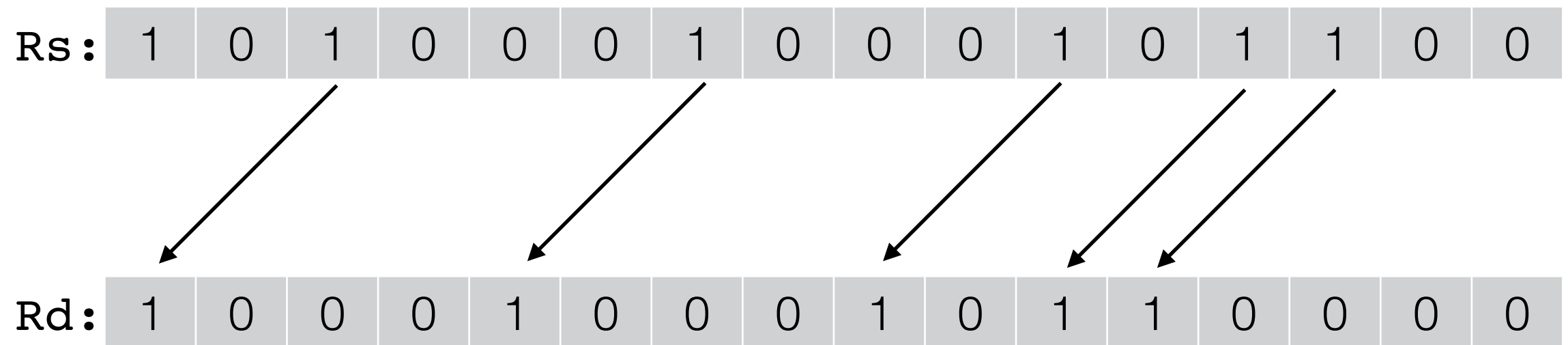
r2 = 0000000000001000

r3 = 0000000011000000

Left and Right Shift

LSHIFT Rd, Rs, Rt

Set register Rd to Rs shifted to the left by Rt digits



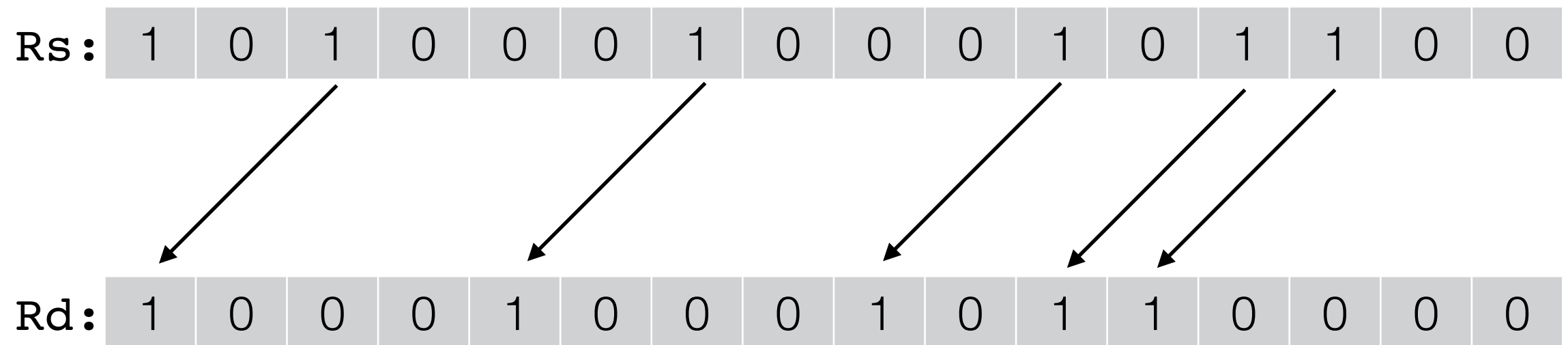
↑
Digits fall off
the left and
disappear

↑
0s come in at
the right

Left and Right Shift

LSHIFT Rd, Rs, Rt

Set register Rd to Rs shifted to the left by Rt digits



↑
Digits fall off
the left and
disappear

↑
0s come in at
the right

RSHIFT is the same except it shifts to the right:

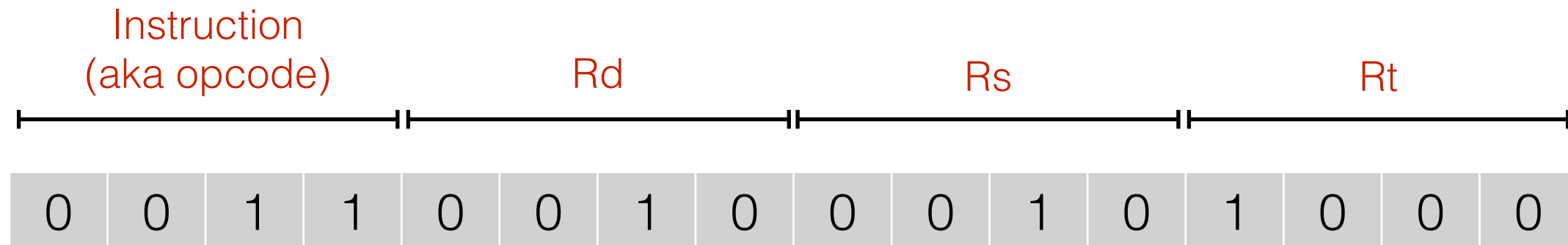
RSHIFT Rd, Rs, Rt

Set register Rd to Rs shifted to the **right** by Rt digits

AND, XOR, LSHIFT, RSHIFT

AND	Rd, Rs, Rt	Set register Rd to Rs AND Rt
XOR	Rd, Rs, Rt	Set register Rd to Rs XOR Rt
LSHIFT	Rd, Rs, Rt	Set register Rd to Rs << Rt
RSHIFT	Rd, Rs, Rt	Set register Rd to Rs >> Rt

The instruction format similar to ADD, SUB:



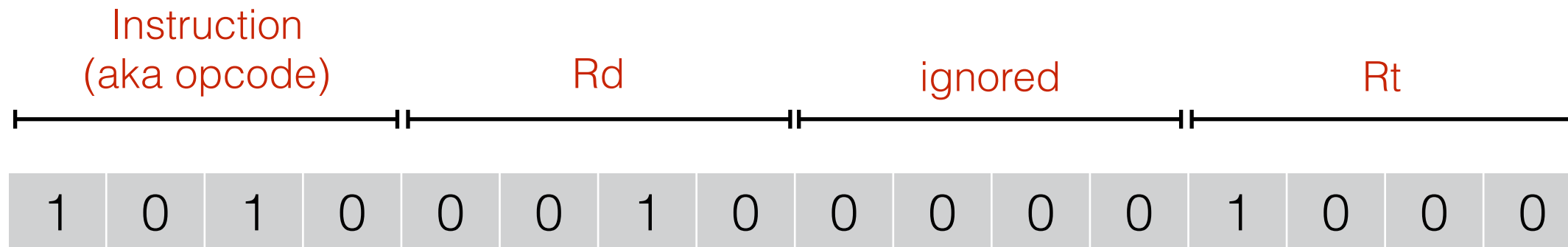
3 = AND	2 = R2	2 = R2	8 = R8	3228 ₁₆
4 = XOR	2 = R2	2 = R2	8 = R8	4228 ₁₆
5 = LSHIFT	2 = R2	2 = R2	8 = R8	5228 ₁₆
6 = RSHIFT	2 = R2	2 = R2	8 = R8	6228 ₁₆

Load Indirect

Use the value in a register as an address into RAM to read from:

`LOAD.I Rd, Rt`

Set register Rd to ram[Rt]



10 = `LOAD.I`

2 = R2

8 = R8

$A228_{16}$

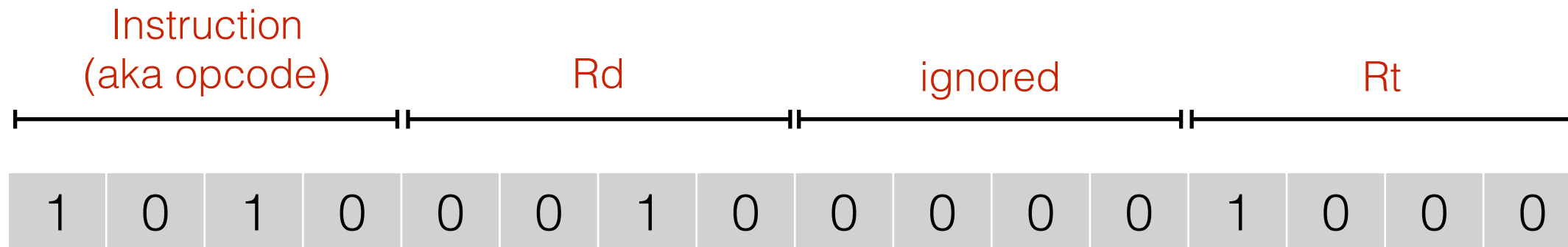
What's the analog in Go of this operation?

Load Indirect

Use the value in a register as an address into RAM to read from:

`LOAD.I Rd, Rt`

Set register Rd to ram[Rt]



10 = `LOAD.I`

2 = R2

8 = R8

$A228_{16}$

What's the analog in Go of this operation?

Pointer dereferencing with *:

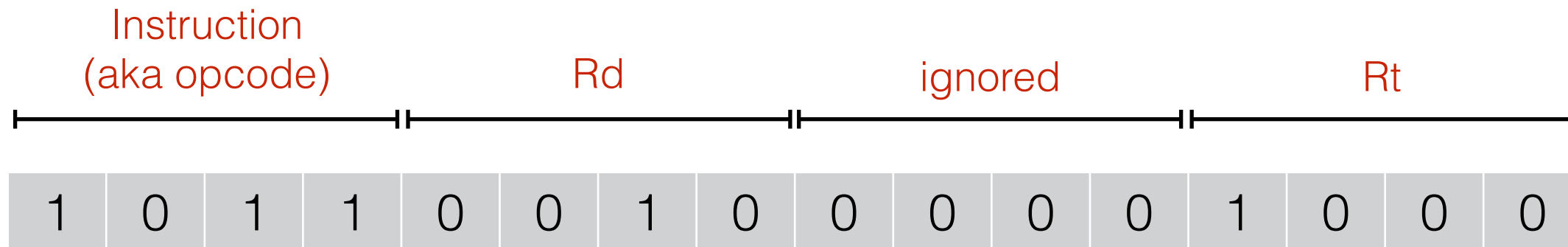
```
var r8 *int = 70 // not legal in Go
var r2 int
r2 = *r8         // LOAD.I R2 R8
```


Store Indirect

Use the value in a register as an address into RAM to write to:

STORE.I Rd, Rt

Set register ram[Rt] to Rd



11 = LOAD.I

2 = R2

8 = R8

B228₁₆

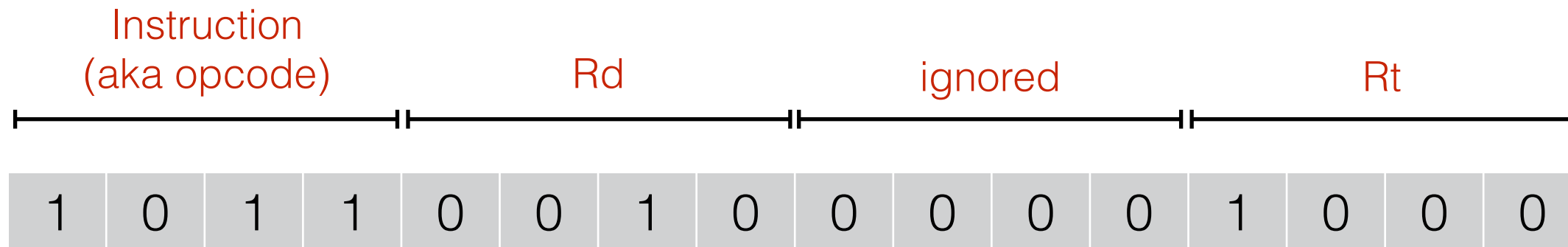
What's the analog in Go of this operation?

Store Indirect

Use the value in a register as an address into RAM to write to:

`STORE.I Rd, Rt`

Set register `ram[Rt]` to `Rd`



11 = `LOAD.I`

2 = `R2`

8 = `R8`

`B22816`

What's the analog in Go of this operation?

Pointer dereferencing with `*`
in an assignment:

```
var r8 *int = 70 // not legal in Go
var r2 int
*r8 = r2          // STORE.I R2 R8
```

Summary So Far

- Instructions are encoded as integers stored in memory.
- PC incremented after each instruction.
- Can read / write to memory using either an explicit address (immediate), or the contents of another register as the address (indirect)
- Can perform arithmetic operations on registers.
- Input / Output done via reads/writes to special memory locations.

How would we write an **for** loop?

Jumps: Manipulating the PC

JUMP Rd

Set PC to Rd

JMP0 Rd, addr

If Rd == 0, set PC to addr

```
15: LIMM R1, 1          // 7101
16: LIMM R5, 18         // 7518
17: ADD R6, R6, R0      // 1600
18: JMP0 R3, 1C         // C31C
19: ADD R6, R6, R2      // 1662
1A: SUB R3, R3, R1      // 2441
1B: JUMP R5             // E500
1C: STORE R2, FF        // 92FF
```

```
func mul(r2, r3 int) {
    r1 := 1
    r4 := r3 + 0

    for r4 != 0 {
        r2 = r2 + r3
        r4 = r4 - r1
    }
    fmt.Print(r2)
}
```

If Statements

JMPP Rd, addr

If $Rd > 0$, set PC to addr

```
if r3 >= r4 {  
    fmt.Println(r3)  
} else {  
    fmt.Println(r4)  
}
```

```
10: LIMM r5, 16  
11: SUB r2, r4, r3  
12: JMPP r2, 15  
13: STORE r3, FF  
14: JUMP r5  
15: STORE r4, FF  
16:
```

How would we write a condition $a == b$?

If Statements

JMPP Rd, addr

If $Rd > 0$, set PC to addr

```
if r3 >= r4 {  
    fmt.Println(r3)  
} else {  
    fmt.Println(r4)  
}
```

	10: LIMM r5, 16
condition	┌ 11: SUB r2, r4, r3
then part	┌ 13: STORE r3, FF
else part	┌ 15: STORE r4, FF

How would we write a condition $a == b$?

If Statements

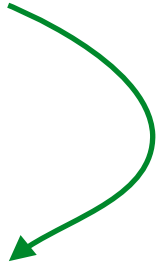
JMPP Rd, addr

If $Rd > 0$, set PC to addr

```
if r3 >= r4 {  
    fmt.Println(r3)  
} else {  
    fmt.Println(r4)  
}
```

	10:	LIMM r5, 16
condition	11:	SUB r2, r4, r3
	12:	JMPP r2, 15
then part	13:	STORE r3, FF
	14:	JUMP r5
else part	15:	STORE r4, FF
	16:	

if condition was false
($r4 - r3 > 0$)



How would we write a condition $a == b$?

If Statements

JMPP Rd, addr

If $Rd > 0$, set PC to addr

```
if r3 >= r4 {  
    fmt.Println(r3)  
} else {  
    fmt.Println(r4)  
}
```

	10:	LIMM r5, 16
condition	11:	SUB r2, r4, r3
	12:	JMPP r2, 15
then part	13:	STORE r3, FF
	14:	JUMP r5
else part	15:	STORE r4, FF
	16:	

if condition was false
($r4 - r3 > 0$)

Skip the else part if
we did the then part

How would we write a condition $a == b$?

Example If Statement #2

```
if r3 == r4 {  
    fmt.Println(r3)  
} else {  
    fmt.Println(r4)  
}
```

```
10: LIMM r5, 16  
11: SUB r2, r4, r3  
12: JMPO r2, 15  
13: STORE r4, FF  
14: JUMP r5  
15: STORE r3, FF  
16:
```

Example If Statement #2

```
if r3 == r4 {  
    fmt.Println(r3)  
} else {  
    fmt.Println(r4)  
}
```

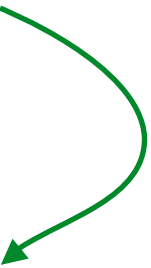
	10: LIMM r5, 16
condition	11: SUB r2, r4, r3
	12: JMPO r2, 15
else part	13: STORE r4, FF
	14: JUMP r5
then part	15: STORE r3, FF
	16:

Example If Statement #2

```
if r3 == r4 {  
    fmt.Println(r3)  
} else {  
    fmt.Println(r4)  
}
```

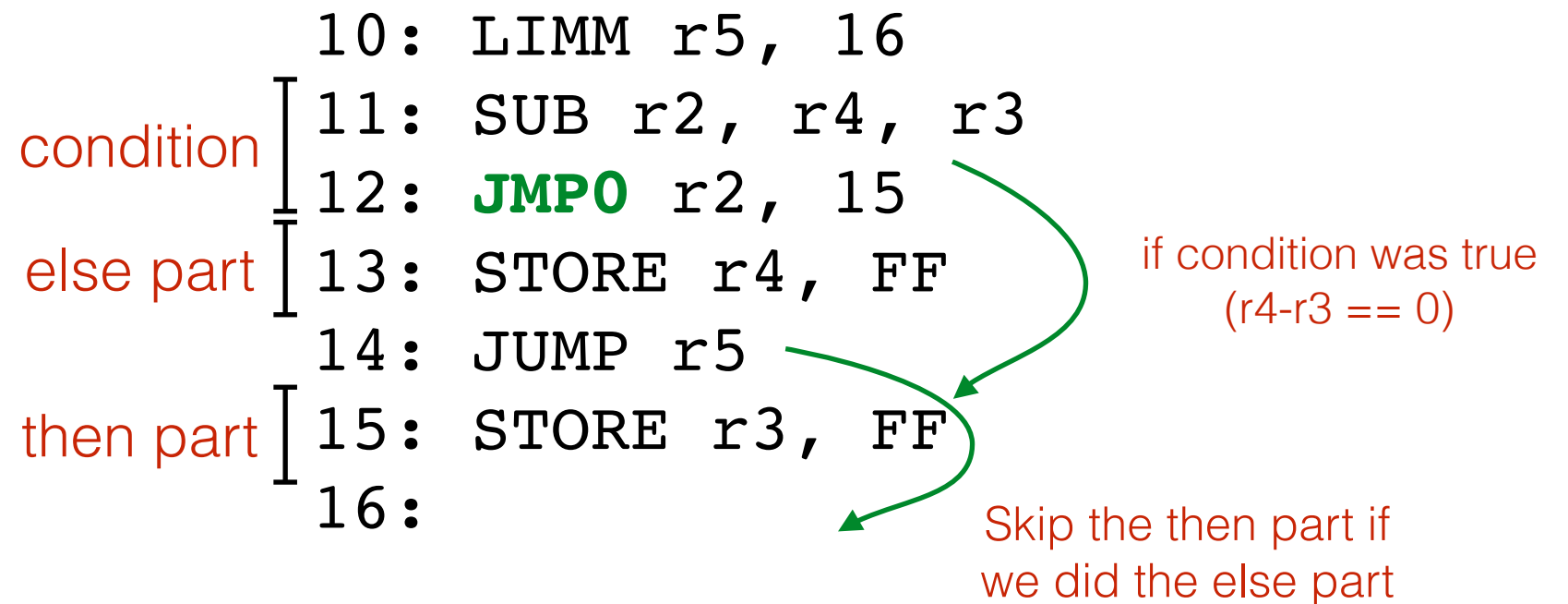
	10:	LIMM r5, 16
condition	11:	SUB r2, r4, r3
	12:	JMPO r2, 15
else part	13:	STORE r4, FF
	14:	JUMP r5
then part	15:	STORE r3, FF
	16:	

if condition was true
(r4-r3 == 0)



Example If Statement #2

```
if r3 == r4 {  
    fmt.Println(r3)  
} else {  
    fmt.Println(r4)  
}
```



Function Calls

Many processors (including Intel) have explicit “call” and “return” instructions.

X-TOY doesn't: it has an instruction that lets you write your own RET (RETURN) and CALL functions:

some code

RET fcn

JAL Rd, addr

Set Rd to PC+1
Set PC to addr

some other
code code
CALL fcn

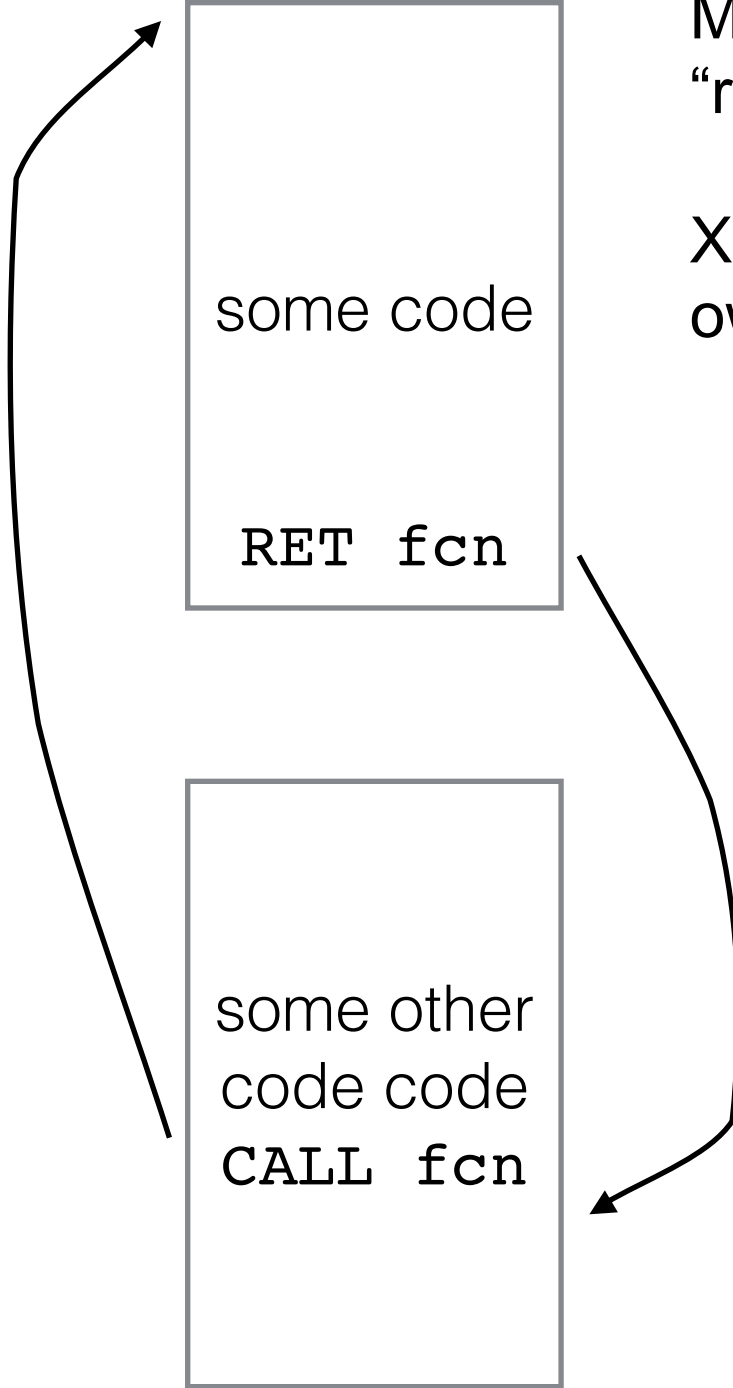
This is “jump and link”: it jumps to an address, and saves where you were in a register.

CALL addr

JAL R15, addr

RETURN

JUMP R15



Function Call Parameters

Note: a function is just a block of instructions that we plan to jump into from elsewhere in the program.

How can we pass parameters into a “function”?

Function Call Parameters

Note: a function is just a block of instructions that we plan to jump into from elsewhere in the program.

How can we pass parameters into a “function”?

Option 1: The caller and the function just agree about which registers to store the parameters in:

```
// R2 and R3 should contain the
// numbers to multiply; R15 should
// contain the address to return to
15: LIMM R1, 1           // 7101
16: LIMM R5, 18          // 7518
17: ADD R6, R6, R0       // 1600
18: JMP0 R3, 1C          // C31C
19: ADD R6, R6, R2       // 1662
1A: SUB R3, R3, R1       // 2441
1B: JUMP R5              // E500
1C: STORE R2, RF         // 92FF
1D: JUMP RF              // EF00
```

```
func mul(r2, r3 int) {
    r1 := 1
    r4 := r3 + 0

    for r4 != 0 {
        r2 = r2 + r3
        r4 = r4 - r1
    }
    fmt.Print(r2)
}
```

Example Call in X-TOY

```
program Mul
// Input: None
// Output: 8 * 2 = 16 = 0x10
//
10: 7208    R[2] <- 0008
11: 7302    R[3] <- 0002
12: FF15    R[F] <- pc; goto 15
13: 0000    halt
```

```
function mul
// Input: R2 and R3
// Return address: R15
// Output: to screen
// Temporary variables: R5, R6
15: 7101    R[1] <- 0001
16: 7518    R[5] <- 0018
17: 1600    no-op
18: C31C    if (R[3] == 0) goto 1C
19: 1662    R[6] <- R[6] + R[2]
1A: 2331    R[3] <- R[3] - R[1]
1B: E500    goto R[5]
1C: 96FF    write R[6]
1D: EF00    goto R[F]
```

Notes:

Program starts at address 0x10

You must say the address of every line of code by prefixing it with addr:

(X-TOY Bugs? 1600 is not a no-op and FF15 sets RF to **pc+1**)

Option 2: Push Parameters onto the Stack

Agree that the stack grows from memory address FE downward towards 0

Agree that R14 always holds a pointer to the top of the stack

"PUSH R7"

```
LIMM R1, 1
ADD RE, RE, R1
STORE.I R7 RE
```

"POP R9"

```
LOAD.I R9 RE
LIMM R1, 1
SUB RE, RE, R1
```



Option 2: Push Parameters onto the Stack

```
// The top of the stack should contain the
// two numbers to multiply; R15 should
// contain the address to return to
```

10: LOAD.I R2 , RE	// A20E	← Grab the number at the top of the stack
11: LIMM R1, 1	// 7101	┌ "pop": move the top of the stack └ down by 1
12: SUB RE, RE, R1	// 2EE1	
13: LOAD.I R3, RE	// A30E	← Grab the number at the top of the stack
14: SUB RE, RE, R1	// 2EE1	← move the top of the stack down by 1
15: LIMM R1, 1	// 7101	
16: LIMM R5, 18	// 7518	
17: ADD R6, R6, R0	// 1600	
18: JMP0 R3, 1C	// C31C	
19: ADD R6, R6, R2	// 1662	
1A: SUB R3, R3, R1	// 2441	
1B: JUMP R5	// E500	
1C: STORE R6, FF	// 96FF	
1D: JUMP RF	// EF00	

How many registers are there?

16 in X-TOY

This is a typical number (8-32)

What if you “run out”?

Yep, that’s a problem: you may have to shuffle variables between RAM and registers if you need to use the registers for something.

Summary of X-TOY Computer

INSTRUCTION FORMATS

		
Format 1:		op		d		s		t	
Format 2:		op		d		imm			

ARITHMETIC and LOGICAL operations

1: add	$R[d] \leftarrow R[s] + R[t]$
2: subtract	$R[d] \leftarrow R[s] - R[t]$
3: and	$R[d] \leftarrow R[s] \& R[t]$
4: xor	$R[d] \leftarrow R[s] \wedge R[t]$
5: shift left	$R[d] \leftarrow R[s] \ll R[t]$
6: shift right	$R[d] \leftarrow R[s] \gg R[t]$

TRANSFER between registers and memory

7: load immediate	$R[d] \leftarrow \text{imm}$
8: load	$R[d] \leftarrow \text{mem}[\text{imm}]$
9: store	$\text{mem}[\text{imm}] \leftarrow R[d]$
A: load indirect	$R[d] \leftarrow \text{mem}[R[t]]$
B: store indirect	$\text{mem}[R[t]] \leftarrow R[d]$

CONTROL

0: halt	halt
C: branch zero	if ($R[d] == 0$) $pc \leftarrow \text{imm}$
D: branch pos.	if ($R[d] > 0$) $pc \leftarrow \text{imm}$
E: jump register	$pc \leftarrow R[d]$
F: jump and link	$R[d] \leftarrow pc; pc \leftarrow \text{imm}$

$R[0]$ always reads 0.

Loads from $\text{mem}[\text{FF}]$ come from stdin.

Stores to $\text{mem}[\text{FF}]$ go to stdout.

From the X-TOY instructions

X-TOY Environment

The screenshot displays the X-TOY environment interface, titled "Mul - Visual X-TOY". The interface is divided into several sections:

- File Editor:** Contains a menu bar (File, Edit, Mode, Workspace, Tools) and a toolbar with icons for file operations (new, open, save, print, copy, paste, delete, undo, redo, zoom in, zoom out, full screen, help).
- Code Editor:** Displays assembly code for a program named "Mul". The code includes comments and instructions for input, output, and arithmetic operations. The current instruction being executed is highlighted in blue.
- Execution Controls:** Located at the bottom left, it includes fields for "Steps..." (0), "Elapse..." (0.000 s), "Refre..." (1 spr), and "Target Clock..." (100 ms). It also features buttons for "Step", "Run", "Reset", and "Interrupt".
- Core Dump View:** Located on the right side, it shows the state of the program's core. It includes tabs for "Reference", "Stdin", "Stdout", and "Core". The "Core" tab is selected, showing the "Program Counter" (0010), "Current Instruction" (7208), and a list of registers (R[0] through R[15]) with their current values. Below the registers is a "Memory" section showing the state of memory locations (mem[00] through mem[09]).

```
1 program Mul
2 // Input: None
3 // Output: 8 * 2 = 16 = 0x10
4 // -----
5 10: 7208 R[2] <- 0008
6 11: 7302 R[3] <- 0002
7 12: FF15 R[F] <- pc; goto 15
8 13: 0000 halt
9
10 function mul
11 // Input: R2 and R3
12 // Return address: R15
13 // Output: to screen
14 // Temporary variables: R5, R6
15 15: 7101 R[1] <- 0001
16 16: 7518 R[5] <- 0018
17 17: 1600 no-op
18 18: C31C if (R[3] == 0) goto 1C
19 19: 1662 R[6] <- R[6] + R[2]
20 1A: 2331 R[3] <- R[3] - R[1]
21 1B: E500 goto R[5]
22 1C: 96FF write R[6]
23 1D: EF00 goto R[F]
```

Core Dump View:

Core

Program Counter: 0010 (0000 0000 0001 0000,)

Current Instruction: 7208 (R[2] <- 0008)

Registers:

- R[0] = 0000 (0000 0000 0000 0000, 0)
- R[1] = ??? (Uninitialized Value)
- R[2] = ??? (Uninitialized Value)
- R[3] = ??? (Uninitialized Value)
- R[4] = ??? (Uninitialized Value)
- R[5] = ??? (Uninitialized Value)
- R[6] = ??? (Uninitialized Value)
- R[7] = ??? (Uninitialized Value)
- R[8] = ??? (Uninitialized Value)
- R[9] = ??? (Uninitialized Value)

Memory:

- mem[00] = ??? (Uninitialized Value)
- mem[01] = ??? (Uninitialized Value)
- mem[02] = ??? (Uninitialized Value)
- mem[03] = ??? (Uninitialized Value)
- mem[04] = ??? (Uninitialized Value)
- mem[05] = ??? (Uninitialized Value)
- mem[06] = ??? (Uninitialized Value)
- mem[07] = ??? (Uninitialized Value)
- mem[08] = ??? (Uninitialized Value)
- mem[09] = ??? (Uninitialized Value)

Intel 8088 Instruction Set

ADD	Add
-----	-----

SUB	Subtraction
-----	-------------

AND	Logical AND
-----	-------------

XOR	Exclusive OR
-----	--------------

SHL	Shift left (unsigned shift left)
-----	----------------------------------

SHR	Shift right (unsigned shift right)
-----	------------------------------------

JMP	Jump
-----	------

JCXZ	Jump if CX is zero
------	--------------------

JNS	Jump if not negative
-----	----------------------

INC	Increment by 1
-----	----------------

DEC	Decrement by 1
-----	----------------

Another motivation for the ++ and -- statements in Go (and C, c++, Java..): They correspond directly to a machine instruction.

PUSH	Push data onto stack
------	----------------------

POP	Pop data from stack
-----	-------------------------------------

Has several instructions to push and pop data onto THE stack.

and about 80 others...

http://en.wikipedia.org/wiki/X86_instruction_listings#Original_8086.2F8088_instructions

MacPaint



<http://www.computerhistory.org/atcm/macpaint-and-quickdraw-source-code/>

Summary

- Trees are an incredibly common way to organize data:
 - folders on your hard drives
 - URLs: <http://www.cs.cmu.edu/~ckingsf/software/sailfish>
 - BST, Splay trees, AVL trees, B-trees, Quad-trees, kd-trees, red-black trees, M-trees, ... probably thousands of variants that are good for different data and different queries.
- Binary trees in particular are nice because each node partitions the data into 2 subsets and because there are nice relationships between # of nodes and # of leaves, etc.
- Typically, trees are represented using nodes & pointers, though this does not have to be the case.