SCATwheel repository

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1 Introduction

This document describes the SCATwheel repository.

1.1 Model

tbd

References

[1] Pablo Inigo-Blasco, "The Shared Control Dynamic Window Approach for Non-Holonomic Semi-Autonomous Robots" in *ISR/Robotik 2014; 41st International Symposium on Robotics, 2-3 June 2014*

[2] https://projects.coin-or.org/CppAD