Gesture Recognition Case Study

In this project, we are supposed to build a deep learning model which takes videos of 30 fps as inputs and helps us in recognizing which gesture in the input has been performed to link to a well-defined action in the television.

Each gesture is linked to some action to be performed on the television.

Thumbs Up: Increase the volume
Thumbs Down: Decrease the volume
Left Swipe: 'Jump' backwards 10 seconds
Right Swipe: 'Jump' forward 10 seconds

• Stop: Pause the movie

We first begin with building a generator function. The generator function is used for better utilization of memory as memory is used according to the batch size.

Now, to further reduce the training time, we do not use all the 30 frames. We may reduce the number of frames to be used per video using the following option:

• **Using Alternate Images:** We chose this option because consecutive frames/images might contain similar information. Hence, we may use only one of them. Through this method, we take the number of frames as just 15.

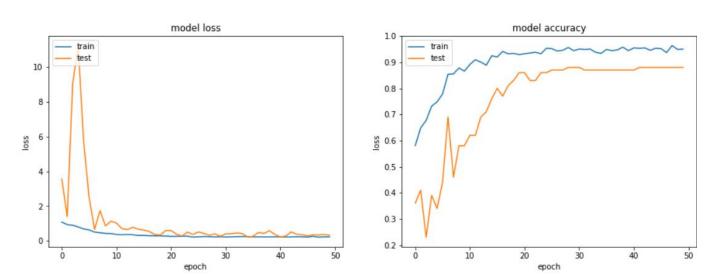
We then resize the images using cv2.resize() command from the Open CV Library in Python. We use the divide by 255 method to normalize the images.

Model History: Each of us tried at least 30 experiments before. But in all these experiments, our models were overfitting. (You may check those experiments here). We already used different kind of models which reduced the number of training parameters. Upon careful thought, we realized that our generator code was not properly made. We assumed that the images shall have central cropping which was wrong. So we used the cv2.resize() function to resize our images. After the change in generator code, we started getting good results. We chose the models from which we got the best results during our earlier experiments. The results of our experiments after changing the generator code are as follows:

Experiment			Batch	Image	Number of		Explanation for next
No.	Model Type	Brief Description	Size	Size	Epochs	Result	step
		Three convolution					
		groups with 8,16 and					
		32 filters of size (3,3,3).					
		Each conv groups					
		consists of two conv					
		layers and each group					
		is followed by					
		maxpooling layer with					
		(2,2,2) filter size. This is					
		followed by a dense					
		layer with 128 neurons					
		and then again by a				-	
		dense layer with 16				Training	
		neurons. Lastly, there is				Accuracy: 100%,	Clearly, the model is
1	Conv2D	a softmax layer with 5	61	(00.00)	12	Validation	learning but there is
1	Conv3D	neurons.	64	(90,90)	12	Accuracy: 24%	overfitting. Overfitting has been
		The same model as					reduced. Moreover,
		mentioned above but					seeing the Loss
		we add dropout of					Accuracy plot, we think
		value 0.5 in the first					there is scope for
		dense layer and				Training	further improvement
		another dropout of				Accuracy: 72.4%,	rate. We increase the
	Conv3D with	value 0.25 in the				Validation	learning rate to 0.1 for
2	Dropouts	second dense layer.	64	(90,90)	50	Accuracy: 71%	faster training.
							Overfitting is reduced
							and we have
							improvement in
							accuracies. Moreover,
		Th				-	seeing the loss
		The same model as				Training	accuracy plot, we
	Conv 2D with	mentioned above but				Accuracy: 95%,	realize the model
3	Conv 3D with Dropouts	we change the learning rate to 0.1.	64	(90,90)	50	Validation Accuracy: 88%	training has reached its plateau (flatter curve).
<u> </u>	Diopouts	Five time distributed	04	(30,30)	30	Accuracy. 00/0	piateau (nattei cuive).
		conv layers with				Training	We observe
		number of filters from				Accuracy: 80%,	overfitting. We now try
	CNN+RNN:	2^3 to 2^7. Each filter				Validation	Transfer Learning for
4	Self-Made	is of (3,3,3) size.	32	(90,90)	13	Accuracy: 30%	faster training.
				,			There is no overfitting.
							However, seeing the
	CNN+RNN:						Loss Accuracy plot, we
	Using Transfer	We use Mobilenet as				Training	observe that there is
	Learning with	base model and then to				Accuracy: 76%,	scope for
	Mobilenet as	the time based analysis				Validation	improvement in
5	base model.	using GRU	32	(90,90)	14	Accuracy: 75%	accuracy.

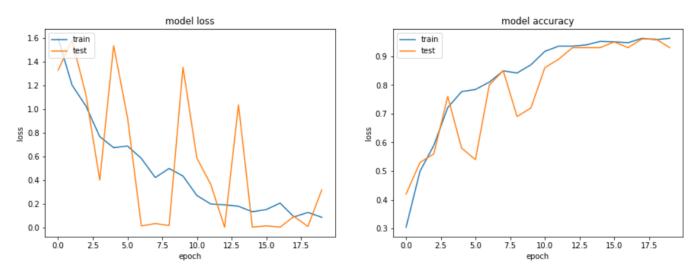
6	CNN+RNN: Using Transfer Learning with Mobilenet as base model.	Same as above	20	(90,90)	25	Training Accuracy:86%, Validation Accuracy:81%	We observe that there is an improvement in accuracy with reduction in batch size. Therefore, we build another model with even lesser batch size and a little higher learning rate.
7	CNN+RNN: Using Transfer Learning with Mobilenet as base model.	Same as above	16	(90,90)	20	Training Accuracy:96%, Validation Accuracy:93%	There is hardly any overfitting and we reach very high accuracy.
8	Conv3D with Dropouts	We use the same model as in Experiment 3 but apply edge detection as a preprocessing step in the data.	64	(90,90)	14	Training Accuracy: 95.3%, Validation	There is overfitting in the model.
9	Conv 3D with Dropouts	Same as above but we add dropouts in the 3rd convolution group layers with 0.2 q value.	32	(90,90)	13	Training Accuracy: 60%, Validation Accuracy:16%	Again, there is overfitting. Therefore, we do not try this approach anymore and stick with the best models achieved before.

BEST CONV 3D MODEL:



Experiment 3: This model has 95% Training Accuracy and 88% Validation Accuracy. Moreover, the loss is almost similar for both. You may find the .h5 link here.

BEST CNN+RNN MODEL:



Experiment 7: This model has 96% Training Accuracy and 93% validation accuracy. This is our best model because it gives us high accuracy with minimal overfitting. You may find the .h5 link here.

FINAL MODEL:

We choose the Mobilenet CNN+RNN model because it gives us high accuracy with minimal overfitting. Even though this model has more than 3 million parameters, we are certain that it will run very fast as per the following reference from tensorflow:

Model Name	Device	CPU, 4 threads	GPU	NNAPI
Mobilenet_1.0_224(float)	Pixel 3	23.9 ms	6.45 ms	13.8 ms
	Pixel 4	14.0 ms	9.0 ms	14.8 ms
Mobilenet_1.0_224 (quant)	Pixel 3	13.4 ms		6.0 ms
	Pixel 4	5.0 ms		3.2 ms