# Surafel Anshebo

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#### **EDUCATION**

VIRGINIA TECH May 2023 - Present

Master of Science, Mechanical Engineering

ABABA SCIENCE AND TECHNOLOGY UNIVERSITY

2013 - 2018

Bachelor of Science, Mechanical Engineering

## PROFESSIONAL EXPERIENCE

#### VIRGINIA TECH

#### Graduate research assistant

May 2023 - Present

- Provided guidance to up to 50 students for drone technology and flight operations classes through office hours. Assisted with coursework, assignments and projects.
- Developed a BVLOS (Beyond visual line of sight) flight simulator using Python, Docker, Leaflet, and Dronekit-Python, enabling mission planning and flight risk assessment.

## **COCA COLA BEVERAGES**

# Line process engineer

Dec 2018 - Dec 2023

- Maintained compliance with Safety, Health, Environment, and Quality (SHEQ) standards.
- Optimized overall Equipment Efficiency (OEE) by understanding the structure of all machines to detect abnormalities and conduct Root Cause Analysis (RCA) on different breakdowns using SAP.
- Achieved and maintained 90% Machine efficiency (ME) and 85% Unconstrained system line efficiency, exceeding production targets and ensuring operational reliability.

#### **SKILLS**

- Software: Python, C++, MATLAB, ROS, Flask, Docker, OpenCV, Dronekit-Python, SolidWorks, QGIS, SAP
- Hardware: Raspberry pi, STM32, Arduino, Vicon motion capture, 3D Printing
- Certifications: Part 107, SolidWorks Associate (CSWA)

## **PROJECTS**

# Vicon motion capture for an indoor flight

Nov 2024

- Conducted system calibration to minimize tracking errors, ensuring millimeter accuracy in position estimate.
- Configured and integrated a Raspberry Pi 3B as a companion computer to enhance drone capabilities in autonomous flight
- Deployed ROS nodes on the Raspberry Pi to handle communication between the motion capture system, flight controller and onboard sensors.

# Full state feedback control using pole placement

Dec 2023

• Developed a smooth and controlled landing system for a simulated drone by implementing full-state feedback control in MATLAB. Utilized pole placement techniques to optimize system dynamics, ensuring a stable and precise descent.

## Flood Hazard Mapping and Drone-Based Life-Saving Vest Delivery System

Nov 2022

• Mapped areas that are prone to flood hazard using aerial image using QGIS and designed a gripper in SolidWorks to be mounted on S500 drones used for delivering lifesaving vests.

## **PUBLICATION**

 D. Aggarwal, S.T. Anshebo, K. Kochersberger, A.L. Abbott. "Comparative Study of Vision-Based Methods for Real-Time Traffic Monitoring," XPONENTIAL 2024 Conference, pp. 68-79. DOI: 10.52202/075106-0004.

## **LEADERSHIP**

## AMERICAN SOCIETY OF MECHANICAL ENGINEERS

# TREASURER

May 2024 - Present

Maintain financial records and ensure that all accounts and records are maintained in accordance with the school and ASME policies.