PRACTICAL 4(b)

Aim: To solve the system of equations using Gauss Jordan method.

ASSIGNMENT

1 Q1. Solve the following system of equations

2x1 + x2 - x3 = 1

5x1 + 2x2 + 2x3 = -4

3x1 + x2 + x3 = 5

using the Gauss-Jordan method.

 $R2 \rightarrow R2 - -9.0 * R3$

```
kill(all)$
     keepfloat:true$
                                  /*...Coefficient Matrix...*/
     A:matrix(
             [2.0, 1.0, -1.0],
             [5.0, 2.0, 2.0],
             [3.0, 1.0, 1.0])$
                                  /*...Constants Matrix...*/
     B:matrix(
             [1.0], [-4.0], [5.0])$
     X:matrix(
                                  /*...Variables Matrix...*/
             [x], [y], [z])$
     print("Now, the augmented matrix will be,")$
     Aug:addcol(A,B); /*...Creating Augmented Matrix...*/
     print(" ");
     print("Now, the Echelon Form is,")$
     S : echelon(Aug);
                                 /*..Calculates Echolen Form of Matrix..*/
     print(" ");
     print("R2 -> R2 - ", float(S[2][3]), " * R3")$
     S[2] : S[2] - S[2][3].S[3]$
     S;
     print(" ");
     print("R1 -> R1 - ",float(S[1][3])," * R3")$
     S[1] : S[1] - S[1][3].S[3]$
     S:
     print(" ");
     print("R1 -> R1 - ",float(S[1][2])," * R2")$
     S[1] : S[1] - S[1][2].S[2]$
     S;
     print(" ");
     print("The Solution Matrix is: ")$
     X=col(S,4);
     Now, the augmented matrix will be,
     2.0 1.0 -1.0 1.0
(%06) 5.0 2.0 2.0 -4.0
      3.0 1.0 1.0 5.0
     Now, the Echelon Form is,
      1 0.5 -0.5 0.5
(%09) 0 1 -9.0 13.0
```

2 Q2.Solve the following system of equations

$$x + y - z = -3$$

 $6x + 2y + 2z = 2$
 $-3x + 4y + z = 1$

using the Gauss-Jordan method.

 $R2 \rightarrow R2 - -2.0 * R3$

```
kill(all)$
     keepfloat:true$
                                  /*...Coefficient Matrix...*/
     A:matrix(
              [1.0, 1.0, -1.0],
              [6.0, 2.0, 2.0],
              [-3.0, 4.0, 1.0])$
                                  /*...Constants Matrix...*/
     B:matrix(
              [-3.0], [2.0], [1.0])$
     X:matrix(
                                  /*...Variables Matrix...*/
              [x], [y], [z])$
     print("Now, the augmented matrix will be,")$
     Aug:addcol(A,B); /*...Creating Augmented Matrix...*/
     print(" ");
     print("Now, the Echelon Form is,")$
     S : echelon(Aug);
                                 /*..Calculates Echolen Form of Matrix..*/
     print(" ");
     print("R2 -> R2 - ", float(S[2][3]), " * R3")$
     S[2] : S[2] - S[2][3].S[3]$
     S;
     print(" ");
     print("R1 -> R1 - ",float(S[1][3])," * R3")$
     S[1] : S[1] - S[1][3].S[3]$
     S:
     print(" ");
     print("R1 -> R1 - ",float(S[1][2])," * R2")$
     S[1] : S[1] - S[1][2].S[2]$
     S;
     print(" ");
     print("The Solution Matrix is: ")$
     X=col(S,4);
     Now, the augmented matrix will be,
      1.0 1.0 -1.0 -3.0
     6.0 2.0 2.0 2.0
-3.0 4.0 1.0 1.0
     Now, the Echelon Form is,
      1 1.0 -1.0 -3.0
(%09) 0 1 -2.0 -5.0
```

3 Q3.Using the Gauss-Jordan method, find the inverse of the following matrix.

([1 2 3]

[0 1 5]

[5 6 0])

```
kill(all)$
keepfloat:true$
A:matrix(
                            /*...Given Matrix...*/
        [1.0, 2.0, 3.0],
        [0.0, 1.0, 5.0],
        [5.0, 6.0, 0.0])$
                            /*...Identity Matrix...*/
B:matrix(
        [1.0, 0.0, 0.0],
        [0.0, 1.0, 0.0],
        [0.0, 0.0, 1.0])$
print("Now, the augmented matrix will be,")$
Aug:addcol(A,B);
                         /*...Creating Augmented Matrix...*/
print("")$
print("The Echelon Form is :")$
                           /*..Calculates Echolen Form of Matrix..*/
S : echelon(Aug);
print(" ")$
/*..Operations so as to form reduced row echelon form..*/
print("R2 -> R2 - ",float(S[2][3])," * R3")$
S[2] : S[2] - S[2][3].S[3]$
print(" ")$
print("R1 -> R1 - ",float(S[1][3])," * R3")$
S[1] : S[1] - S[1][3].S[3]$
S;
print(" ")$
print("R1 -> R1 - ",float(S[1][2])," * R2")$
S[1] : S[1] - S[1][2].S[2]$
S;
print(" ")$
print("The Inverse of the Given Matrix is: ")$
Inv: submatrix(S, 1, 2, 3);
Now, the augmented matrix will be,
1.0 2.0 3.0 1.0 0.0 0.0
0.0 1.0 5.0 0.0 1.0 0.0
5.0 6.0 0.0 0.0 0.0 1.0
The Echelon Form is:
1 1.2 0 0 0 0.2
  1 5.0 0 1.0
R2 \rightarrow R2 - 5.0 * R3
1 1.2 0 0 0 0.2
  1 0.0 5.0 -3.0 -1.0
```

1 -1.0 0.8

4 Q4.Solve the following given system of equations -3y + 7z = 2 x + 2y - z = 35x - 2y = 2

using the Gauss-Jordan method

```
kill(all)$
keepfloat:true$
                           /*...Coefficient Matrix...*/
A:matrix(
        [0.0, -3.0, 7.0],
        [1.0, 2.0, -1.0],
        [5.0, -2.0, 0.0])$
                           /*...Constants Matrix...*/
B:matrix(
        [2.0], [3.0], [2.0])$
X:matrix(
                           /*...Variables Matrix...*/
        [x], [y], [z])$
print("Now, the augmented matrix will be,")$
Aug:addcol(A,B); /*...Creating Augmented Matrix...*/
print(" ");
print("Now, the Echelon Form is,")$
S : echelon(Aug);
                          /*..Calculates Echolen Form of Matrix..*/
print(" ");
print("R2 -> R2 - ", float(S[2][3]), " * R3")$
S[2] : S[2] - S[2][3].S[3]$
S;
print(" ");
print("R1 -> R1 - ",float(S[1][3])," * R3")$
S[1] : S[1] - S[1][3].S[3]$
S:
print(" ");
print("R1 -> R1 - ",float(S[1][2])," * R2")$
S[1] : S[1] - S[1][2].S[2]$
S;
print(" ");
print("The Solution Matrix is: ")$
X=col(S,4);
Now, the augmented matrix will be,
0.0 -3.0 7.0 2.0
1.0 2.0 -1.0 3.0
5.0 -2.0 0.0 2.0
Now, the Echelon Form is,
1 -0.4
               0
                              0.4
    0.9130434782608696
```

5 Q5.Show that the following
 system of equations have
 infinite number of solutions
 :

$$x + y - 3z = 4$$

 $2x + y - z = 2$
 $3x + 2y - 4z = 6$.

```
kill(all)$
     keepfloat:true$
     A:matrix(
                                 /*...Coefficient Matrix...*/
              [1.0, 1.0, -3.0],
              [2.0, 1.0, -1.0],
              [3.0, 2.0, -4.0])$
                                  /*...Constants Matrix...*/
     B:matrix(
              [4.0], [2.0], [6.0])$
                                  /*...Variables Matrix...*/
     X:matrix(
              [x], [y], [z])$
     print("Now, the augmented matrix will be,")$
     Aug:addcol(A,B);
                        /*...Creating Augmented Matrix...*/
     print(" ");
     print("Now, the Echelon Form is,")$
                                 /*..Calculates Echolen Form of Matrix..*/
     S : echelon(Aug);
     print(" ");
     print("R2 -> R2 - ",float(S[2][3])," * R3")$
     S[2] : S[2] - S[2][3].S[3]$
     S;
     print(" ");
     print("R1 -> R1 - ",float(S[1][3])," * R3")$
     S[1] : S[1] - S[1][3].S[3]$
     S:
     print(" ");
     print("R1 -> R1 - ",float(S[1][2])," * R2")$
     S[1] : S[1] - S[1][2].S[2]$
     S;
     /*..The last row after solving the matrix consists of all zeroes
     this shows that the given set of equations has infinite number of
     solutions...*/
     Now, the augmented matrix will be,
     1.0 1.0 -3.0 4.0
(%06) 2.0 1.0 -1.0 2.0
      3.0 2.0 -4.0 6.0
     Now, the Echelon Form is,
      1 1.0 -3.0 4.0
                      * R3
     R2 \rightarrow R2 - -5.0
      1 1.0 -3.0 4.0
```